EY-D5283-SG-002

DIGITAL

VAX 11/750

MAGIC BOOK

Rev. 8 JAN-1-1983

V A X 1 1 / 7 5 0 M A G I C B O O K
FOR INTERNAL USE ONLY

THIS TEXT WAS CREATED IN AN ATTEMPT TO CENTRALIZE THE ESSENTIAL INFORMATION REQUIRED TO MAINTAIN THE 11/750 AT A BRANCH LEVEL. CONTAINED IN THIS TEXT IS INFORMATION CONCERNING BOARD LOCATIONS, GATE ARRAYS LOCATED ON EACH BOARD, BASIC FUNCTIONS OF THE CHIPS, PART NUMBERS, AND MISC. OTHER INFORMATION YOU MIGHT FIND USEFUL WHEN INSTALLING OR MAINTAINING THE VAX 11/750 SYSTEMS.

THE INTENT OF THIS GUIDE IS NOT TO BECOME A STEP BY STEP TROUBLESHOOTING TOOL, ONLY TO MAKE SOME USEFUL INFORMATION AVAILABLE IN A SINGLE PACKAGE.

INDEX OF MAIN TOPICS

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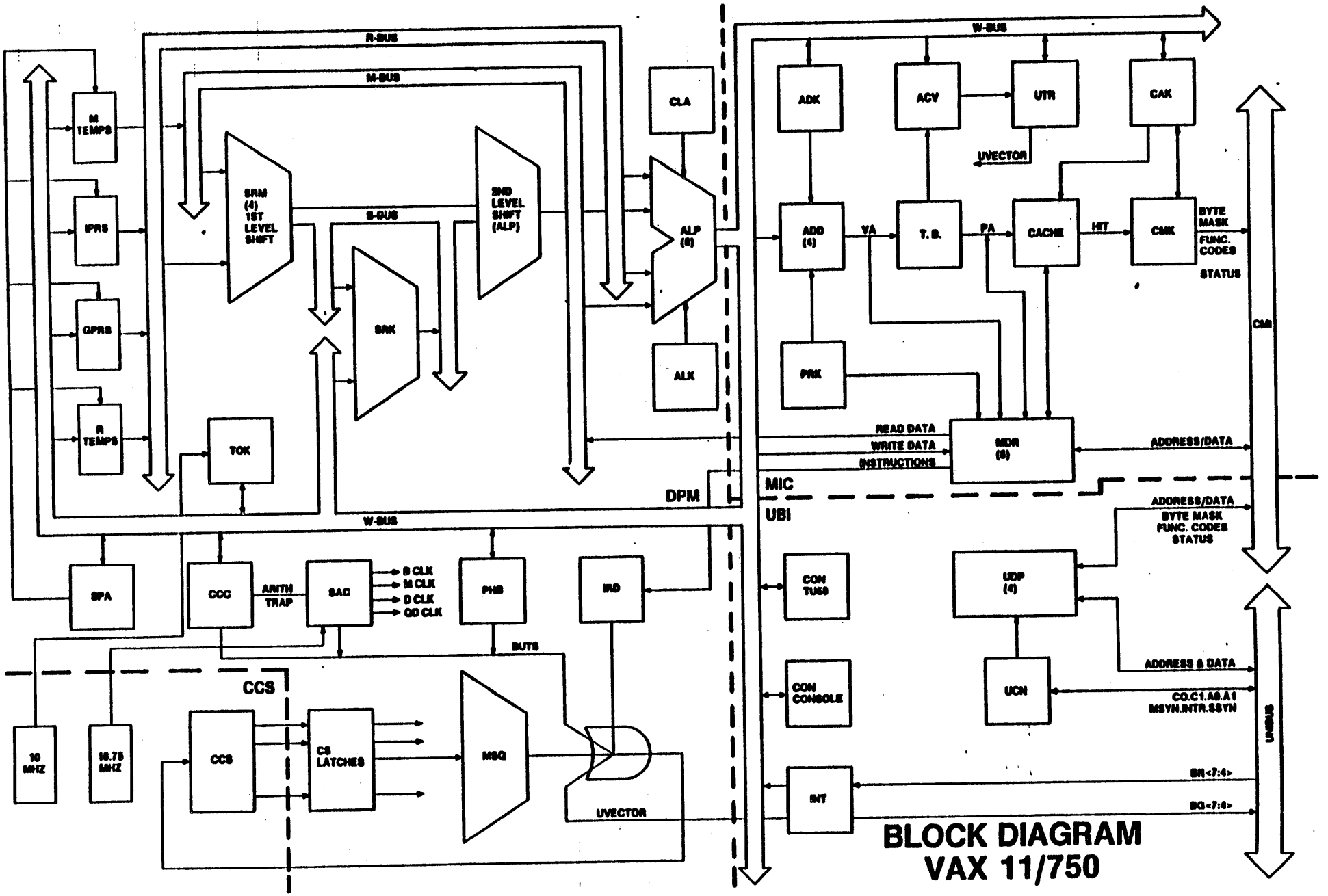


BLOCK DIAGRAM
VAX 11/750

(GATE ARRAY LEVEL)

VAX 11/750 MAINTENANCE PHILOSOPHY

- THE CUSTOMER IS REQUIRED TO PROVIDE A VOICE GRADE TELEPHONE LINE AND CONNECTOR FOR DDC (DIGITAL DIAGNOSTIC CENTER) COMMUNICATION. (THIS REQUIREMENT IS INCLUDED WITH POWER AND ENVIRONMENTAL REQUIREMENTS IN THE VAX 11/750 SITE PREPARATION GUIDE. P/N EK-CORP-SP-003) (REV. IS SUBJECT TO CHANGE)

- THE RDM OPTION WILL BE INSTALLED IN THE BACKPLANE OF ALL VAX 11/750 SYSTEMS DIGITAL INSTALLS, TO PROVE THE VALUE OF RD TO THE CUSTOMER DURING THE WARRANTY PERIOD. IT WILL BE LEFT IN THE BACKPLANE FOR ALL CUSTOMERS WITH THE STANDARD RD MAINTENANCE CONTRACT.

BASIC FLOW:

- THE CUSTOMER CALLS THE DDC "TOLL FREE NUMBER" WHEN THERE IS A PROBLEM.

  (NOTE: NUMBERS ARE SUBJECT TO CHANGE)

  1-800-525-6570 FOR DDC CONNECTION

  1-303-599-4000 FOR ENGINEER ASSISTANCE (NOT TOLL FREE)

  1-303-593-7890 U.S.F.S. LIBRARY D.E.C. EMPLOYEES ONLY

- MAIL STOP CX/DDC COLORADO SPRINGS, COLORADO

- THE DDC PERFORMS REMOTE SUBSYSTEM ISOLATION.

- THE DDC IDENTIFIES THE FAILING OPTION TO THE BRANCH OFFICE.

- THE BRANCH OFFICE SEND THE RIGHT ENGINEER WITH THE RIGHT PARTS TO FIX THE PROBLEM.

- FOR CPU PROBLEMS:

  THE ENGINEER TAKES THE CPU SPARES AND RDM TOOL TO THE SITE.

  THE ENGINEER RUNS THE TU58 MICRODIAGNOSTIC CASSETTE TAPES.

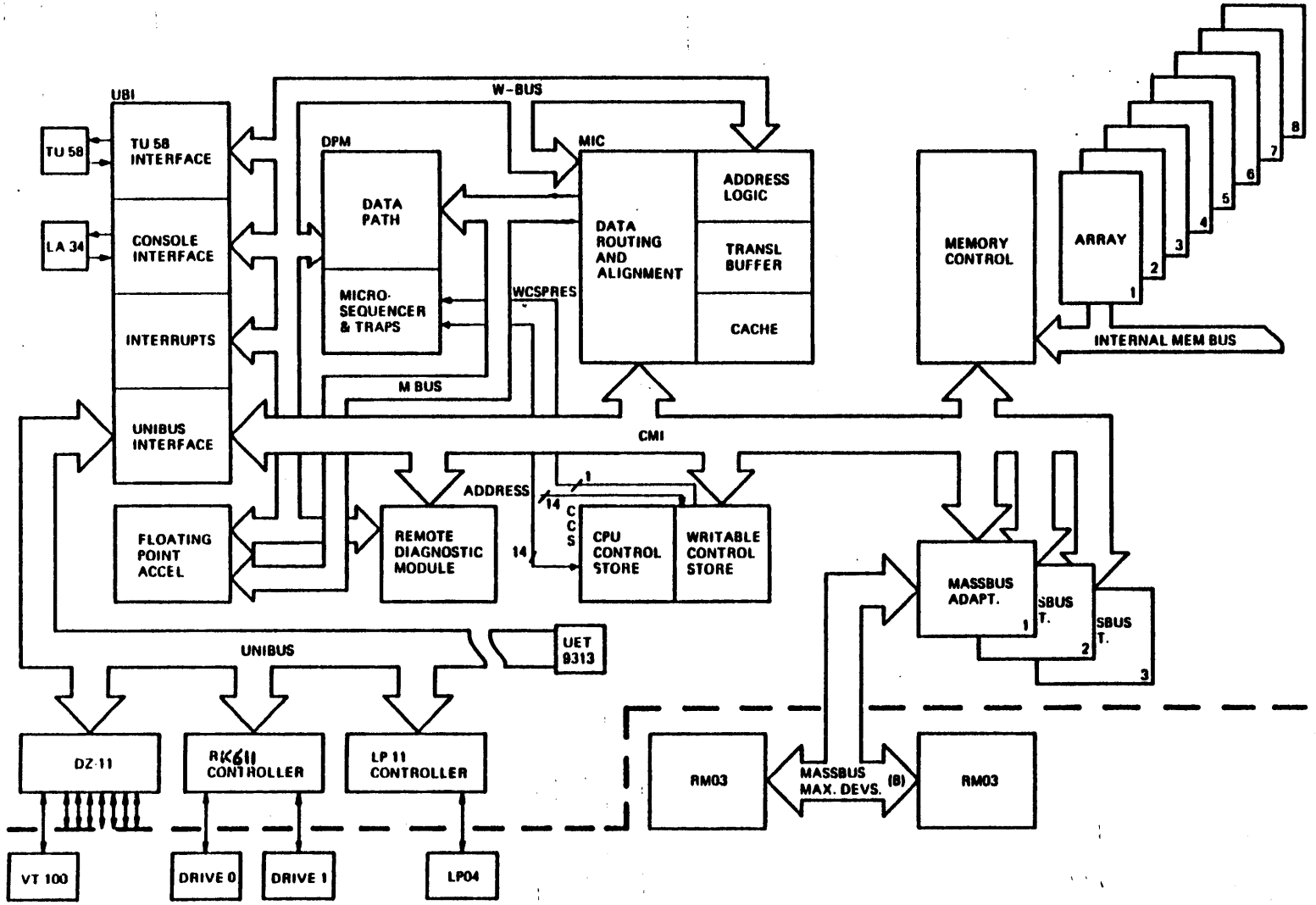
  FOR CUSTOMERS WITH NON-RD CONTRACTS, THE ENGINEER INSTALLS THE RDM TOOL INTO THE VAX 11/750 BACKPLANE, AND REMOVES IT WHEN HE/SHE COMPLETES THE WORK.

- ON CPU LOGIC MODULES, FAULTS ARE ISOLATED TO A SPECIFIC MODULE AND SIMULTAINEOUSLY TO A STRING OF CHIPS (AVERAGE OF TWO GATE ARRAYS).

- THE ENGINEER PERFORMS COMPONENT LEVEL REPLACEMENT (CLR) BY REPLACING THE INDICATED GATE ARRAYS.

- THE FIX SHOULD THEN BE VERIFIED WITH THE DDC CENTER TO ASSIST THEM WITH BUILDING A CASE HISTORY OF FAILURES FOR THE 11/750. THIS IS IMPORTANT!!!

- WHEN CLR DOES NOT CORRECT THE FAULT ON CPU LOGIC MODULES, AND ALL OTHER CPU FAILURES, THE FAILING MODULE OR ASSEMBLY IS REPLACED.



VAX-11/750 Simplified System Block Diagram

```
!2448   .TOC "  Comet Micro Word Chart"
!2449
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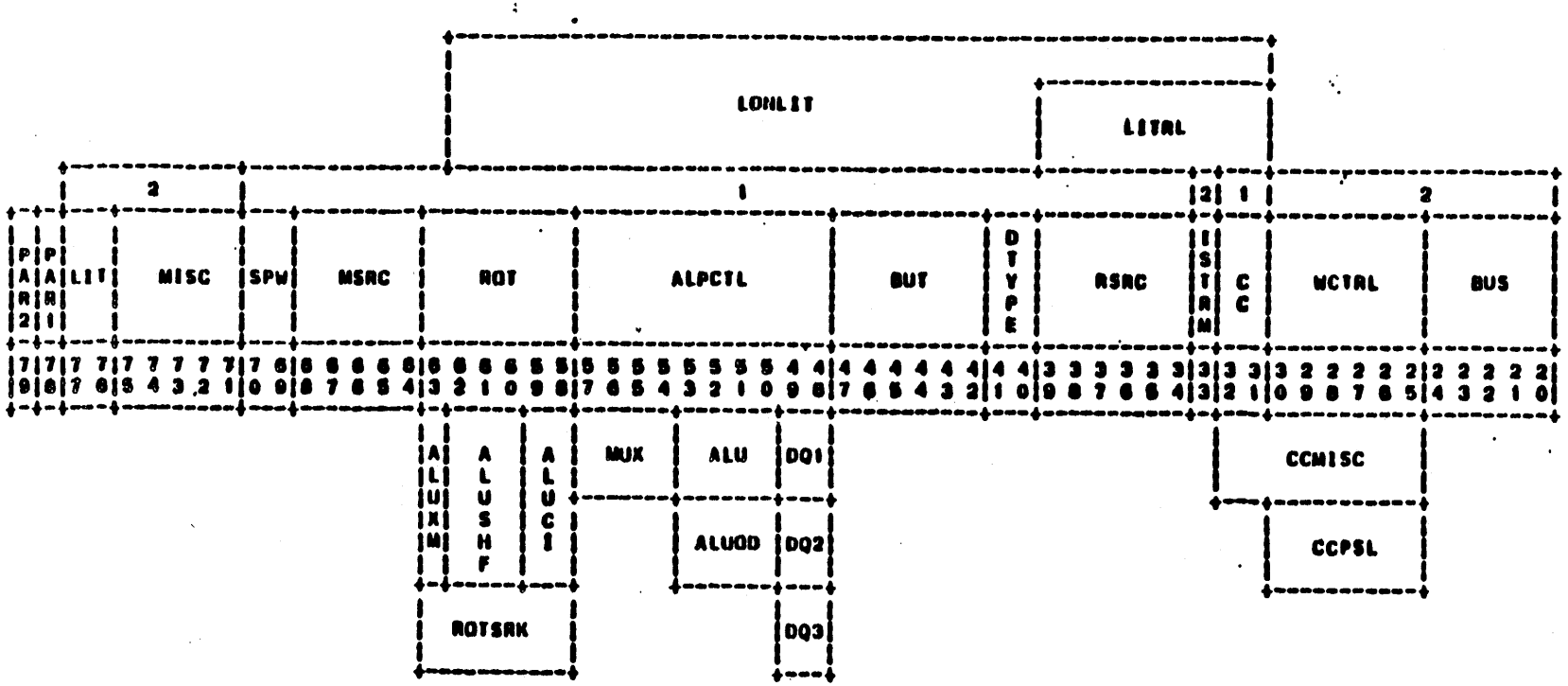
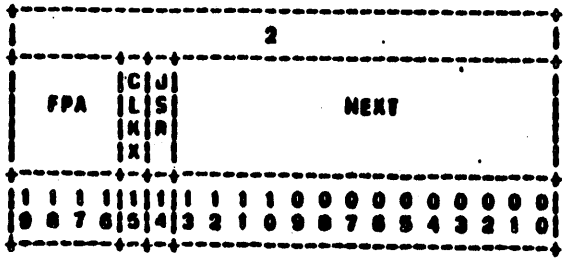




MAJOR BUS DEFINITIONS

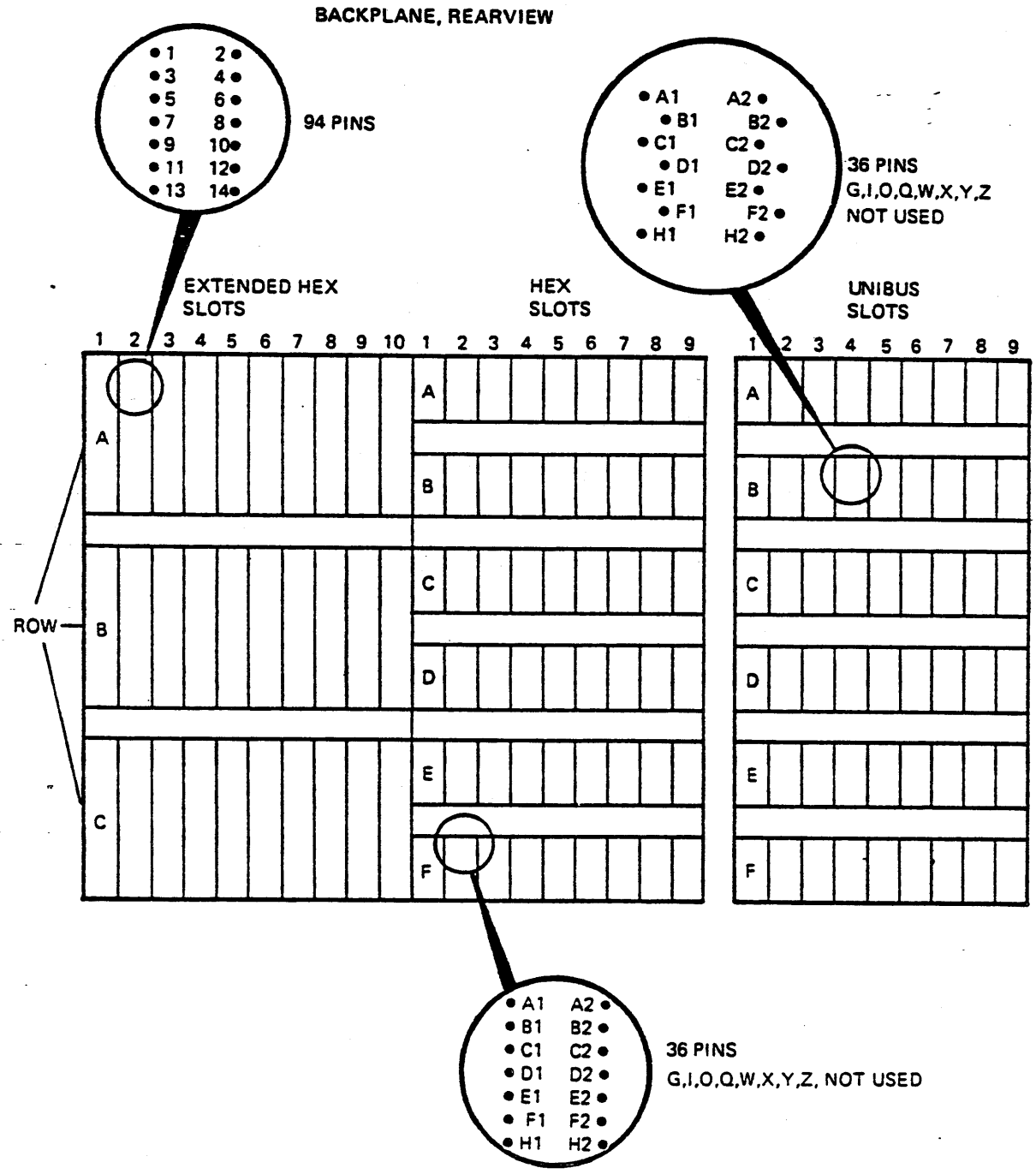
THE MAJOR COMPONENTS OF THE PROCESSOR ARE INTERCONNECTED VIA TWO 32 BIT "LOW TRUE" BUSSES CALLED THE MEMORY BUS (MBUS) AND THE WRITE BUS (WBUS).

MBUS: THE MEMORY BUS IS PRIMARILY USED WHEN SOURCING PROGRAM INSTRUCTION OPERAND DATA FROM MEMORY, THROUGH THE MIC MODULE AND TO THE DPM FOR PROCESSING. IT MAY ALSO BE UTILIZED WHEN THE OPTIONAL FLOATING POINT ACCELERATOR REQUIRES OPERAND DATA FROM THE MIC MODULE OR MEMORY. THE MBUS IS NORMALLY SOURCED FROM THE MIC MODULE BUT IT CAN ALSO BE LOADED BY THE MTEMP REGISTERS ON THE DPM MODULE. CONTROL OF THE MBUS IS ACCOMPLISHED BY MICROCODE FIELDS AND CANNOT BE DIRECTLY ACCESSED BY THE CONSOLE TERMINAL.

WBUS: THE WRITE BUS IS THE BASIC INTERCONNECTION BETWEEN FOUR OF THE MAJOR CPU MODULES (DPM, MIC, UBI, FPA). THE WRITE BUS ACTIVITY IS CONTROLLED VIA MICROCODE FIELDS AND CAN BE UTILIZED BY MOST COMPONENTS INTERNAL TO THE CPU KERNAL. THE WBUS LIKE THE MBUS CANNOT BE DIRECTLY ACCESSED BY THE CONSOLE TERMINAL.

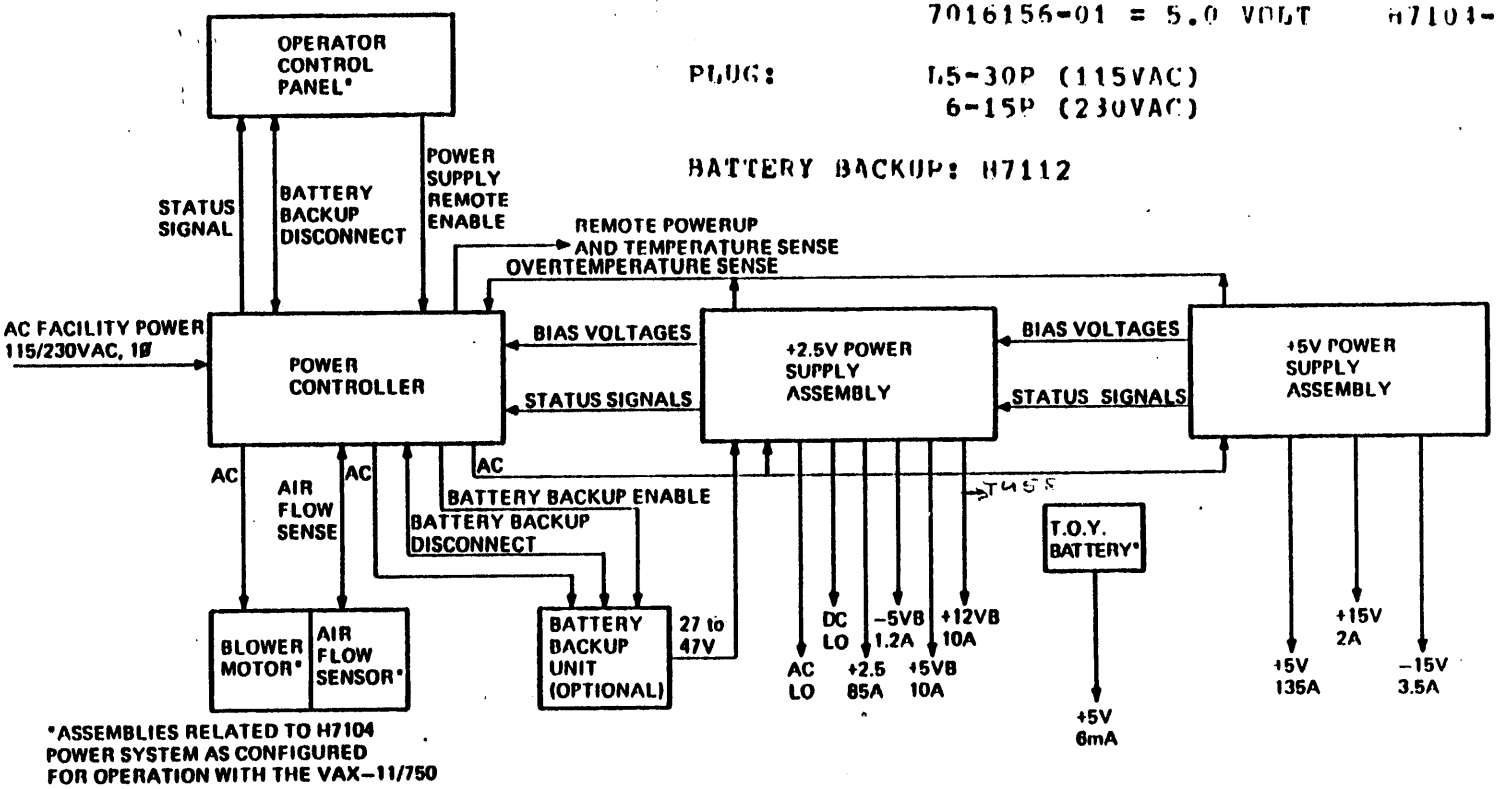
CMI: THE CPU MEMORY INTERCONNECT BUS IS THE MAJOR CENTRAL BUS. IT IS A TRI-STATE BUS (SOME SIGNALS ARE LOW TRUE AND OTHERS ARE HI TRUE) WHICH PROVIDES THE HIGH SPEED TRANSFER OF DATA BETWEEN CPU, MEMORY, AND DEVICE ADAPTERS (I.E. RH750, DW750, FP750,DR750,CI750 ETC.).

NOTE: INDIVIDUAL MODULES AND GATE-ARRAYS MAY HAVE THIER OWN INTERNAL BUS STRUCTURES BUT THEY WILL BE DEALT WITH AS WE ENCOUNTER THEM IN THIS TEXT.

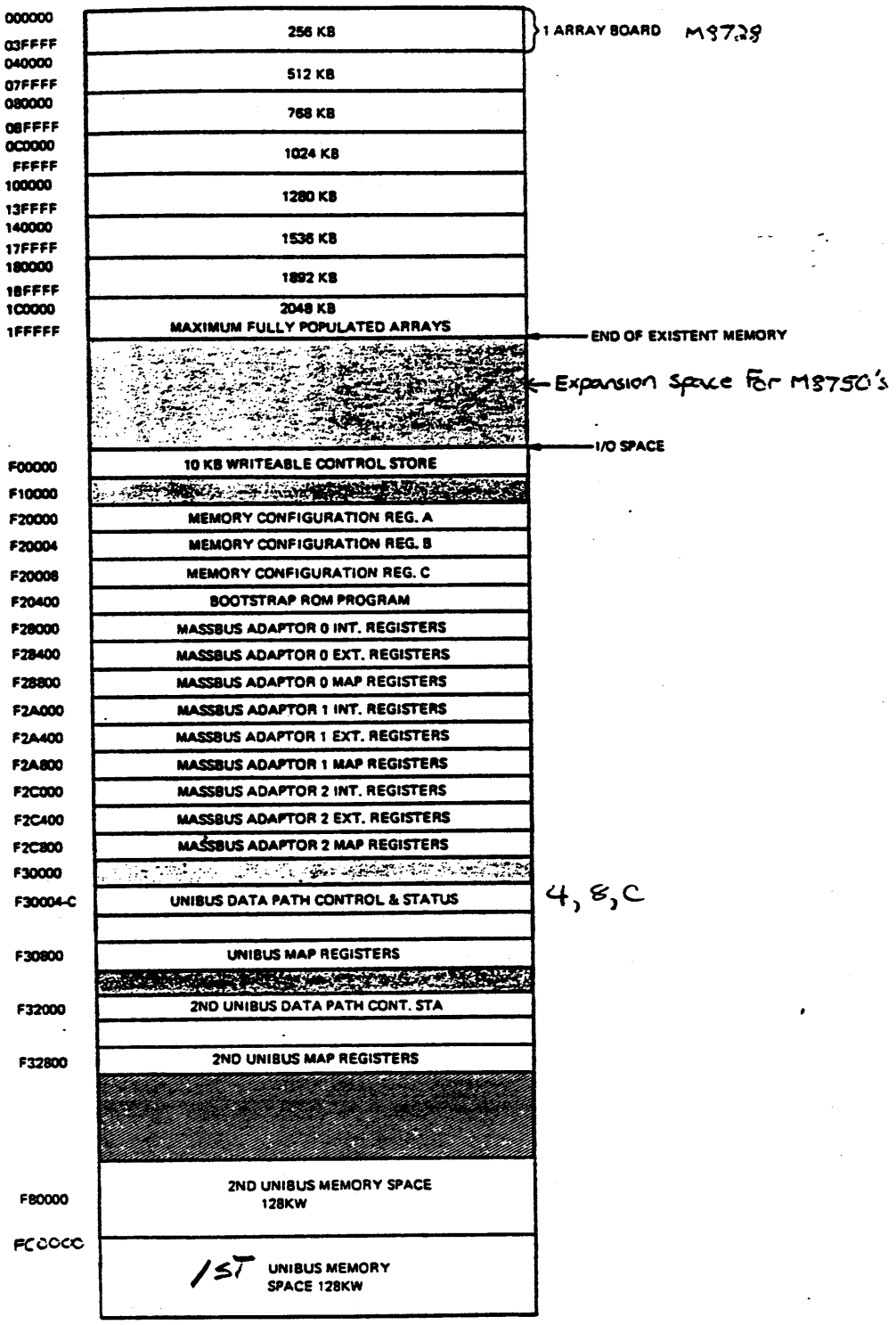

BACKPLANE, REARVIEW
1 2
3 4
5 6
7 8
9 10
11 12
13 14
94 PINS
A1 A2
B1 B2
C1 C2
D1 D2
E1 E2
F1 F2
H1 H2
36 PINS
G,I,O,Q,W,X,Y,Z
NOT USED
EXTENDED HEX
SLOTS
HEX
SLOTS
UNIBUS
SLOTS
1 2 3 4 5 6 7 8 9 10
1 2 3 4 5 6 7 8 9
1 2 3 4 5 6 7 8 9
ROW
A
B
C
D
E
F
A1 A2
B1 B2
C1 C2
D1 D2
E1 E2
F1 F2
H1 H2
36 PINS
G,I,O,Q,W,X,Y,Z, NOT USED

POWER SUPPLY PART NUMBERS

	OLD PART #'S	NEW PART #'S
CONTROLLERS:	7015929-00 = 115 VOLT	
	7015929-01 = 230 VOLT	
SUPPLIES:	7016157-01 = 2.5 VOLT	H7104-C
	7016156-01 = 5.0 VOLT	H7104-D
PLUG:	L5-30P (115VAC)	
	6-15P (230VAC)	
BATTERY BACKUP:	H7112	



H7104 Power System Block Diagram



VAX-11/750 Physical Memory Organization

VMS SHUTDOWN PROCEDURE

TO BRING THE VAX/VMS OPERATING SYSTEM DOWN, ONE MUST HAVE THE PROPER PRIVILEGES. THESE CAN BE HAD BY LOGGING INTO THE SYSTEM MANAGERS ACCOUNT. THE NORMAL FIELD SERVICE ACCOUNT MAY NOT HAVE THE PRIVILEGES TO BRING THE SYSTEM DOWN.

SO LOGOUT FROM THE ACCOUNT YOU ARE IN, IF YOUR IN, AND LOG INTO THE SYSTEM MANAGERS ACCOUNT AS SHOWN BELOW (UNDERLINED).

(OF COURSE IN THE FIELD YOU PROBABLY WILL NOT HAVE THE PASSWORD)

USERNAME:SYSTEM

PASSWORD:MANAGER

NOTE THE PASSWORD IS NOT DISPLAYED.

AFTER YOU HAVE THE "$" PROMPT, THEN TYPE THE UNDERLINED RESPONSES.

Welcome to VAX/VMS Version VX.X

$ @SYS$SYSTEM:SHUTDOWN OR $ @[SYSEXE]SHUTDOWN

System shutdown command procedure.
23-MAR-1980 09:35:23
How many minutes until shutdown?: 10 (or whatever)

Reason?: PM (or <CR> if no message is desired)

Do you want to spin down the disks?: YES (or <CR> if not)

Expected uptime? (<CR> if not known):

Enable automatic reboot?:

YOU HAVE NOW STARTED THE SHUTDOWN PROCEDURE. YOU HAVE GIVEN IT TEN MINUTES TO DO THIS, ALSO GIVEN THE REASON AS SYSTEM PM, AND TOLD IT THAT YOU WANTED TO SPIN DOWN THE USER PACKS (NOT THE SYSTEM PACK). THE SYSTEM WILL SEND OUT A WARNING AT PREDETERMINED TIMES. IT WILL STOP ALL QUEUES, LOG EVERYONE OUT AND FINALLY COME UP WITH THE FOLLOWING MESSAGE:

SYSTEM SHUTDOWN COMPLETE - USE CONSOLE TO HALT SYSTEM

NOW YOU CAN TYPE A CONTROL "P" TO GET BACK TO CONSOLE COMMAND LANGUAGE MODE WITH THE PROMPT ">>>".

L0001 FPA

FP750

The Floating Point Accelerator (FPA) -
An optional high-speed processor extention
to the Vax-11/750 CPU. FP750.

A. Purpose:

1. To increase the speed at which the Vax-11/750 can execute certain floating point instructions.

   a. Single-precision floating

   b. Double-precision floating

   c. Extended Modulus (EMOD)

   d. Polynomial (POLY)

2. To enhance the execution of integer multiply instructions

3. It will not accelerate execution of grand (G) or huge (H) floating instructions.

B. Characteristics:

1. Extended-Hex Module

2. 28 gate arrays

3. 64-bit fraction data path

4. No internal diagnostics

5. 80-bit micro-word

6. Operates independently of the CPU

   a. Uses CPU data cache for data fetch

   b. Uses the CPU Instruction buffer for instruction fetch

   c. While FPA is executing, the CPU can;

      1) Calculate memory addresses

      2) Fetch data

      3) Prepare to transmit data

4) Store FPA results

7. Can operate on numbers from .29 X 10 to 1.7 X 10

8. Can operate on signed integers from 2 to 2 -1.

C. Interfacing to the CPU.

1. M-Bus

2. W-Bus

3. Miscellaneous

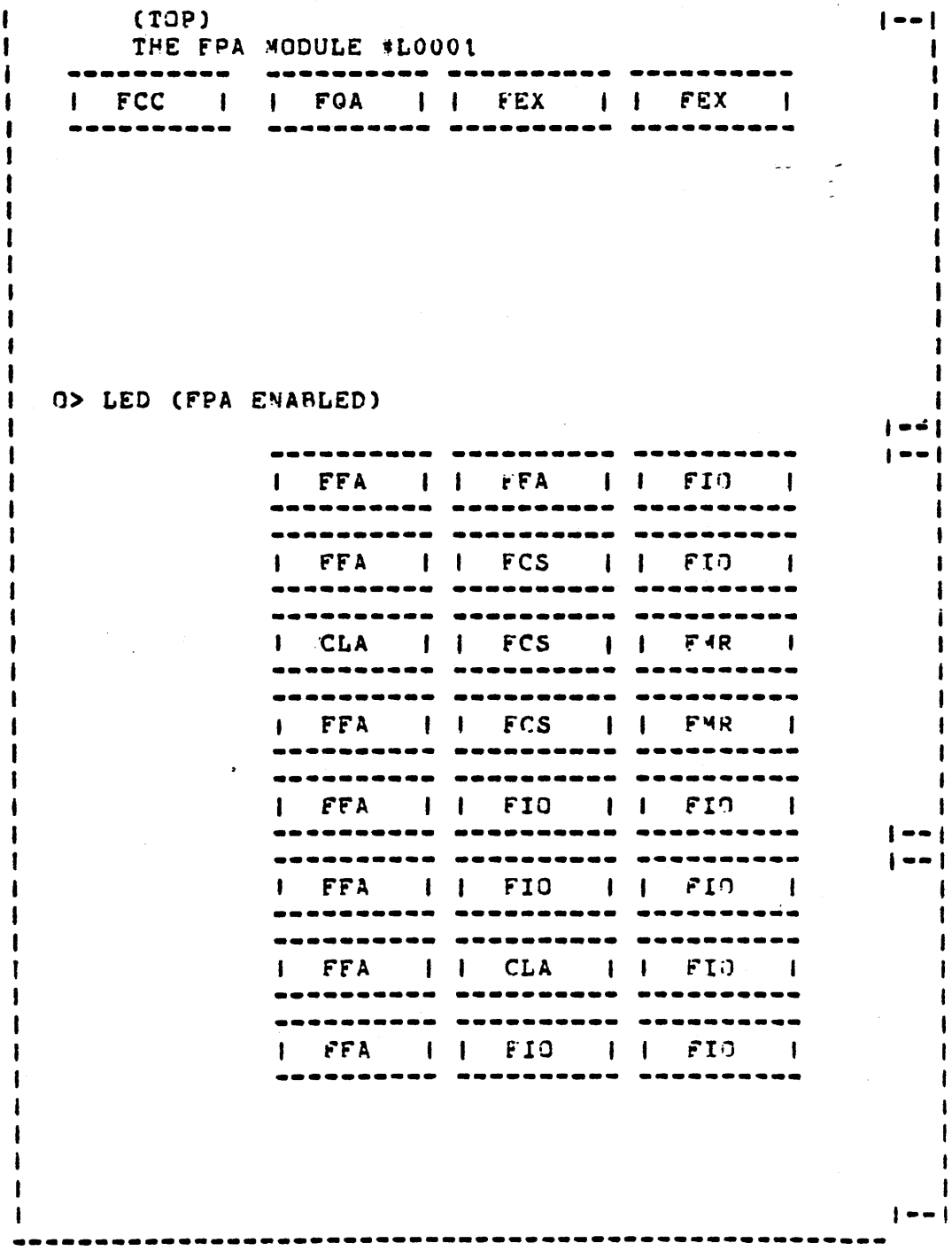
   a. Control store address lines from CCS.

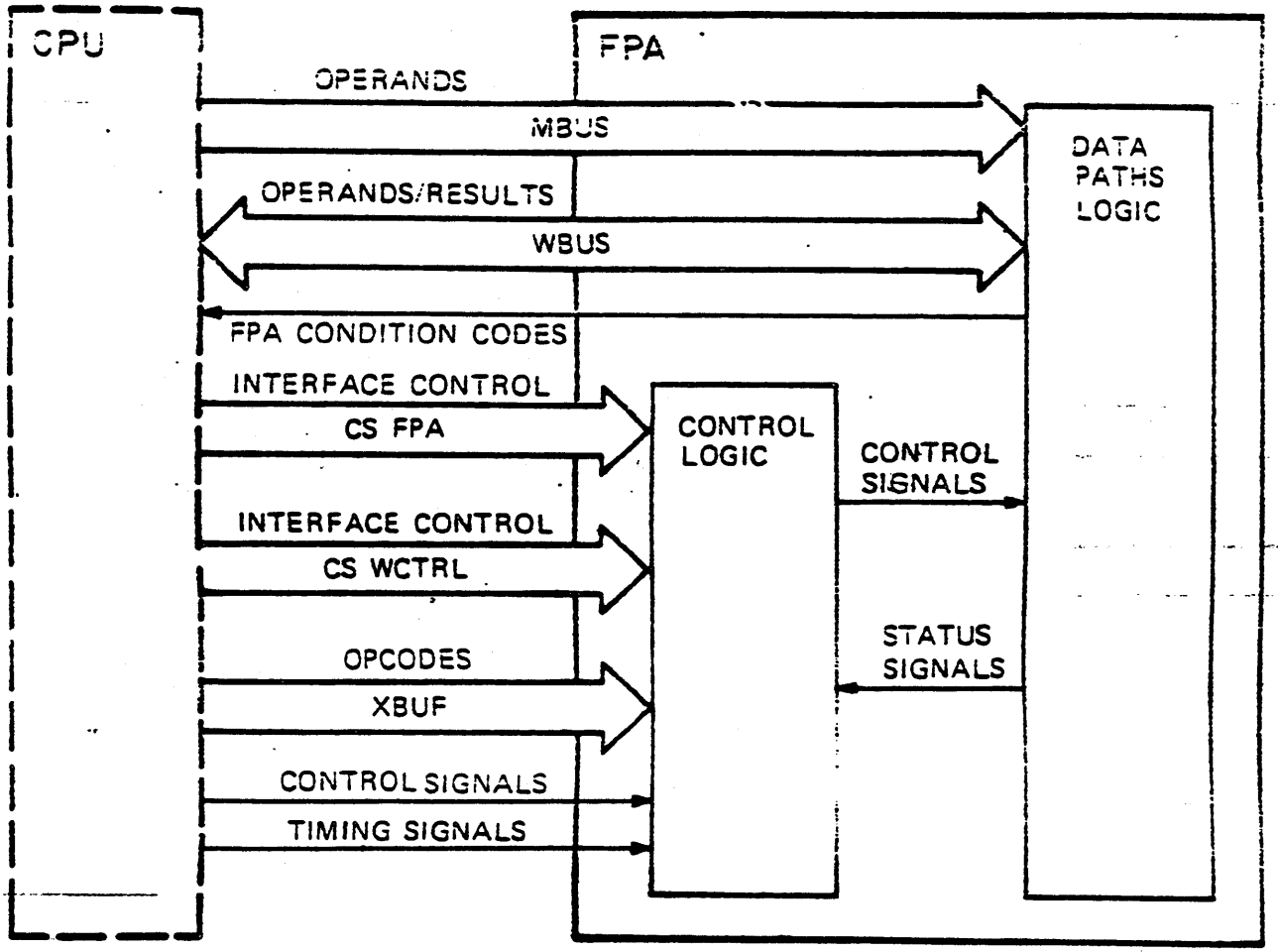
   b. Exceptions/Interrupts to UBI.

   c. Clock signals from the DPM.

   d. Others, to and from all of the above.

THE MICROFICHE LISTINGS FOR ECKAB.EXE AND ECKAC.EXE GIVE BOARD LAYOUTS AND LOCATIONS OF EACH GATE ARRAY.





FPA I/O CPU SIGNAL INTERFACE

*** CAUTION ***

THE L0001 MODULE, AS ALL 11/750 MODULES,
CONTAINS ELECTROSTATIC DISCHARGE SENSTIVE DEVICES (ESDS).
THE USE OF THE VELOSTAT KIT IS ESSENTIAL
TO PREVENT DAMAGE WHICH MAY NOT
BECOME IMMEDIATELY APPARENT.
(VELOSTAT KIT NUMBER A2-W0299-10)

1) Run system shutdown or the equivalent (@SYSSSYSTEM:SHUTDOWN)

2) Verify that the hardware revision level is Rev 3 or higher, and microcode revision level is equal to or greater that 94 decimal (step 4).

3) The FP750 will only work correctly in 11/750 systems that contains MINIMUM CPU Microcode revision 94. To verify revision level of the 11/750 system examine the System IDENTIFICATION Register (SID).

4) Place the keyswitch to the LOCAL position, HALT system (^P) and type the following:

```
>>>E/I 3E

(printout)      I 0000003E      02005EXX
                                    ^  ^
                                    |  |
                                    |  `------ ***
                                    '          Hardware Rev
                              Ucode Rev 94
                                (HEX 5E)
```

XX = 03 L0011 controller/old backplane
XX = 30 L0011 controller/old backplane/SID switch
XX = 38 L0016 controller/new backplane/SID switch

NOTE: VAX750-R-003 FCO (REV 94 Micro code) is a prerequisite before the installation of a FP750 option. This FCO consists of rework to the L0004 UBI module and replacement of the L0005 CCS module, this will bring both modules (CCS and UBI) to REV "H".

This FCO can be ordered using E0-01128-01 number.

*** DO NOT INSTALL THE L0001 MODULE WITHOUT PROPER MICROCODE LEVEL ***

5) Place the frontpanel Action on Power Switch to the HALT position, and remove power from the system.

6) Unpack the VeloStat tool from its container, open package, and attach the 15' pot ground cord to the VeloStat snap fastener, which attached to the wrist strap. Attach the end with the alligator clip to a reliable electrical ground on the 11/750 system.

7) Install the L0001 FPA module in slot #1 of the CMI backplane. If the RDM or DM L0006 module is not already resident in the CPU, install it in slot #6, move the console and TU58 cables from the left side to the right side of slot #6 on the processor backplane (looking at the back of the processer).

8) Reapply primary power by turning the keyswitch to local position, on the console panel. The system will come up in the HALT state, with the console prompt >>>.

9) Test the FPA's ON/OFF (enable/disable) capability by using the following console commands:

```
>>> D/I 28   0
>>> E/I 28

    (print out)      00000028   00000000
```

Depositing 0 to IPR# 28 disables FPA (GREEN LED will not be lit)

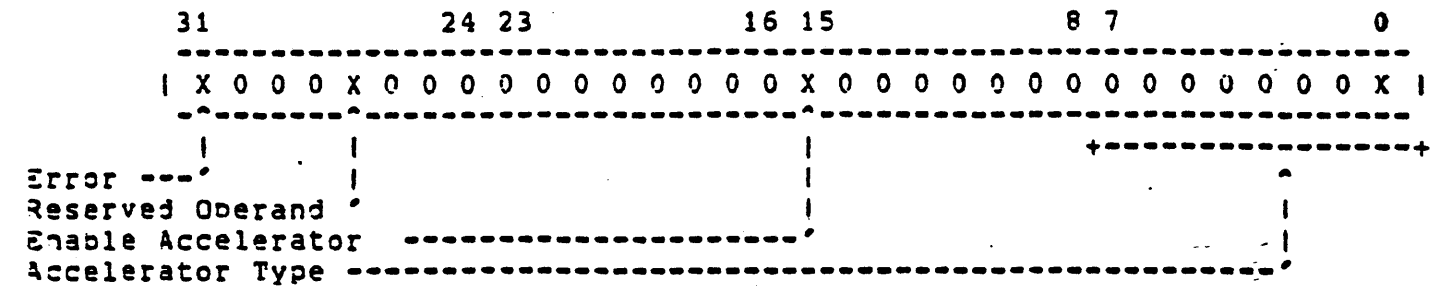
```
>>> D/I 28   8000
>>> E/I 28

    (print out)      00000028   00000001
```

Depositing 8000 to IPR# 28 enables FPA (GREEN LED will be lit)

NOTE: FP750 uses the Accelerator Status/Control register IPR #28

The following diagram describes the bit position of the Accelerator Control/Status Register (ACCS)



Bit <15> - FPA Enable (WO)

Bit <7:0> - Accelerator Type

0 = No accelerator (or disabled FPA)
1 = Enabled FPA
2-255 = reserved

Note: ACCS <15> always reads as 0. In order to determine if an 11/750 has an FPA you must first write a 1 to ACCS <15> then read ACCS <0>. If it reads 0 there is no FPA present, if it reads back as an 1 there is an FPA and it is now Enabled.

gnostic Acceptance

The VAX Architectural and Floating Point Instruction Exercisers are used to verify the integrity of the FP750 option. These instruction exercisers will run under the Diagnostic Supervisor stand-alone or on-line, but to properly test the FP750 they should be run stand-alone. (In on-line mode, they cannot disable and enable the FP750). The enhanced DPM micro diagnostic is used to verify the logic which interfaces the FP750 from the DPM module of the 11/750 processor.

Version V07.2 or greater of the ECKAB DPM micro diagnostic will verify some of the CPU-FPA interface logic. Verification of this interface logic, which is resident in the DPM module of the CPU and is not activated until the FPA is enabled, is tested under test D2-DC of this diagnostic. These test are listed below:

D2	The FPA Enable/Disable Function
D3	FPA Stall/Wait Test
D4	MBUS/WBUS Interface Test
D5	FPA Reserved Operand Trap Test
D6	FPA Trap Logic Test
D7	Condition Code Test (1 of 4)
D8	Condition Code Test (2 of 4)
D9	Condition Code Test (3 of 4)
DA	Condition Code Test (4 of 4)
DB	FPA Copy fo Condition Codes
DC	FPA Copy of the FU Bit

10) Boot Diagnostic Supervisor (ECSAA) and attach the processor.

```
>>> B/10   [device]
DS> ATT KA750 CMI KA0 NO NO YES 0 1
                                  ^
                                  |    (Accelator type)
                                  `--- ( 1=FPA 0=No FPA)
DS> SELect ALL
DS> SET TRace
```

11) Run EVKAB

The ARCHITECTURAL instruction exerciser will run first with the FP750 disabled (Green LED on the L0001 module will not be lit). When this first pass has completed successfully, another pass with the FP750 enabled will be performed.

12) Run EVKAC

The FLOATING POINT instruction exerciser like EVKAB, will also run with the FP750 disabled on the first pass. Again after when successful completion, the FP750 is enabled and tested.

If a failure occurs when running either EVKAB or EVKAC, run ECKAB (DPM micro diagnostic) to verify the integrity of the interface logic on the DPM module. If the failure is not detected when running ECKAB, replace the L0001 module and rerun EVKAB,EVKAC, and ECKAB.

13) Run ECKAB

Run DPM micro diagnostic to verify the interface logic

^P	(go to console mode(halt any macro program activity))
^D	(go to RDM console control mode)
RDM>	(get RDM Prompt;install TU58 tape)
RDM> TE	(start test)

14) Error Free Passes of EVKAB,EVKAC and ECKAB indicate verification is complete (diagnostic runtime is about 45 minutes).

15) If RDM is to be removed, power down system, remove L0006 module, replace Console and TU58 cables to their original positions.

16) Dis-connect the VelaStat tool and repack it in the kit container.

17) Power up system.

18) Bootstrap customer's operating software.

L0002 DPM

SLOT 2). THE DATA PATHS MODULE (DPM) #L0002

IT HOUSES THE GENERAL PURPOSE REGISTERS (GPR'S), INTERNAL PRIVILEGED REGISTERS (IPR'S), MTEMP AND RTEMP MICROCODED REGISTERS, ARITHMETIC LOGIC UNIT (ALU), ROTATOR LOGIC, Q AND D REGISTERS, P AND S LATCHES, SYSTEM CLOCKS, MICROSEQUENCER, IR DECODE ROMS.

THE DPM IS CONNECTED TO THE W BUS AND M BUS.
(THE MICROSEQUENCER IS CONNECTED TO THE CCS OF COURSE)

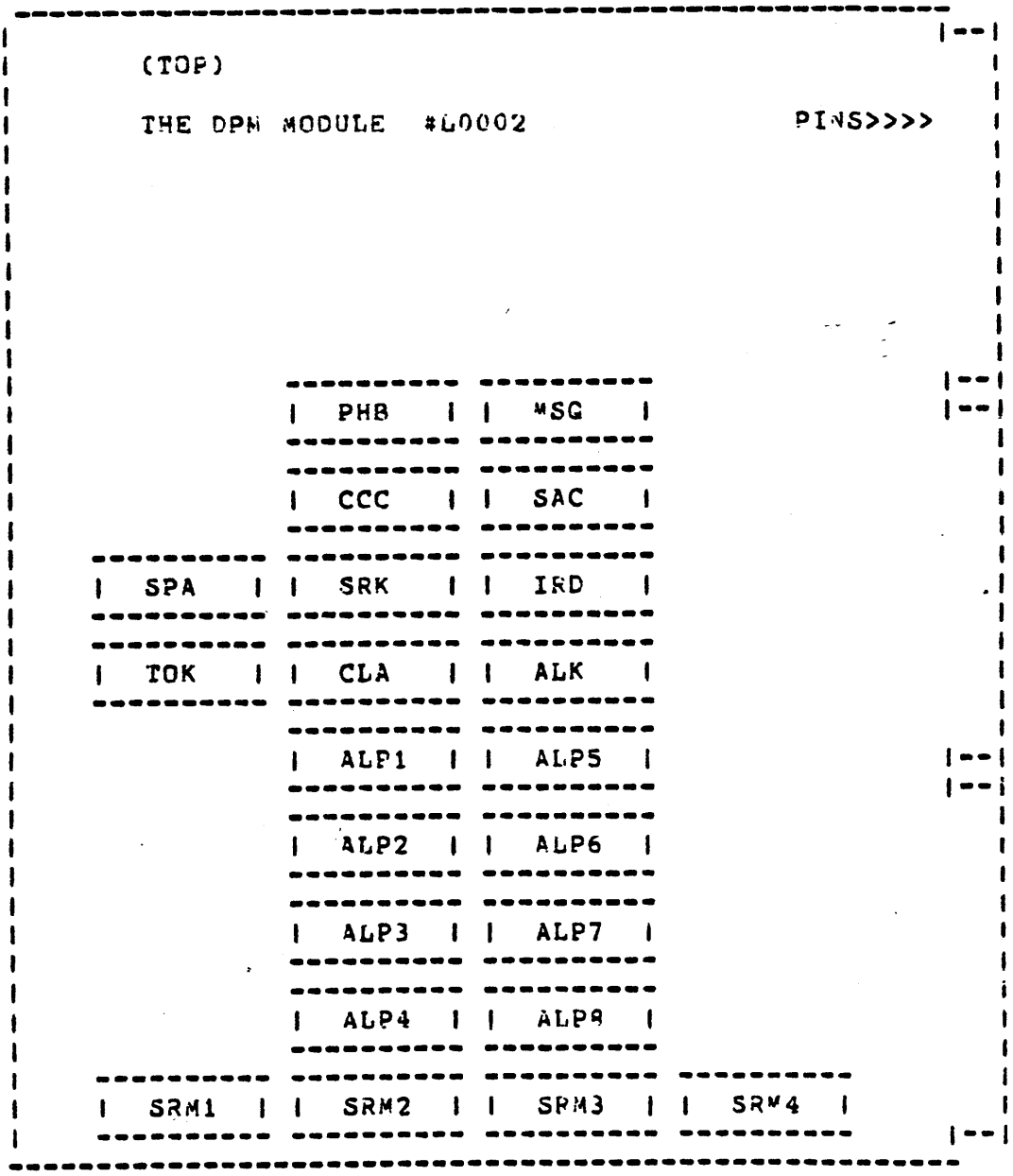
NOTE: THERE IS NO PARITY CHECKING AT ALL ON THE DPM MODULE OTHER THAN CONTROL STORE MICROCODE PARITY WHICH IS LATCHED ON THE MIC, UBI, DPM, AND CCS MODULES AND CHECKED ON THE DPM.

THE MICRODIAGNOSTIC ECKAB.EXE TAPE #1 WILL TEST THE DPM.

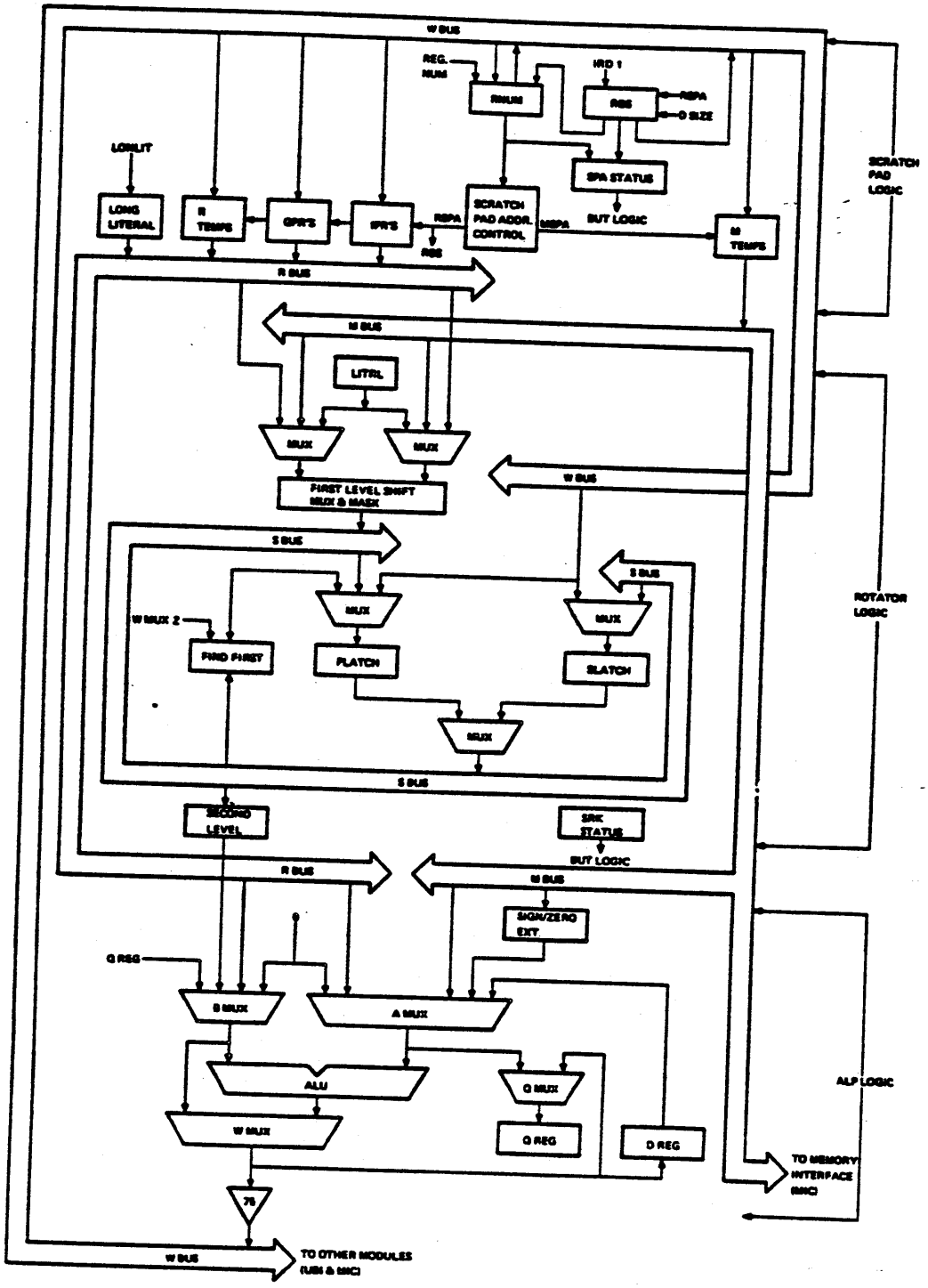
GATEARRAYS: ALP,ALK,CCC,CLA,IRD,MSQ,PHB,SAC,SPA,SRK,SRM,TOK

GATE-ARRAY MAGIC BOOK PICTURE SYMBOLOGY

X:X = COMPLETE RANGE OF BITS CONTAINED IN EACH CHIP
N = NOT APPLICABLE IN THIS CHIP
<> = BI-DIRECTIONAL (MAJOR BUS)
o = INVERTED


(TOP)
THE DPM MODULE #L0002
PINS>>>>
PHB
MSG
CCC
SAC
SPA
SRK
IRD
TOK
CLA
ALK
ALP1
ALP5
ALP2
ALP6
ALP3
ALP7
ALP4
ALP8
SRM1
SRM2
SRM3
SRM4

DATA PATH



Data Path Block Diagram

ALP: ARITHMETIC LOGIC PROCESSOR(ALU)
CONTAINS LOGIC TO PERFORM 1094 ARITHMETIC AND LOGICAL FUNCTIONS. ALSO CONTAINS A "SECOND LEVEL" SHIFTER FOR USE WITH THE SUPER ROTATOR MULTIPLEXER. (SEE SRK AND SRM CHIPS)

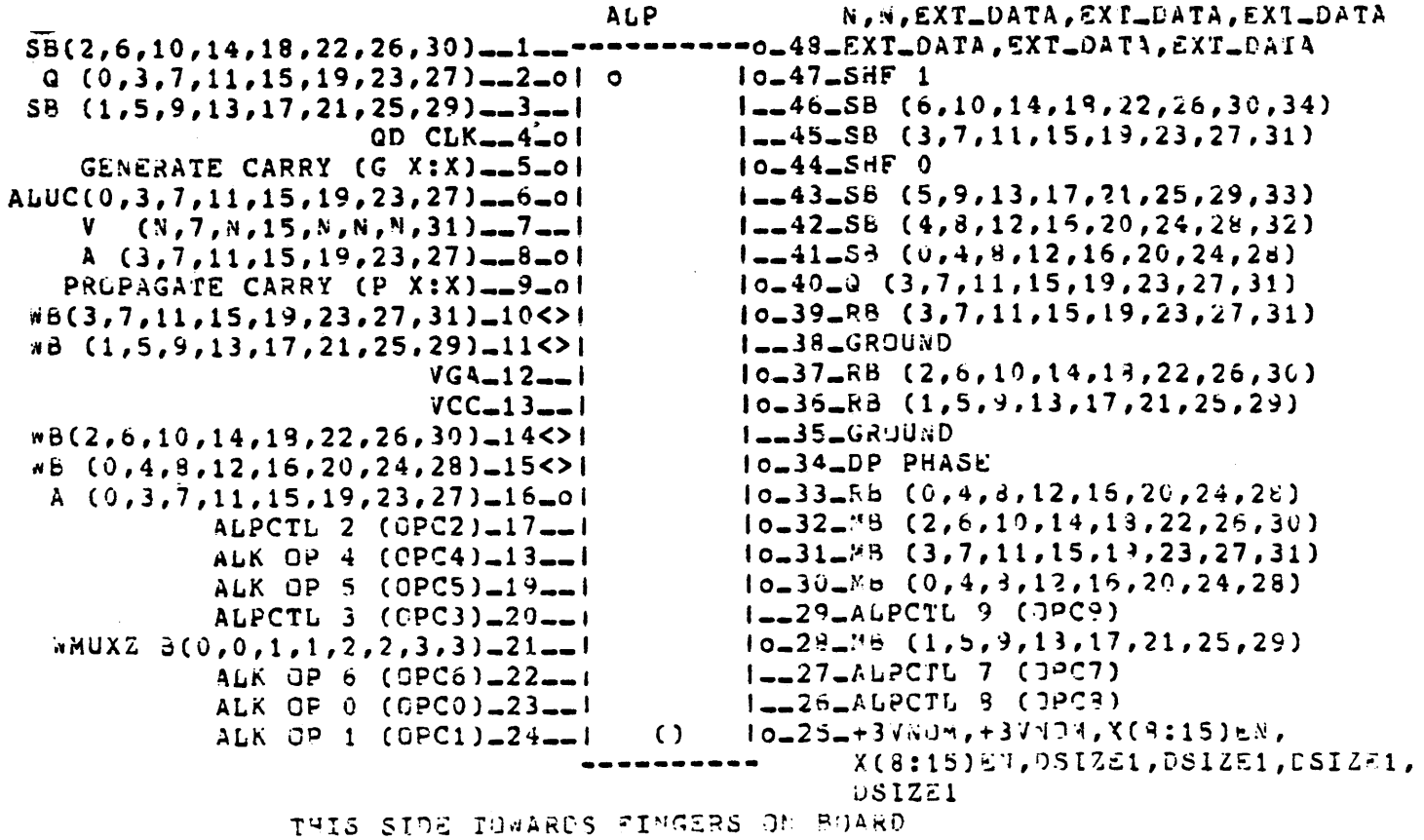
8 CHIPS:	CHIP	BIT SLICE
	ALP 1	<3-0>
PART NUMBER	ALP 2	<7-4>
19-14682	ALP 3	<11-8>
	ALP 4	<15-12>
	ALP 5	<19-16>
	ALP 6	<23-20>
	ALP 7	<27-24>
	ALP 8	<31-28>

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: ALP (1 THROUGH 8)

BUS DEFINITIONS: SB = SBUS (SUPER ROTATOR BUS INTERNAL TO DPM ONLY)
USED TO TRANSFER INTERNAL ROTATOR DATA BETWEEN FIRST AND SECOND LEVEL SHIFTERS.
RB = RBUS (ROTATOR BUS INTERNAL TO DPM ONLY)
USED TO TRANSFER DATA FROM SCRATCH PAD REGISTERS (EXCLUDING MTEMPS) TO ALU.
MB = MBUS (MEMORY BUS. SEE MAJOR BUS DEFINITIONS PAGE)
WB = WBUS (WRITE BUS. SEE MAJOR BUS DEFINITIONS PAGE)

TERM DEFINITIONS: WMUXZ = W BUS MULTIPLEXER EQUAL TO ZERO



THIS SIDE TOWARDS FINGERS ON BOARD

ALK: ARITHMETIC LOGIC CONTROL

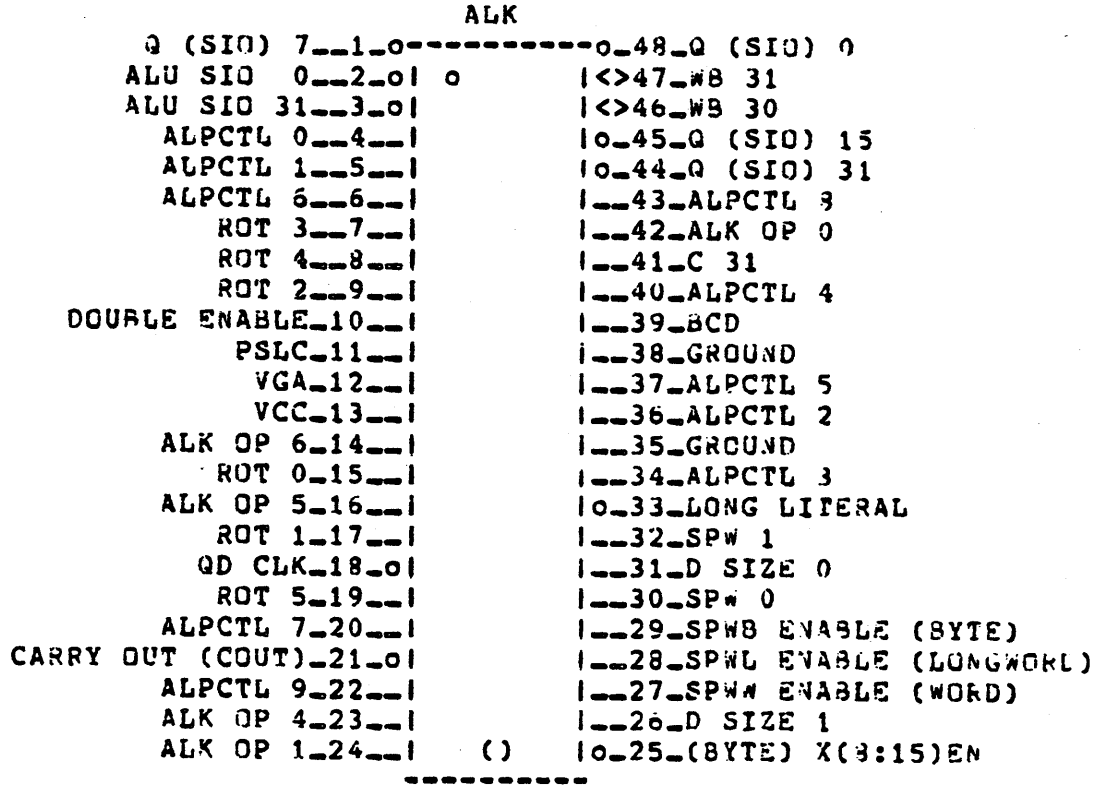
CONTROLS THE ALP FUNCTIONS BY DECODING MICROCODE INPUTS AND GENERATING THE CONTROL SIGNALS.

PART NUMBER 19-14689

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: ALK

TERM DEFINITIONS: (SIO) = SHIFT IN/OUT



THIS SIDE TOWARDS FINGERS ON BOARD

CCC: CONDITION CODE CHIP

CONTAINS PSL(PSW) BITS <C,V,Z,N,IV,FU,DV>

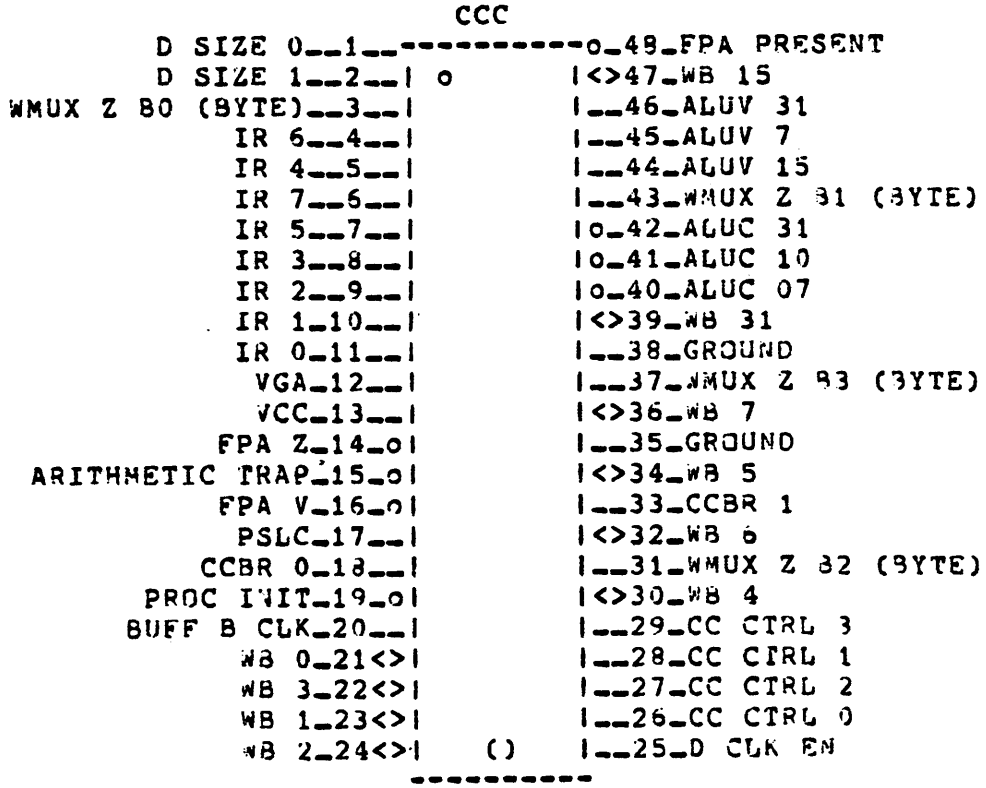
CONTROLS THE SETTING OF ALL CONDITION CODES FOR VAX NATIVE AND COMPATABILITY MODE INSTRUCTIONS AT THE REQUEST OF THE MICROCODE.
WORKS IN CONJUNCTION WITH THE ALU.

PART NUMBER: 19-14684

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE
MIC MICRO'S ECKAC.EXE

MODULE: DPM GATE ARRAY: CCC

TERM DEFINITIONS: CCBR = CONDITION CODE BRANCH



THIS SIDE TOWARDS FINGERS ON BOARD

CLA: CARRY LOOK AHEAD

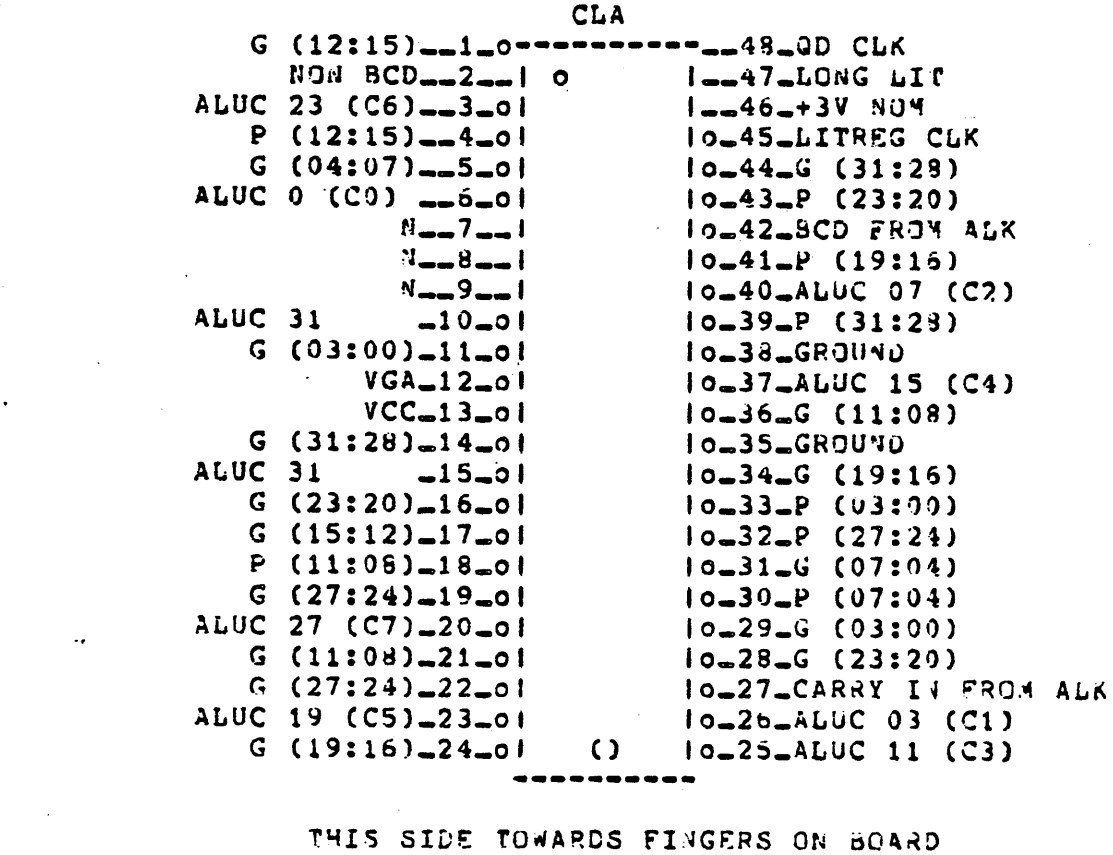
LOOKS AT ALP CHIPS (P AND G SIGNALS)TO GENERATE AND/OR PROPAGATE CARRIES, AS WELL AS DEALING WITH THE STATE OF THE MOST SIGNIFICANT BITS OF EACH DATA TYPE TO AID THE CCC CHIP WITH DETERMINATION OF POSITIVE OR NEGATIVE CHARACTERISTICS.

PART NUMBER: 19-14686

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: CLA

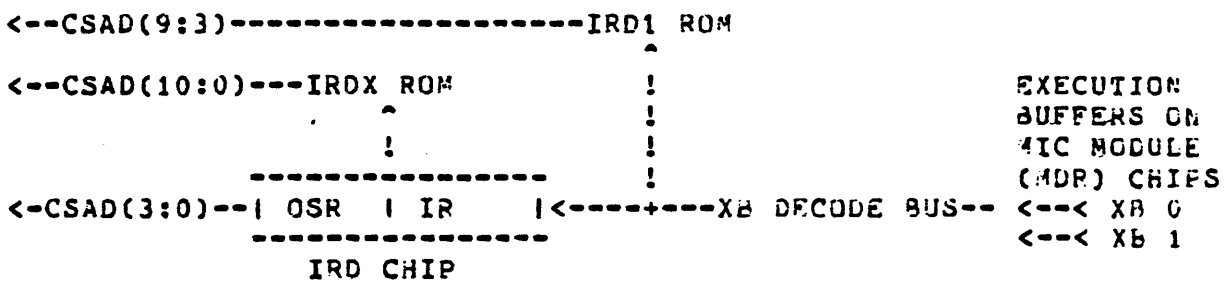
TERM DEFINITIONS: BCD = BINARY CODED DECIMAL
ALUC = ALU CARRY BITS



THIS SIDE TOWARDS FINGERS ON BOARD

IRD: INSTRUCTION REGISTER DECODE CHIP

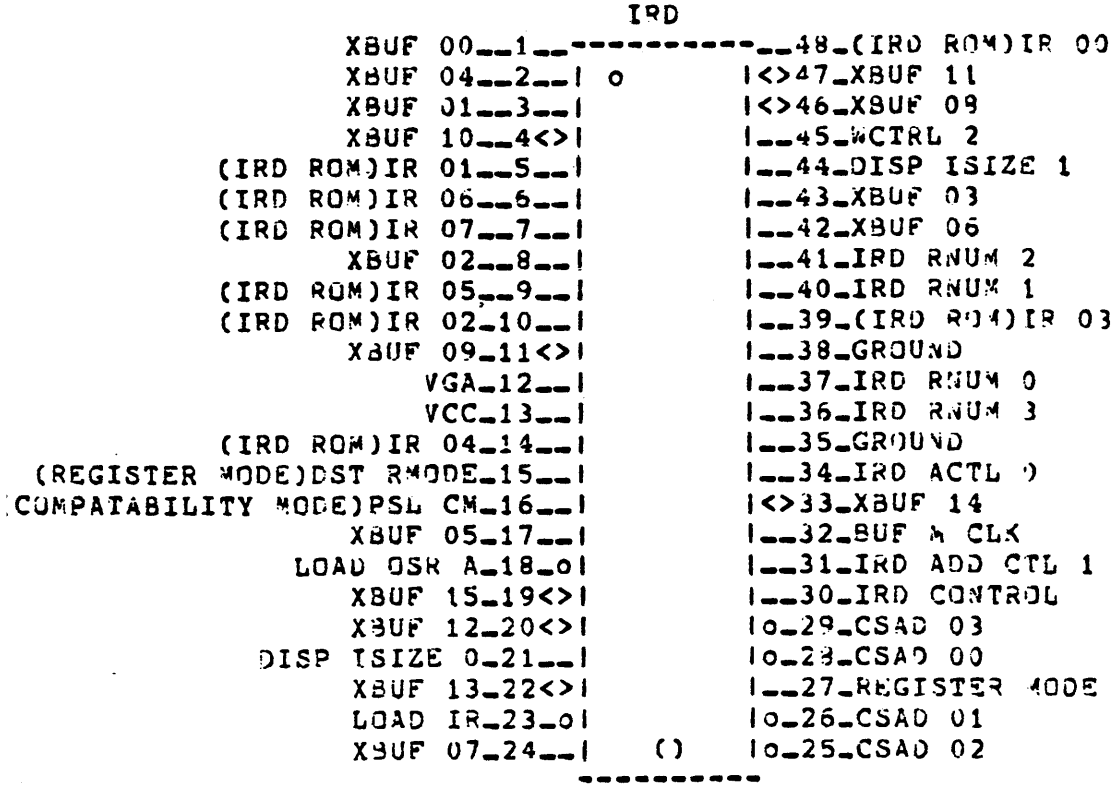
RECEIVES INSTRUCTION STREAM DATA FROM THE EXECUTION BUFFERS, HELPS DECODE THE OP CODE AND 1st OPERAND SPECIFIER, AND ASSISTS THE IRD1 DECODE ROMS IN GENERATING THE PROPER MICROCODE ADDRESS FOR EACH INSTRUCTION AND ADDRESSING MODE. OP CODES ARE LATCHED IN IRD UNTIL NEXT IRD1 TIME.



PART NUMBER: 19-14696

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: IRD



THIS SIDE TOWARDS FINGERS ON BOARD

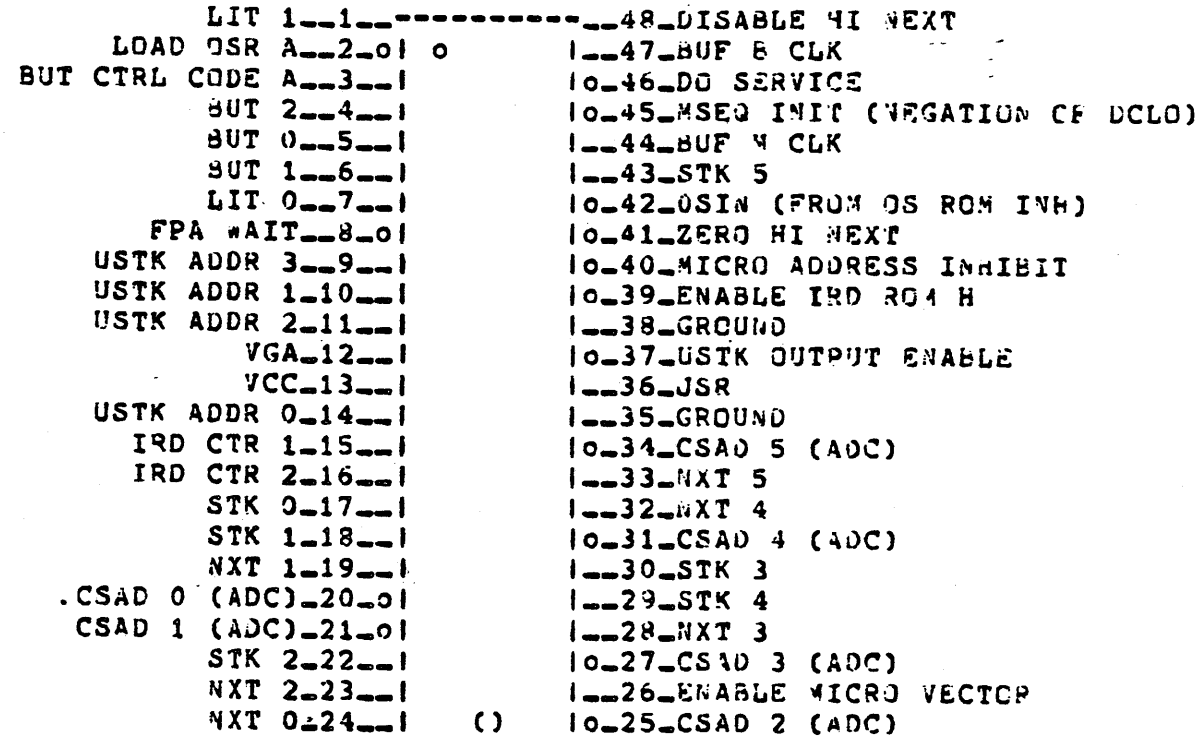
MSQ: MICRO SEQUENCER

SEQUENCES THE MICROCODE, FORMS LOW 6 BITS OF CONTROL STORE ADDRESS, CONNECTED TO THE MICRO STACK AND NEXT FIELD LATCHES.

PART NUMBER: 19-14695

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

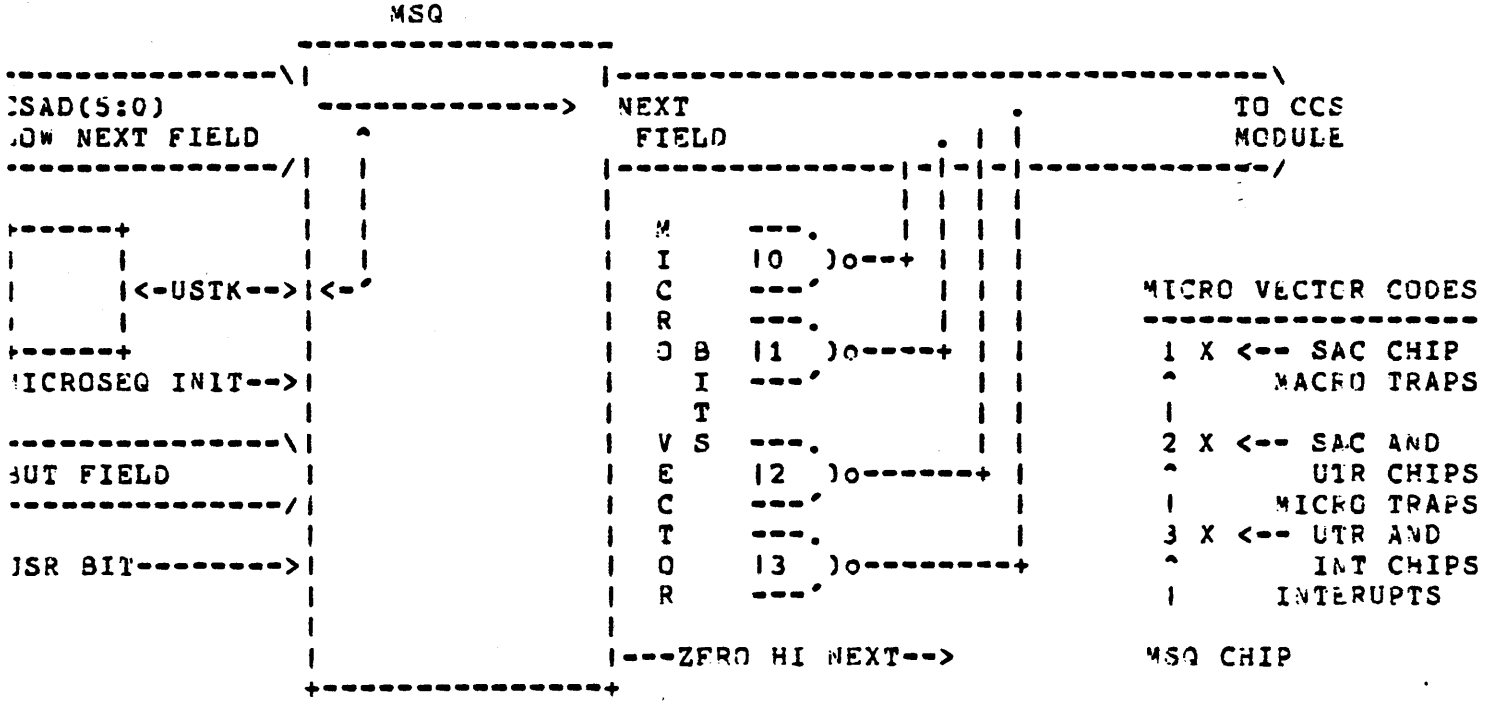
MODULE: DPM GATE ARRAY: MSQ



THIS SIDE TOWARDS FINGERS ON BOARD

THERE ARE FIVE WAYS OF SEQUENCING THE MICROCODE:

1). STRAIGHT THROUGH NEXT FIELD ADDRESSING (NO MODIFICATIONS)
2). BRANCHING ON BUT CONDITIONS IN HARDWARE
3). PERFORMING MICRO VECTOR OPERATIONS
4). JUMPS TO AND RETURNS FROM MICRO SUBROUTINES
5). INSTRUCTION DECODE



PHB: PRACTICALLY HALF BUTS

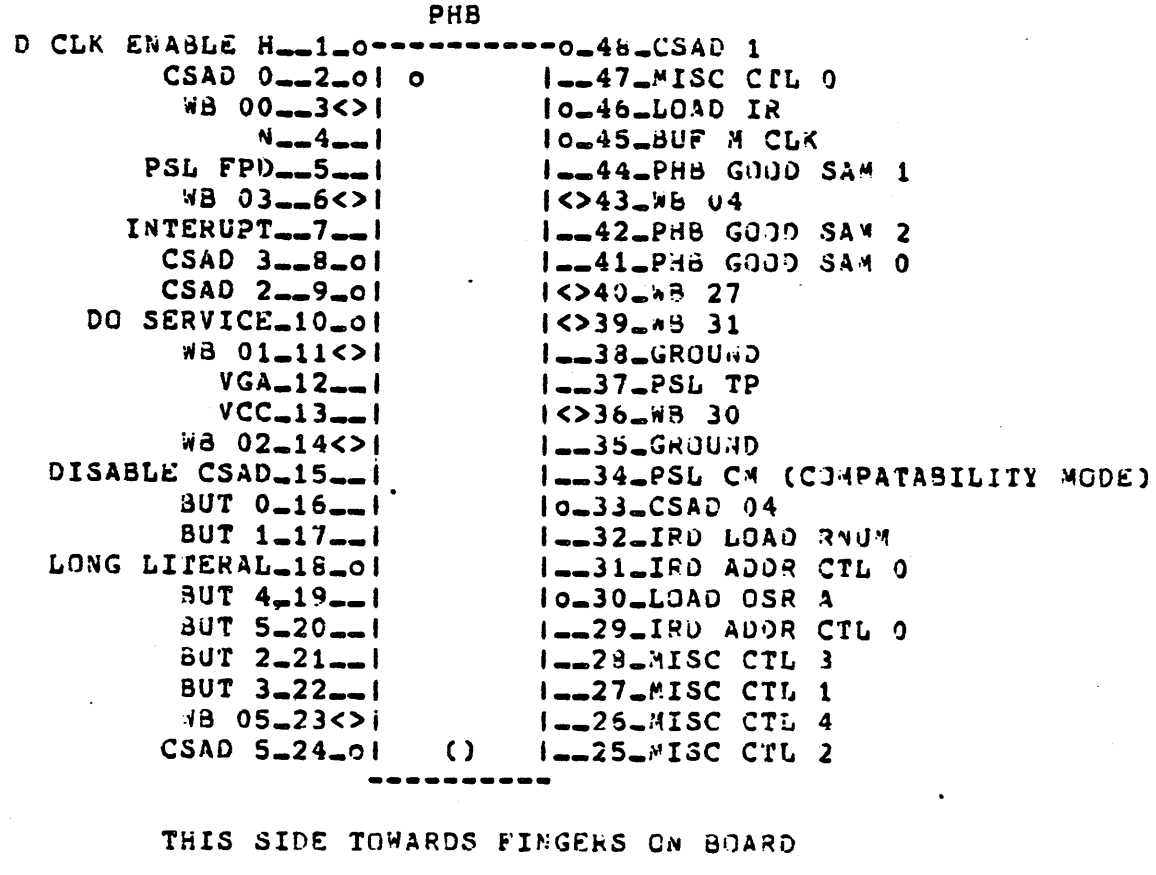
CONTAINS PSL BITS <CM,TP,FPD>, STEP COUNTER, STATUS FLAGS, AND ABOUT HALF THE LOGIC TO PERFORM (BUT)BRANCH AN MICRO-TEST MICRO-ORDERS.

PART NUMBER: 19-14703

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: PHB

TERM DEFINITIONS: PHB GOOD SAM = GOOD SAMARITAN BUS



THIS SIDE TOWARDS FINGERS ON BOARD

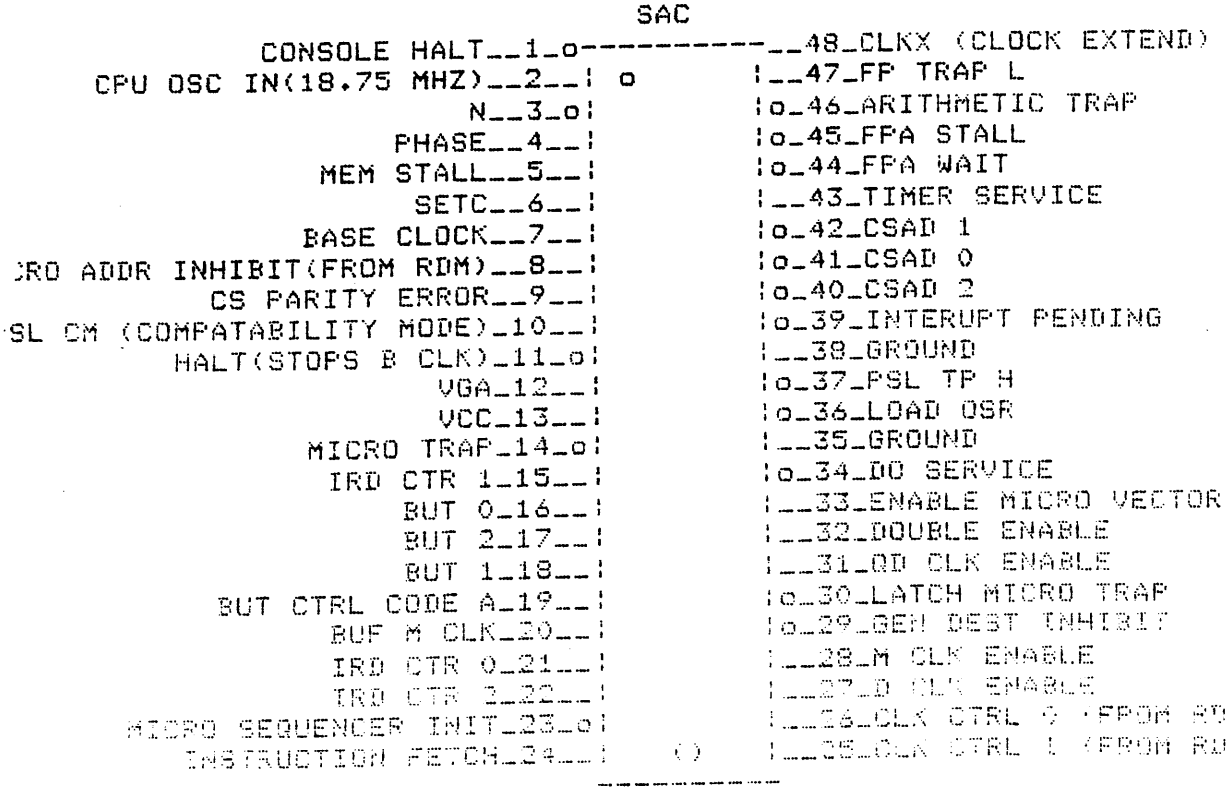
CONTAINS THE IRD COUNTER (WHICH IS USED PRIMARILY TO TRACK THE NUMBER OF BYTES OF ISTREAM DATA THAT HAS BEEN EXECUTED), SERVICE ARBITRATION REFERS TO THE PRIORITIZING OF TRAPS AND MICROTRAPS, AND FINALLY THE SAC CHIP CREATES ALL SYSTEM CLOCKS. (BASE,B,QD,M,PHASE) FROM THE OSCILLATOR INPUT (B27-B29 ON BACKPLANE), SAC ALSO HAS CONNECTIONS TO THE RDM MODULE TO HANDLE CLOCKING CONTROL AND DISABLES THE CCS BOARD FROM DRIVING THE MICRO ADDRESSES DURING MICRO DIAGNOSTIC EXECUTION.
THE SAC CHIP ALSO MONITORS THE FIRST CS PARITY ERROR (DETECTED BY THE ACV CHIP ON THE MIC MODULE), LOOKING FOR ANOTHER ONE BEFORE THE FIRST IS DONE WITH IT'S MICRO-TRAP (IN WHICH CASE IT WILL IMMEDIATELY HALT THE CLOCK.

BASE CLOCK = 160 NS 6.25 MHZ RUNS CONSTANTLY
B CLOCK = 160 NS 6.25 MHZ BASIC SYNCHRONIZED CLOCK USED THROUGHOUT THE CPU AND CMI.
M CLOCK = 320 NS CAN BE EXTENDED WITH THE CLKX BIT OF MICROCODE TO 480 NS THIS CLOCK IS THE MAIN MICROSEQUENCER CLOCK USED TO STROBE MICROCODE FROM CCS.
PHASE CLOCK= SPLITS THE M CLOCK INTO TWO HALFS. PHASE IS HIGH DURING THE FIRST 160 NS DURING WHICH TIME ALL READS OCCUR, THE PHASE IS LOW DURING THE SECOND 160 NS WHEN ALL WRITES OCCUR. THE PHASE CLOCK IS ALSO EXTENDED WITH THE CLKX BIT.
QD CLOCK = FOLLOWS M CLOCK, IT IS USED TO CLOCK THE Q (QUOTIENT) AND D (DIVIDEND) REGISTERS INTERNAL TO THE ALU SECTION OF THE DPM MODULE.

PART NUMBER: 19-14691

BEST DIAGNOSTICS: ALL MICRO'S DPM MICRO'S

MODULE: DPM GATE ARRAY: SAC



SPA: SCRATCH PAD ADDRESSING CHIP

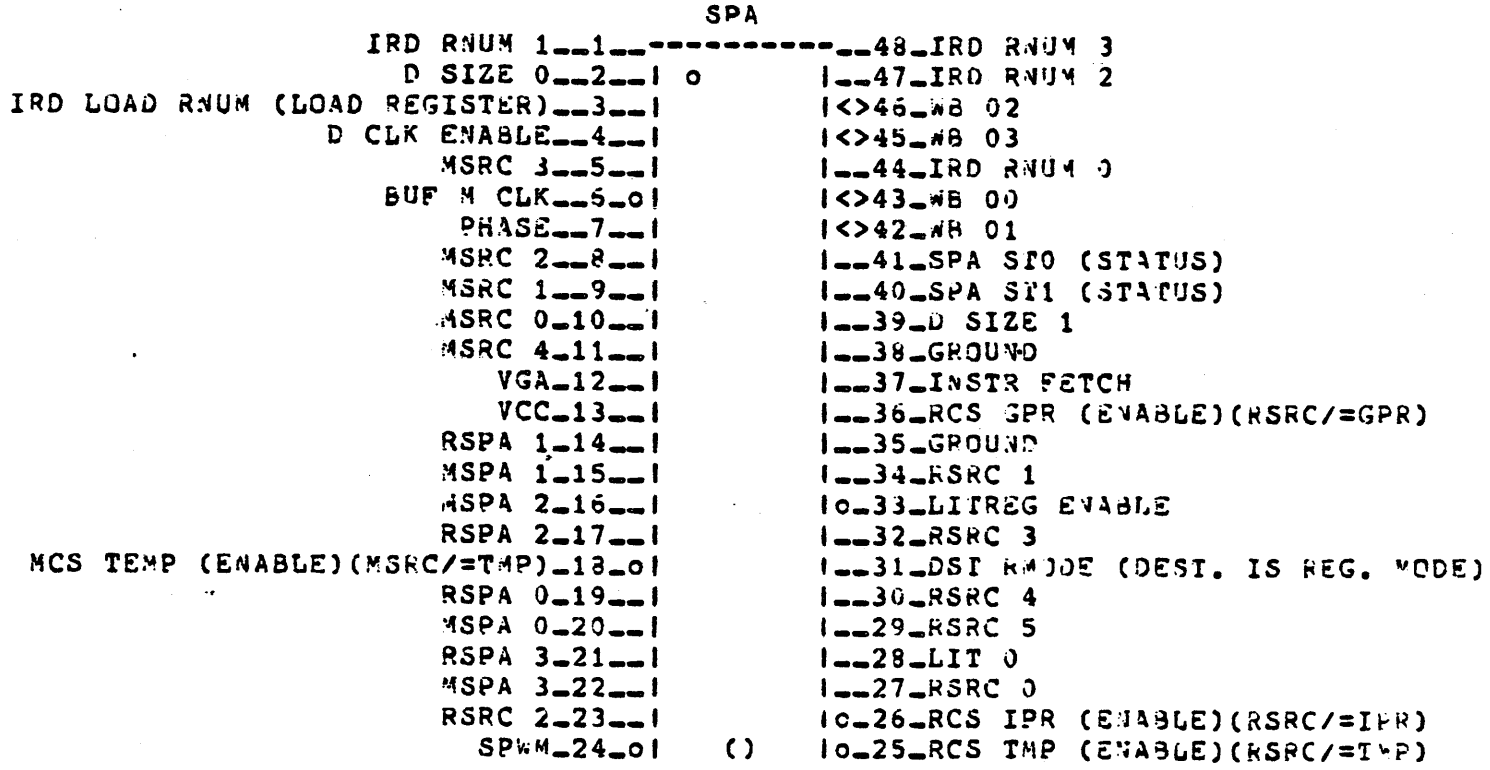
THE SPA CONTROLS THE ADDRESSING OF THE 64 SCRATCHPAD REGISTERS AND IT CONTROLS THE REGISTER BACKUP STACK (BACKS UP UP TO 6 GPR REGISTERS), CONTAINS LOGIC TO KEEP TRACK OF THE AUTO-INCREMENTING/DECREMENTING OF THE GPR'S, DEVELOPS IT'S OWN STATUS BITS AND ENABLE SIGNALS FOR THE VARIOUS REGISTERS.

PART NUMBER: 19-14690

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

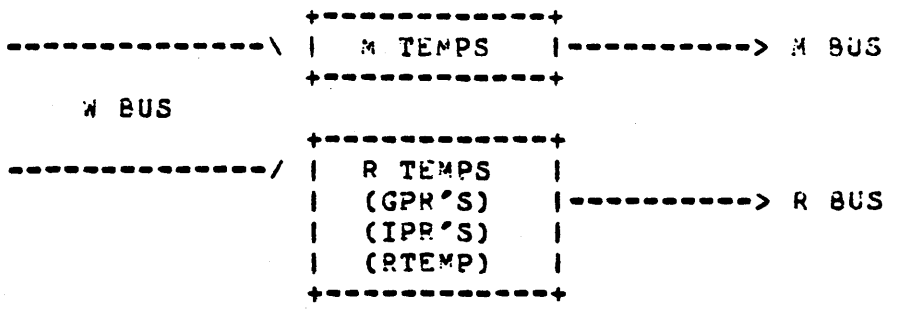
MODULE: DPM GATE ARRAY: SPA

TERM DEFINITIONS: MSPA = MTEMP SCRATCHPAD ADDRESS
RSPA = RTEMP SCRATCHPAD ADDRESS
RNUM = REGISTER NUMBER BUS (FROM RNUM REGISTER)



THIS SIDE TOWARDS FINGERS ON BOARD

REGISTERS FALL INTO TWO CATEGORIES RTEMPS AND MTEMPS. THE DEFINITION OF THESE CATEGORIES IS AS FOLLOWS:



M TEMP'S = M BUS TEMPORARY REGISTERS USED BY THE MICROCODE FOR TEMPORARY STORAGE OF DATA.
(CAN ONLY BE ACCESSED BY MICROCODE OR MICRO-MONITOR)

R TEMP'S = CONSIST'S OF ALL REGISTERS THAT FEED THE R BUS;

R BUS	TEMPORARY REGISTERS (MICROCODE OR MICROMONITOR)
GPR'S	16 GENERAL PURPOSE REGISTERS
IPR'S	INTERNAL PRIVILEGED REGISTERS (TEMPORARY HOLDING POINT FOR DATA DESTINED FOR MEMSCR'S

NOTE: RTEMP AND MTEMP 0-7 ARE DUAL PORTED TOGETHER.
EX. WRITING RTEMP 5 ALSO WRITES MTEMP 5
READS STILL ONLY AFFECT ONE OF THEM

SRK: SUPER ROTATOR CONTROL

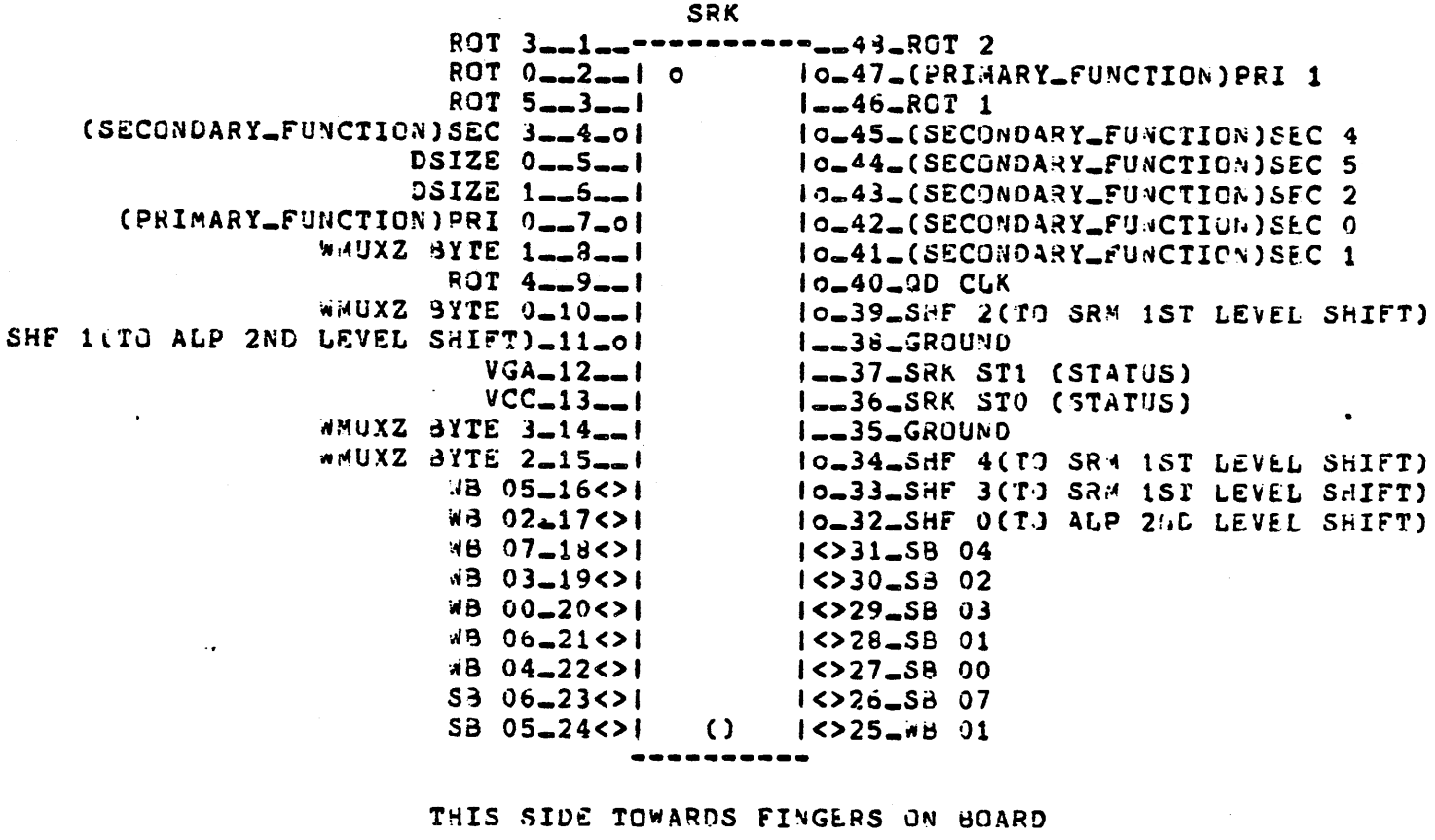
CONTROLS SUPER ROTATOR MULTIPLEXER OPERATIONS. LOOKS AT ROT FIELD OF MICROCODE AND TELLS THE SRM CHIPS WHAT TO DO. S AND P LATCHES (SIZE AND POSITION) ARE CONTAINED IN THIS CHIP.

NOTE: THE SRK CHIP CONTROLS THE SRM CHIP FUNCTIONS VIA A COMPLEX ARRAY OF SIGNALS CALLED PRI (PRIMARY), SEC (SECONDARY), AND SHF (SHIFT). THESE SIGNALS AND MALFUNCTIONS OF THESE SIGNALS CAN BE QUITE CONFUSING AND ARE BEST DIAGNOSED USING THE MICRO-DIAGNOSTICS.

PART NUMBER: 19-14688

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: SRK



THIS SIDE TOWARDS FINGERS ON BOARD

SRM: SUPER ROTATOR MULTIPLEXER

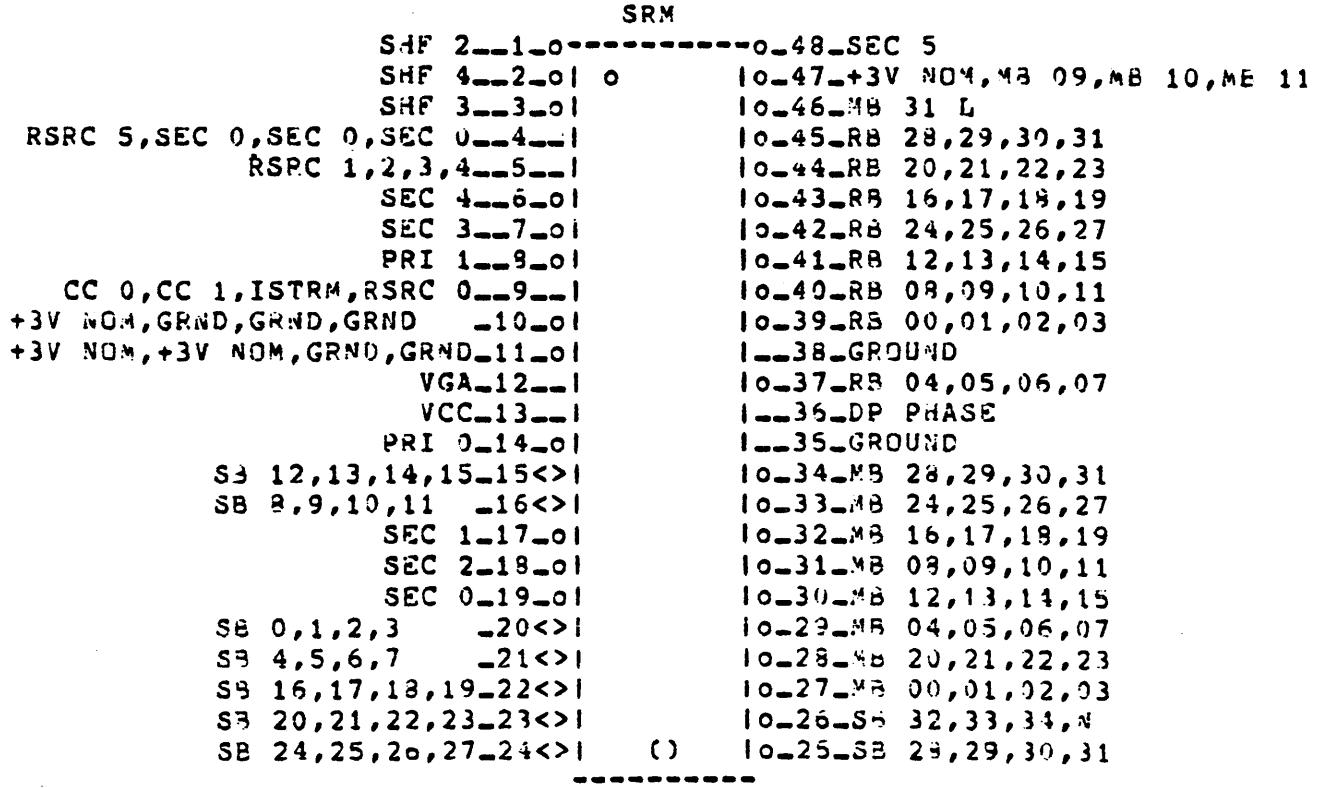
4 CHIPS PERFORM THE 64 FUNCTIONS UNDER SRK CONTROL. THESE CHIPS CONTAIN A "FIRST LEVEL" SHIFTER WHICH IS CAPABLE OF TAKING A 64 BIT INPUT FROM ANY COMBINATION OF THE R BUS, M BUS, OR SHORT LITERAL FIELD OF MICROCODE, AND SHIFTING ANY MULTIPLE OF FOUR BITS (NIBBLE). THE 35 BIT OUTPUT FROM THE SHIFTER IS PLACED ON THE SUPER BUS (S BUS) AND SENT TO THE ALU SECTION OF THE DPM MODULE WHERE IF DESIRED IT CAN BE ROTATED FROM 0 TO 3 MORE BITS INSIDE A SECOND LEVEL SHIFTER (COMPLETE WITH BIT BUCKET) INTERNAL TO THE ALP CHIP'S. THE OUTPUT OF THIS SECOND LEVEL SHIFTER IS ONCE AGAIN 32 BITS.

CHIP	BITS
SRM 1	0,4,8,12,16,20,24,28,32
SRM 2	1,5,9,13,17,21,25,29,33
SRM 3	2,6,10,14,18,22,26,30,34
SRM 4	3,7,11,15,19,23,27,31

PART NUMBER: 19-14687

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: SRM (1 THROUGH 4)



THIS SIDE TOWARDS FINGERS ON BOARD

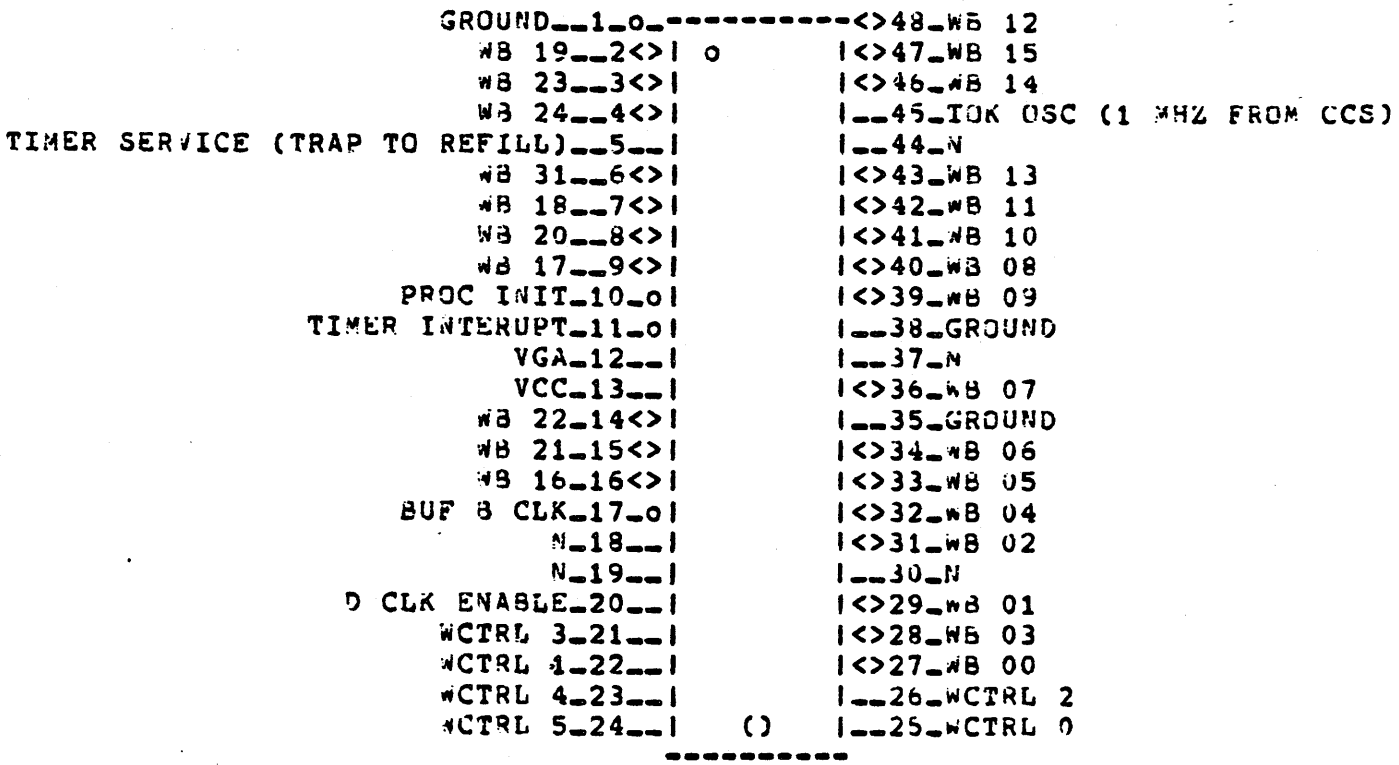
TOK: TIMED OPERATION CONTROL

PROGRAMMABLE INTERVAL CLOCK, 1 MICRO SECOND CLOCK, ABLE TO GENERATE INTERUPTS AT PROGRAMMABLE INTERVALS.

PART NUMBER: 19-14694

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE

MODULE: DPM GATE ARRAY: TOK



THIS SIDE TOWARDS FINGERS ON BOARD

L0003 MIC

MIC SLOT 3). THE MEMORY INTERCONNECT MODULE (MIC) #L0003

THE MEMORY INTERCONNECT MODULE IS THE SECOND MAJOR PART OF THE CPU, IT HOUSES THE DATA ROUTING AND ALIGNMENT LOGIC, ADDRESS LOGIC, TRANSLATION BUFFER, DATA CACHE, EXECUTION BUFFERS, SEVERAL PC REGISTERS, VA (VIRTUAL ADDRESS) AND MA (MEMORY ADDRESS) REGISTERS, CMI LATCH, PA (PHYSICAL ADDRESS) MUX, MDR'S (MEMORY DATA REGISTER) AND WDR (WRITE DATA REGISTER)

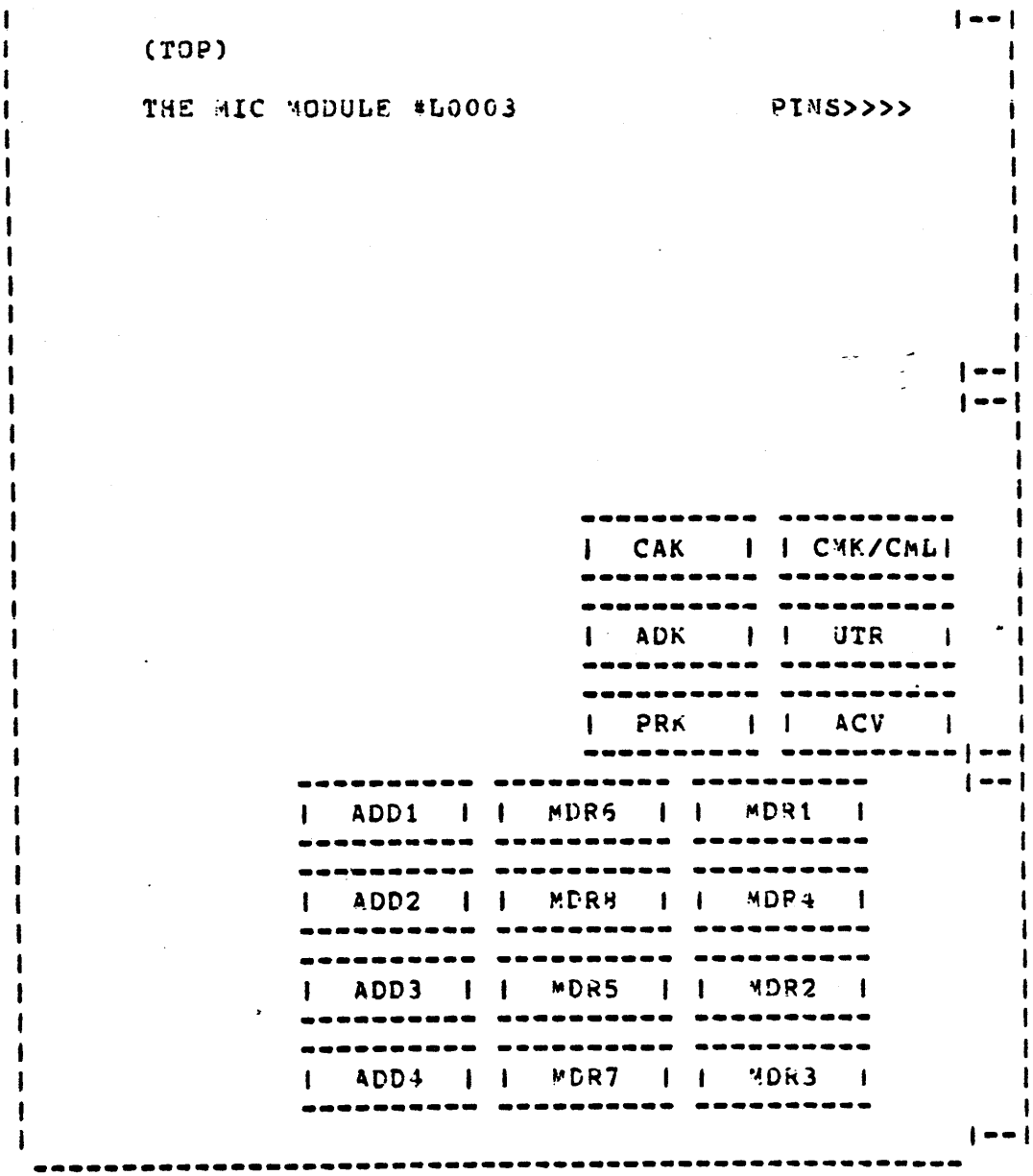
ALL ADDRESSES AND DATA PASS THROUGH THIS MODULE, IT PROVIDES THE INTERFACE TO AND FROM THE DPM MODULE AND CMI BUS, IT ALSO DETECTS UNIBUS ADDRESSES AND SIGNALS THE UBI MODULE WITH A SIGNAL CALLED "UB REQ H" PIN <C45>.

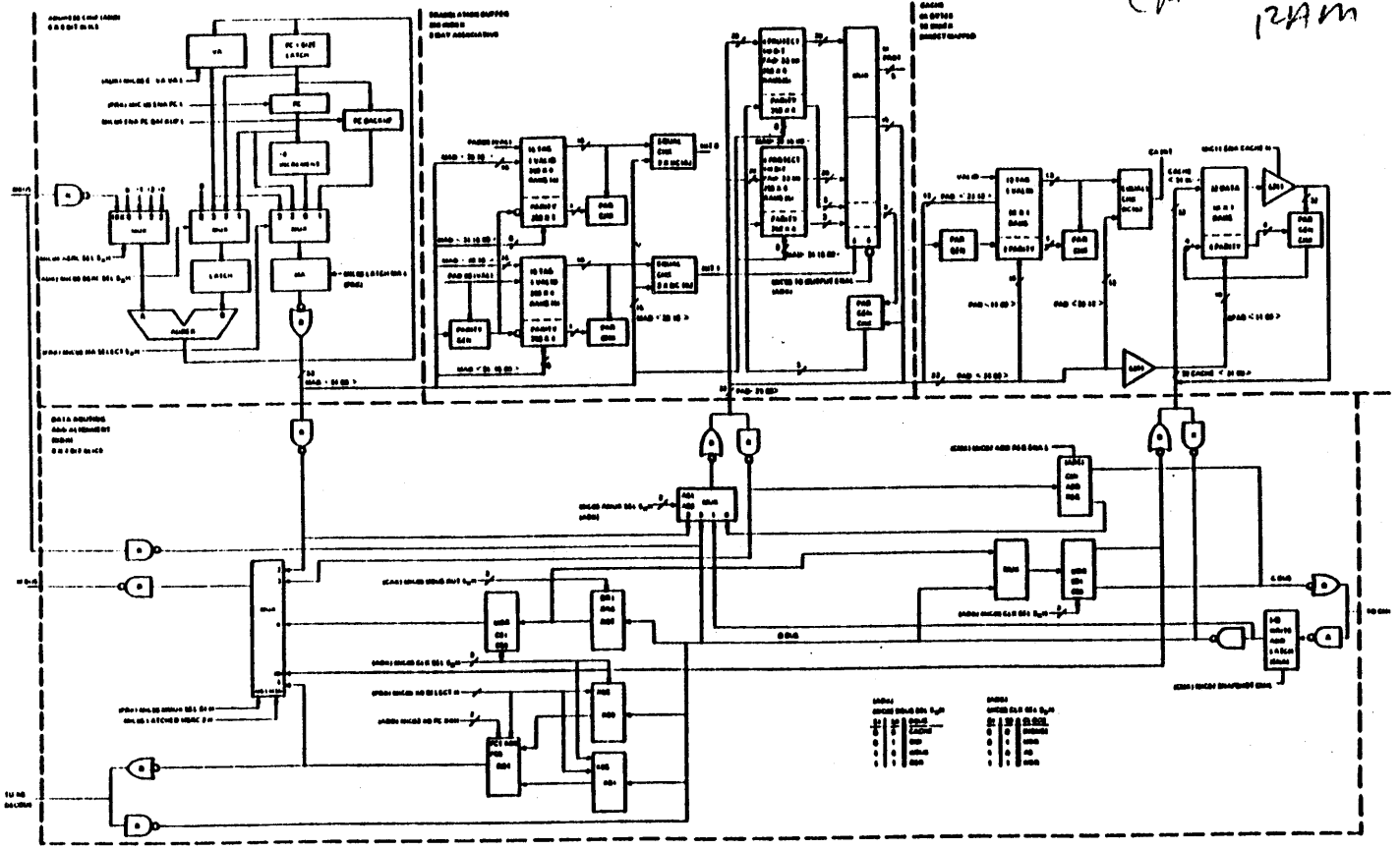
DATA PARITY, CHECKING AND GENERATING LOGIC FOR BOTH CACHE AND TRANSLATION BUFFERS ARE LOCATED ON THE BOARD.

THE MIC IS CONNECTED TO THE M BUS, MBUS, AND CMI.

THE MICRODIAGNOSTICS ECKAC.EXE TAPE #2, ECKAB.EXE TAPE #1 AND ECKAL.EXE TB AND CACHE DIAGNOSTICS WILL TEST THE MIC MODULE.

GATEARRAYS: ACV,ADD,ADK,CAK,CMK,MDR,PRK,UTR


(TOP)
THE MIC MODULE #L0003
PINS>>>>
CAK
CMK/CML
ADK
UTR
PRK
ACV
ADD1
MDR6
MDR1
ADD2
MDR8
MDR4
ADD3
MDR5
MDR2
ADD4
MDR7
MDR3



MIC Block Diagram

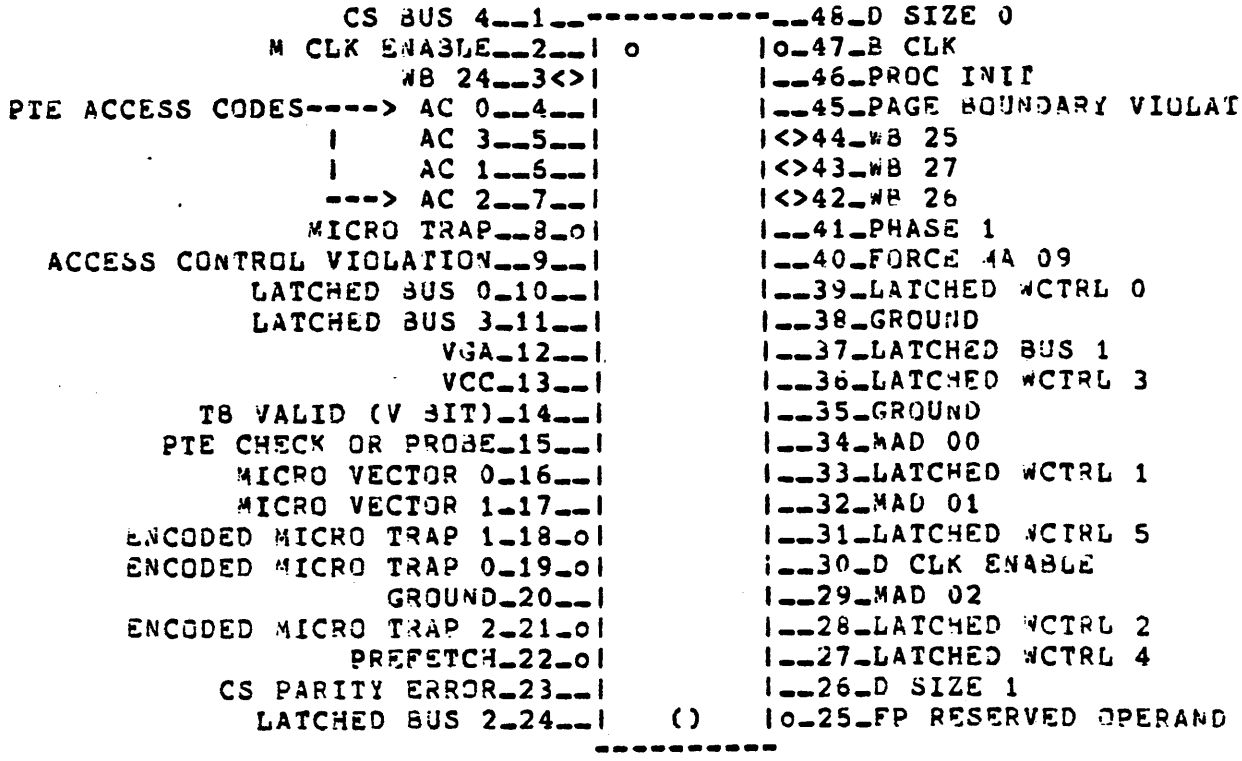
ACV: ACCESS VIOLATION CHIP

CAUSES CS PARITY ERROR MICRO TRAPS, FPA RESERVED OPERANDS, UNALLIGNED DATA, PAGE BOUNDRY VIOLATIONS, AND ACCESS CONTROL VIOLATIONS FROM THE TB. THE ACV WORKS WITH THE UTR CHIP TO HANDLE MICRO-TRAPS. CONTAINS THE MEMORY MANAGEMENT ENABLE LATCH. (IF MEM. MGMNT. IS OFF, THE ACV WILL MONITOR CS PARITY AND FPA RESERVED OPERANDS ONLY).

PART NUMBER: 19-14699

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE
DPM MICRO'S ECKAB.EXE
TB + CACHE ECKAL.EXE

MODULE: MIC GATE ARRAY: ACV



THIS SIDE TOWARDS FINGERS ON BOARD

ADD: ADDRESS CHIPS

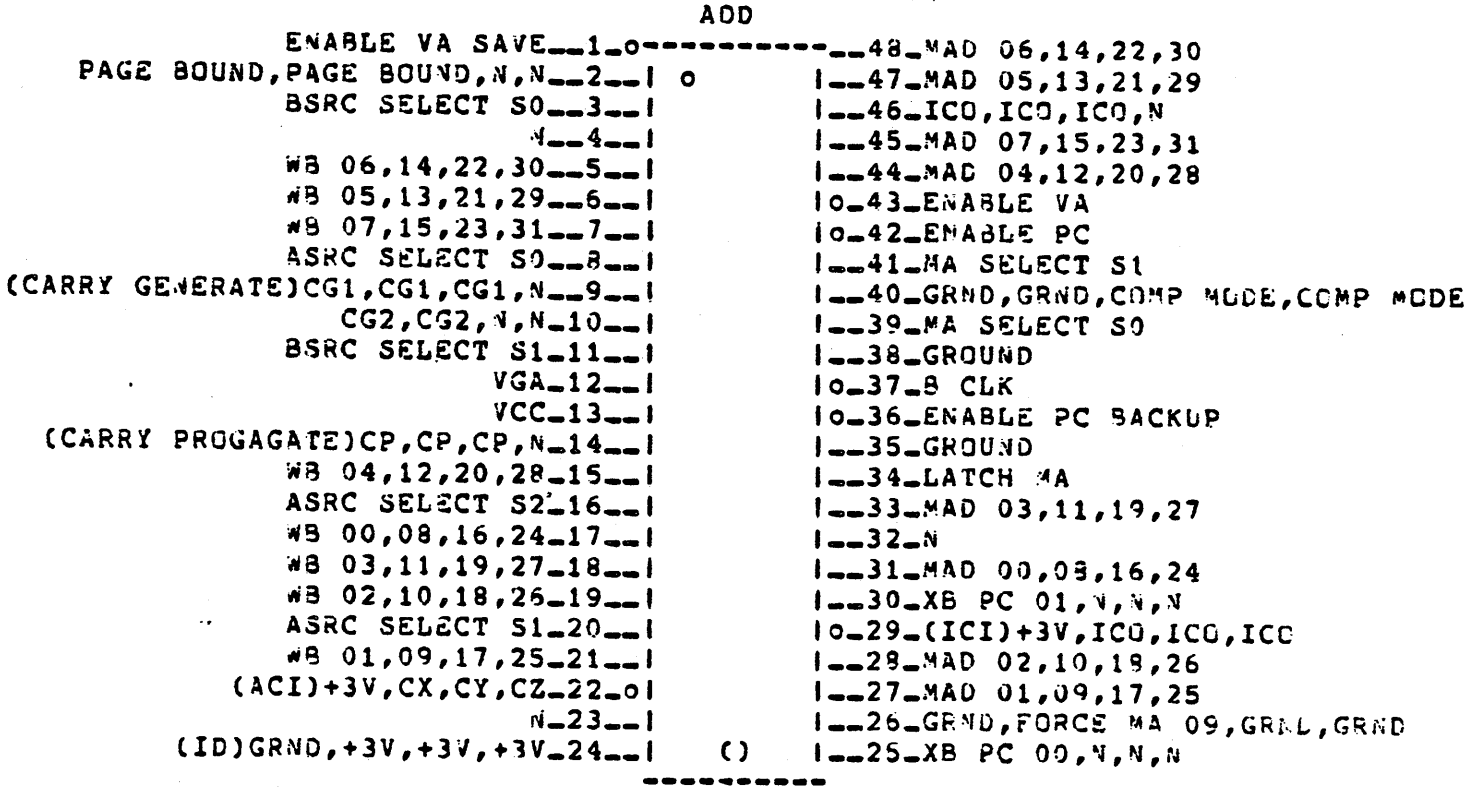
CONTAINS THE PC'S AND VA CIRCUIT, ENABLE LINES AND LOAD PATHS, PLUS A AND B SOURCE MUX SELECT CONTROLS. THE ADD CHIPS CONTAIN AN INTERNAL ADDER CAPABLE OF BUMPING THE PC OR VA BY 1, 2, 4, OR FROM THE N BUS.

4 CHIPS	CHIP	BIT SLICE
	ADD 1	<7-0>
	ADD 2	<15-8>
	ADD 3	<23-16>
	ADD 4	<31-24>

PART NUMBER: 19-14683

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE

MODULE: MIC GATE ARRAY: ADD (1 THROUGH 4)



THIS SIDE TOWARDS FINGERS ON BOARD

ADK: ADDRESS CONTROL CHIP

CONTAINS IPR COMPONENTS (MEMSCR'S) FOR TB, MEMORY MANAGEMENT, AND THE RANDOM FLIP FLOP. THE ADK WORKS WITH THE PRK, ADD AND MDR CHIPS. THE ADK DETECTS TB HITS AND MISSES.

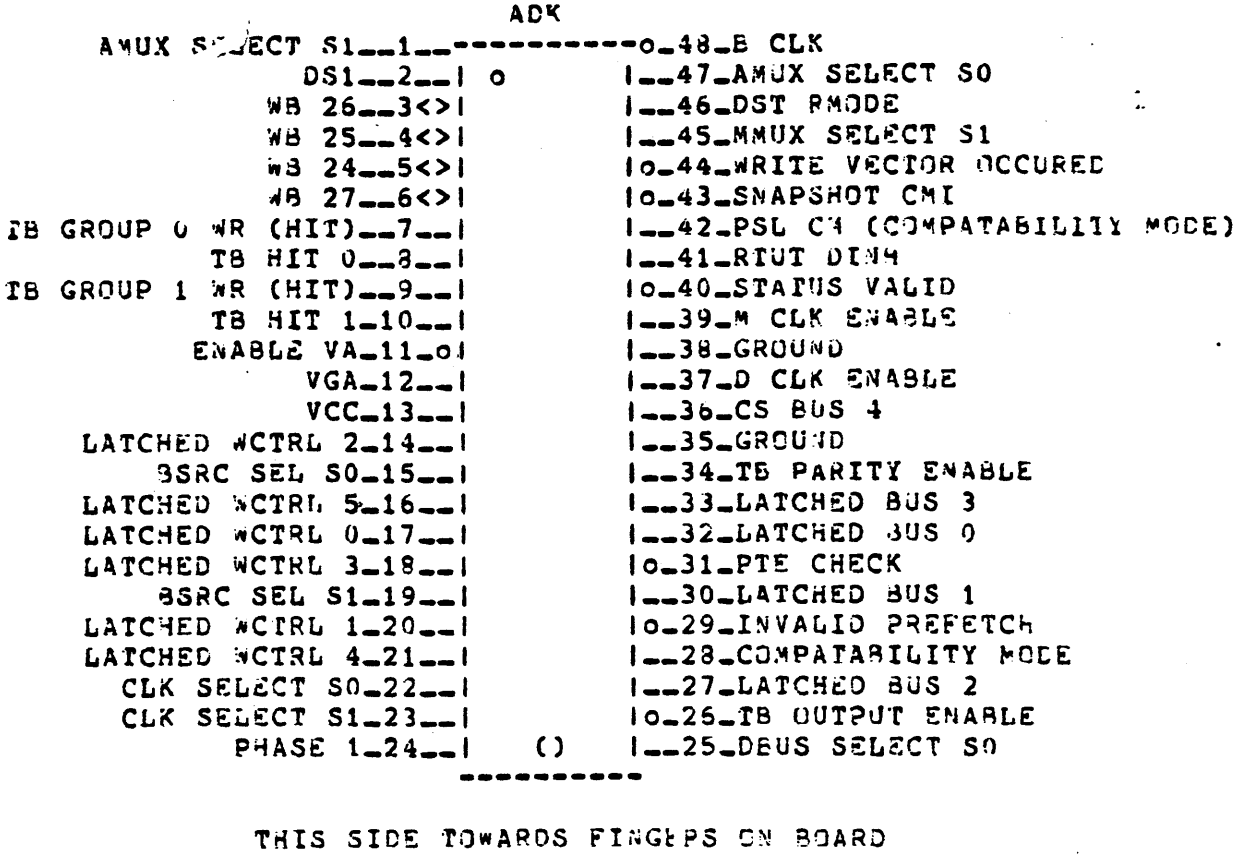
NOTE: TO DISABLE HALF OF THE TB ON A LIVE VMS SYSTEM:

1). REMOVE ALL USERS FROM THE SYSTEM TEMPORARILY
2). TYPE ^P ON THE CONSOLE TERMINAL
3). TYPE: >>>D/I 24 D (FOR GROUP 0) OR D/I 24 A (FOR GROUP 1)
4). TYPE: >>>C

PART NUMBER: 19-14700

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE

MODULE: MIC GATE ARRAY: ADK



THIS SIDE TOWARDS FINGERS ON BOARD

CAK: CACHE CONTROL CHIP

CONTROLS THE ENABLING AND DISABLING OF CACHE, THE TRANSFER OF DATA TO AND FROM THE MDR CHIPS, AND CACHE HIT VALIDATION.

NOTE: TO DISABLE CACHE TYPE: >>>D/I 25 1
TO RE-ENABLE CACHE TYPE: >>>D/I 25 0

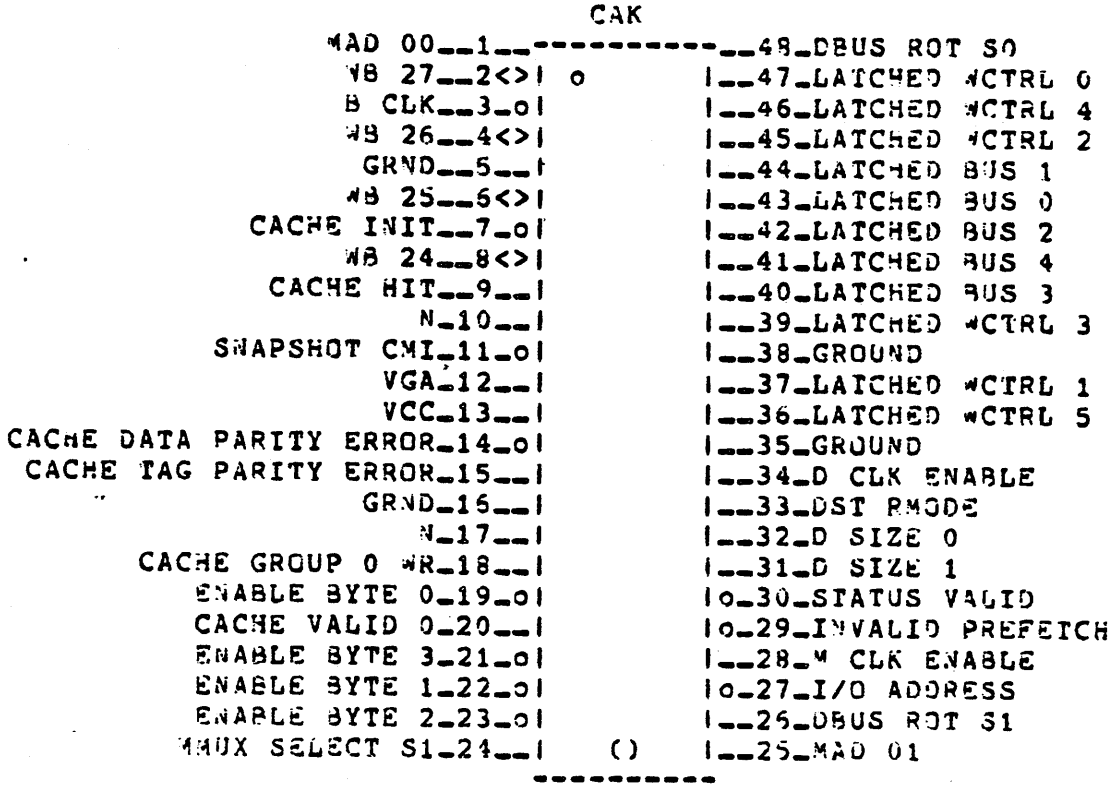
ON A LIVE VMS SYSTEM:

1). REMOVE ALL USERS FROM THE SYSTEM TEMPORARILY
2). TYPE ^P ON THE CONSOLE TERMINAL
3). TYPE: >>>D/I 25 1 (OFF) OR D/I 25 0 (ON)
4). TYPE: >>>C

PART NUMBER: 19-14701

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE
TB + CACHE ECKAL.EXE

MODULE: MIC GATE ARRAY: CAK



THIS SIDE TOWARDS FINGERS ON BOARD

CMK/CML: CPU MEMORY INTERCONNECT CHIP

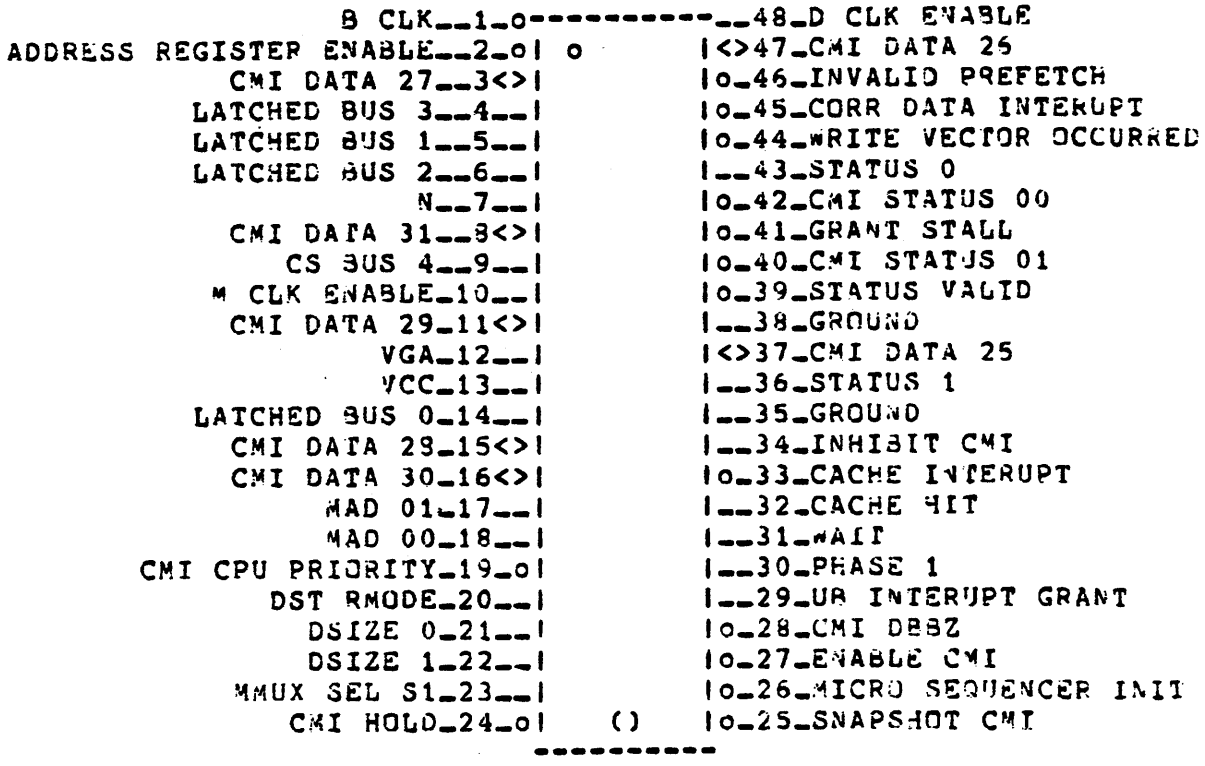
MONITORS AND CONTROLS SIGNALS TO AND FROM THE CMI AND STALLS THE MICROCODE ON CERTAIN CONDITIONS.

NOTE: THIS IS THE ONLY CHIP THAT CONTROLS THE CPU'S ACCESS TO THE CMI BUS. OPERATION OF THE CMK/CML CHIP CAN BE VERIFIED BY DOING CONSOLE MODE DEPOSITS AND EXAMINES OF MAIN MEMORY WITH CACHE DISABLED AND AGAIN FROM ROM MODE WHICH DOES NOT USE THE CMK/CML CHIP.

PART NUMBER: 19-14697

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE

MODULE: MIC GATE ARRAY: CMK



THIS SIDE TOWARDS FINGERS ON BOARD

MDR: MEMORY DATA REGISTER CHIPS

CONTAINS THE EXECUTION BUFFERS, WRITEDATA REGISTER, MEMORY DATA REGISTER, PHYSICAL ADDRESS MUX AND CONTROL LOGIC FOR ROUTING DATA IN AND OUT, TO AND FROM THE CMI, M BUS AND M BUS.

8 CHIPS

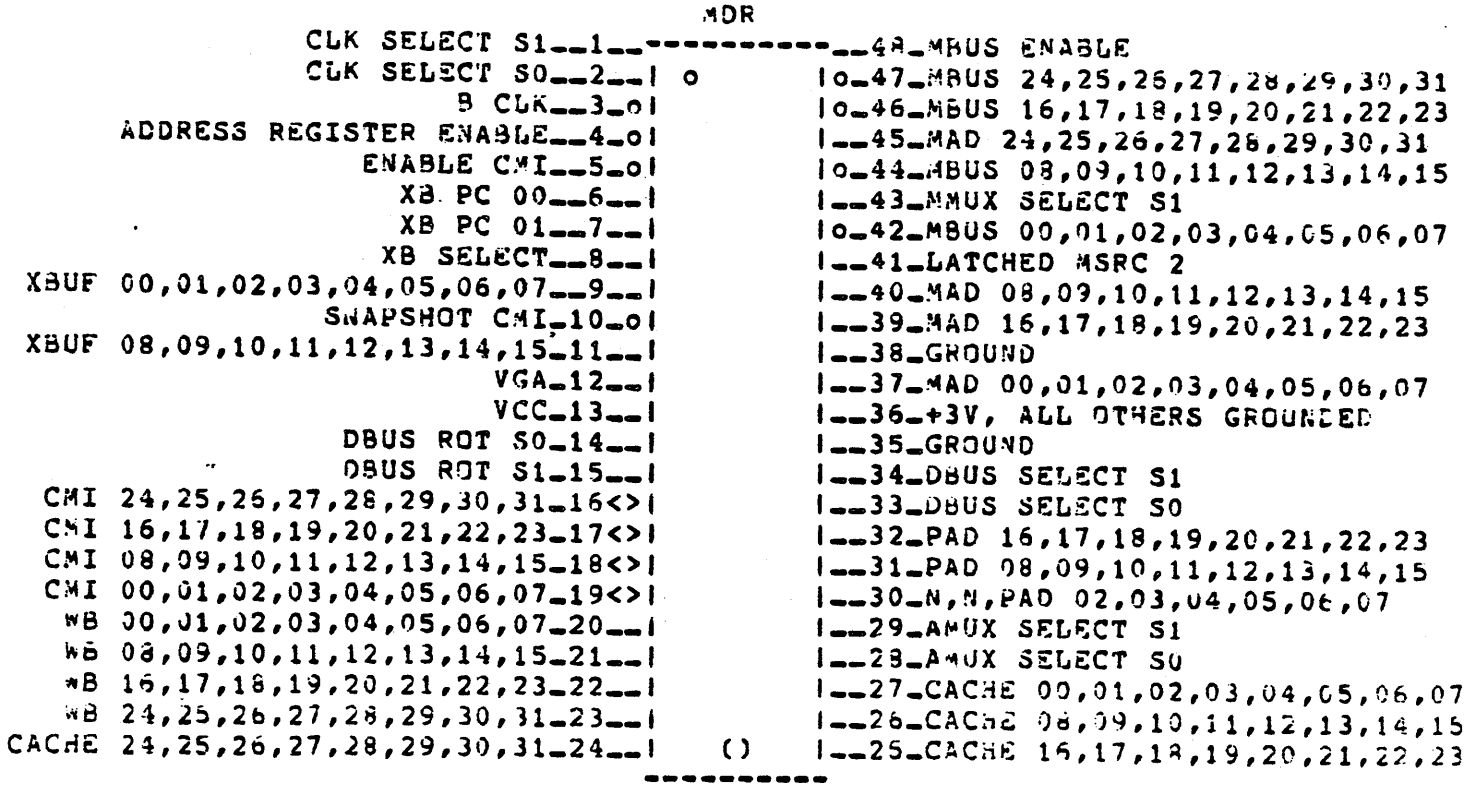
CHIP	BITS
MDR 1	0,8,16,24
MDR 2	1,9,17,25
MDR 3	2,10,18,26
MDR 4	3,11,19,27
MDR 5	4,12,20,28
MDR 6	5,13,21,29
MDR 7	6,14,22,30
MDR 8	7,15,23,31

BUS DEFINITION: D BUS = DATA BUS (AN INTERNAL BUS INSIDE THE MDR CHIPS)

PART NUMBER: 19-14681

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE

MODULE: MIC GATE ARRAY: MDR (1 THROUGH 8)



THIS SIDE TOWARDS FINGERS ON BOARD

PRK: PREFETCH CONTROL CHIP

USED IN CONJUNCTION WITH THE ADL, AND MDR CHIPS TO MONITOR USAGE OF THE EXECUTION BUFFERS. WHEN EXECUTION BUFFERS ARE EMPTY, OR A NEW ADDRESS IS PLACED IN THE PC, THE PRK CHIP FORCES PREFETCHING OF A NEW INSTRUCTION FROM MEMORY USING THE ADDRESS IN THE PC (NEW ADDRESS IN PC) OR PC+4 (EX. BUF. EMPTY).

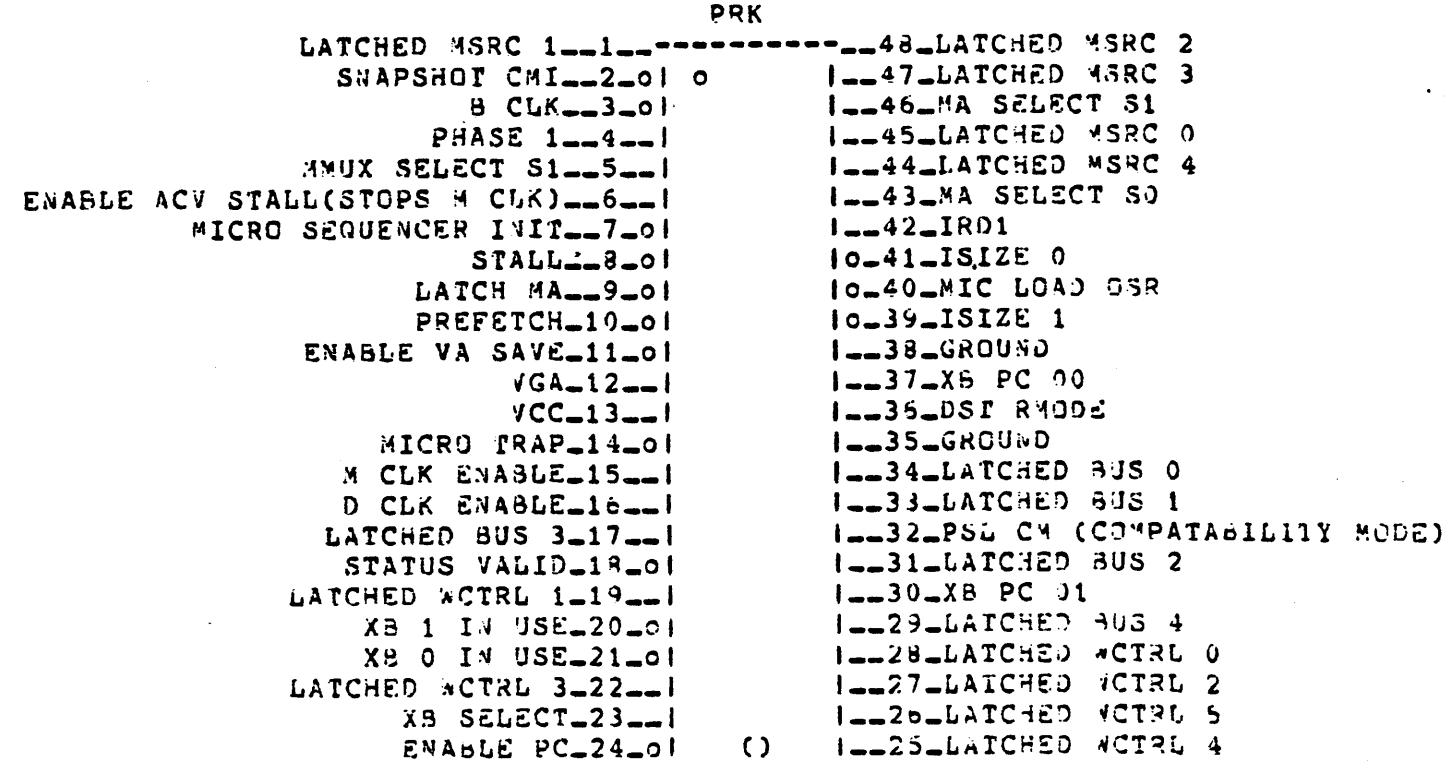
PREFETCHING IS INDEPENDANT OF THE MICROCODE AND WILL HAPPEN WHENEVER AN XB IS EMPTY AND THERE IS NO BUS CYCLE IN PROGRESS. THE PRK WILL STALL THE M CLOCK WHEN BOTH XB'S ARE EMPTY AND THE CPU ATTEMPTS AN IRD1. (THIS CAN OCCUR WHEN A DEVICE IS TYING UP THE CMI WITH TRANSFERS AND THE PRK HAS TO WAIT FOR COMPLETION BEFORE IT CAN PREFETCH (CPU HAS A PRIORITY OF 0)). THE PRK WILL ALSO HAVE TO STALL WHENEVER THE PC GETS A NEW ADDRESS SUCH AS A BRANCHING INSTRUCTION OR A NEW PROGRAM. THIS ALLOWS TIME TO PERFORM THE FIRST PREFETCH FROM THE NEW PC PRIOR TO THE START OF NORMAL EXECUTION.

PREFETCHES ARE LONGWORDS ONLY!

PART NUMBER: 19-14698

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE

MODULE: MIC GATE ARRAY: PRK



THIS SIDE TOWARDS FINGERS ON BOARD

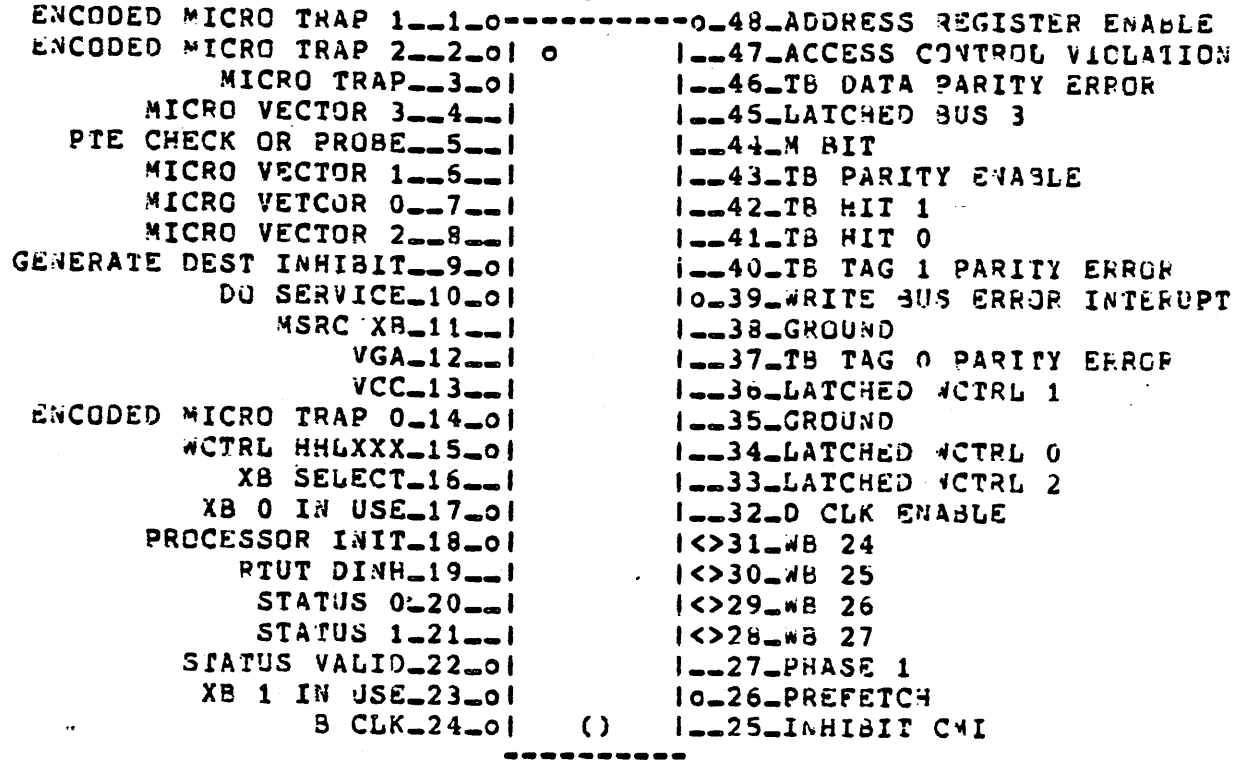
UTR: MICRO TRAP CHIP

MONITORS THE MACHINE CONDITIONS THAT CAN CAUSE A MICRO-TRAP. GENERATES MICRO-VECTOR ADDRESSES, AND DECODES THE HIGHEST PRIORITY TRAP CONDITION. THE UTR RECEIVES ENCODED MICRO TRAP INPUTS FROM VARIOUS HARDWARE COMPONENTS AND DECODES THEM INTO THIER APPROPRIATE MICRO-VECTOR ADDRESSES TO BE PLACED ON THE CONTROL STORE ADDRESS LINES WHEN PERFORMING A MICRO TRAP.

PART NUMBER: 19-14702

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE

MODULE: MIC GATE ARRAY: UTR



THIS SIDE TOWARDS FINGERS ON BOARD

L0004 UBI

UBI SLOT 4). THE UNIBUS INTERFACE MODULE (UBI) #L0004

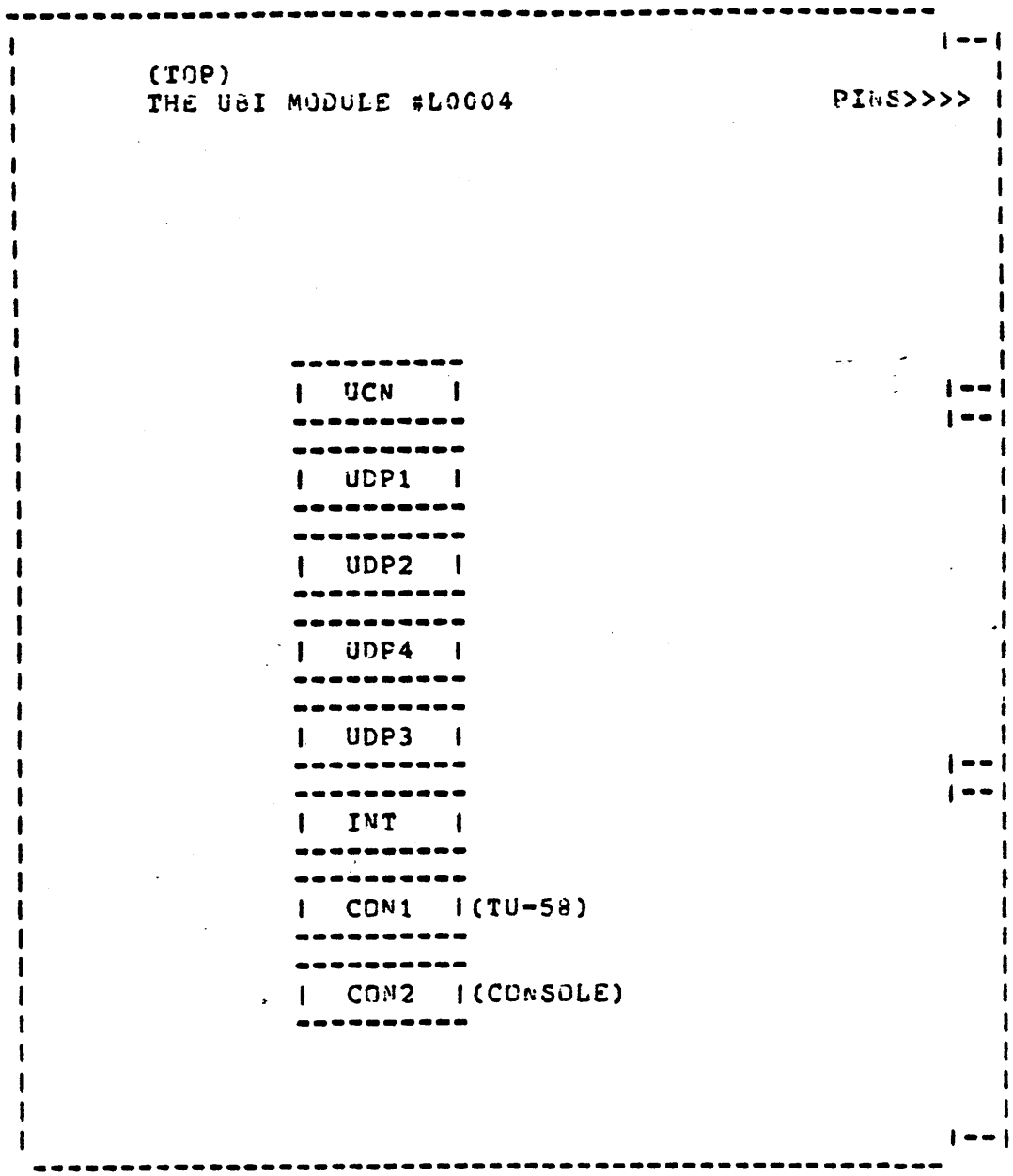
THE UNIBUS INTERFACE MODULE IS MUCH LIKE ANY UNIBUS ADAPTER WITH THE EXCEPTION OF HAVING ADDITIONAL LOGIC ON IT TO HANDLE COMMUNICATIONS FOR THE TU-58 AND CONSOLE AND ALSO HANDLING ALL INTERUPTS WITHIN THE CPU, ALL UNIBUS AND MASSBUS DEVICES INTERUPT VIA THE UBI. THE UBI CONTAINS POWER FAIL LOGIC, THE T.O.Y. CLOCK AND CHARGING CIRCUIT, THE UNIBUS DATA LATCH, 3 BUFFERED DATA PATHS, 1 DIRECT DATA PATH, BYTE SWAPPING LOGIC, ADDRESS BUFFERS AND MAPS.

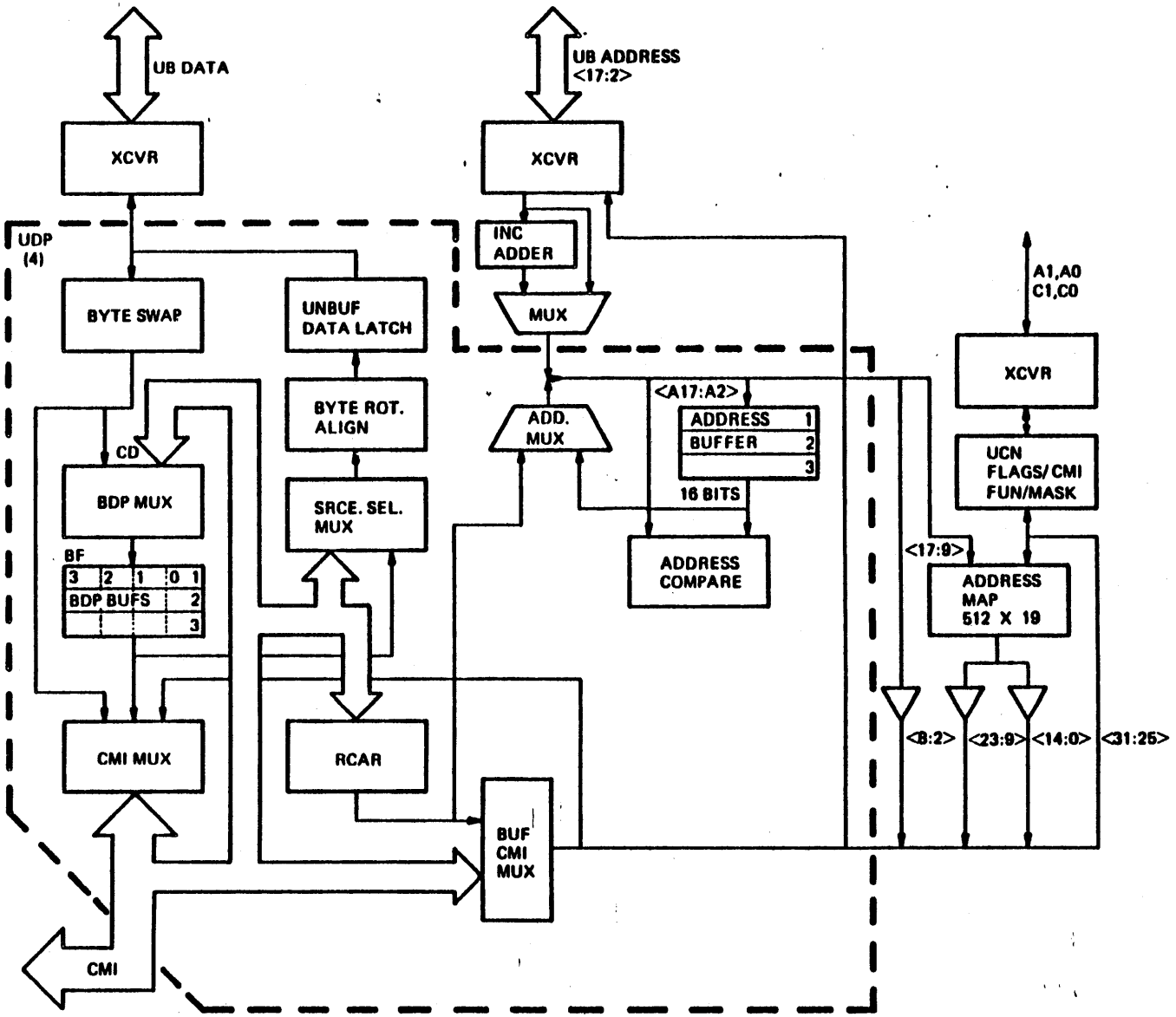
THE UBI IS CONNECTED TO THE W BUS, CMI, AND UNIBUS.

THE DPM MICRO-DIAGNOSTIC ECKAB.EXE WILL TEST THE COMMUNICATIONS SECTIONS AND THE LEVEL 3 DIAGNOSTIC ECCBA.EXE TAPE #6 WILL TEST THE ADAPTER SECTION.

THE SECOND UNIBUS OPTION (SUB MODULE) WILL ALSO BE TESTED BY ECCBA.EXE

GATEARRAYS: CON,INT,UCN,UDP


(TOP)
THE U8I MODULE #L0004
PINS>>>>
UCN
UDP1
UDP2
UDP4
UDP3
INT
CON1
(TU-58)
CON2
(CONSOLE)



UNIBUS Interface Block Diagram

CON: CONSOLE CHIP

THE CON CHIPS CONVERT SERIAL DATA FROM THE TU-58 OR THE CONSOLE TERMINAL TO PARALLEL DATA FOR THE W BUS, OR PARALLEL TO SERIAL IF ROUTING IN THE OPPOSITE DIRECTION.

PART NUMBER: 19-14685

REST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE
DW750 MACRO ECCBA.EXE (LEVEL 3)

MODULE: UBI GATE ARRAY: CON (TU58 AND CONSOLE)

CON (TU58,CONSOLE)

WCTRL 0,+3V_1		48_TU/CON DONE SYNC
MICRO SEQUENCER INIT_2_o	o	47_CKDO (INTERNAL CLOCK SIGNALS)
WCTRL 5_3		46_WCTRL 4
WCTRL 2_4		o_45_+3V
GRND,WCTRL 0_5		o_44_TU/CON T READY SYNC
N,HALT DET BR SYNC_6		o_43_CLCO (INTERNAL CLOCK SIGNALS)
TU/CON DONE SYNC H_7_o		o_42_M CLK
+3V,FRONT PANEL LOCKED_8		41_TU58 INT L,SERIAL LINE INT L
TU/CON SERIAL INPUT_9		<>40_WB 25
CLD1 (INTERNAL CLOCK SIGNALS)_10		<>39_WB 24
TU/CON T READY SYNC_11		38_GROUND
VGA_12		o_37_D CLK ENABLE
VCC_13		36_WCTRL 3
GRND,RD INTERUPT INHIBIT_14		35_GROUND
WB 16_15<>		o_34_CLCI (INTERNAL CLOCK SIGNALS)
N_16_o		33_GRND,HALT DET SYNC
GRND_17		32_WCTRL 1
TU/CON BAUD RATE CLOCK_18		o_31_M CLK
WB 19_19<>		<>30_WB 22
WB 17_20<>		29_BREAK CLK,N
WB 18_21<>		28_GRND,INSTR FETECH
WB 21_22<>		o_27_SET BREAK,CON HALT
WB 20_23<>		o_26_N
WB 23_24<>	()	25_EIA TU/CON SERIAL OUTPUT

THIS SIDE TOWARDS FINGERS ON BOARD

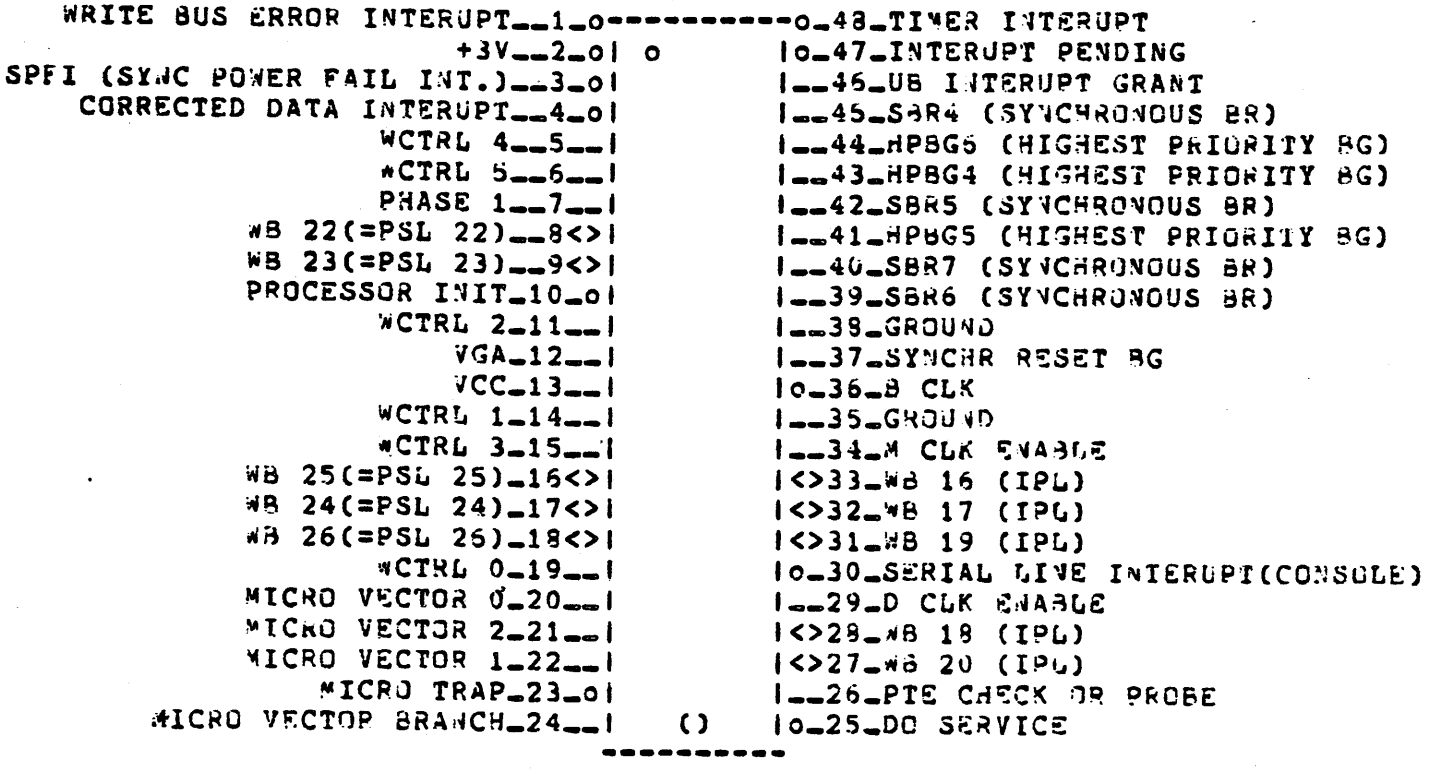
INT: INTERUPT CHIP

THE INTERUPT CHIP ENABLES THE HANDLING OF ALL INTERUPT REQUEST: BOTH MASSBUS AND UNIBUS, CONTAINS PSL BITS <22-26 and IPL>, PERFORMS INTERUPT ARBITRATION, ISSUES BUS GRANTS, AND INSERTS VALUES ON THE MICRO-VECTOR LINES.

PART NUMBER: 19-14704

BEST DIAGNOSTICS: DPM MICRO'S ECKAB.EXE
DW750 MACRO ECC9A.EXE (LEVEL 3)

MODULE: UBI GATE ARRAY: INT



THIS SIDE TOWARDS FINGERS ON BOARD

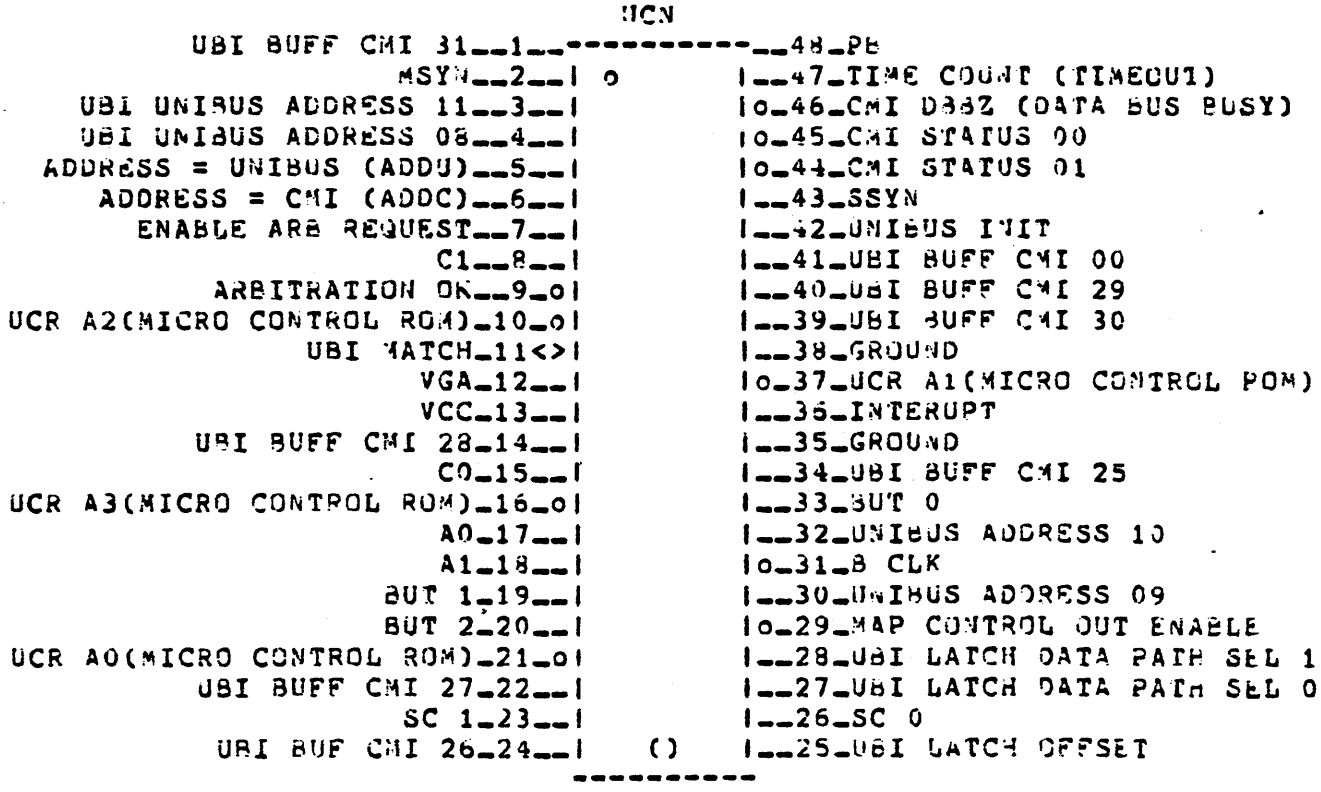
UCN: UNIBUS DATA PATH CONTROL CHIP

THE UCN CHIP CONTROLS THE UDP CHIP FUNCTIONS, ENABLES UBI ARBITRATION FOR THE CMI, ISSUES AND MONITORS UNIBUS CONTROL SIGNALS AND CMI STATUS LINES FOR USE BY THE UBI MICROCODE. THE UBI IS ROM CONTROLLED AND THE UCN CHIP PLACES THE PROPER MICRO-ADDRESS ON THE UBI MICRO-ADDRESS LINES AFTER DECODING WHAT FUNCTION NEEDS TO BE DONE.

PART NUMBER: 19-14693

BEST DIAGNOSTICS: DW750 MACRO ECCBA.EXE (LEVEL 3)

MODULE: UBI GATE ARRAY: UCN



THIS SIDE TOWARDS FINGERS ON BOARD

UDP: UNIBUS DATA PATHS CHIP

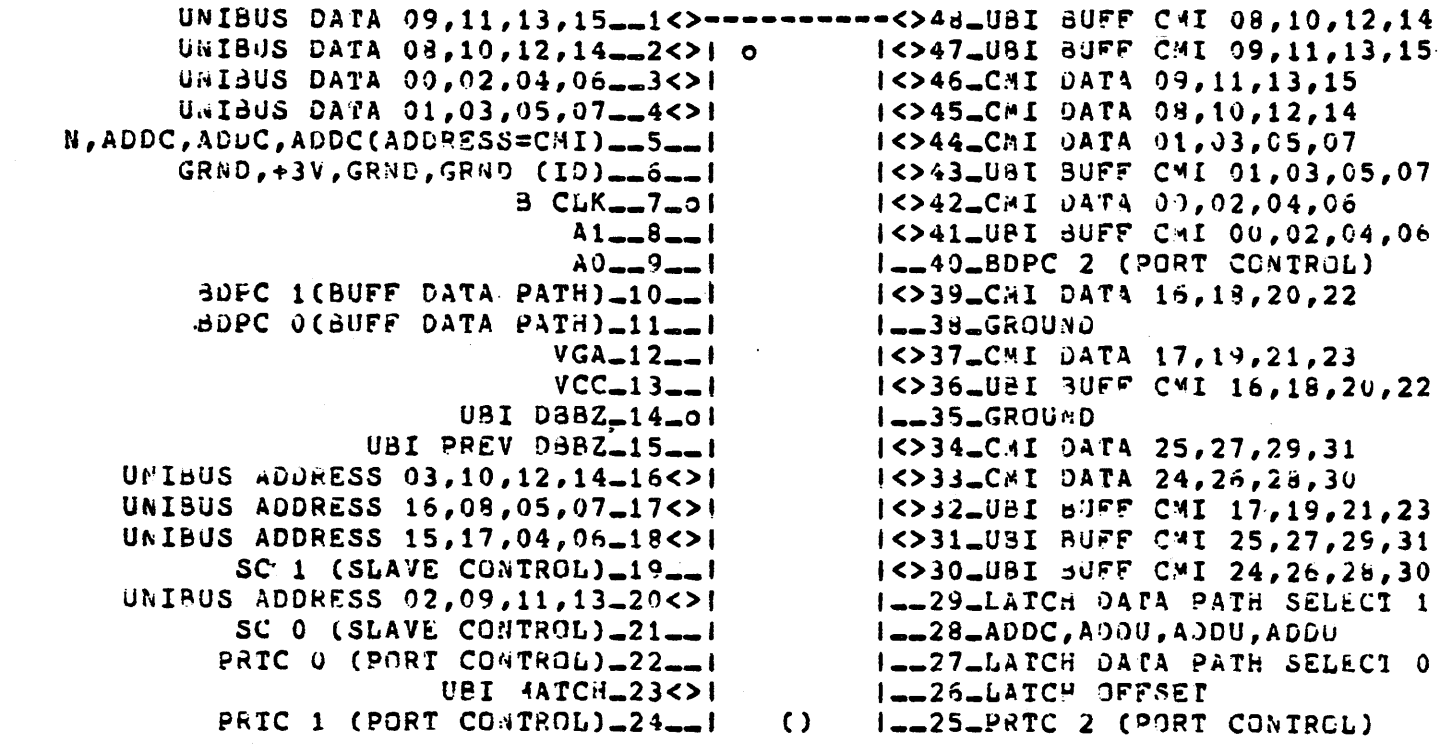
COMPLETE UNIBUS DATA PATHS CONTAINED IN THESE CHIPS, 3 BUFFERED AND 1 DIRECT, BYTE SWAPPING AND OFFSET LOGIC. PROVIDES A PATH FOR ALL ADDRESSES AND DATA BETWEEN THE CMI AND UNIBUS.

4 CHIPS	CHIP	BITS
	UDP 1	0,1,8,9,16,17,24,25
	UDP 2	2,3,10,11,18,19,26,27
	UDP 3	4,5,12,13,20,21,28,29
	UDP 4	6,7,14,15,22,23,30,31

PART NUMBER: 19-14692

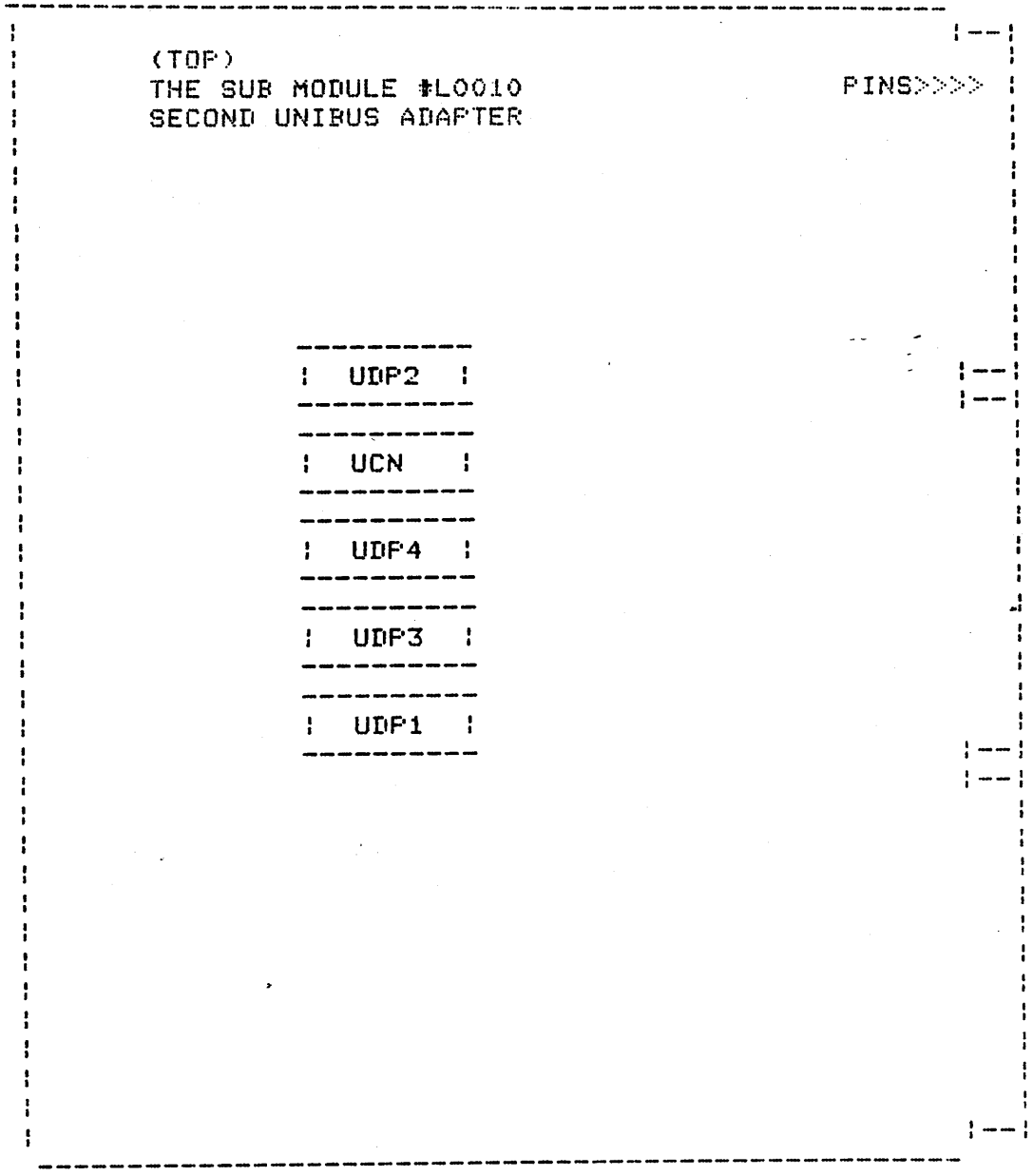
BEST DIAGNOSTICS: DW750 MACRO ECCBA.EXE (LEVEL 3)

MODULE: UBI GATE ARRAY: UDP (1 THROUGH 4)



THIS SIDE TOWARDS FINGERS ON BOARD

L0010 SUB


(TOP)
THE SUB MODULE #L0010
SECOND UNIBUS ADAPTER
PINS>>>>
UDP2
UCN
UDP4
UDP3
UDP1

CTION 1 INSPECT PARTS

The basic DW750 option consist of the following hardware parts. Check that none are missing or damaged before you procede.

QUANTITY	DESCRIPTION
1	L0010 Second UNIBUS(SUB) Module
1	Ribbon cable assembly consisting of: (3) 40-conductor BC06 ribbon cables, tie wrapped and formed.
1	M9014 Transition module
1	M9302 UNIBUS Terminator

There should be an expansion box, and possibly an expansion cabinet.The expansion box and, or cabinet are not part of the DW750 option,but should have been ordered separately.

ECTION 2 INSTALL EQUIPMENT

2.1 CHECK HARDWARE REVISION LEVEL AND POWER SYSTEM DOWN

2.1.1 If VMS is running bring it down in an orderly fashon by either having the customer bring it down, or with his permission typing the following command.

EX:

```
$ @sys$system:shutdown
```

2.1.2 Examine the CPU hardware revision level to assure compatability between the option and the CPU. If the CPU is not at the correct revision level, do not procede with this option installation until the CPU is updated and checked out. The following example shows you how to check the CPU rev.

EX:

```
>>> E/I 3E

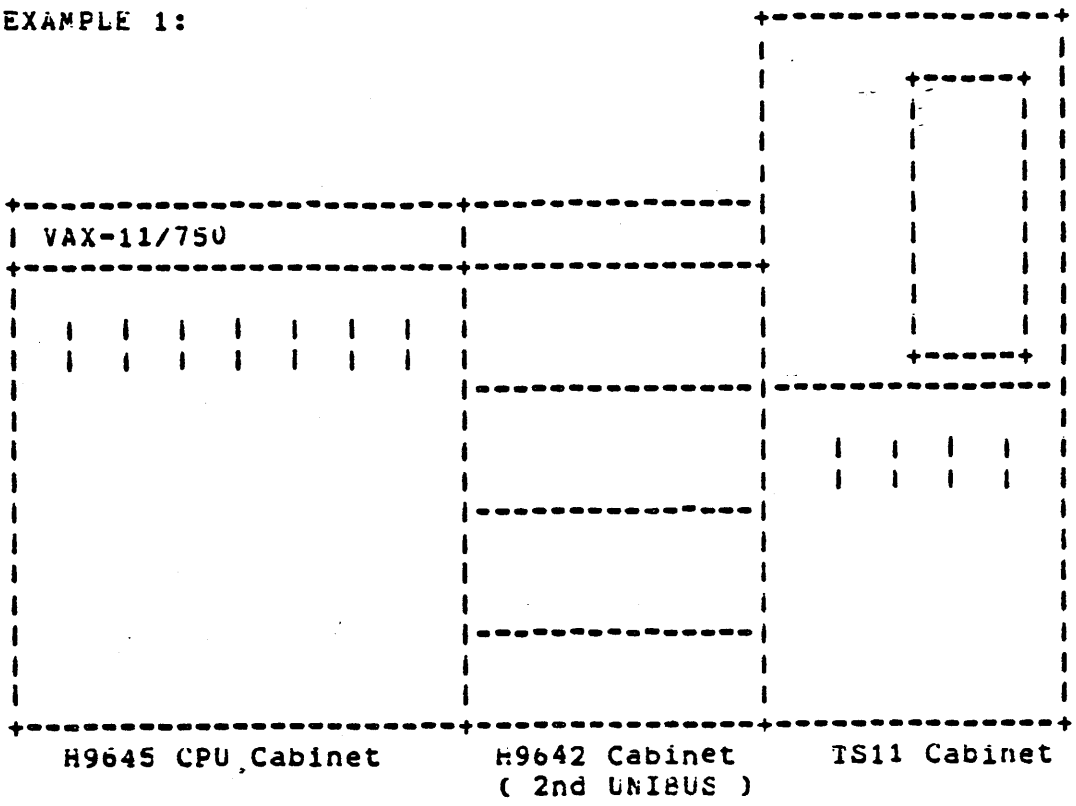
                I  00000003E      02005E30
(for systems with 16K arrays)
                      CR
                1  00000003E      02005E48
(for systems with 1meg arrays)
```

2.1.3 Power the system off using the key switch.

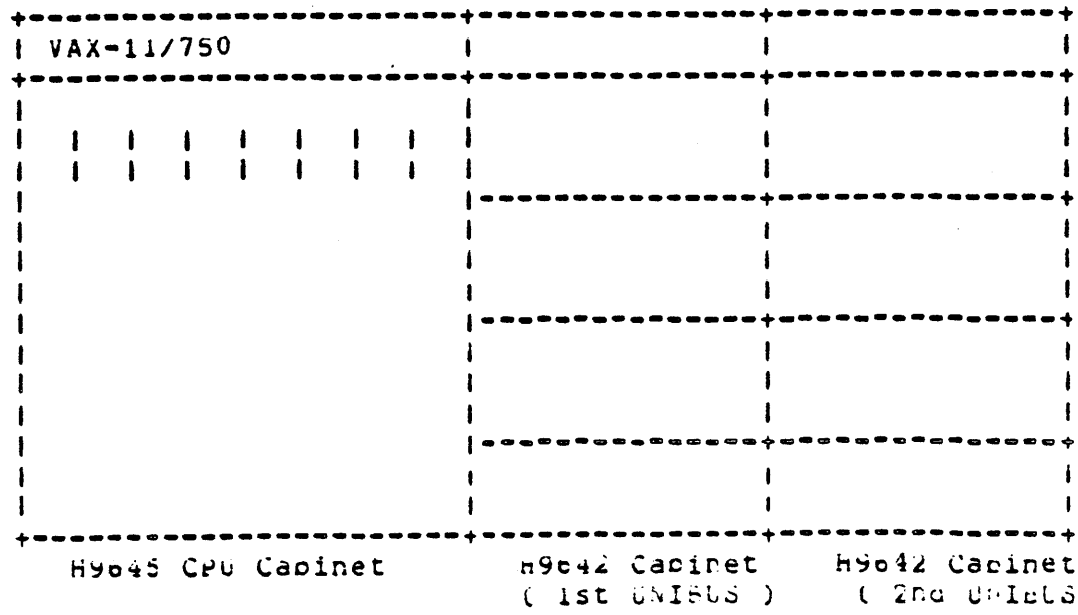
2.2 INSTALL EXPANSION BOX OR CABINET

2.2.1 Install expansion box or cabinet per appropriate installation documentation included with the option.
Expansion cabinet should be installed to the right of the CPU cabinet per the following examples.

EXAMPLE 1:



EXAMPLE 2:



2.3 SET UP VELOSTAT KIT PN 29-11762

2.3.1 Unfold the VELOSTAT mat to full size (24x24).

2.3.2 Attach the 15' ground cord to the VELOSTAT snap fastener on the mat, and the alligator clip of the ground cord to a good ground on the VAX-11/750.

2.3.3 Attach the wrist strap to either wrist and the alligator clip to a convenient portion of the mat.

2.4 UNPACK THE L0010 MODULE

2.4.1 Place the L0010 module while still in the box on the VELOSTAT mat.

2.4.2 Remove the module from the box and protective covering and lay it flat on the VELOSTAT mat. This will bring the module to the same potential as the CPU and eliminate static discharge damage.

2.5 INSTALL DW750 OPTION

2.5.1 With the wrist strap still attached to your wrist install the L0010 module in a CMI option slot. The first CMI option slot is recomended (VAX-11/750 slot number 7) to alleviate cabling problems.

2.5.2 Remove grant jumpers from backplane slot where L0010 is installed. No jumpers need to be added for the DW750 option because it has fixed addresses, and a fixed CMI Arbitration Level of 3.

NOTE

RH750s START WITH CMI ARBITRATION LEVEL (3), IF YOU HAVE ONE OR MORE IN YOUR SYSTEM YOU MUST MOVE THEM DOWN ONE CMI ARBITRATION LEVEL.

EX:

WITHOUT DW750 INSTALLED

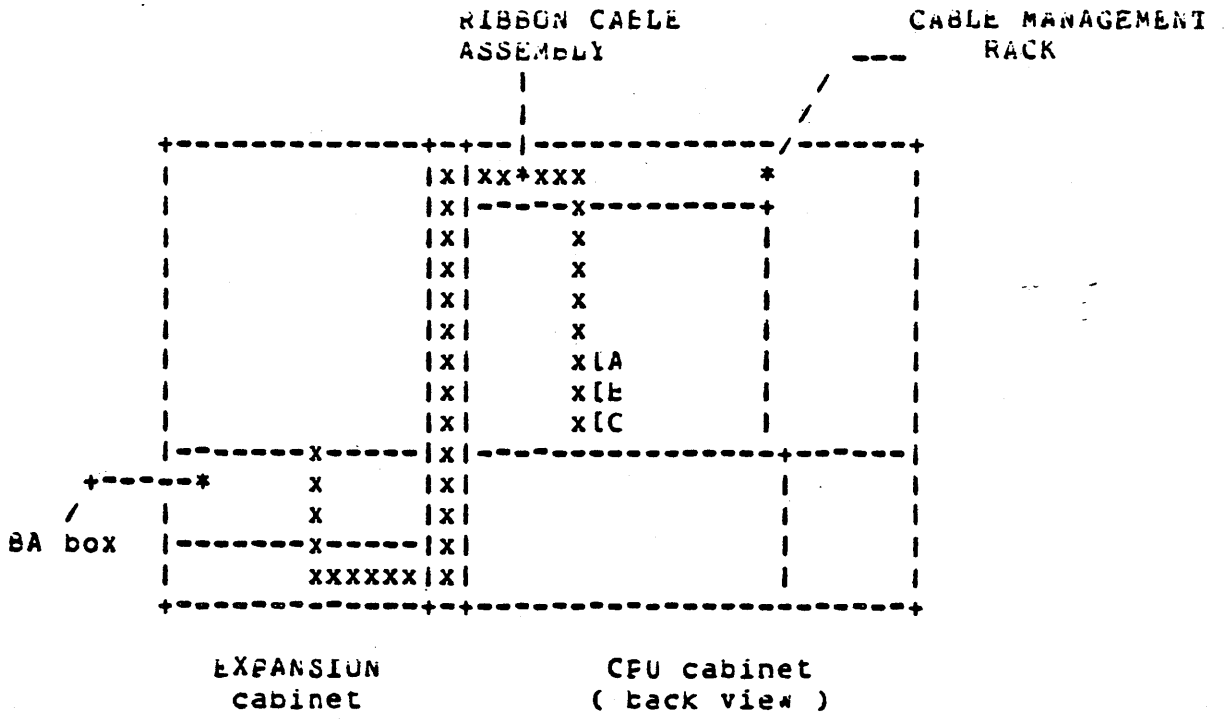
RH750#0	ADDRESS F28000	CMI ARB LEVEL 3
RH750#1	ADDRESS F2A000	CMI ARB LEVEL 2

WITH DW750 INSTALLED

RH750#0	ADDRESS F28000	CMI ARB LEVEL 2
RH750#1	ADDRESS F2A000	CMI ARB LEVEL 1

2.5.3 Connect the three ribbon cables to backplane slots B and C as in the MASSBUS option.

2.5.4 Route the cable assembly up the backplane to the cable management rack, and then to the left. Next route it between the VAX-11/750 CPU cabinet, and the expansion cabinet, then across the bottom of the expansion cabinet and up the back to the BA box. See diagram.



2.5.5 Install the M9014 on the end of the cable, and install it in the UNIBUS IN slot of the expansion DD11 backplane.

2.5.6 Install the UNIBUS options that are going on the second UNIBUS per their installation manuals.

2.5.7 Install the M9302 UNIBUS Terminator module in slot AB of the last DD11 backplane.

2.5.8 Install the UNIBUS Exerciser (UBE) module (M7855) from your Field Service Spares Kit into an SPC slot in the expansion DD11 backplane. Remove the NPG jumper wire (CA1 to CB1) in the backplane slot where the UBE is located.

NOTE

UBE ADDRESS MUST BE SET FOR 770000
AND VECTOR SET FOR 510

SWITCHES	ADDRESS (E 125)	VECTOR (E 88)
S1	ON	ON
S2	ON	ON
S3	ON	ON
S4	ON	ON
S5	ON	OFF
S6	ON	OFF
S7	ON	ON
S8	ON	OFF

2.6 CHECK FOR POWER AND GROUND SHORTS IN EXPANSION BOX

2.7 CHECK REMOTE SENSE CABLE

Check that remote sense cable is connected from the CPU to the expansion cabinet.

2.8 POWER SYSTEM ON

2.8.1 Turn on all breakers.

2.8.2 Turn on key switch.

SECTION 3 HARDWARE CHECKOUT

3.1 EXAMINE THE BUFFER DATA PATH REGISTERS OF SECOND UNIBUS

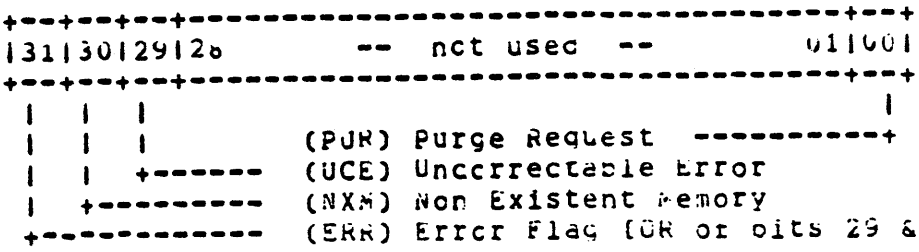
There are three buffer data path registers, and they are at the following addresses.

CSR1	F32004
CSR2	F32008
CSR3	F3200C

EX:

```
>>> E/P F32004
```

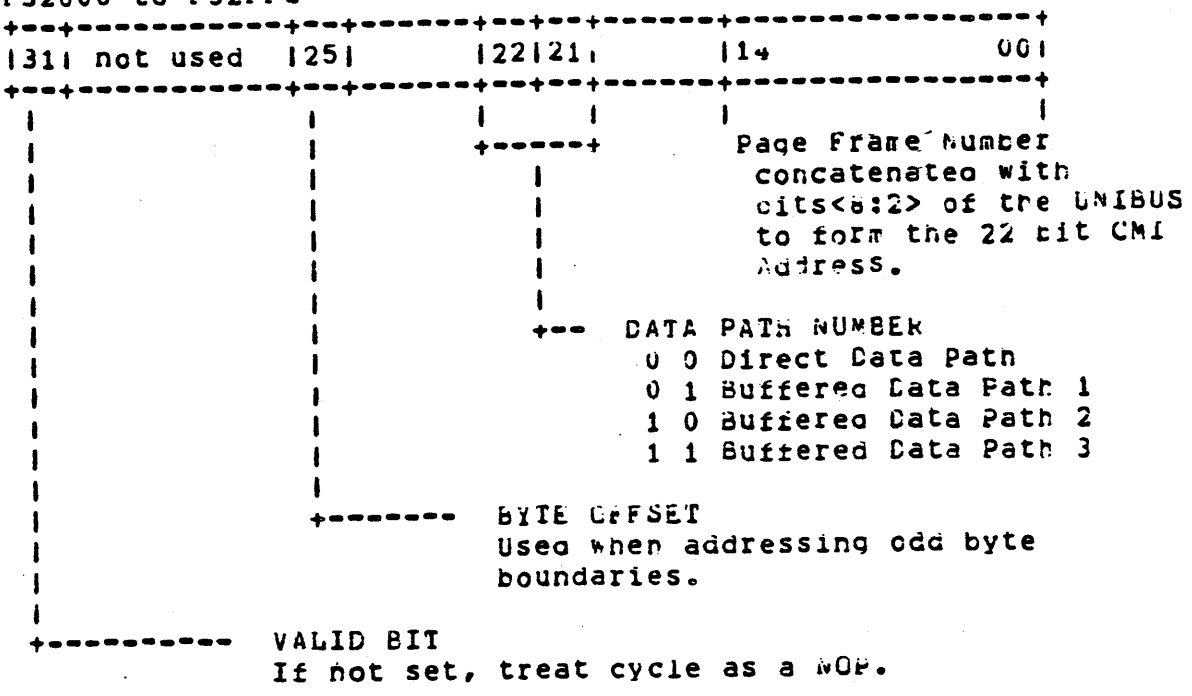
The register format of each of the registers is as follows.



3.2 EXAMINE SOME OF THE MAP REGISTERS OF THE SECOND UNIBUS

They fall into the addresses between F32600 and F32FFC and the registers have a format as follows.

F32800 to F32FFC



3.3 EXAMINE THE IPEC REGISTERS

3.3.1 These registers are similar in function to the UET registers of the UBI module. They are physically located on the L0010 module, but accessed via the Second UNIBUS. Therefore if you can examine these registers you have proven you can access the Second UNIBUS, and it is not hung.

IPEC REGISTERS	CMI ADDRESS	UNIBUS ADDERSS
Address register	FBF460	772140
Data register	FBF462	772142
Control register 1	FBF4c4	772144
Control register 2	FBF466	772146

EX:

>>> E/W/P FBF460

NOTE

WHEN EXAMINING OR DEPOSITING THESE REGISTERS, USE WORD LENGTH FORMAT RATHER THAN LONG WORD FORMAT.

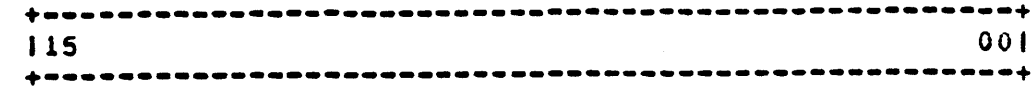
EX: E/W FBF460

3.3.2 The following is a description of the IPEC registers:

ADDRESS REGISTER FBF460

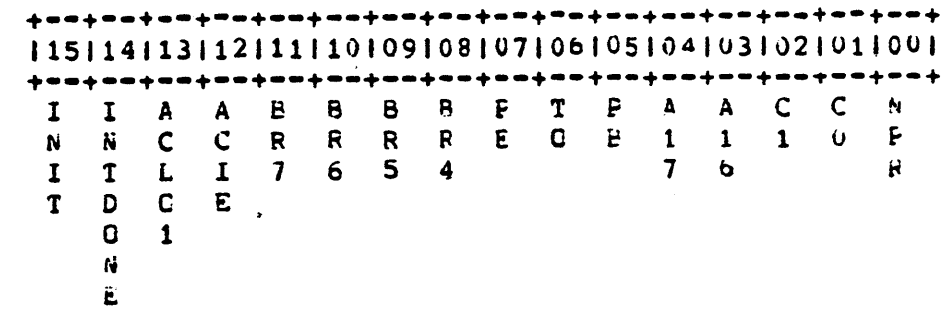
This register contains sixteen of the address bits used during an NPR transfer initiated by control register 1. The upper two bits, 16 and 17, are contained in control register 1.

DATA REGISTER FBF462



This register has a duel funtion. For an NPR cycle it contains the data either sent or received by the NPR. For a BR cycle it contains the vector passed with the interrupt.

CONTROL REGISTER 1 FBF464



NPR - Setting this bit causes the device to do an NPR cycle with the data contained in the address and data registers. If the bit fails to clear ,it indicates that the device was unable to become bus master. This bit is also cleared by INIT.

C0, C1 - These bits determine what type of transfer will be done when NPR is set. They are as follows.

C1	C0	
0	0	DATI
0	1	DATIP
1	0	DATO
1	1	DATOB

A17, A16 - These bits are the upper two bits of the address register. INIT does not clear these bits.

PB - Setting this bit simulates a memory parity error setting the BUS PB signal on the UNIBUS when the data register is read. This bit is cleared by INIT.

TO - This bit indicates that a UNIBUS transfer timed out and SSYN was not returned. It is reclocked every transfer, and cleared by INIT. READ ONLY.

PE - This bit indicates that BUS PB on the UNIBUS occured during a DATI. It is reclocked every DATI cycle, and also cleared by INIT. READ ONLY.

BR7-BR4 - These four bits cause the device to assert their respective BR requests, and attempt to interrupt at that level. They may be set in any combination to verify the arbitration logic. Once these bits are set the IPEC will attempt to interrupt until either the bit is cleared or the interrupt has taken place. These bits are not cleared by the interrupt taking place, and must be explicitally cleared by either writing a zero to the appropriate bit position, or by INIT before they can be set again to initiate another interrupt.

ACIE - This bit is ACLO Interrupt Enable. When set, it will cause an interrupt to vector 1E4 on the leading edge of a UNIBUS ACLO signal (power going down) and again approximately 100 ms after the trailing edge of ACLO (power coming up). Cleared by INIT.

ACLO1 - This bit is set by a power fail condition, and causes an interrupt if ACIE is set.
READ ONLY

INTDONE - This bit indicates an interrupt has taken place that was caused by one of the BR bits being set. The bit is cleared by writing a (1) to it or by INIT.

INIT - This bit will initialize the internal logic of the IPEC when set. The output is undefined when read.

CONTROL REGISTER 2 FBF466

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
E	I	A	B	B	B	B	V	V	V	V	V	V	V	V	V
X	N	C	R	R	R	R	8	7	6	5	4	3	2	1	0
T	I	L	7	6	5	4									
M	D	C													
C	O	2													
D	N														
	E														

V8-V0 - These bits specify the vector to be used by an interrupt initiated by Control Register 2.
These bits are NOT cleared by INIT.

BR7-BR4 - These bits cause the device to interrupt in the same manner as the BR bits in Control Register 1. Cleared by INIT.

ACLO2 - This bit when set will cause ACLO on the UNIBUS to be asserted for approximately 1.5 ms. The bit is self clearing. This bit is NOT affected by INIT.

INTDONE - This bit works the same as the INTDONE bit in Control Register 1, but for interrupts initiated by by the BR bits in Control Register 2. This bit is cleared by writing a one to it or by INIT.

EXTMOD - This bit is reserved for future use, should be zero when read. READ ONLY.

3.4 EXAMINE A UNIBUS EXERCISER REGISTER

Examine location FBF000, this will give you location 770000 on the second UNIBUS. For a description of what the bits in the UBE registers do, consult the UBE Users Manual.

By examining a UBE register you are checking that you can get out to the BA box.

3.5 BOOT UP THE DIAGNOSTIC SUPERVISOR IN STANDALONE MODE

Minimum revision of the Diagnostic Supervisor that can be be used is (6.4).

EX:

```
B/10 XXXX
```

where (XXXX) is the boot device.

3.6 ATTACH THE DW750

This can be done in two ways, either by running the Autosizer program EVSBA or by doing a manual attach.

EX:1

```
DS> RUN EVSBA
DS> SELECT ALL
```

EX:2

```
DS> ATTACH DW750 CMI DW1
DS> ATTACH UBE DW1 UB0 770000 510
DS> SELECT DW1
DS> SELECT UB0
```

3.7 RUN THE UBI/DW750 DIAGNOSTIC

A minimum of two passes of this diagnostic should be run. The program is called ECCBA, and should be REV 1.3 or higher.

EX:

```
DS> RUN ECCBA
```

03.8 RUN APPROPRIATE DIAGNOSTICS FOR DEVICES ON THE SECOND UNIBUS

Run whatever other appropriate diagnostics are necessary to verify the peripherals that were added to the DW750'S UNIBUS. These diagnostics can be determined by referring to the installation manuals for the added devics, looking them up in EVNDX, or by using the Diagnostic Supervisor help file as follows.

EX:

```
DS> HELP DEV XXXX
```

Where (XXXX) is the device you want know about.

3.9 REMOVE THE UNIBUS EXERCISER MODULE

3.9.1 Remove the UBE module.

3.9.2 Replace the NPG jumper wire on the backplane (wire from pins CA1 to CB1 in slot where M7655 is installed).

3.9.3 Replace the Grant card back in it's original slot (slot D of an SPC slot).

3.10 BRING UP VMS AND RUN UETP

For information on setting up and running UETP refer to the VAX/VMS UETP User's Guide (AA-D643A-TE)

3.11 RETURN SYSTEM TO CUSTOMER

L0005 CCS/WCS

CCS SLOT 5). THE CPU CONTROL STORE (CCS) #60005

THE CPU CONTROL STORE CONTAINS THE MICROCODE ROMS FOR THE SYSTEM (6K BY 80 BITS), A "NEXT" ADDRESS LATCH, AND MISC. BANK SELECT AND PARITY GENERATOR LOGIC (HI NEXT FIELD ONLY).
THE CCS BOARD IS THE MOTHER BOARD FOR THE WCS (WRITEABLE CONTROL STORE) OPTION. THE WCS IS PRESSED ON THE PINS ON THE BOARD AND IF IT MUST BE REMOVED, USE A GRANI CARD AS A PRY BAR TO PREVENT IT FROM CRACKING. THERE IS A JUMPER ON SOME CCS BOARDS TO TIE BIT 13 OF THE "NEXT" FIELD OF THE MICROCODE LOW, IT MUST BE REMOVED TO ENABLE WCS USE.

THERE IS NO DIAGNOSTIC TO TEST THE CCS ROM CONTENTS, THE BEST WAY TO DETERMINE THE CONDITION OF THE CCS IS TO DO A PARITY CHECK UNDER ROM MODE (RDM>PAR 0) IF YOU GET A PARITY STOP AT CSAD 17FD, IT IS OK. (AS FAR AS WE CAN TELL) KEEP IN MIND THAT DIFFERENT REVS. OF CCS BOARDS WILL CAUSE FAILURES UNDER THE WRONG REV. OF DIAGNOSTICS. THE REV. OF THE CCS CAN BE DETERMINED BY EXAMINING THE IPR 3E BITS 8-15 (SID) THE NUMBER WILL BE IN HEX AND MUST BE CONVERTED TO DECIMAL TO BE ABLE TO INTERPRET THE REV. LEVEL (EXAM: 3E = REV 62) THE DPM MICRODIAGNOSTICS DO SOME MINOR INTEGRITY TESTS ON THE CCS IF YOU WANT TO RUN THEM, RUN ECKAB.EXE DPM MICRO'S.

THE CCS MICROCODE FIELDS CONNECT TO THE DPM, MIC, AND UBI MODULES THROUGH BACKPLANE WIRING.

THE WCS IF INSTALLED IS CONNECTED TO THE CMI.
THE WCS CAN BE TESTED USING THE LEVEL 3 DIAGNOSTIC ECKAX.EXE.

THE MODULE ALSO CONTAINS TWO OSCILLATORS ONE 19.75 MHZ FOR THE SAC CHIP TO CREATE SYSTEM CLOCKS, AND ONE 1 MHZ FOR THE TOK CHIP'S COUNTER.

THE CCS MODULE HAS NO GATE ARRAYS.

WRITEABLE CONTROL STORE KU750

THE KU750 WRITEABLE CONTROL STORE OPTION IS DESIGNED TO ALLOW THE LOADING OF OPTIONAL MICROCODE TO HANDLE FLOATING GRAND AND HUGE INSTRUCTIONS NOT NORMALLY SUPPORTED BY THE BASIC CPU MICROCODE. THE WCS WILL ALSO ALLOW THE LOADING OF CUSTOMER WRITTEN ROUTINES IN MICROCODE PROVIDED THAT THE CODE IS WRITTEN IN THE PROPER FORMAT AND CARE IS TAKEN TO CALCULATE CORRECT MICRO-FIELD USAGE AND PARITY.

THE WCS IS LOADED VIA THE CMI BUS FROM ADDRESSES BEGINNING FROM F00000. EACH MICRO WORD WILL REQUIRE FOUR WRITES ACROSS THE CMI TO ASSEMBLE ALL 80 BITS. IF THE CODE IS DIGITAL'S FLOATING POINT OPTIONAL PACKAGE THEN A LOADER ROUTINE WILL BE PROVIDED ON A CASSETTE TAPE AND INSTRUCTIONS WILL BE GIVEN EXPLAINING HOW TO MAKE THE LOADING PROCESS A PART OF THE STARTUP COMMAND PROCEEDURE.

INSTALLATION: THE WCS IS A SMALL PC BOARD WITH RAM CHIPS ON IT AND HAS NO METAL FRAMEWORK OR HANDLES. IT IS INSTALLED "PIGGYBACK" ON THE CONTROL STORE (CCS 50005) MODULE BY FIRST REMOVING THE PUSH ON JUMPER (IF INSTALLED) FROM THE PINS PROTRUDING FROM THE CCS BOARD. THIS JUMPER WAS INSERTED BY MANUFACTURING TO TIE BIT 13 OF THE CONTROL STORE "NEXT" FIELD TO GROUND THUS PREVENTING ACCESS OF MICRO ADDRESSES IN THE WCS RANGE (2000 ^) FROM BEING ACCESSED WITHOUT WCS INSTALLED.
NEXT REMOVE (IF INSTALLED) THE PLASTIC PIN GUARDS FROM THE PIN PORTS ON THE CCS. THESE GUARDS SERVED TO PROTECT THE PINS AND ALSO ASSURE THEY ARE STRAIGHT.
THE WCS MEST BE C A R E F U L L Y PRESSED DOWN AGAINST THE CCS AND SECURED BY TWO NYLON SCREWS PROVIDED IN THE KIT. FINALLY RE-INSTALL THE CCS MODULE IN THE CPU.

NOTE: THIS TEXT IS INTENDED TO BE A REMINDER OF THE BASIC INSTALLATION PROCEEDURE AND SHOULD NOT BE SUBSTITUTED FOR THE KU750 INSTALLATION GUIDE IN ANY WAY...

TESTING AND DIAGNOSIS: THE WCS CAN BE TESTED BY RUNNING THE LEVEL 3 MACRO DIAGNOSTIC ECKAX.EXE THIS TEST SHOULD BE RUN IN THE MANUAL MODE (DS>R ECKAX/SEC:MANUAL) AND THE WCS FORMATTING TEST WILL GIVE A "LAST ADDRESS" OF WCS. THIS ADDRESS SHOULD BE REMEMBERED AND USED IN THE ATTACH COMMAND FOR THE KA750 CPU.
IF THE DIAGNOSTIC FAILS AND THE CPU IS KNOWN TO BE IN GOOD CONDITION, THEN THE WCS MUST BE REPLACED.

TECH TIP: WHEN REPLACING THE WCS USE A G727 UNIBUS GRANT CARD AS A PRY BAR TO EVENLY DISTRIBUTE THE PRESSURE OF REMOVAL. IF A SCREWDRIVER IS USED, THERE IS A VERY GOOD CHANCE THAT YOU WILL CRACK THE PC BOARD.

NOTE: THE WCS IS NOT GOING TO BE STOCKED IN YOUR FIELD SPARES KITS DUE TO THE PROJECTED LOW DEMAND FOR THIS OPTION, THEREFORE IT IS LEFT UP TO YOUR INDIVIDUAL OFFICES TO KEEP A SPARE ON HAND IF YOU SUPPORT THE OPTION.

USER ACCESS: FOR A USER TO ACCESS A USER WRITTEN MICROCODE ROUTINE IN THE WCS, HE/SHE MUST FIRST BE SURE THAT THE REQUIRED MICROCODE IS LOADED.
IN THE MACRO PROGRAM THAT IS ATTEMPTING ACCESS WCS HE/SHE MUST USE A "XFC" NATIVE MODE INSTRUCTION. THE XFC (EXTENDED FUNCTION CALL) INSTRUCTION WILL SEND US TO SCBB+14 AND THE LOWER TWO BITS OF THE VECTOR ADDRESS AT THAT LOCATION MUST BE EQUAL TO 2. IF THIS IS THE CASE WE WILL TRAP TO WCS LOCATION 2001 AND HOPEFULLY PICK UP THE FIRST MICROWORD OF OUR ROUTINE. TO RETURN TO CCS AFTER EXECUTION OF THE MICRORCUTINE WE SIMPLY HAVE TO HAVE A CCS ADDRESS IN THE "NEXT" FIELD OF OUR FINAL MICROWORD IN WCS. OBVIOUSLY SOME CARE MUST BE GIVEN IN THE SELECTION OF A RETURN ADDRESS AND THE USER IN ANY CASE SHOULD RESEARCH THE SUBJECT THOROUGHLY AND REFER TO THE ASSOCIATED DOCUMENTATION BEFORE ATTEMPTING AN ADVENTURE OF THIS MAGNATUDE.

NOTE: CUSTOMER WRITTEN MICROCODE IS NOT SUPPORTED BY D.E.C.

L0006 RDM/MTM

RDM/MTM SLOT 6). THE REMOTE DIAGNOSTIC MODULE (RDM) #L0006 (F.S.)
THE MAINTENANCE TOOL MODULE (MTM) #L0006 YA (CUST.)

THE REMOTE DIAGNOSTIC MODULE IS CONSIDERED A DIAGNOSTIC TOOL. IT IS NEVER CUSTOMER OWNED OR REPAIRED ON CUSTOMER TIME! O.E.M. CUSTOMERS CAN PURCHASE A SPECIAL MODULE CALLED THE MTM MODULE WHICH ALLOWS RUNNING MICRO-DIAGNOSTICS BUT DOES NOT ALLOW CONNECTION TO THE DDC CENTERS.

THE RDM ALLOWS RUNNING THE MICRODIAGNOSTICS, AND REMOTE DIAGNOSIS FROM THE DDC CENTERS. WHEN THE RDM IS INSTALLED, THE TU-58 AND CONSOLE SIGNAL CABLES ON THE BACKPLANE MUST BE MOVED TO THE RIGHT SIDE (VIEWED FROM THE REAR) OF THE PINS IN SLOT 6. THIS ALLOWS THE CONSOLE TO TALK DIRECTLY TO THE RDM BOARD, AND THE TU-58 TO LOAD MICRO-DIAGNOSTIC PROGRAMS DIRECTLY INTO THE RAM ON THE RDM BOARD OR LEVEL 4 MACRO-DIAGNOSTICS THROUGH THE RDM INTO MAIN MEMORY.

WHEN IN CONSOLE I/O MODE, (>>>) A ^P THEN ^D WILL ENTER RDM MODE (RDM>). WHEN A MICRODIAGNOSTIC TAPE IS LOADED, THE FIRST PROGRAM TO LOAD IS ECKAA.EXE OUR MICRO MONITOR. ONCE LOADED, THE MICMON HANDLES THE DIAGNOSTIC EXECUTION AND HAS QUITE A FEW OF IT'S OWN UNIQUE COMMANDS.
THE DIAGNOSTIC MINI REFERENCE GUIDE LISTS THE COMMANDS UNDER MICMON (MIC>). THE MICMON CAN BE LOADED BY ITSELF UNDER RDM MODE BY THE COMMAND RDM>TE/C <CR>

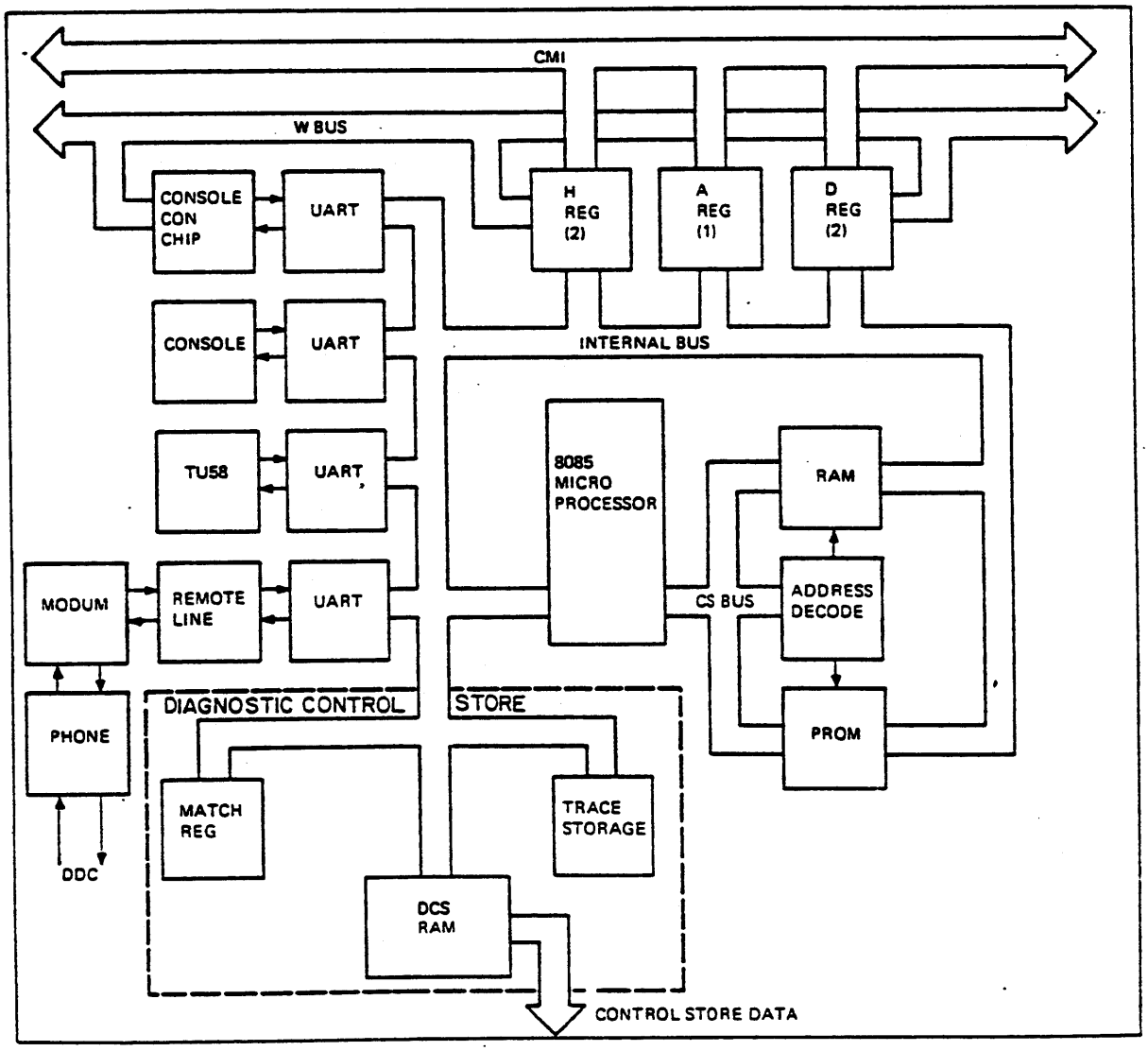
NOTE: MICRO-DIAGNOSTICS REV. 4.XX AND UP HAVE ECKAF.EXE THE RDM'S OWN INTERNAL DIAGNOSTIC AT THE END OF EACH TAPE. TO RUN THE RDM DIAGNOSTIC YOU MUST USE A NEW COMMAND UNDER MICMON, (MIC>DI DM <CR>)
*** THIS DIAGNOSTIC MUST BE RUN IN A KNOWN GOOD CPU! ***

THE RDM MODULE CONNECTS DIRECTLY TO THE CMI TO ALLOW TROUBLESHOOTING ANY MODULE LOCATED ON THE CMI BUS.
*** THE RDM HAS THE HIGHEST CMI PRIORITY OF ANY NEXUS ***
IT IS ALSO CONNECTED TO THE W BUS.

THE RDM MODULE HAS NO GATE ARRAYS.

CONTROL KEY FUNCTIONS, RDM

Control D	Enter RDM console mode
Control P	Enter console mode
Control U	Abort current command line
Control O	Inhibit printing of text
Control R	Retype current command line
Control C	Cancel current function (repeat console command)
Control S	Disable CPU output to active terminal
Control Q	Continue output to terminal after Control S



Remote Diagnostic Block Diagram

OPTIONS SLOTS #7,8,9) OPTION SLOTS

THESE SLOTS CAN BE USED TO INSTALL ANY OF THE CURRENT CPU OPTIONS AVAILABLE. (EXCLUDING THE FPA WHICH MUST BE INSTALLED IN SLOT #1) THE MOST COMMON OPTION IN THESE SLOTS IS THE MASBUS ADAPTER (MBA) OPTION. WHEN AN OPTION IS INSTALLED THE GRANT JUMPERS ON THE BACKPLANE MUST BE REMOVED FOR THAT SLOT AND THE APPROPRIATE ARBITRATION JUMPERS MUST BE SET UP IN ACCORDANCE WITH THE OPTION INSTALLATION GUIDE. OPTIONS AVAILABLE INCLUDE THE MASBUS ADAPTER (MBA), AND A SECOND UNIBUS ADAPTER (SUB), THE SECOND UNIBUS DOES NOT HAVE "CON" CHIPS OR AN "INT" CHIP ON IT, THUS IT IS REFERRED TO AS A "SUB" (SECOND UNIBUS) ADAPTER. THE PURPOSE OF THIS SECOND UNIBUS IS TO ALLOW CONNECTION OF MORE UNIBUS DEVICES.

PLEASE NOTE: THAT THE SYSTEM CANNOT BE BOOTED FROM ANY DEVICES ON THE SECOND UNIBUS.

L0007 MBA

THE RH750 MASSBUS ADAPTER IS A GENERAL PURPOSE INTERFACE BETWEEN THE CMI AND THE HIGH SPEED MASSBUS DRIVES. IT INTERFACES THE 32 BIT CMI DATA PATH TO THE 16 BIT DATA PATH OF THE MASSBUS.

GATE ARRAYS:

MDP: MASSBUS DATA PATH (8 CHIPS)
RESPONSIBLE FOR ROUTING DATA AND ADDRESS INFORMATION TO AND FROM THE CMI AND MASSBUS. EACH CHIP HANDLES 4 BITS EACH. ALSO TELL WHICH MBA YOU ARE LOOKIN FOR

MDC: MASSBUS DATA PATH CONTROL CHIP (1)
CONTROLS AND MAINTAINS STATUS ON MAP PARITY AND VALIDITY. IT DETECTS THE BEGINNING AND END OF A DATA TRANSFER, AND MAINTAINS THE STATUS ON THE SUCCESS OF EACH TRANSFER.

MCI: MASSBUS CMI INTERFACE CONTROL (1)
HANDLES ARBITRATION, COMMAND/ADDRESS CONTROL, STATUS GENERATION AND CHECKING INTERUPTS.

MRC: MASSBUS REGISTER CONTROL (1)
DETECTS THE INITIATION OF DATA TRANSFERS AND PRODUCES THE DATA TRANSFER FUNCTION CODES. IT ALSO PRODUCES THE CONTROL SIGNALS FOR THE MASSBUS CONTROL BUS.

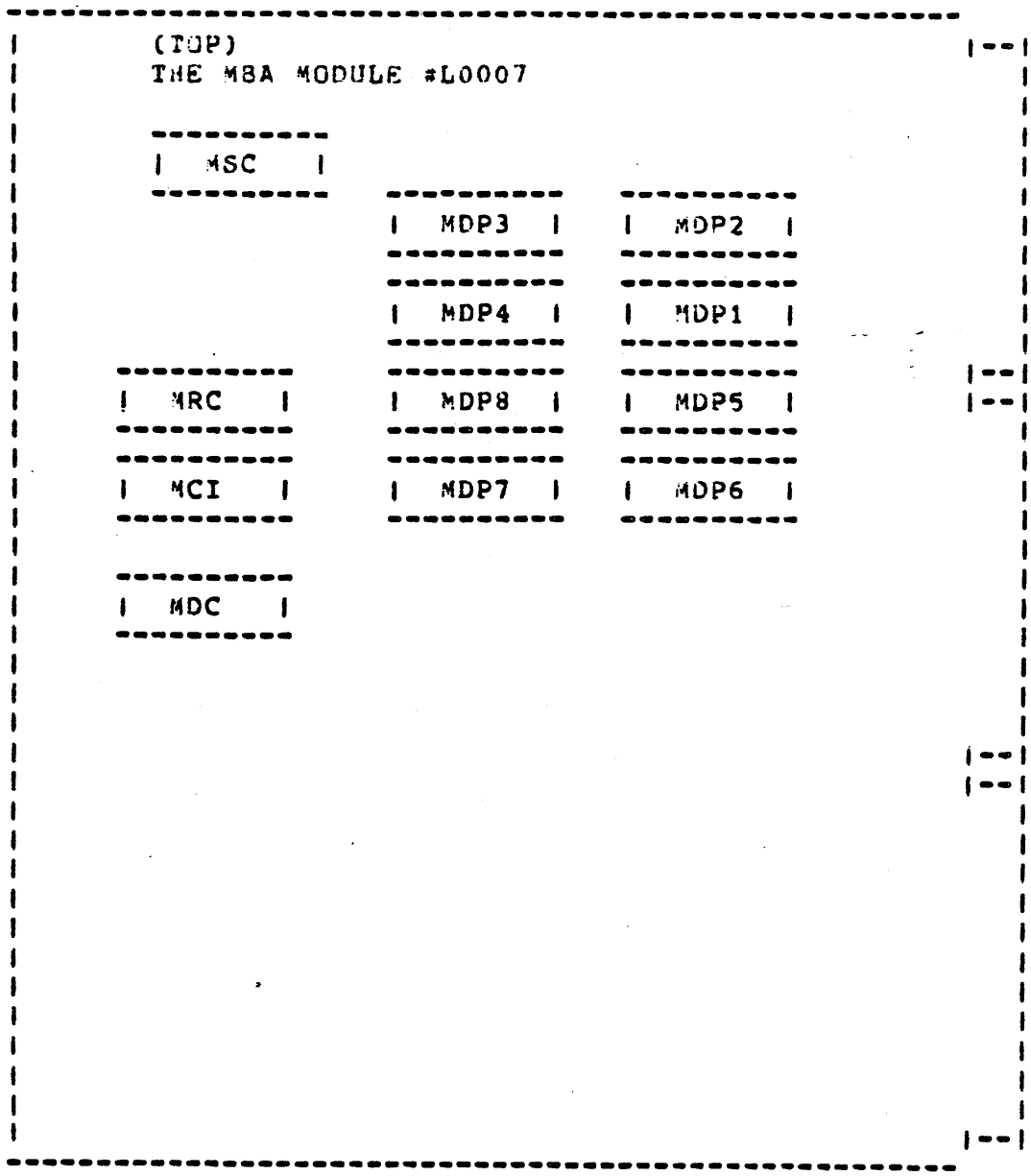
MSC: MASSBUS SILO CONTROL CHIP (1)
CONTAINS THE REGISTERS NEEDED TO ADDRESS THE 32 BYTES OF SILO RAM, AND THE LOGIC USED TO DETECT SILO EMPTY AND SILO FULL. IT CONTROLS THE GENERATION AND CHECKING OF SILO AND MASSBUS DATA BUS PARITY. THE CMI DATA MASK IS GENERATED HERE AS IS THE CONTROL FIELD FOR CONTROLLING THE FLOW OF DATA IN THE MDP CHIPS.

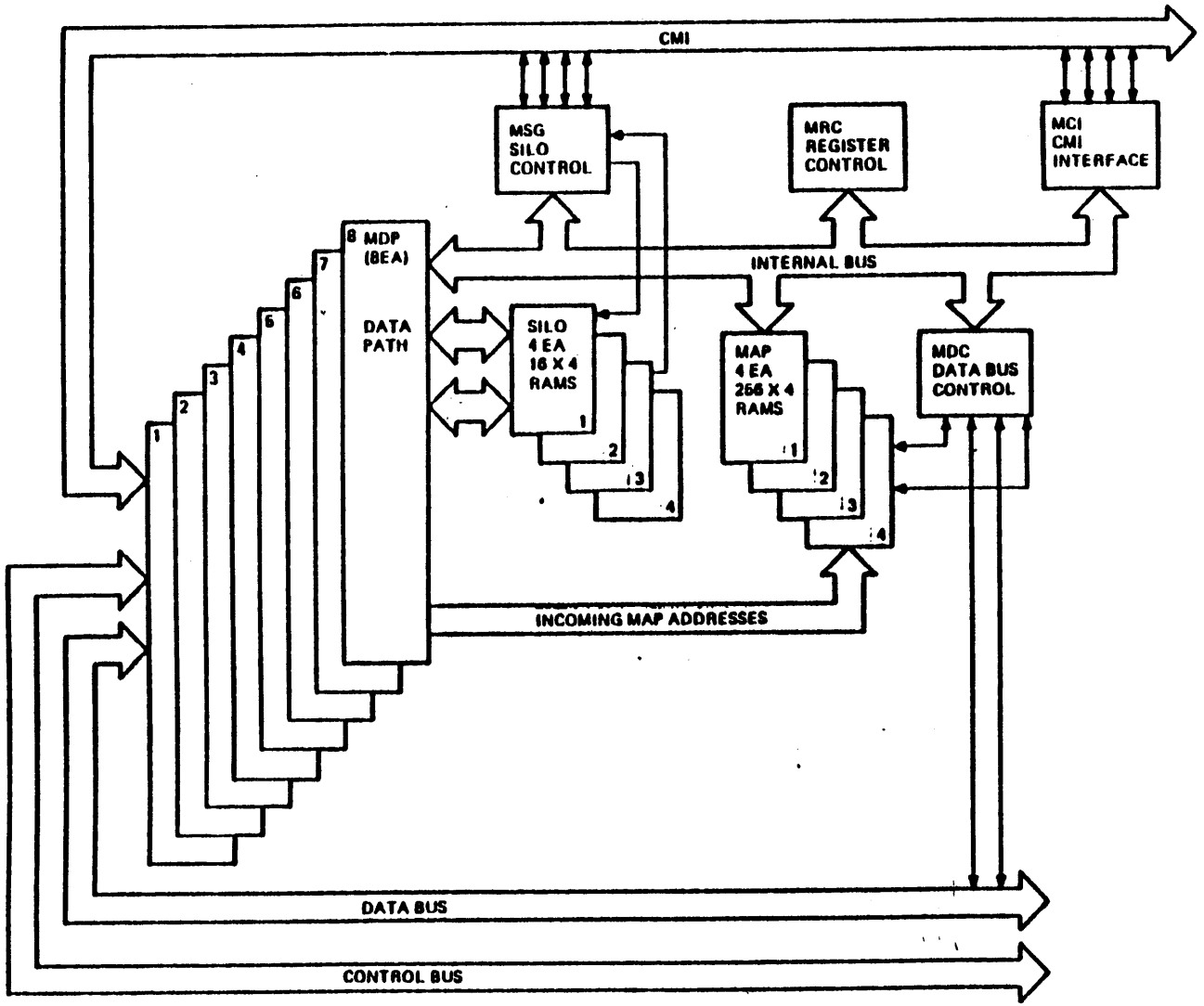
THE BUSSES:

CONTROL BUS: THE MASSBUS CONTROL BUS IS AN ASYNCHRONOUS BUS LINKING THE DRIVE CONTROL/STATUS REGISTERS WITH THE CPU. THE CONTROL BUS IS INDEPENDANT OF THE DATA BUS, ALLOWING NON DATA TRANSFER OPERATIONS TO BE INITIATED WHILE A DATA TRANSFER IS IN PROGRESS. THERE ARE 31 SIGNAL LINES.

DATA BUS: THE MASSBUS DATA BUS IS A HIGH SPEED SYNCHRONOUS BUS USE FOR TRANSFERRING BLOCKS OF DATA. THE MBA MUST BUFFER THE DATA AND GENERATE MEMORY ADDRESSES. THERE ARE 23 SIGNAL LINES.

INTERNAL BUS: INTERFACES ALL THE INTERNAL SIGNALS THAT CONTROL THE ADAPTER. THERE ARE 32 SIGNAL LINES.


(TOP)
THE M8A MODULE #L0007
MSC
MRC
MCI
MDC
MDP3
MDP2
MDP4
MDP1
MDP8
MDP5
MDP7
MDP6



RH-750 MBA Simplified Block Diagram

MASSBUS ADAPTER INSTALLATION JUMPERS

MBA'S MUST BE SET UP FOR PROPER:

1. SILO TRANSFER RATE
2. MBA NUMBER IDENTIFICATION (MBA0,MBA1 OR MBA2)
3. CMI ARBITRATION LEVEL (1,2 OR 3)

1. BEFORE ANY MBA INSTALLATION, FIRST REMOVE ALL BG JUMPERS FROM THE DESIRED SLOT. (PREFERABLY SLOT 9 IF THIS IS THE FIRST MBA)

2. SILO TRANSFER RATE INVOLVES A SINGLE JUMPER BETWEEN PINS 43 AND 45 OF THE DESIRED SLOT. THIS JUMPER MUST BE INSTALLED IN ALL SLOTS CONTAINING MBA'S. SECTION A OF THE DESIRED SLOT.

3. MBA IDENTIFICATION JUMPERS ARE REQUIRED TO INFORM THE CPU WHICH MBA IS IN WHICH SLOT. THE JUMPERS ARE INSTALLED AS FOLLOWS:

ALL JUMPERS INSTALLED IN SECTION A OF THE DESIRED SLOT

MBA0 AS RELATED TO DEVICE CODE D8AX:

JUMPER PINS 51 TO 53 AND 52 TO 54 TO SELECT MBA0

MBA1 AS RELATED TO DEVICE CODE D8BX:

JUMPER PINS 51 TO 53 ONLY TO SELECT MBA1

MBA2 AS RELATED TO DEVICE CODE D8CX:

JUMPER PINS 52 TO 54 ONLY TO SELECT MBA2

4. CMI ARBITRATION JUMPERS ARE TO ESTABLISH A CMI PRIORITY LEVEL FOR THE MBA. KEEP IN MIND THAT IN THE 11/750 THE MBA's USE THE UNIBUS BR5/8G5 LINES TO INTERUPT THE CPU, THUS SOME THOUGHT MUST BE GIVEN TO WHAT LEVEL TO ASSIGN TO WHICH SLOT.

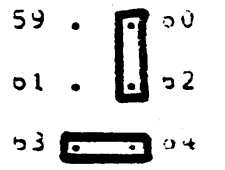
NOTE: BASICALLY THE HIGHER THE SLOT NUMBER, THE HIGHER THE CMI ARB LEVEL. (THIS IS ONLY A GOOD RULE OF THUMB, NOT A REQUIREMENT.)

ALSO SOME THOUGHT SHOULD BE GIVEN TO ACCESS OF CABLES ON THE BACKPLANE WHEN INSTALLING OTHER OPTIONS.

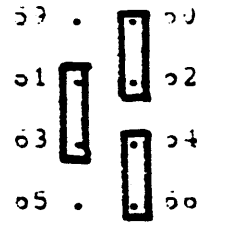
THERE ARE THREE CMI ARBITRATION LEVELS ASSIGNED TO MBA's. THEY ARE AS FOLLOWS:

CMI ARB LEVEL 3: INSTALL JUMPER 62 TO 64 SECTION A

CMI ARB LEVEL 2: INSTALL JUMPERS 60 TO 62 AND 63 TO 64 SECTION A



CMI ARB LEVEL 1: INSTALL JUMPERS 60 TO 62, 61 TO 63 AND 64 TO 60 SECTION A



IF OTHER DEVICES ARE TO BE INSTALLED IN THE OPTION SLOTS, THERE ARE TWO MORE CMI ARB LEVELS RESERVED FOR FUTURE USE.

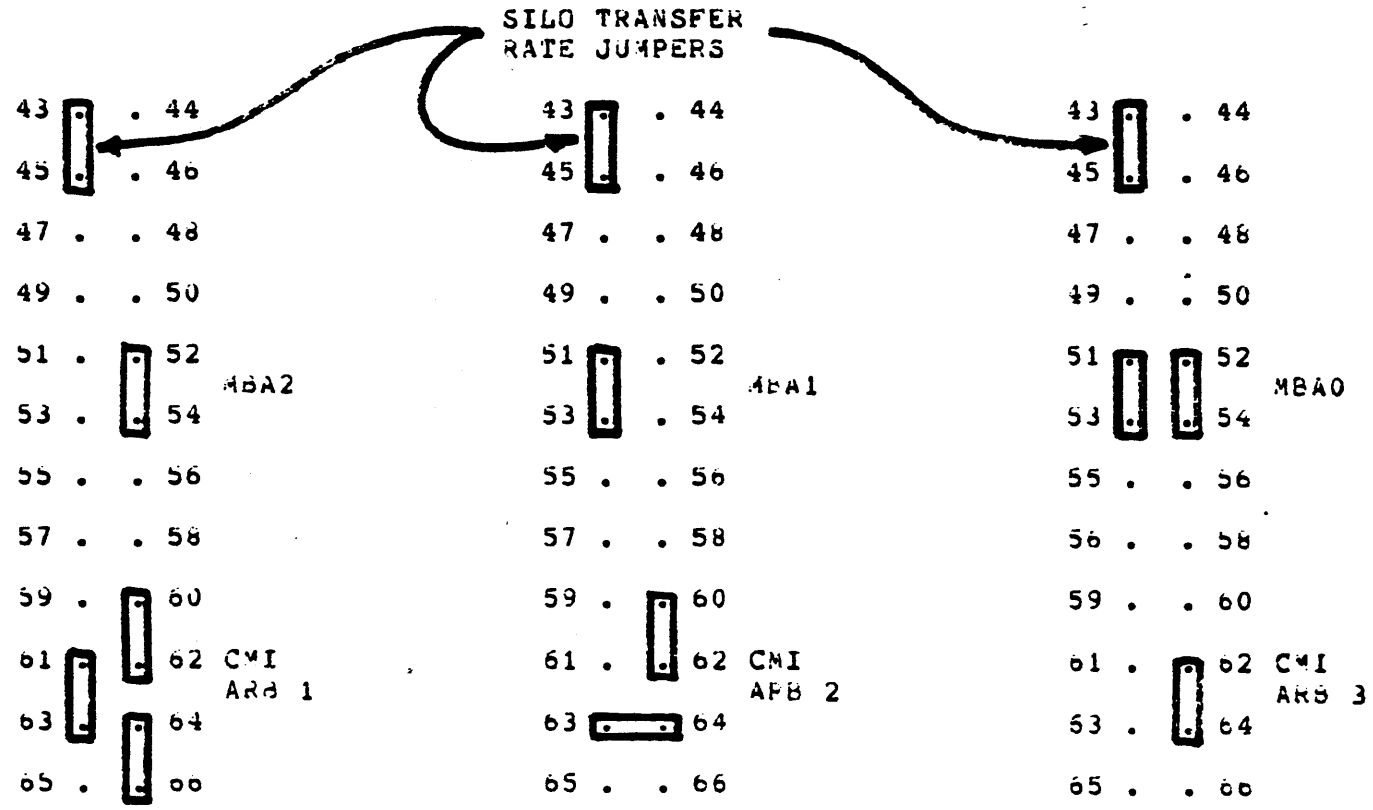
CMI ARB LEVEL 5: INSTALL JUMPER 55 TO 57
SECTION A

AND CMI ARB LEVEL 6: INSTALL JUMPER 57 TO 59
SECTION A

EXAMPLES OF RECOMMENDED MASSBUS ADAPTER JUMPER CONFIGURATIONS

SECTION A OF DESIRED SLOT

WHEN INSTALLING AN OPTION, ALL BG JUMPERS MUST BE REMOVED FROM THAT SLOT!



L0011/16 CMC

CMC SLOT #10). THE CPU MEMORY CONTROLLER (CMC) #L0011 OR #L0016

FIRST NOTE THAT THE BOARD NUMBER IN THIS SLOT IS L0011 OR L0016 NOT 10.

THE CPU MEMORY CONTROLLER MODULE CONTAINS IT'S OWN MICROCODE TO CONTROL MEMORY REFRESHES, DATA BUFFERING, SELECT TIMING (CAS AND RAS). THE BOARD CONTAINS ERROR CHECKING AND CORRECTING LOGIC, STATUS REGISTERS, CONFIGURATION STATUS LOGIC, AND THE BOOTSTRAP ROMS.

STATUS REGISTERS: CSR0 F20000 (ERROR LATCHING REGISTER)
CSR1 F20004 (DIAGNOSTIC REGISTER)
CSR2 F20008 (MEMORY MAP REGISTER)

BOOTSTRAP ROMS: ROM SOCKET A F20400
ROM SOCKET B F20500
ROM SOCKET C F20600
ROM SOCKET D F20700

NOTE: WHEN EXAMINING THE ROMS IN THIER SOCKETS, THE LOW WORD OF THE FIRST LOCATION WILL CONTAIN THE ASCII EQUIVALENT OF THE DEVICE TYPE MNEMONIC FOR THAT ROM.

EXAMPLE: >>>E/L/P F20400

P 00F20400 XX XX 44 44 = DD (DDA0)

THE CMC IS CONNECTED TO THE CMI AND THE MEMORY BUS.

THE LEVEL 3 DIAGNOSTIC ECKAM.EXE TAPE #5 WILL TEST THE MEMORY AND CONTROLLER. PLEASE NOTE THAT THE DIAGNOSTIC WILL TEST ONLY ARRAYS 1-7, TO TEST ARRAY 0, YOU MUST EITHER SWAP POSITIONS WITH ANOTHER BOARD OR RUN THE MIC MICRODIAGNOSTIC (ECKAC.EXE TAPE #2).

THE CMC HAS TWO AVAILABLE VERSIONS:

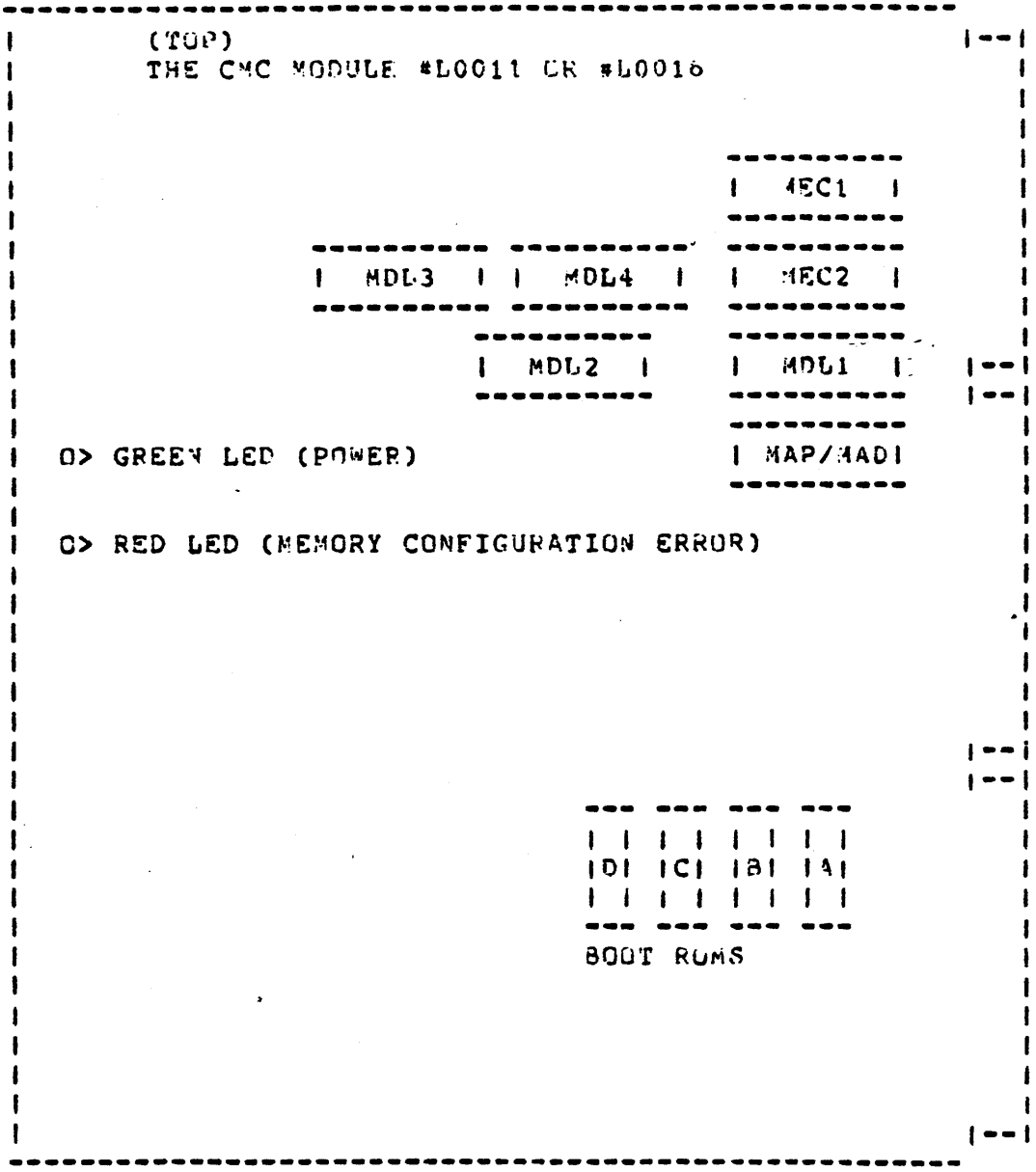
L0011: SUPPORTS M8728 256 KB ARRAYS ONLY (MAX. 2 MB'S)
L0016: SUPPORTS BOTH M8728 AND M8750 MODULES
(M8750 IS A 1 MEGABYTE ARRAY GIVING US A MAX. OF 8 MB'S)
IF BOTH TYPES ARE MIXED, THE M8728'S MUST BE INSTALLED DIRECTLY AFTER THE 1 MEG BOARDS.

NOTE: THE L0016 CMC MODULE REQUIRES A REV. C BACKPLANE WHICH ENABLES THE USE OF BIT 24 OF THE CMI ADDRESS. THE REV. CAN BE DETERMINED BY EXAMINING THE SYSTEM I.D. REGISTER

>>>E/I 3E

I 0000003E 02 00 XX X8
^
AN 8 INDICATES A REV C BACKPLANE (SEE THE REVCON DOCUMENT)

GATEARRAYS: MAP,MDL,MEC


(TOP)
THE CMC MODULE #L0011 OR #L0016
MEC1
MDL3
MDL4
MEC2
MDL2
MDL1
MAP/MAD
O> GREEN LED (POWER)
O> RED LED (MEMORY CONFIGURATION ERROR)
D
C
B
A
BOOT ROMS

MAP/MAD: MEMORY ADDRESS PROCESSOR CHIP

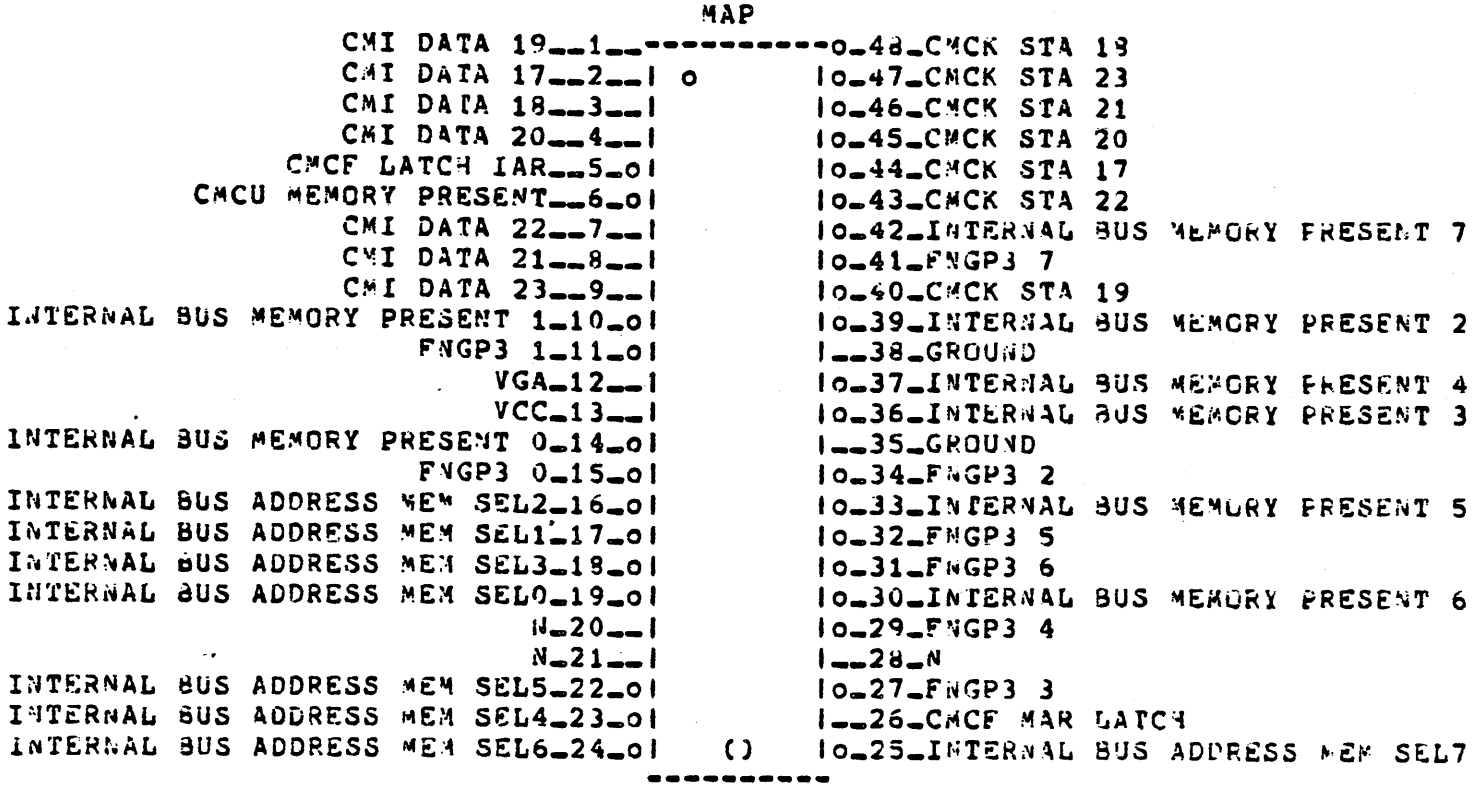
MAP = L0011 MAD = L0015

THE MAP/MAD CHIP PERFORMS THE DECODING OF ADDRESS BITS TO ENABLE MEMORY ARRAYS, DETECT NXM'S, SIZE MEMORY ARRAY BOARD POPULATIONS, AND DETERMINE STARTING ADDRESS OFFSET. THE MAP/MAD CHIP ISSUES NXM STATUS ON THE CMI, AND LIGHTS THE RED LED IF IT DETECTS AN ILLEGAL CONFIGURATION OF MEMORY.

PART NUMBER: 19-14706

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE
MS750 MACRO ECKAM.EXE (LEVEL 3)

MODULE: CMC GATE ARRAY: MAP



THIS SIDE TOWARDS FINGERS ON BOARD

MDL: MEMORY DATA LOOP CHIPS

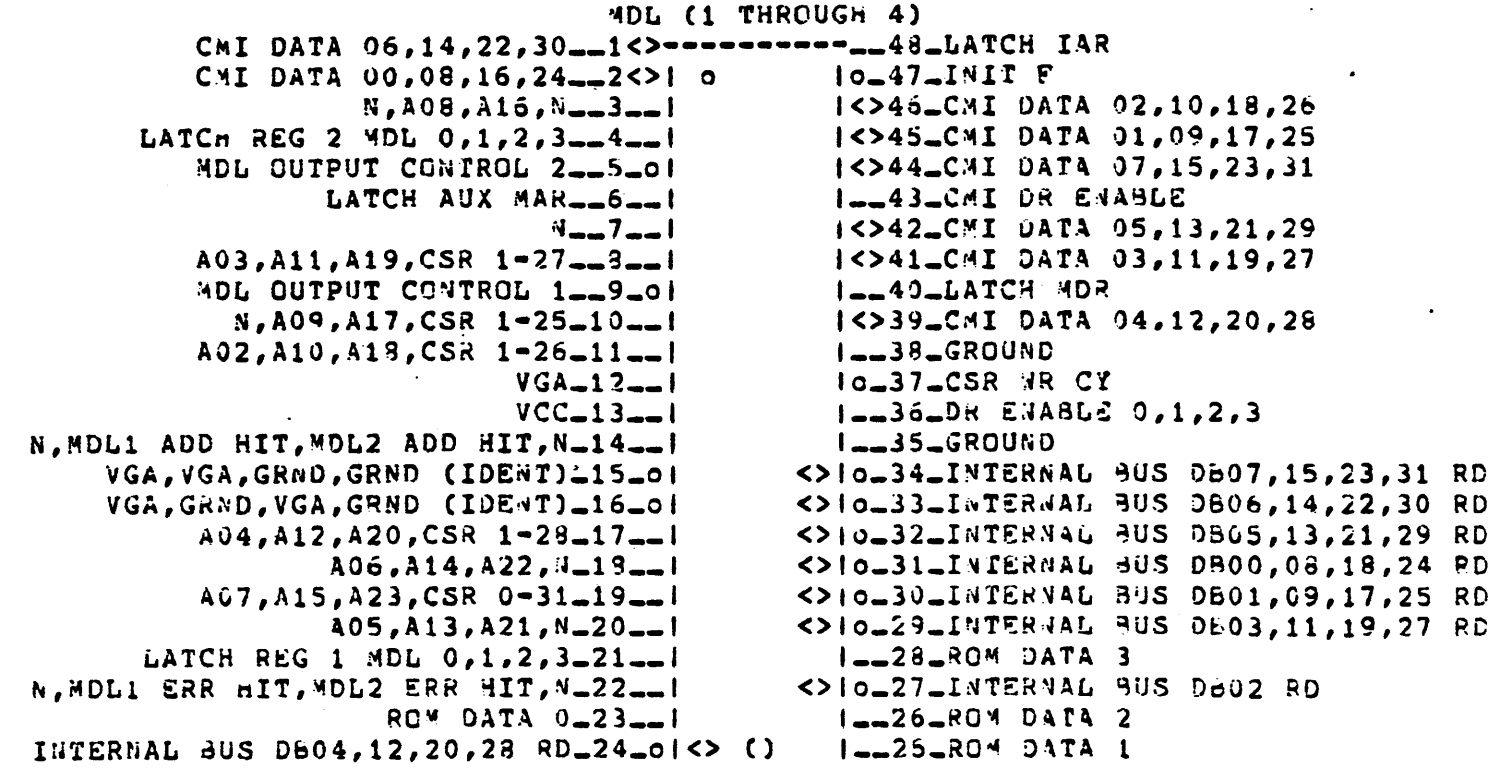
THE MDL CHIPS FUNCTION LIKE THE MDR CHIPS ON THE MIC MODULE, THEY PASS ALL DATA AND ADDRESSES TO AND FROM THE CMI AND INTERNAL MEMORY BUSES. THEY PROVIDE VARIOUS STATUS REGISTERS (CSR'S), AND A PATH FOR THE BOOTSTRAP ROMS TO MEMORY.

4 CHIPS	CHIP	BIT SLICE
	MDL 1	<7-0>
	MDL 2	<15-8>
	MDL 3	<23-16>
	MDL 4	<31-24>

PART NUMBER: 19-14707

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE
MS750 MACRO ECKAM.EXE (LEVEL 3)

MODULE: CMC GATE ARRAY: MDL (1 THROUGH 4)



THIS SIDE TOWARDS FINGERS ON BOARD

MEC: MEMORY ERROR CORRECTION CHIPS

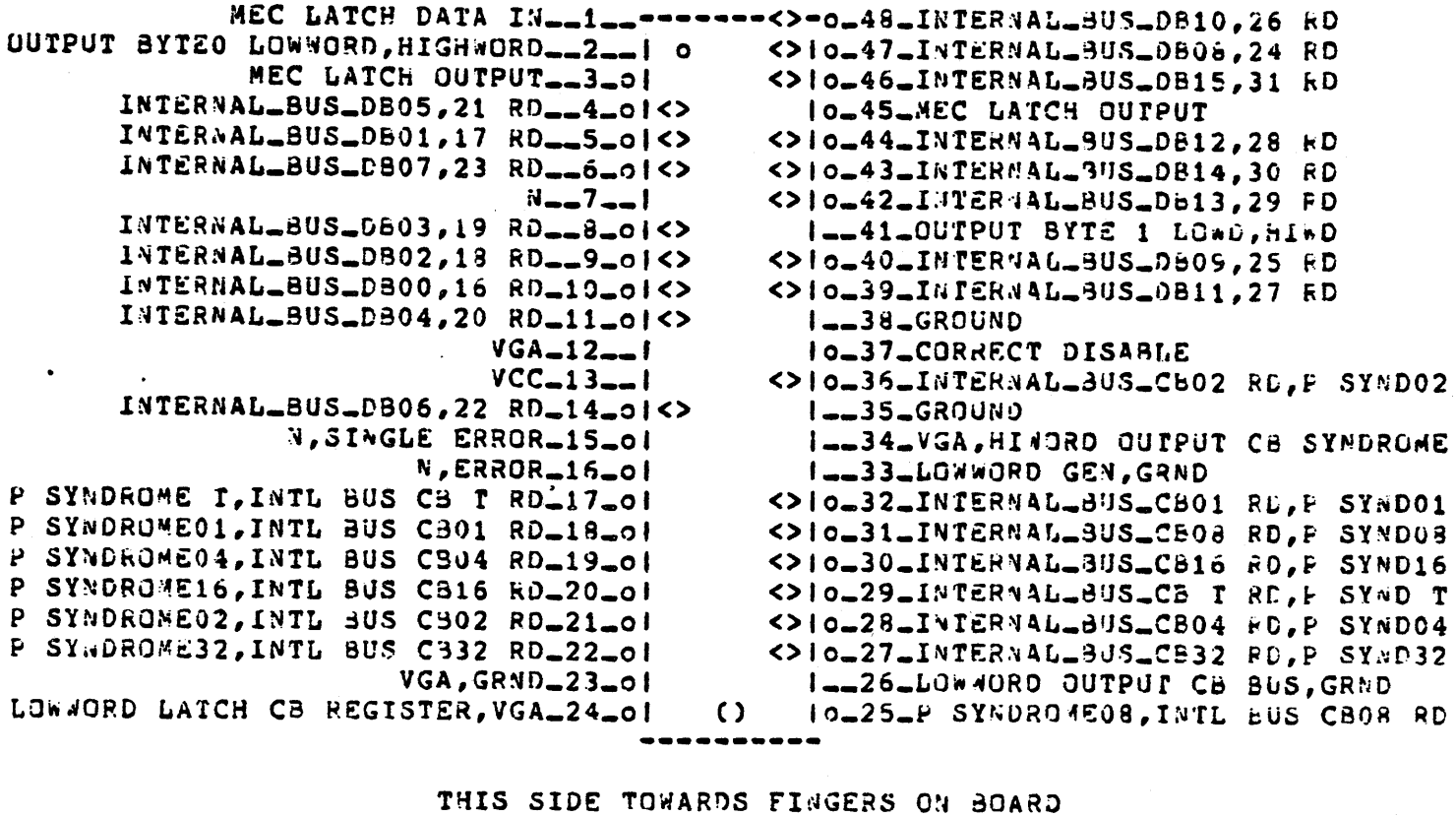
DETECT AND CORRECT ALL SINGLE BIT MEMORY ERRORS
USING THE MODIFIED HAMMING CODE AND SYNDROME BITS,
AND DETECT DOUBLE BIT ERRORS (UNCORRECTABLE).

2 CHIPS	CHIP	BIT SLICES
	MEC 1	<15-0>
	MEC 2	<31-16>

PART NUMBER: 19-14705

BEST DIAGNOSTICS: MIC MICRO'S ECKAC.EXE
MS750 MACRO ECKAM.EXE (LEVEL 3)

MODULE: CMC GATE ARRAY: MEC (1 AND 2)



THIS SIDE TOWARDS FINGERS ON BOARD

M9313 UET

SOME UET PROGRAMS

NPR READ (DATI) USING MAP 0, BDP 1, PFN 8

```
        >>>D/I 37 1                 :INIT
        >>>D/W/P F30004 1           :PURGE BDP 1
***     >>>D/L/P F30800 80200008    :SET UP MAP 0, VALID, ADD PFN = 1000   PFN = 8
        >>>D/P/L 1000 12345678      :DATA
        >>>D/W/P FFF460 0           :SET UP UNIBUS ADDRESS
        >>>D/W/P FFF464 1           :SET NPR "GO" BIT

        TEST THE RESULTS:
        >>>E/W FFF462
                Should get:5678

        INCREMENT UET ADDRESS REGISTER:
        >>>D/W/P FFF460 2
        >>>D/W/P FFF464 1

        TEST THE SECOND RESULT:
        >>>E/W FFF462
                Should get:1234
```

OTHER DATA PATHS AND MAP FIELDS CAN BE USED BY SUBSTITUTING THE DATA AT THE "***" FOR THE FOLLOWING: BDP2 = 80400008
BDP3 = 80600008
DIRECT DP = 80000008

MANY OTHER EXAMPLES CAN BE TRIED USING THIS FORMAT:

NPR WRITE (DATO or DATOB)

A). LOAD ADDRESS REGISTER FFF460
B). LOAD DATA REGISTER FFF462
C). LOAD CONTROL REGISTER FFF464 WITH THE FOLLOWING:
CR<0>=1
CR<2,1>=DATO or DATOB (See Chart)
CR<4,3>=A17,A16 (Address bits 17 and 16)

NPR READ (DATI or DATIP)

A). LOAD ADDRESS REGISTER FFF460
B). LOAD CONTROL REGISTER FFF464 WITH THE FOLLOWING:
CR<0>=1
CR<2,1>=DATI or DATIP (See Chart)
CR<4,3>=A17,A16 (Address bits 17 and 16)

B.R.

A). LOAD DATA REGISTER WITH VECTOR ADDRESS
B). LOAD CONTROL REGISTER WITH THE FOLLOWING:
CR<11-8>=BR LEVEL (Example:CR<8>=1; = BR4)

FUNCTION CHART:

C1	C0	
0	0	= DATI
0	1	= DATIP
1	0	= DATO
1	1	= DATOB

FFF460

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00

UET UNIBUS ADDRESS REGISTER

FFF462

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00

UET UNIBUS DATA REGISTER

FFF464

15	14	13	12	11	10	09	08	07	06	05	04	03	02	01	00
INIT				BR7	BR6	BR5	BR4	PE	TO	PB	A17	A16	C1	C0	NPR

BUS REQUEST

ISSUE UNIBUS INIT

UNIBUS PARITY ERROR

UET SSYN TIMEOUT

FORCE PB

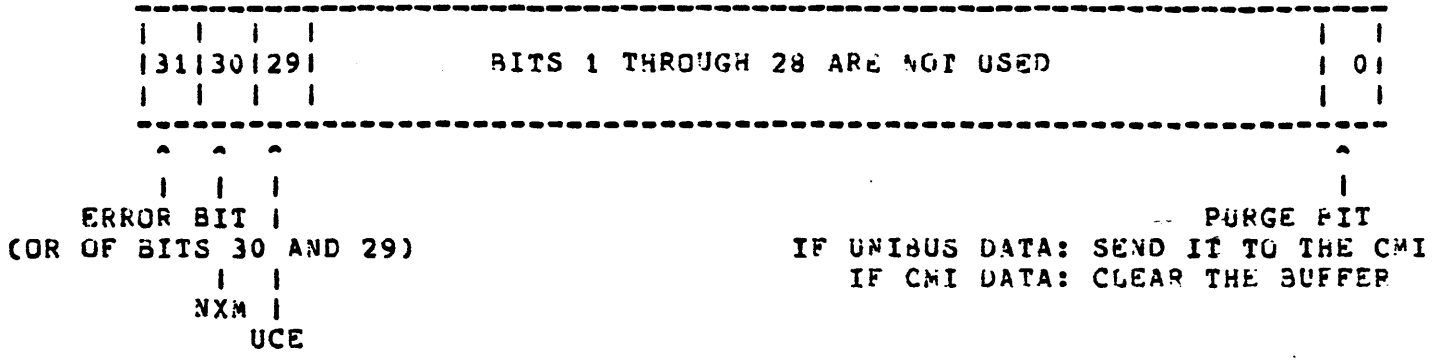
ADDRESS EXTENSION

UNIBUS TRANSFER SELECT

ISSUE NPR "GO"

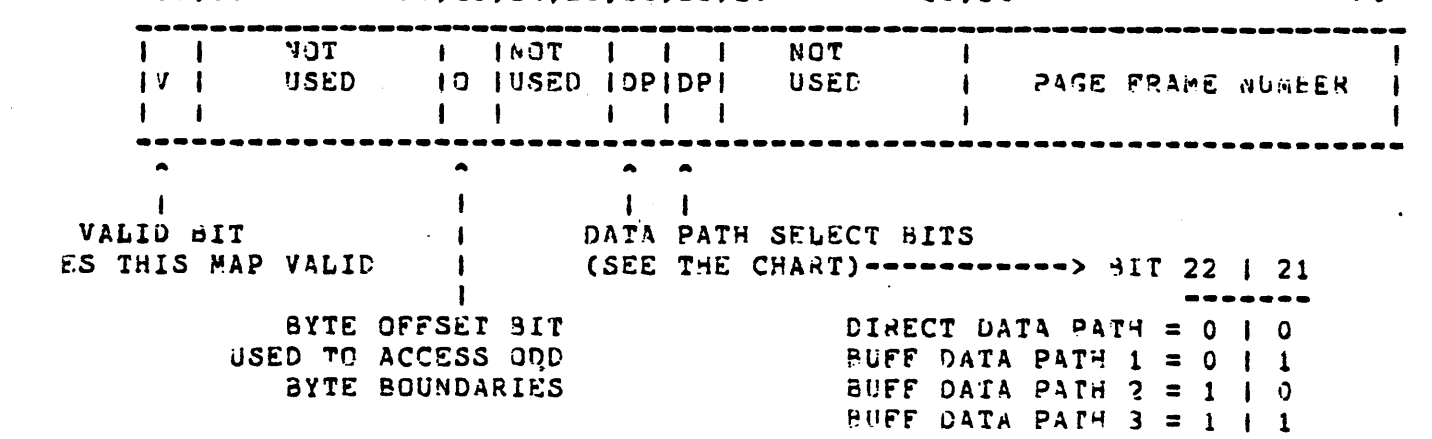
BUFFERED DATA PATH CSR'S

BDP 1 = F30004 BDP 2 = F30008 BDP 3 = F3000C



CMI MAP DATA FIELDS

ADDRESSES F30800 THROUGH F30FFC



DIAGNOSTICS

DIAGNOSTICS AND LEVELS

THE SPECIFIC LEVELS OF ALL DIAGNOSTICS CAN BE FOUND IN EVNDX ON MICROFICHE.

DIAGNOSTIC LEVELS

LEVEL 1) RUNS ONLINE ONLY, WITHOUT DIAG. SUPERVISOR.
(UETP, ERRLOG, SDA ETC.)

LEVEL 2) RUNS ONLINE OR OFFLINE, UNDER DIAG. SUPERVISOR.
(DISK FORMATTERS OR DEVICE RELIABILITY ETC.)

LEVEL 2R) RUNS ONLINE ONLY, WITH DIAG, SUPERVISOR.
(RESTRICTED DUE TO REQUIRED DEVICE DRIVER UNDER VMS)

LEVEL 3) RUNS OFFLINE ONLY, UNDER DIAG. SUPERVISOR.
(MAJORITY OF DIAGNOSTICS FOR REPAIR LEVEL)

LEVEL 4) RUNS OFFLINE ONLY, WITHOUT DIAG. SUPERVISOR.
(STANDALONE AND BOOTABLE DIAGNOSTICS)

LEVEL 5) MICRO-DIAGNOSTICS

DISTRIBUTION OF DIAGNOSTICS TO TAPES IS SUBJECT TO VARIATION.

DIAGNOSTICS **97** LEVEL

TAPE AA)	CANCELLED		
TAPE #1)	ECKAA.EXE	5	MICMON
	ECKAB.EXE	"	DPM MICRODIAGNOSTICS
	ECKAF.EXE	"	RDM DIAGNOSTICS
TAPE #2)	ECKAA.EXE	5	MICMON
	ECKAC.EXE	"	MIC MICRODIAGNOSTICS
	ECKAF.EXE	"	RDM DIAGNOSTICS
TAPE #3)	CANCELLED		
TAPE #4)	CANCELLED		
TAPE #5)	ECKAL.EXE	4	CACHE AND TB DIAGNOSTICS
	ECKAM.EXE	3	MAIN MEMORY DIAGNOSTICS
	ECKAX.EXE	3	"CLUSTER" EXERCISER
TAPE #6)	ECSAA.EXE	N/A	DIAG. SUPERVISOR
	ECSAA.HLP		HELP FILE
	EVSBA.EXE	3	VAX AUTOSIZER
	EVSBA.HLP		HELP FILE
	CONFIG.COM or UBIATT.COM (CONFIGURATION FILES FOR THE 11/750 DIAGNOSTICS)		
TAPE #7)	EVKAA.EXE	4	"HARDCORE" INSTRUCTION TESTS
TAPE #8)	EVKAB.EXE	2	VAX-11 ARCHETECHURAL INSTRUCTIONS
	EVKAC.EXE	2	VAX-11 FLOATING POINT INSTRUCTIONS
	EVKAD.EXE	2	VAX-11 COMPATABILITY MODE INSTRUCTIONS
	EVKAE.EXE	3	VAX-11 PRIVILEGED ARCHETECTURE INSTRUCTIONS
TAPE #9)	EVQDB.EXE	3	LOADABLE DRIVER FOR RP04/5/6
	EVJDR.EXE	3	LOADABLE DRIVER FOR RM03/5
	EVQDM.EXE	3	LOADABLE DRIVER FOR RK06/7
	EVQDL.EXE	3	LOADABLE DRIVER FOR RL02
	EVABA.EXE	2R	VAX-11 CR11 DIAGNOSTIC
	EVRAA.EXE	2	VAX-11 RP/RM/RK RELIABILITY DIAGNOSTICS
	EVRAC.EXE	2	VAX-11 RP/RM/RK DISK FORMATTER

TAPE #10)	EVDMA.EXE	3	VAX-11 M9203 REPAIR LEVEL DIAG.
	EVDXA.EXE	3	VAX-11 COM IOP REPAIR LEVEL DIAGNOSTIC
	EVDAA.EXE	3	VAX-11 DZ11 8 LINE ASYNC. MUX
TAPE #11)	ECSAA.EXE	N/A	DIAG. SUPERVISOR
	EVREA.EXE	3	VAX-11 RK611 DIAG. PART A
	EVREB.EXE	3	VAX-11 RK611 DIAG. PART B
TAPE #12)	EVREC.EXE	3	VAX-11 RK611 DIAG. PART C
	EVRED.EXE	3	VAX-11 RK611 DIAG. PART D
	EVREE.EXE	3	VAX-11 RK611 DIAG. PART E
TAPE #13)	EVREF.EXE	3	VAX-11 RK611/RK06/7 DRIVE FUNCTIONAL PART 1
	EVREG.EXE	3	VAX-11 RK611/RK06/7 DRIVE FUNCTIONAL PART 2
TAPE #14)	EVQDR.EXE	3	LOADABLE DRIVER FOR RM03/5
	EVRDA.EXE	3	VAX-11 RM03/5 DISKLESS DIAG.
	EVRDB.EXE	3	VAX-11 RM03/5 FUNCTIONAL DIAG.
TAPE #15)	EVQTS.EXE	3	LOADABLE DRIVER FOR TS-11
	EVMAA.EXE	2	VAX TM03/TS11/TU78 DATA RELIABILITY DIAGNOSTIC
	EVMAD.EXE	3	VAX TS11 SUBSYSTEM REPAIR DIAG.
TAPE #16)	EVRFA.EXE	3	VAX-11 RL02 DISK SUBSYSTEM FUNTIONAL DIAGNOSTIC
	EVRGA.EXE	3	VAX-11 RM80 DISK FORMATTER
	EVRGB.EXE	3	VAX-11 RM80 DISK DRIVE FUNCTIONAL DIAGNOSTIC
TAPE #17	ECCAA.EXE	3	RH750 (HBA) DIAGNOSTICS
	ECCBA.EXE	3	DW750 (UBI) DIAGNOSTICS
	ECSAA.EXE	N/A	DIAGNOSTIC SUPERVISOR

THE DIAGNOSTICS LISTED ABOVE ARE ONLY THOSE WHICH APPEAR IN THE STUDENT GUIDES, THESE ARE THE MAIN DIAGNOSTICS FOR THE 11/750 SYSTEM "PACKAGES". ADDITIONAL DIAGNOSTICS FOR PERIPHERAL DEVICES AND COMMUNICATION EQUIPMENT CAN BE FOUND IN EVNOX MICROFICHE.

COPYING DIAGNOSTIC MEDIA

COPYING THE DIAGNOSTIC MEDIA TO THE SYSTEM DEVICE. THE PROCEDURE IS EXPLAINED FOR THE 3 POSSIBLE DIAGNOSTIC MEDIA.

NOTE: VERSION 3.X VMS TAKES UP CONSIDERABLY MORE DISK SPACE THAN PREVIOUS VERSIONS. THERE WILL NOT BE ROOM FOR ALL OF THE VAX SYSTEM DIAGNOSTICS ON THE PACK. IT IS RECCOMMENDED THAT YOU BE SELECTIVE OF THE DIAGNOSTICS NEEDED OR PUT ALL DIAGNOSTICS ON A SEPARATE PACK OR MAGTAPE.

1. TU58 DIAGNOSTIC DISTRIBUTION (RK07 PACKAGE SYSTEM)

   A. IF THE DIAGNOSTIC UPDATE OR DIAGNOSTIC KIT HAS TO ENTERED INTO THE SYSTEM FROM TU58 CARTRIDGES, THE FLX UTILITY MAY BE USED TO ACCOMPLISH THE TRANSFER.

   B. PERFORM THE FOLLOWING COMMANDS ONCE THE NEW VMS SYSTEM HAS BEEN INSTALLED AND BOOTED. LOG INTO THE SYSTEM MANAGER'S ACCOUNT TO PERFORM THIS PROCEDURE.

   C.
```
$ RUN SYS$SYSTEM:SYSGEN
SYSGEN>CONNECT CONSOLE
SYSGEN>EXIT
$ MOUNT CS1:/FOR
$ SET DEF SYS$MAINTENANCE
$ MCR FLX
FLX>/RS=CS1:*.*/RT
FLX>
```
   D. ALL THE DIAGNOSTICS AND FILES ON THIS TAPE HAVE BEEN TRANSFERRED TO THE [SYSMAINT] DIRECTORY AT THIS POINT.

   E. INSERT THE NEXT TAPE AND REPEAT THE FLX> COMMAND TO COPY THE NEXT TAPE.

```
FLX> /RS=CS1:*.*/RT
FLX>
```
   F. REPEAT THIS PROCESS UNTIL ALL TAPES HAVE BEEN TRANSFERRED TO THE [SYSMAINT] AREA.

   G. A CONTROL Y WILL EXIT FROM THE FILEX UTILTY.

```
FLX>^Y
```

2. RK07 VAXPAX DIAGNOSTIC DISTRIBUTION (DUAL RK07 PACKAGE SYSTEMS)

A. MOUNT THE VAXPAX DISK CARTRIDGE IN DRIVE 1.

B. MOUNT THE NEWLY CREATED VMS SYSTEM IN DRIVE 0.

C. BOOT THE NEW VMS SYSTEM FROM DRIVE 0 AND LOG INTO THE SYSTEM MANAGERS ACCOUNT. PERFORM THE FOLLOWING COMMANDS TO TRANSFER THE VAXPAX DIAGNOSTICS TO THE SYSTEM DEVICE.

```
$ MOUNT DMA1: VAXPAX
$ SET DEF SYS$MAINTENANCE
$ COPY DMA1:[SYSMAINT]*.*;* *
$ DIR/FULL DIAGBOOT.EXE,ECSAA.EXE,CONFIG.COM
```

D. MAKE CERTAIN THAT DIAGBOOT.EXE, ECSAA.EXE AND CONFIG.COM ARE CONTIGUOUS DISK FILES. IF THEY ARE NOT COPY THEM TO THEMSELVES USING THE /CONTIG SWITCH, THEN PURGE THE OLD VERSIONS OUT OF THE DIRECTORY.

```
$ COPY/CONTIG DIAGBOOT.EXE,ECSAA.EXE,CONFIG.COM *
$ PURGE DIAGBOOT.EXE,ECSAA.EXE,CONFIG.COM
```

E. THIS COMPLETES THE DIAGNOSTIC TRANSFER TO THE SYSTEM DEVICE. YOU MAY WISH TO DELETE ANY OF THE DIAGNOSTICS WHICH RELATE TO THE 11/780 AND 11/730.

```
$ DELETE ES*.*;*
$ DELETE EN*.*;*
```

3. MAGTAPE VAXPAX DIAGNOSTIC DISTRIBUTION (RM03/TS11 OR RM80 PACKAGE SYSTEMS)

A. THIS PROCEDURE WILL TRANSFER THE DIAGNOSTIC MEDIA FROM THE TS11 MAGTAPE TO THE SYSTEM DEVICE DRA0:.

B. BOOT THE NEWLY CREATED VMS SYSTEM AND LOG INTO THE SYSTEM MANAGERS ACCOUNT. PERFORM THE FOLLOWING COMMANDS TO TRANSFER THE MAGTAPE DISTRIBUTION TO THE [SYSMAINT] AREA OF THE NEWLY CREATED DISK.

```
$ MOUNT MSA0: VAXPAX
$ SET DEF SYS$MAINTENANCE
$ COPY MSA0:*.*;* *
```

C. THIS WILL TRANSFER ALL THE DIAGNOSTICS ON THE MAGTAPE TO THE [SYSMAINT] AREA OF THE NEW DISK.

D. MAKE CERTAIN THAT DIAGBOOT.EXE, ECSAA.EXE AND CONFIG.COM ARE CONTIGUOUS DISK FILES. IF THEY ARE NOT COPY THEM TO THEMSELVES USING THE /CONTIG SWITCH, THEN PURGE THE OLD VERSIONS OUT OF THE DIRECTORY.

```
$ COPY/CONTIG DIAGBOOT.EXE,ECSAA.EXE,CONFIG.COM *
$ PURGE DIAGBOOT.EXE,ECSAA.EXE,CONFIG.COM
```

E. THIS COMPLETES THE DIAGNOSTIC TRANSFER TO THE SYSTEm DEVICE. YOU MAY WISH TO DELETE ANY OF THE DIAGNOSTICS WHICH RELATE TO THE 11/780 AND 11/730.

```
$ DELETE ES*.*;*
$ DELETE EN*.*;*
```

Title: Autosizer
Author:
Processor Applicability: VAX Family

Have all your VAX 11/780 and 11/750 systems CONFIGURED for you using EVSBA.EXE released in the Diagnostic Update release 3. This program, available after November 1981, will pass configuration information on to the Diagnostic Supervisor. It builds a series of ATTACH commands based on the hardware it found during its sizing process which is passed on to the Supervisor and may be written to the console load media for later use. You will nolonger need to build a configuration command file! It will be built for you!

PERTINANT INFORMATION

1. The program is a level 3 standalone program that runs under the Diagnostic Supervisor.

2. It requires 256KB Memory, a Console Terminal and Load Device in working order.

3. The program operates in three modes: Default, Manual, and Selftest.

   To select any of these modes type after the DS> prompt:

```
RUN EVSBA.EXE                      for Default
RUN EVSBA.EXE/SECTION:MANUAL       for Manual
RUN EVSBA.EXE/SECTION:SELFTEST     for Selftest
```

3.1 Default: In the default mode the program sizes the system passing the configuration information on to the Diagnostic Supervisor. After the execution of the program this information may be seen by the operator by typing SHOW DEVICE after the DS> prompt.

ALWAYS VERIFY this information when using this mode since the program makes educated guesses reguarding some necessary information. In particular UNIBUS devices which use floating addresses for their Control Status Registers and vectors may be configured incorrectly for a particular system. (See EVSBA.DOC for further information)

3.2 Manual: The Manual option may be executed by typing the following command after the DS> prompt: RUN EVSBA.EXE/SECTION:MANUAL
This causes the program to give the following prompt: COMMAND?

Legal responses to this prompt are: ATTACH, CHANGE, EXIT, HELP, LIST, READ, SIZE, and WRITE. Explanations of these commands may be read by accessing the program's help file. (DS> H EVSBA HELP)

note: You must use an ATTACH command to pass the configuration information on to the Supervisor after SIZEing the system in this mode.

Commands READ and WRITE access only the console media.

3.3 Selftest: The Selftest option may be executed by typing the following command after the DS> prompt: RUN EVSBA.EXE/SECTION:SELFTEST
As in the Manual mode the COMMAND? prompt is given. Any manual mode command is valid. The primary difference between these two modes is that when using the SIZE command in the Selftest mode all the configuration information is shown to the operator on the console.

4. There is a "QUICK" execution of the program available in all modes. A response of SET FLAG QUICK to the DS> prompt prior to running the program will cause it to ignore the presence of terminals connected to a DZ11. For systems with a large number of terminals this can save a considerable amount of time and the program will proceed very quickly.

5. The autosizer can be run from either the console subsystem or from the system diagnostic media. This fact can be useful in situations where mass storage devices are inoperable.

6. A recommended sequence of operation is:

   1. Boot the Diagnostic Supervisor.
   2. DS> SET QUICK if quick execution is desired.
   3. DS> RUN EVSBA/SEC:SELFTEST
   4. COMMAND? SIZE (sizes system)
   5. COMMAND? CHANGE (only if configuration information needs change)
   6. COMMAND? WRITE (writes configuation information to console media)
   7. COMMAND? ATTACH (passes configuation information to Supervisor)
   8. COMMAND? EXIT (exit from EVSBA back to the Supervisor)
   9. DS> SHOW DEVICE (to see results of autosizer)
   10. DS> CLEAR QUICK (clears the QUICK FLAG)
   11. DS> SELECT or DESELECT devices for running desired diagnostic
   12. DS> RUN desired diagnostic
   13. To copy CONFIG.COM file created by program to [SYSMAINT] (assuming that you logged into FIELD SERVICE) use the FILEX utility after Booting VMS as follows:

```
$ MOUNT/FOR CS1:
$ MCR FLX
FLX>=CS1:CONFIG.COM/RT
FLX>^Y
$ DISMOUNT CS1:
```

MC SYSGEN
SYSGEN> CONNECT CONSOLE
SYSGEN> EX

UUT-Type	LINK	GENERIC	PARAMETERS	TYPICAL
AA11K	DWn	??an	CSR VCT BR	770460 350 5
AD11K	DWn	??an	CSR VCT BR	770400 xxx 6
CR11	DWn	CRa	CSR VCT BR	777160 230 4
DL11	DWn	??a	CSR VCT BR	
DMC11	DWn	XMa	CSR VCT BR	760050 xxx 5
DMP11	DWn	XDan	CSR VCT BR	
DMR11	DWn	XMan	CSR VCT BR	
DR11B	DWn	??a	CSR VCT BR	772410 124
DR11K	DWn	??a	CSR VCT BR	767770 xxx 4
DR11W	DWn	??a	CSR VCT BR	
DR780	SBI	XFn	TR BR	
DUP11	DWn	XJa	CSR VCT BR	
DV11	DWn	XVa	CSR VCT BR	775000
DW750	CMI	DWn	BR	
DW780	SBI	DWn	TR BR	3 4 (#1 UBA)
DW780	SBI	DWn	TR BR	4 4 (#2 UBA)
DZ11	DWn	TTa	CSR VCT BR EIA/20MIL	760100 xxx 5 EIA
KA750	CMI	KAn	G H TOY WCS ACC	NO NO YES 0 0
KA780	SBI	KAn	G H WCS ACC	No No 0 0
KMC11	DWn	XMan	CSR VCT BR	
KW11K	DWn	??a	CSR VCT BR	770404 xxx 6
LA34	TTa	TTan		
LA36	TTa	TTan		
LA38	TTa	TTan		
LA120	TTa	TTan		
LA180	LPa	LPan		
LP05	LPa	LPan		
LP06	LPa	LPan		
LP11	DWn	LPa	CSR VCT BR	777514 200 4
LP14	LPa	LPan		
LP25	LPa	LPan		
LPA11K	DWn	LAan	CSR VCT BR	770460 350 5
MA780	SBI	MAn	TR BR MPM PORT	
MBE	RHn	MBn	DRIVE #	
MS750	CMI	MSn	BR	
MS780	SBI	MSn	TR	
PCL11	DWn	??a	CSR VCT BR	764200 170 x
RH750	CMI	RHn	BR	5
RH780	SBI	RHn	TR BR	8 5 (RH0)
RH780	SBI	RHn	TR BR	9 5 (RH1)
RK06	DMa	DMan		
RK07	DMa	DMan		
RK611	DWn	DMa	CSR VCT BR	777440 210 5
RL01	DLa	DLan		
RL02	DLa	DLan		
RL11	DWn	DLa	CSR VCT BR	774400 160 5
RM03	RHn	DRan		
RM05	RHn	DRan		
RM80	RHn	DRan		
RP04	RHn	DBan		
RP05	RHn	DBan		
RP06	RHn	DBan		
RP07	RHn	DRan		
RX02	DYa	DYan		
RX211	DWn	DYa	CSR VCT BR	777170 264 5
TE16	MTa	MTan		
TM03	RHn	MTa	DRIVE #_	
TM78	RHn	MFa		
TS11	DWn	MSan	CSR VCT BR	772520 224 5
TU45	MTa	MTan		
TU58 Unibus	DWn	DDan	CSR VCT BR	776500 xxx x
TU77	MTa	MTan		
TU78	MFa	MFan		
UBE	DWn	UBan	CSR VCT BR	
VT50	TTa	TTan		
VT52	TTa	TTan		
VT55	TTa	TTan		
VT100	TTa	TTan		

Note: The typical column is only a partial list because of the great amount of possibilities in configurations - these are by no means any sort of standard.

a = Alpha Character
n = Numeric Character

SOME BASIC CONSOLE COMMANDS

UNDER CONSOLE I/O MODE >>>

EXAMINE >>>E/X/Y (ADDRESS IN HEX) <CR>

	B=BYTE		P=PHYSICAL
X=	W=WORD	Y=	V=VIRTUAL
	L=LONGWORD		I=IPR (SPECIFY REGISTER #)
			G=GPR (SPECIFY REGISTER #)

DEPOSIT >>>D/X/Y (ADDRESS IN HEX) (DATA IN HEX) <CR>

INITIALIZE >>>I

START >>>S <ADDRESS>

CONTINUE >>>C

BOOT >>>B/(FLAG)/(QUALIFIER) (DEVICE) <CR>

SOME FLAGS:/1 =CONVERSATIONAL BOOT
/10 =DIAG.SUPERVISOR
/100 =SOLICIT FILE NAME

ENTER ROM MODE FROM CONSOLE I/O MODE = >>>^P
>>>^D

ENTER ROM MODE FROM VMS = S@SYSSSYSTEM:SHUTDOWN or S@[SYSEXE]SHUTDOWN

THEN ^P
>>>^D

SOME COPY COMMANDS

FILEX COPY FROM DISK (DEFAULT DRIVE) TO TU-58

```
$ RUN SYSSSYSTEM:SYSGEN          NOTE: FILEX DOES NOT USE ANY
SYSGEN>CONNECT CONSOLE          CONTROLLER CODES, ONLY DDU.
SYSGEN>EXIT
$ MOUNT CS1:/FOREIGN
$ SET DEFAULT [SYSMAINT]
$ MCR FLX
FLX>CS1:/RT/ZE            ZERO OUT EXISTING DIRECTORY ON TAPE
                          (OPTIONAL)
FLX>CS1:/RT/LI            LIST DIRECTORY (OPTIONAL)
FLX>CS1:/RT/XX = [device]filename.ext/RS <CR>
     {TO}           {FROM}
        XX = IM = IMAGE MODE (EXE,OLB,SML,SYS,OLB,TSK)
             DE = DELETE THE SPECIFIED FILE
             FB = FORMATTED BINARY (OBJ,STB,BIN,LDA)
             FA = FORMATTED ASCII (ALL OTHER EXTENSIONS)
             CO = CONTIGUOUS FILE TO DISK (FILES COMMING
                  FROM DISK TO TAPE ARE ALWAYS CONTIGUOUS)
             RS = RS-11 FORMAT (SYSTEM)
             RT = RT-11 FORMAT (TAPE)

FLX>^Y

$
```

TO COPY FROM TU58 TO DISK (RK07)

```
$ RUN SYSSSYSTEM:SYSGEN
SYSGEN>CONNECT CONSOLE
SYSGEN>EXIT
$ MOUNT CS1:/FOREIGN
$ SET DEFAULT [SYSMAINT]
$ MCR FLX
FLX>DM0:/RS/CO=CS1:filename.ext/RT
    {TO}        {FROM}
FLX> ^Y
$
```

TO REBUILD VMB.EXE

SAME AS ABOVE COPY PROCEDURE BUT

```
$ SET DEF [SYSEXE]
```

NOTE: WHEN USING FILEX UNDER VERSION 3.X VMS, THE DEVICE MNEMONICS (DDU) MAY NOT BE RECOGNIZED SINCE VERSION 3.X LIKES LOGICAL NAMES INSTEAD OF DEVICE NAMES. UNFORTUNATELY FILEX DOES NOT LIKE LOGICAL NAMES. SO... TO AVOID UNKNOWN DEVICE ERRORS YOU MUST EITHER SET YOUR DEFAULT TO THE CORRECT DIRECTORY FIRST AND OMIT THE DESTINATION SPEC.

```
EXAMPLE:    $ SET DEF SYSSMAINTENANCE
            $ MC FLX
            FLX> CS1:/RT=FILENAME.EXT/RS

OR... BE SURE TO USE THE FULL FILESPEC AS REQUIRED BY VERSION 3

EXAMPLE:    FLX> CS1:/RT=DR0:[SYS0.SYSMAINT]FILENAME.EXT/RS
```

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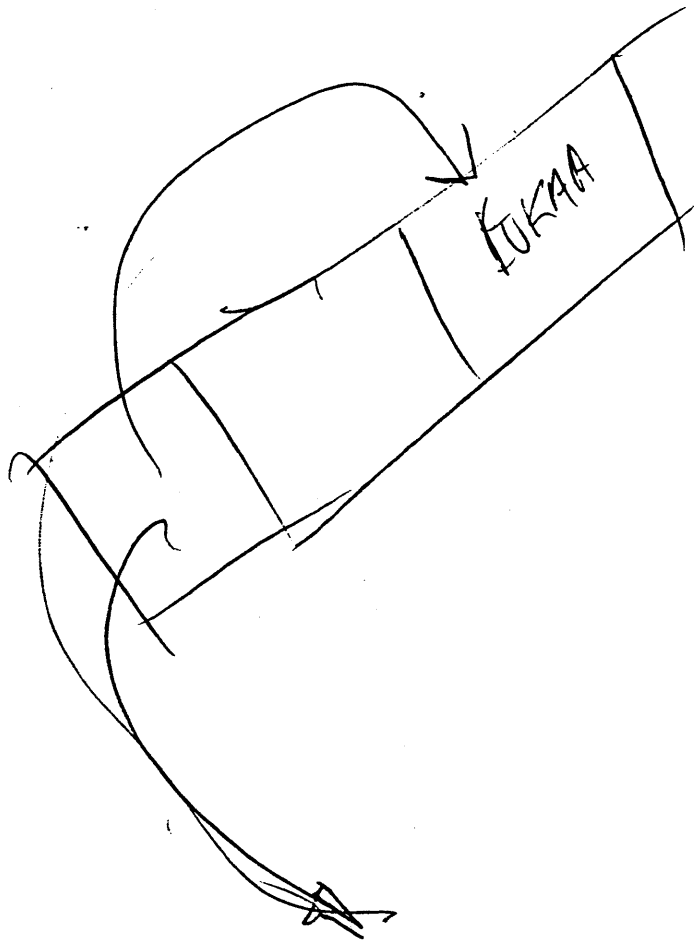
$ XFER VME.EXE
$ mcr WRITE



TO WRITE A BOOTBLOCK ON TAPE OR DISK

```
$ MCR WRITEBOOT

Target System Device (and bootfile if not VMB.EXE)...: DDCU:filename.ext
Enter VBN to Boot File (default is 1)...: 1 or 2
Enter Load Address (default is 200)  ...: 10000 or 200 or C000
$
```

DDCU = DEVICE NAME, CONTROLLER AND UNIT #
(CSA1:,DMA0:, ETC.)

LEVEL 4 DIAGNOSTICS AND MONITORS ARE THE ONLY BOOTABLE PROGRAMS

THE VAX 11/750 HAS FOUR BOOTABLE PROGRAMS AT THIS TIME...

PROGRAM NAME	VBN	LOAD ADDRESS	DESCRIPTION
EVKAA.EXE	2	200	HARDCORE
ECKAL.EXE	2	200	TB AND CACHE
ECSAA.EXE	2	10000	DIAGNOSTIC SUPERVISOR
BOOT58.EXE	1	C000	BOOT58 MONITOR

NOTE: TO REBUILD A BOOTBLOCK ON THE SYSTEM DISK, SIMPLY SPECIFY THE DISK'S NAME (DDCU:) AND STRIKE 3 <CR>'S

NOTE: WHEN USING WRITEBOOT UNDER VERSION 3.X VMS, THE DEVICE MNEMONICS (DDCU) MAY NOT BE RECOGNIZED SINCE VERSION 3.X LIKES LOGICAL NAMES INSTEAD OF DEVICE NAMES. SO... TO AVOID UNKNOWN DEVICE ERRORS YOU MUST BE SURE TO USE THE CORRECT LOGICAL NAME OR USE THE LONG DIALOGUE FOR THE DEVICE AND DIRECTORY SPECS.

EXAMPLE: DRA0:[SYS0.SYSMAINT]FILENAME.EXT

REVCON

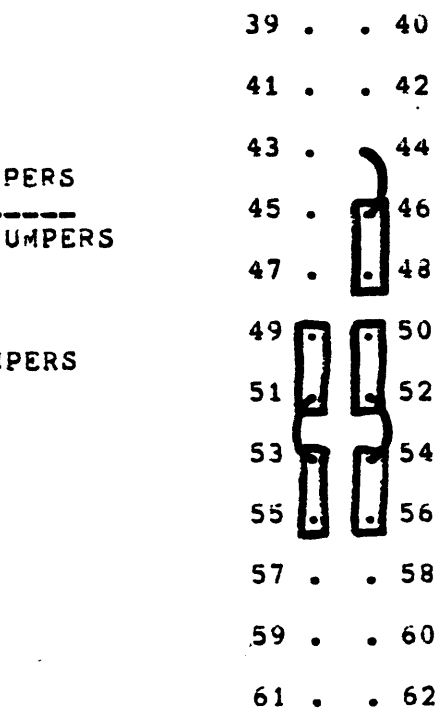
BACKPLANE WIRING FOR SID REGISTER IPR 3E <7:0>

SLOT 4 SECTION B

REVISION 0
INITIAL JUMPERS

WIRE WRAP JUMPERS
44-46
51-53
52-54

PUSH ON JUMPERS
46-48
49-51
50-52
53-55
54-56



44,51,52 ARE GROUND PINS

BIT BREAKDOWN

PIN	BIT
56	0
55	1
54	2
53	3
50	4
49	5
48	6
46	7

HARDWARE REV. 0 = ALL JUMPERS INSTALLED IPR 3E = 00
HARDWARE REV. 1 = REMOVE JUMPER 54-56 (FLOATS BIT 0 HI) IPR 3E = 01
HARDWARE REV. 2 = REMOVE JUMPER 53-55 (FLOATS BIT 1 HI) IPR 3E = 02
AND RE-INSTALL JUMPER 54-56 (GROUNDS BIT 0)
HARDWARE REV. 3 = REMOVE JUMPER 54-56 AND 53-55 IPR 3E = 03
(FLOATS BITS 0 AND 1)
ETC.

PUSH ON JUMPER PART NUMBER = 12-14314-00

Date: 8/1/82

Updates:

CSSE
VW01-1/C05

11/750 REVISION CONTROL DOCUMENT

CHANGES IN THIS UPDATE:

- Added compatibility chart (1.1)
- Added Kernal ID Register and SID Switch Info (3.0)
- Revised and updated 11750 Kernal Rev history (4.0)
  - Rev B and Rev C backplane compatibility info
- Added MS750-CA memory option info (5.2)
- Updated info on all options (5.0)

TABLE OF CONTENTS

INTRODUCTION

This document is intended to define the revision history of the VAX 11/750 system for purposes of identifying the compatible diagnostics, firmware, and operating system software. (All references to the 11750 apply to the 11751 as well, unless otherwise noted.)

This document will be updated on a quarterly basis and released to microfiche in the VAX Library Update and the Speed Bulletin.

The following VAX LIBRARY CARDS will be required as reference to the revision control plan. This document will state the source of information necessary for understanding firmware, diagnostic, and system software compatibility.

DOCUMENT	INITIAL STARTING DOCUMENTATION DESCRIPTION
ZZ-EVNDX-W.0	VAX Diagnostic Index
ZZ-ECOAB-1.0	VAX 11/750 Control Store Microcode Listing CMT050
ZZ-ECOAD-1.0	VAX 11/750 Boot Rom Listing TU58 RK07 RL02

1.1 11/750 COMPATIBILITY CHART

The following chart summarizes the compatible hardware, software, microcode and diagnostic revision levels for each kernal revision. For information concerning the module revisions for each option revision, see Section 5.0.

11750 KERNAL REV WITH SID	00	10	20	30/38	4X	5X	6X
11750 KERNAL REV W/OUT SID	00	01	02	03			
H/W Options:							
KA750	00	01	02	03			
MS750-AA	00	00	00	01			
MS750-CA	-	-	-	-			
RH750	-	-	00	01			
FP750	-	-	-	01			
KU750	-	-	-				
DR750							
DW750							
DX: * EVNDX	V - 7	V - 7	V - 7	V - 7			
RELEASE:	2.X	2.X	2.X	2.X,3			
MICROCODE:	050	052	062	094			

* Check VAX Diagnostic Evaluations (distributed in the Speed Bulleti for bugs that exist in a particular diagnostic release.

2.0 REVISION CRITERIA

Architectural or functional changes in the system must cause a change of the kernal revision level. This includes changes to the hardware that changes performance or operation of the system that is detectable to the diagnostics and operating system software. Modifications to cables, power subsystems, ventilation equipment, or mechanical design should not cause a change to the kernal revision level. The VAX 11/750 revision history for a particular subsystem or option will be designated as follows...

OPTION-XXN

where, OPTION is the five letter neumonic (i.e. KA750), XX is a functional change description code (i.e 01), and N is a non-functional change to the option. Non-functional changes to an option include relayout of modules to eliminate rework wires or changes to documentation that do not affect operation of the system. Changes to purchase part numbers at the module level should not cause the hardware revision to be raised either. Functional changes to any of the modules in the kernal subsystem (i.e. KA750 CPU and MS750) increments each module revision, as well as the kernal revision. A brady marker indicating the module revision should be wrapped around the third tab down from the top of the module handle. Manufacturing will be instructed to attach the brady markers as soon as possible.

A switch pack and pull up resistor assembly has been designed and will be installed in all Rev "C" backplanes shipped from manufacturing. The switch pack will be set by manufacturing before it is shipped. An engineering spec has been written which contains instructions as to how the switch pack should be set. This document will be under ECO control, so that when there is an ECO that changes the switch pack setting (i.e. a change to the kernal revision), the document will be ECOd and the new switch pack settings added. (See Section 3.1 for more detailed information on the switch pack).

0 VAX 11/750 KERNAL REVISION LEVEL

The VAX 11/750 processor has a system identification register (SID) register similiar to the VAX 11/780 processor; however, there are two basic differences between the VAX 11/750 and VAX 11/780 processor SID registers. These are...

* VAX 11/750 SID does NOT contain the system serial number
* VAX 11/750 SID DOES contain a field describing current control store microcode revision. This is because VAX 11/750 does not have the FPLA to intercept ECO'd microcode locations.

The figure 2-1 illustrates the format of the VAX 11/750 system identification register (SID). This register is accessible to macro code and the console terminal through IPR address ^X3E. Examination of the register shows 4 bytes, 3 of which are functional. The high byte is the processor type code byte used by the diagnostics and operating system to decide which type of processor the software is operating on. Known type codes are listed below.

TYPE CODE BYTE	PROCESSOR
00000000	undefined
00000001	VAX 11/780
00000010	VAX 11/750
00000011	VAX 11/730

Byte 2 of the SID register is always zero. Byte 1 of the SID register is the microcode revision of the control store. This number is generated by the microprogrammer in the REV750.MIC file of the microcode listing ECOAB. There is a MICRO2 assembler directive called .SET/MICROREV=version at the top of the page which is upgraded for each major assembly of the the microcode. In the MFPR microinstruction flows this equated value is substituted into the short literal field of the microinstruction and becomes the microcode revision that appears in byte 1 of the SID register. The number following MICROREV is DECIMAL. You must convert the hex byte to decimal after examining the SID register. Byte 0 of the SID register is the hardware revision of the kernal. The hardware revision is programmable on the CPU backplane. There is a 74LS244 tri-state driver on the UBI module that interfaces to the CPU WBUS. The MFPR microinstruction flows read this byte when referencing the SID register. At Limited Release (LR) this byte should be 00. That means all the bits are grounded on the CPU backplane. (See Section - Electrical Requirements of Kernal Revision Level Input Device.) Each hardware change that changes the functionality of the hardware will INCREMENT the hardware revision by one. The number in byte 0 of the SID register is a BINARY revision level programmed on the SID input device.

SID REGISTER FORMAT — IPR ADDRESS ^X3E

00000010	00000000	00110010	00000000
TYPE CODE = 2	MUST BE 0	MICROCODE REV = 62 = 94	HARDWARE REV 2 3

Figure 2-1

NOTE: This example shows the type code as 2 (VAX 11/750), Microcode revision is 32 hex or 50 decimal, and the hardware revision level is equal to zero zero.

3.1 Kernal Identification Register Hardware Revision Level Input Device Description

The Hardware revision level of the kernal that is visible in byte 0 of the SID register is generated by a 16 pin DIP switchpack consisting of 8 single-pole single-throw switches that ground or open SID bits <7:0> to produce a binary number corresponding to the kernal revision level. Each bit of byte 0 of the SID is pulled up to +5V through a resistor contained in a 14 pin DIP pull-up resistor package.

The Kernal Rev Level Input device is manufactured using a 1.6" X 2.6" standard size fingerless board that has an edge mounted 40 pin AMP connector to press on the backplane of the system on slot 4. There are 2 ICs on this device, they are the DIP switch-pack assembly and DIP pull-up resistor package. This SID switch, part number < ??????? > is manufactured with shelf items listed below.

Kernal Hardware Revision Level Input Device Parts List

Qty.	Description	DEC PN
1	40 pin edge connector	12-11620-00
1	DIP rocker-switch 8 sw	12-11164-04
1	DIP 4.7K terminator	13-00005-00
1	PC board 1.6" X 2.6"	50-15141-00
1	Housing backplane conn	12-16821-00

3.1.1 Electrical Requirements of the Kernal Revision Level Input Device

The kernal revision level input device requires +5V and ground to operate properly. The input signals SYS ID <7:0> H must also be interfaced to the input device. The electrical connection is made via the 40 pin AMP connector that is pressed on the backplane. The following list describes signal locations on the backplane and AMP connector. A signal with a dash "-" implies a no connect to the input device.

Signal	AMP pin	11/750 Backplane 400Bxx	AMP pin	Signal
-	A	19	20	B -
-	C	21	22	D -
GND	E	23	24	F -
-	H	25	26	J -
-	K	27	28	L -
-	M	29	30	N -
-	P	31	32	R -
-	S	33	34	T -
-	U	35	36	V -
-	W	37	38	X -
-	Y	39	40	Z -
-	AA	41	42	BB -
-	CC	43	44	DD -
-	EE	45	46	FF SYS ID 7 H
-	HH	47	48	JJ SYS ID 6 H
SYS ID 5 H	KK	49	50	LL SYS ID 4 H
-	MM	51	52	NN -
SYS ID 3 H	PP	53	54	RR SYS ID 2 H
SYS ID 1 H	SS	55	56	TT SYS ID 0 H
-	UU	57	58	VV +5V

Power consumption with all switches closed is approximately equal to 42 milliwatts.

.1.2 Kernal Revision Level Input Device Installation Procedure

1. Remove primary power from the system by turning CB1 to OFF position.

2. Open rear door of the VAX 11750 and remove the backplane cover plate by loosening 4 screws and lifting off.

3. Install the Backplane Connector Housing (12-16821) on slot 4 of the CPU backplane so that the blind holes at each end of the connector cover pins B40017, B40018 on top, and B40059 and B40060 on the bottom.

4. Set the binary revision level on the switch to desired number (see table two page 3) according to the following example...

Example is for: Hardware revision level 20 Hex

SYS ID	<7>	<6>	<5>	<4>	<3>	<2>	<1>	<0>
SWITCH	S8	S7	S6	S5	S4	S3	S2	S1
	ON	ON	OFF	ON	ON	ON	ON	ON

NOTE: Early SID switch modules have the switch pack reversed.
---- Use etched bit position on board for reference. Disregard switch positions marked on switch pack.

When the switch is ON, ground is connected to the input of the 74LS244 on the L0004 (UBI) module producing a "0" data bit in byte 0 of the SID register. If the switch is OFF the current path is removed and the inputs to the 74LS244 are pulled up to +5V causing a "1" to be generated in the that bit position.

5. Install the Kernal Rev Level Input Device in the backplane connector housing with component side (Side 1) facing the right side of the VAX 11750 CPU cabinet (when viewed from the rear).

6. Secure backplane cover plate and rear door of the VAX 11/750 and set the POWER ON ACTION switch to HALT. Turn CB1 to the ON position.

7. Verify the hardware revision level by examining the SID register in console mode by typing...(at the console)

```
>>>E/I 3E<CR>
    I  0000003E  02003E20
```

This example shows a Kernal that has CMT062 microcode and a hardware revision of 20. (See Tables 1 and 2 on next page).

The following diagram show what the switch pack actually looks like; the section containing the bits that must be set is depicted in a larger scale at the right.

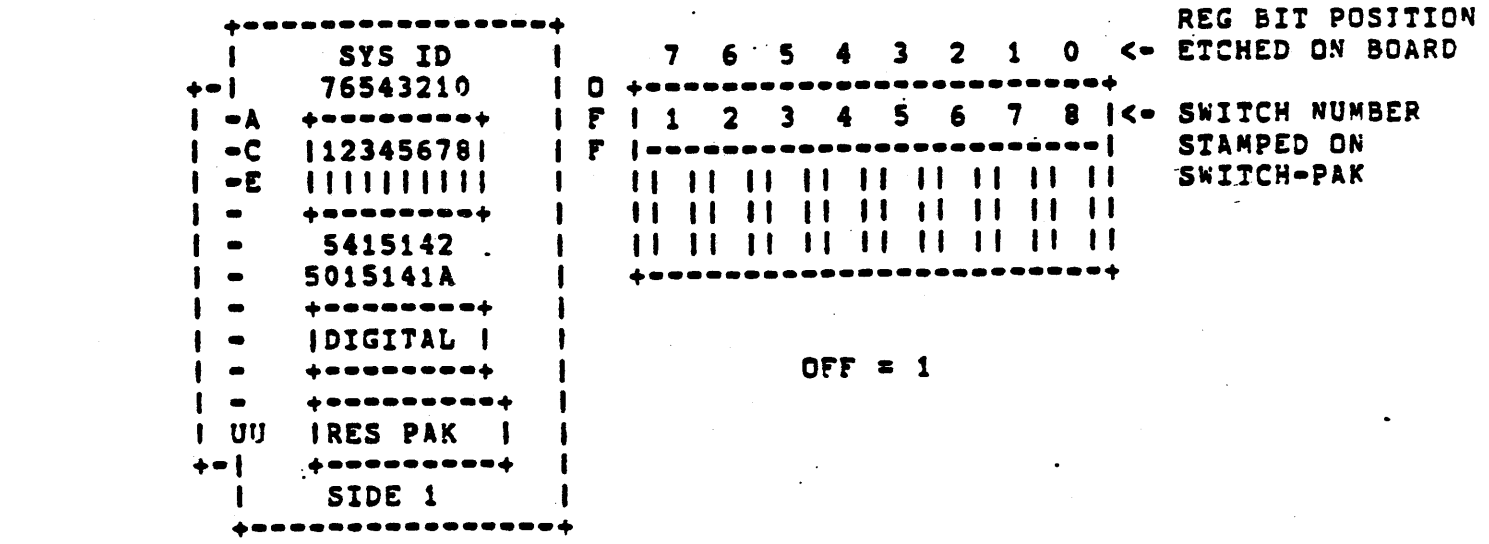


TABLE 1
Microcode Identifier Field

xxxxyyyy
00110000 = 30 = CMT050
00110010 = 32 = CMT052
00111110 = 3E = CMT062
01011110 = 5E = CMT094

TABLE 2
Hardware Revision Identifier

nnnnrrrr
00000000 = Kernal Rev 00
00010000 = Kernal Rev 10
00100000 = Kernal Rev 20
00110000 = Kernal Rev 30
00111000 = Kernal Rev 38

3.2 SID Register Hardware Revision Problem

The current design of the SID register hardware revision byte 0, has an 8 bit 74LS244 tri-state driver chip interfaced to the backplane. The chip inputs are not inverted in the driver and are not pulled up either so the resultant data with SID register byte 0 not programmed is FF. Since the inputs just "floats" at times the output may not always be FF This is a problem when running the DIAGNOSTIC SUPERVISOR. The supervisor "forgets" where it came from and the program data must be entered manually to get the supervisor to "remember" where it came from. This is time consuming, especially if the field engineer must power the machine up and down to replace modules. The result is the MTTR is extended to repair the machine. The register must be wired HI or LO, but wiring the bits HI is another problem. The CPU power supply must be connected to the chip inputs directly. If the 74LS244 fails by shorting the input pin to ground, hopefully the chip will burn open, but if not, other damage could result. There should be a pulled up +5V through a 1K resistor to several unused backplane pins. The SID register switch pack and pull-up assembly attaches across slots 3 and 4 section B of the backplane. Back plane pins will protrude through the PC board and pins used will have a female socket that is easily grasped with a scope probe.

3.3 Microcode Revision History

A comprehensive revision history of VAX 11/750 microcode is contained in the microcode listing in the VAX LIBRARY fiche set. Revision W of the VAX LIBRARY contains the microcode listing for control store version CMT050. Since there have been numerous changes to the microcode since version CMT050, it is suggested that you read the microcode revision history contained in the REV750.MIC file of the microcode listing. Changes to the VAX 11/750 microcode AFTER CMT062 will be described briefly in this document and what the symptoms and corrective actions were.

4.0 11/750 KERNAL REVISION HISTORY

Listed below is the revision history of the 11750 kernal, indicating the compatible module revisions for each hardware revision. Equivalent module revisions are separated by commas.

This history has been separated into two charts:

Chart 1 - 11/750 with a Rev "B" backplane
SID Switch Setting = xxxxxxx0-7

Chart 2 - 11/750 with a Rev "C" backplane
SID Switch Setting = xxxxxxx8-F

KA750 Module Revision Charts

CHART 1

11750 KERNAL REV WITH SID		00	10	20	30	4X	5X
11750 KERNAL REV W/OUT SID		00	01	02	03		
MODULE	SLOT						
L0002	2	B	C	C	C,D		
L0003	3	B	C	C,D	C,D		
L0004	4	E	F	H,J	H,J		
L0005	5	D	E	F	H		
L0011	10	D	D	D	D		
L0016	10	*,A	*,A	*,A	*,A		
M8728	11-18	C	C	C	C		
M9313	28 A-B	A	A	A,B	A,B		
TU58	UNIBUS	F	F	F	F		
TU58	CON	B	B	B	B		
CONT PANEL		C	C	C	C		
BACKPLANE		A	B	B	B		

* = LR Release

CHART 2

11750 KERNAL REV WITH SID	00	10	20	38	4X	5X
11750 KERNAL REV W/OUT SID	00	01	02	03		
MODULE / SLOT						
L0002 / 2	B	C	C	C,D		
L0003 / 3	B	C	C,D	C,D		
L0004 / 4	E	F	H,J	H,J		
L0005 / 5	D	E	F	H		
L0011 / 10	D	D	D	N/A		
L0016 / 10	*,A	*,A	*,A	*,A		
M8728 / 11-18	C	C	C	C		
M8750 / 11-18	N/A	N/A	N/A	N/A		
M9313 / 28 A-B	A	A	A,B	A,B		
TU58 / UNI BUS	F	F	F	F		
TU58 / CON	B	B	B	B		
CONT PANEL	C	C	C	C		
BACKPLANE	C	C	C	C		

The L0011 or the L0016 controllers are valid for hardware revision 00,01 (10) and 02 (20); however, these revisions will not support the MS750-CA memory option. The minimum acceptable revision for inclusion of the MS750-CA is hardware Rev 48. See MS750-CA option chart (Section 5.2) for requirements.

4.2 KA750-00 REVISION SUMMARY

* This is the initial introduction of revision control on the 11750 and represents the minimum module revision levels at FCS - October 1980.

* Compatible Revision Levels:

  - Microcode version at FCS - CMT050.

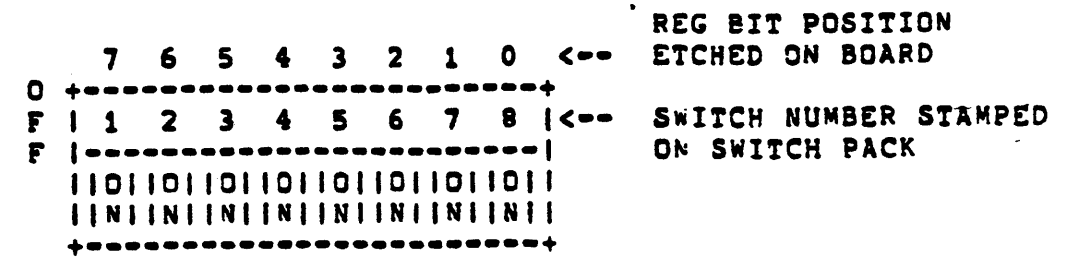
  - VAX/VMS version at FCS - 2.0.

  - Diagnostics

    Current Diagnostic Release is V. Refer to EVNDX and the VAX Diagnostic Evaluations for each Diagnostic release (see Spead Bulletin) for compatibility problems.

* Quick Check - >>>E/I 3E
I 0000003E 02003200
>>>

* SID Register Switch Pack Setting - Set bits 0 to 7 to the ON position (See below)



4.3 KA750-01/KA750-10 REVISION SUMMARY

* This represents VAX750-M-0001 FCO - began shipping from manufacturing 12/1/80. Field implementation began 3/81.

* This FCO combines a microcode change and a hardware change to the L0003, L0004, and L0005 Modules. The CPU backplane is also modified. The following ECOs are incorporated...

L0003-TW001
L0004-TW003
L0005-TW002
70-16486-TW001

This FCO was implemented to inhibit the possible interruption of an instruction that references the Unibus address space performing a DATIP. If the instruction is faulted because of a TB miss and external interrupts are pending, the Unibus is hung until the DATOB is done after the microcode completes the translation. The following instruction would cause this possible conflict:

ADDW3 #12, physical translation to @#^XFFFF20

Part of this FCO also connects some signals from the CPU to the FPA (slot 1 to slot 2) for FPA interfacing and also the drawing set of the FPA is modified for signal name continuity.

* Compatible Revision Levels:

- Microcode - CMI052
- VAX/VMS Version 2.2 - backwards compatible to 2.0

- Diagnostics

  Current EVNDX release is W. The following diagnostic compatibility problems have been identified:

  ECKAX - Test fails MACHINE CHECK TEST 7 with optional WCS module installed. Diagnostic Bug.
  EVKAB - Intermittant failures on the CVTPL and other instructions. Absence of post-process CLKX bit?
  ECKAC - 4.0 or higher will fail test 7C if this FCO is missing.
  ECKAM - 1.2 fails with 8 array boards present.

  Refer to EVNDX and the VAX Diagnostic Evaluations for each Diagnostic release (see Speed Bulletins) for incompatibilities.

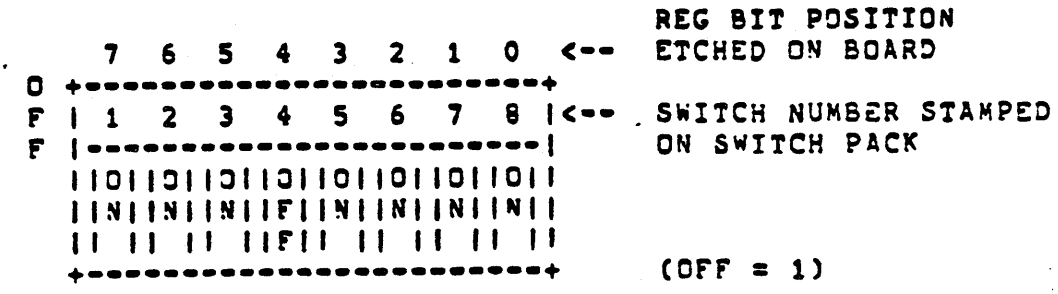
* Quick Check -

  A. >>>E/I 3E
  I 0000003E 02003401 (w/out SID)
  >>>

  >>> I 0000003E 02003410 (with SID)

  B. Inspect L0003 module and look for a 7427 in chip position E1. Also inspect the backplane assembly a look for a wire from 100B10 to 200B10 (MEM STALL H

* SID Register Switch Pack Setting - Set bits 0 to 3 and 5 to 7 to the ON position; set bit 4 to OFF position



KA750-02/KA750-20 REVISION SUMMARY

* This represents VAX750-A-0002 FCO. Mfg. began shipping 3/30/81. Field implementation began 6/81.

* This FCO corrects a large collection of problems in the microcode and hardware. The following ECOs are incorporated. There is the possibility of Unexepected System Service Exceptions caused by the CON gate array that is fixed with the ECO to L0004 module.

  L0005-TW003
  L0004-TW004

  Some systems in the field may have L0004 ECO without the L0005 ECO when the FCO is implemented.

* Compatible Revision Levels:

  - Microcode - CMT062 (replaces CMT052). Refer to REV750.MIC file for a list of all fixes to the microcode.

  - VAX/VMS Version 2.2 - backwards compatible to 2.0

  - Diagnostics

    Current EVNDX Release is Y. The following problems exist in the upgrade to CMT062 as far as diagnostics are concerned:

    ECKAL 2.0 Fails at PC 5000FFF1 ?
    Microcode change makes it impossible to force a TB Miss in both groups of the TB. Diagnostic attempted to read and write the TBDR which now causes a reserved operand fault.

    ECKAX 1.2 to 3.2
    Fails at TEST 1. The diagnostic expects a reserved operand fault when accessing IPR ^X3F and it does not occur. This is because of the addition of the IPR ^X3E which is called TBCHK. It allows the programmer to probe the TB at a VA and then branch on the state of the PSL VBIT indicating a TB hit. Diagnostic bug.

    ECKAX 1.2 to 3.2
    Fails at TEST 7 with optional KU750 module. Diagnostic forces a machine check in a WCS location with bad parity. Diagnostic bug.

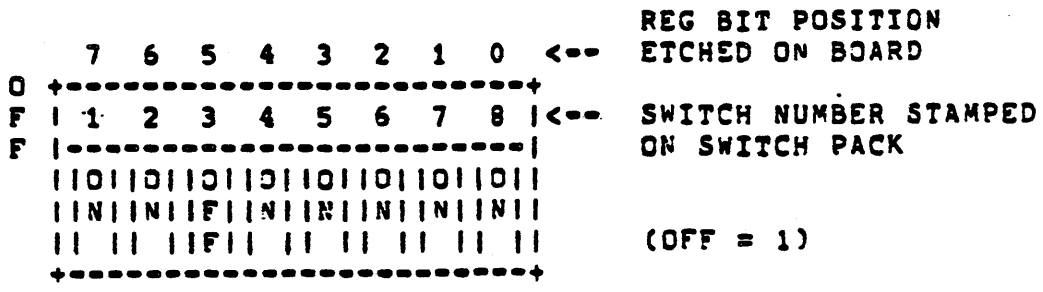
    ECKAM 1.2
    Diagnostic does not work properly when there are 8 array boards installed. Does not report correctable errors correctly.

Refer to EVNDX and the VAX Diagnostic Evaluations for each Diagnostic release (see Speed Bulletins) for incompatibilities.

* Quick Check - >>>E/I 3E
I 0000003E 02003E02 (W/out switch)
>>>
>>> I 0000003E 02003E20 (With Switch)

* SID Switch Setting -

Set SID register switch bit 0 to 4, 6 and 7 to ON position
Set SID register switch bit 5 to OFF position. (See below)



4.5 KA750-03/KA750-30 REVISION SUMMARY

* This represents VAX750-R-0003 FCO. Mfg. began shipping 2/22/82; field implementation began January 1982.

* This FCO is based on ECO L0005-TW005
L0004-TW004

and corrects interface problems with the floating point accelerator FP750 which began shipping Jan-1982.

Also, the layered software product DBMS must have this FCO in order to operate correctly. This product will report to operator if the system does not have this ECO installed.

* Compatible Revision levels:

- Microcode - CMT094 replaces CMT052 or CMT062. Refer to REV750.MIC file for a list of all fixes to the microcode.

- VAX/VMS - Current version is 2.4 and is backwards compatible to 2.0.

- Diagnostics

  Current EVNDX release is 3.0. Refer to EVNDX and the VAX Diagnostic Evaluations for eacn Diagnostic release (see Speed Bulletins) for incompatibilities.

* Quick Check -

Examine the SID register in console mode.

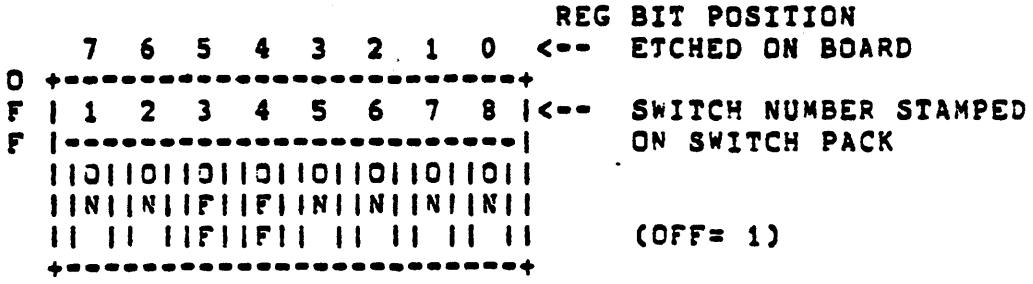
```
>>>E/I 3E
        I 0000003E  02005E03

>>>     I 0000003E  02005E30
```

Inspect the L0005 module for an IC in location E27 with the part number 932F1.

* SID Switch Setting

Set switch bit positions 0 to 3, 6 and 7 to the ON position
Set switch bit positions 4 and 5 to the OFF position



4.6 KA750-38 REVISION SUMMARY

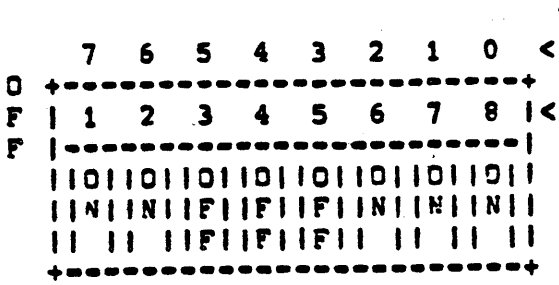
* This represents VAX ECO 7016486-TW002, which brings the backplane rev to C. Manufacturing began shipping 6/1/82. This ECO does not increase the hardware revision on the kernal.

* ECO was done to expand the backplane addressing capabilities to support the optional 1 megabyte memory array system.

* SYS ID Switch has been installed by manufacturing on all Rev C backplanes. This switch identifies both the kernal rev and the backplane addressing capabilities.

  Rev C backplane - last two hex digits will be reversed when the SID switch is installed. Last digit is used to indicate the backplane rev. (i.e. 8 = C backplane; 0 = B backplane)

Set switch bit positions 0 to 2, 6 and 7 to the ON position.
Set switch bit positions 3 to 5 to the OFF position.



5.0 OPTION REVISION CONTROL

The option interfaces and adaptors will have a separate revision history from the CPU. The KA750 CPU Kernal subsystem will include the following integral subsystems.

CPU	KA750 -	70-16486	CPU Backplane Asembly
		L0002	DPM Module
		L0003	MIC Module
		L0004	UBI Module
		L0005	CCS Module
		TU58-XA	Tape Drive Unit
		54-13489	TU58 Tape Controller Unit
		M9313	UET Unibus Terminator/ Exerciser
	MS750-AA	L0011	CMC Module
		M8728	256KB array board
	MS750-CA	L0016	Controller
		M8750	1MB array board
		M8728	256KB array board

OPTION	RH750	L0007	MBA Module
	KU750-YG	5413865-C	Add on daughter board
	FP750	L0001	FPA Module
	DW750	L0010	2nd Unibus Module
	DR750	L0014	Interprocessor I/F Module

The internal options of the 11750, with the exception of the MS750-AA and MS750-CA, will be tracked at the unit revision level only. This means that a functional change to the RH750, DW750, FP750 and KU750 will not increment the kernal revision level.

Each option revision summary will indicate any hardware, operating system, diagnostic and microcode constraints. The option will be considered compatible with the kernal hardware, VMS and microcode revisions used during the development of the option. Earlier compatible revisions will be noted only if they have been tested and proven to work.

Pertinent diagnostics to be run for each option (and the required revision, if any) will also be noted.

MS750-AA OPTION REVISION DESCRIPTION

MS750-AA Revision		00	01	02	03	04	05
MODULE	SLOT						
L0011	10	D	D				
L0016	10	A	N/A				
M8728	11-18	C	C				
BACKPLANE	70-16486	B	C				

MS750AA-00 REVISION SUMMARY

* Creation date is October 1980.

* This is the initial introduction of revision control on the MS750-AA and represents the minimum module revision levels at FCS.

* Note that only L0011 memory controllers shipped at FCS. Note that the L0016 controller, which will support both the M8728 and the new M82750 memory arrays and will be available in 01FY83, can also be used in a Rev 00 machine.

* Shortly after FCS, VAX750-M-0001 was done which increased the Rev of the backplane from A to B. Only 27 machines were shipped with "A" backplanes.

MS750AA-01 REVISION SUMMARY

* Creation date July 82.

* New revision of the backplane is introduced to increase the addressing capabilities.

* The L0016 is not valid for Revision 01 - that combination (L0016 and Rev C backplane) is a new option designation - MS750-CA (See below).

* The M8750 memory array will not function in an MS750-AA option configuration.

* Diagnostics - ECKAC and ECKAM. Run ECKAC first; run ECKAM in QUICK VERIFY mode.

5.2 MS750-CA OPTION REVISION DESCRIPTION

MS750-CA Revision		00	01	02	03	04	05
MODULE	SLOT						
L0016	10	A					
M8728	11-18	C					
M8750	11-18	A					
BACKPLANE	70-16486	C					

MS750CA-00 REVISION SUMMARY

* Creation date - projected August 1982.

* This is the initial introduction of revision control for the MS750-CA and represents the minimum revision levels required for FCS of this option - July 1982.

* Note that the L0011 cannot be used in this option.

* Any mixture of M8728 and M8750 arrays will function; however, M8750 arrays must occupy the slots adjacent to the L0016 controller, starting with slot 11.

* This option requires VMS V 3.0 or higher.

* Minimum 11750 kernal rev to support this option is 48.

* Diagnostics - ECKAC (min. rev. 6.2) - EVNDX 7.0 (July 1982)
  ECKAM (min. rev. 2.4) "

  Run ECKAC first; run ECKAM in QUICK VERIFY mode.

5.3 RH750 OPTION REVISION DESCRIPTION

RH750 Revision	00	01	02	03	04	05
MODULE / SLOT						
L0007 / 7,8 or 9	A	A1,B				

RH750-00 REVISION SUMMARY

* Creation date is FCS - April 1981.

* This represents the initial introduction of revision control for the RH750 and represents the minimum revision level for the L0007 module at FCS.

* Diagnostics - ECCAA and EVRAA.

RH750-01 REVISION SUMMARY

* Creation date is October, 1981.

* Represents RH750-R-0001 FCO, which consisted of ECO L0007-IW002 to fix the problem of data lates on multiple MASSBUS systems. Replace 23-909A9 at location E12 with 23-969A9.

* FCO done on "C" etch modules only. Etch Revision "D", Module Rev "B" is a relaycut of the L0007 module and is equivalent to Etch Rev "C", Module Rev "A1".

* Diagnostics - ECCAA and EVRAA.

5.4 FP750 OPTION REVISION DESCRIPTION

FP750 Revision		00	01	02	03	04	05
MODULE	SLOT						
L0001	1	B	C				

FP750-00 REVISION SUMMARY

* Creation date is FCS - December 1981. This represents the minimum module revision level required at FCS.

* 11750 kernal rev must be at Rev 3 (Rev 94 microcode required).

* Diagnostics - ECKAB (min. rev. 7.2) - EVNDX 4.0 (Jan 1982)
  ESCAA (min. rev. 6.4) - "
  EVKAB (min. rev. 2.5) - "
  EVKAC (min. rev. 4.0) - "

FP750-01 REVISION SUMMARY

* Creation date is March 1981.

* Represents FP750-R-0001 FCO consisting of ECO L0001-TW002, which fixes the problem of the FPA not powering up "enabled" due to incomplete initialization of circuitry.

* Diagnostics - ECKAB (min. rev. 7.2) - EVNDX 4.0 (Jan 1982)
  ESCAA (min. rev. 6.4) - "
  EVKAB (min. rev. 2.5) - "
  EVKAC (min. rev. 4.0) - "

5.5 KU750 OPTION REVISION DESCRIPTION

KU750 Revision		00	01	02	03	04	05
MODULE	SLOT						
5413865-C	attaches to L0005	C	1				

KL750-00 REVISION SUMMARY

* Creation date is FCS - March 82.

* This represents the minimum module revision level required at FCS.

* Requires KU780-YG microcode rev at 2.0 or higher.

* Diagnostic - ECKAX - 11750 Cluster Exerciser - EVNDX 7.0 (July 82) (minimum rev 3.4)

5.6 DW750 OPTION REVISION DESCRIPTION

DW750 Revision		00	01	02	03	04	05
MODULE	SLOT						
L0010		?					

DW750-00 REVISION SUMMARY

* FCS scheduled for September 1982.

* 11750 kernal rev must be 30/38 or higher.

* Requires Version 3.0 or higher.

* Diagnostics - ECSAA - min. rev 6.4 - EVNDX Release 4.0 (Jan 82)
ECCBA - min. rev 1.3-

5.7 DR750 OPTION REVISION DESCRIPTION

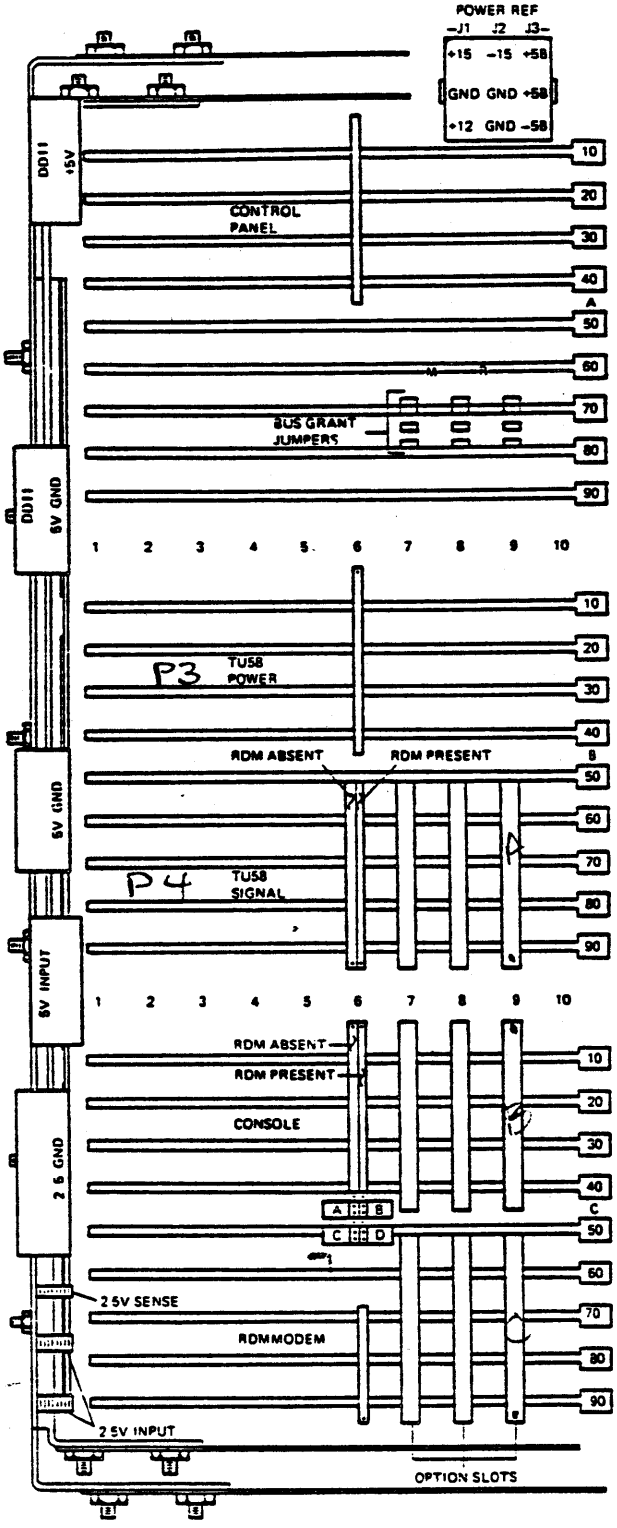
DR750 Revision		00	01	02	03	04	05
MODULE	SLOT						
L0014		?					

* FCS scheduled for September 1982.

* 11750 kernal rev must be 40/48 or higher.

* Requires VMS Version 3.0.

* Diagnostics - EVDFD - rev 1.0 - EVNDX Release 7.0 (July 82)
EVDFE - Rev 1.0
EVDFF - rev 1.0
EVDFG - rev 1.0
ECDFA - rev 1.0
ECDFB - rev 1.0
ECSAA - min rev 6.7



OPTION SLOT BUS GRANTS	
TO SELECT	REMOVE JUMPER
BG 4	A00X 67
BG 5	A00X 69
BG 6	A00X 73
BG 7	A00X 77
X=SLOT 7,8,9	

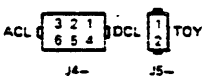
TEST POINTS		
RDM 19	MATCH PULSE	C00681
RDM 23	SA CLOCK	C00673
RDM 23	SA ST/SP	C00675
DPM 17	M CLOCK	B00205
DPM 17	BASE CLOCK	A00273
DPM 17	B CLOCK	B00209
MIC 04	MEM STALL	B00210
DPM 17	PHASE 1	A00590

HARDWARE REV LEVEL (SYS ID)	
BIT	PIN #
0	B00456
1	B004 55
2	B00454
3	B004 53
4	B00450
5	B00449
6	B00448
7	B00446

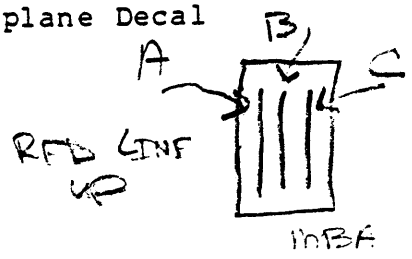
1 = Jumper In

CONSOLE BAUD RATE				
	CON BR			
RATE	A	B	C	D
300	0	0	1	0
600	0	1	1	0
1200	1	1	1	0
2400	0	0	0	1
3600	1	0	0	1
4800	1	1	0	1
9600	1	0	1	1
19200	0	1	1	1
38400	1	1	1	1
PIN #	C00645	C00646	C00649	C00650
JUMPER TO GND	C00643	C00644	C00651	C00652

BAUD RATE JUMPERS FOR CONSOLE



VAX-11/750 Backplane Decal



OPTION SLOT JUMPERS

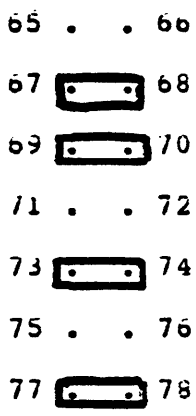
SECTION A OF DESIRED SLOT

BUS GRANT JUMPERS SLOTS 7,8,9 OF THE EXTENDED HEX SECTION

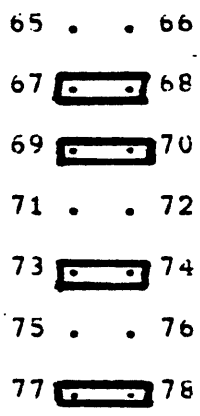
WHEN AN OPTION IS NOT INSTALLED IN A SLOT, ALL BG JUMPERS MUST BE INSTALLED!

WHEN INSTALLING AN OPTION, ALL BG JUMPERS MUST BE REMOVED FROM THAT SLOT!

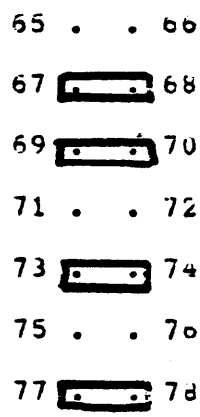
SLOT 7



SLOT 8



SLOT 9



ERROR LOGGER

ERROR LOG DESCRIPTION AND USE

THE ERROR LOGGER CONSISTS OF BASICALLY THREE PARTS:

1). A SET OF EXECUTIVE ROUTINES THAT DETECT ERRORS AND EVENTS AND RECORDS RELEVENT INFORMATION INTO AN ERROR LOG BUFFER IN MEMORY.

2). A PROCESS CALLED ERRFMT.EXE THAT PERIODICALLY EMPTIES THE BUFFERS, TRANSFORMS THE DESCRIPTIONS OF THE ERRORS INTO A STANDARD FORMAT AND STORES THE FORMATTED INFORMATION IN A FILE ON DISK.

3). A PROCESS CALLED SYE.EXE THAT GENERATES READABLE REPORTS FROM THE INFORMATION FORMATTED BY ERRFMT.EXE.

THE EXECUTIVE ROUTINES AND ERRFMT.EXE RUN CONTINUOUSLY WITHOUT USER INTERVENTION TO FILL THE BUFFERS WITH RAW DATA ON EVERY DETECTED ERROR AND EVENT. WHEN A BUFFER BECOMES FULL OR A PREDETERMINED TIME HAS EXPIRED, THE BUFFER IS EMPTIED TO A FILE ON DISK. IF A SUDDEN BURST OF ERRORS OCCUR FASTER THAN THEY CAN BE FORMATTED AND STORED, THEY WILL BE ASSIGNED A SEQUENCE NUMBER AND NO OTHER DATA CONCERNING THE EVENT OR ERROR WILL BE LOGGED.

THE FILE WHICH CONTAINS THE ERROR INFORMATION IS CONTAINED IN THE [SYSERR] DIRECTORY AND IS CALLED ERRLOG.SYS. WHEN RUNNING SYE.EXE THE FILE SHOULD BE RENAMED TO PREVENT VERSION NUMBERS FROM ACCUMULATING. ANY NEW ERRORS ENCOUNTERED BY ERRFMT.EXE WILL CAUSE A NEW ERRLOG.SYS TO BE CREATED.

TO RUN SYE.EXE

```
$ SET DEFAULT SYSSDISK:[SYSERR]

$ RENAME ERRLOG.SYS  ERRLOG.OLD/NEW_VERSION

$ DIR

$ RUN SYSSSYSTEM:SYE   or   $ MC SYE
```

THE PROGRAM WILL ASK SEVERAL QUESTIONS:

```
INPUT FILE?      (SPECIFY THE EXACT FILE TO BE COMPILED)
                  Example:  ERRLOG.OLD;23
                  Default:  ERRLOG.OLD

OUTPUT FILE?     (THIS WILL BE THE END RESULT OF SYE)
                  Example:  MYFILE.NEW
                  Default:  SYSSOUTPUT
                  LP WILL SEND OUTPUT TO A PRINTER
```

```
OPTIONS?          (SEVERAL OPTIONS ARE AVAILABLE:)
                   Default:  ROLL-UP
                   Options:  R       ROLL-UP
                             B       BRIEF
                             C       CRYPTIC
                             S       STANDARD
```

ROLL-UP — A QUICK SUMMARY OF ERRORS FOR EACH FAILING DEVICE WITH NO DETAILS ABOUT THE INDIVIDUAL ERRORS. THE TOTAL WILL EQUAL THE SUM OF HARDWARE AND SOFTWARE ERRORS.

BRIEF — CONTAINS A BRIEF DESCRIPTION ABOUT EACH ERROR INCLUDING:
A). TYPE OF ERROR
B). DEVICE OR COMPONENT WHICH CAUSED IT
C). A SEQUENCE NUMBER
D). A TIME WHEN THE ERROR WAS LOGGED

CRYPTIC — DEVICE AND CPU ERRORS ONLY. THE OUTPUT WILL CONTAIN THE CONTENTS OF ASSOCIATED REGISTERS WITH EVERY ERROR BUT NO EXPLANATION.

STANDARD — EVERY ERROR HAS AN ENTRY AND A COMPLETE BREAKDOWN OF REGISTERS AND A DESCRIPTION OF WHAT THE REGISTERS ARE.

```
DEVICE NAME?      (INDIVIDUAL DEVICE OR <CR> FOR ALL)
                  CP          CPU AND CMI
                  CO          CONFIGURATION CHANGES
                  ME          MEMORY AND ALERT
          DEVICES: SY         SYSTEM INFORMATION AND BUGCHECKS
                  DMAX        RK'S
                  DBAX        RP'S etc.
                  D           ALL DISK
                  M           ALL TAPES
                  MT
                  MF
                  UNKNOWN     UNKNOWN DEVICE ERRORS
```

YOU CAN ALSO USE A "-" TO DELETE CERTAIN DEVICES

```
Example: -D               EVERYTHING BUT DISKS
          -/CONFIG        EVERYTHING BUT MOUNTS AND DISMOUNTS

         AFTER DATE?      (DESIRED FIRST DATE OF ENTRY)

         BEFORE DATE?     (DESIRED LAST DATE OF ENTRY)

                 XX-YYY-19ZZ  XX:XX:XX.XX
               DAY MONTH YEAR    DELTA TIME IF DESIRED
Example:         11-SEP-1981  03:22:00.00
                           HRS MIN SEC 100ths
```

IF YOU DID NOT SPECIFY AN OUTPUT FILE OR DEVICE, THE SYE PROGRAM WILL INSTRUCT YOU TO ALIGN THE PAPER AND STRIKE RETURN.

IF YOU SPECIFIED AN OUTPUT FILE OR DEVICE, YOU SHOULD RECEIVE A SUCCESSFUL COMPLETION MESSAGE, AT THIS TIME YOU COULD PRINT OR TYPE THE OUTPUT FILE.

SDA

System Dump Analyzer (SDA) Procurement

This text is intended to demonstrate how to procure a SDA report after a system crash. It is not intended to demonstrate the interpretation of the SDA.

Now normally the crash dump file is contained within the [SYSEXE] directory located on the system disk.

Log in to SYSTEM MANAGER account.

Upon the advent of $ prompt, obtain a list of files contained within the directory [SYSEXE] The file that must be there is:

```
SYSDUMP.DMP
```

```
**********************************************************************
*                                                                    *
*                DO NOT RENAME THIS FILE                             *
*                                                                    *
**********************************************************************
```

Once you have ascertained that the file is present, then type:

```
$ MCR SDA
```

The standard response to that should be:

```
Enter name of the dump file>
```

The response to that statement is:

```
[SYSEXE]SYSDUMP.DMP
```

The response to typing [SYSEXE]SYSDUMP.DMP <CR>, is a brief description of the dump and then a SDA prompt:

```
SDA>
```

After the SDA> prompt, type in the following:

```
SDA> SET OUTPUT SDADUMP.xxx  (let xxx be your initials)
SDA> SHOW SUMMARY
SDA> SHOW CRASH
SDA> SHOW STACK
SDA> SHOW PROCESS
SDA> EXAMINE/PO
SDA> EXIT
```

The EXIT should have returned the you back to DCL.
Obtain a directory. This directory should contain a file SDADUMP.xxx (xxx should be your initials for file type)
Now all you have to do is obtain a hardcopy of the dump.

```
$ PRINT SDADUMP.xxx
```

You also can look at this file at your terminal:

```
$ TYPE SDADUMP.xxx
```

Bootstrap Process

BOOTSTRAP PROCESS

The following lists the steps required to obtain a running system on a VAX-11/750 processor:

1. Power up occurs.

2. The VAX-11/750 microcode detects power on and follows the power on strategy selected by the POWER-ON-ACTION switch located on the processor control panel.

   a. If a restart cannot be done, either an automatic bootstrap from the default bootstrap device or a halt will be done.

   b. If the machine halts, the microcode program gains control. This program:

      (1) Issues the console prompt (>>>) at the console terminal

      (2) Accepts interactive commands to bootstrap the system by means of the default bootstrap device or a user-specified bootstrap device

3. The microcode program looks up and executes the bootstrap device read-only memory (ROM). This ROM is 256 bytes and contains a main routine (at the entry) and a subroutine. The main routine reads block 0 from the bootstrap device and jumps to the boot block entry. The main routine and the boot block routine use the ROM subroutine to read arbitrary blocks from the bootstrap device into memory.

4. The boot block contains the logical block address, size, and entry offset of the program to be executed in the bootstrap process. This program can be either (1) stand-alone BOOT58, when the bootstrap device is the TU58 console drive, or (2) VMB.EXE, when the bootstrap device is the system disk.

   a. If the bootstrap operation is performed from the console TU58 tape cassette using stand-alone BOOT58, the user types BOOT58 commands to set up register input values and to load and start VMB.EXE.

   b. If the bootstrap operation is performed directly from the system disk using VMB.EXE, the microcode program derives the register input values.

5. VMB.EXE is the primary bootstrap program, which contains CPU-independent code and CPU-dependent routines. It also contains a set of primitive non-interrupt-driven drivers for

all possible system devices and a primitive file system for locating and reading Files-11 Structure Level 1 and Structure Level 2 files.

VMB.EXE performs the following steps:

a. Saves the register values and some values calculated from the register values in the restart parameter block (RPB).

b. Reads the system identification register to determine the processor type and to select the table of appropriate processor-dependent data and subroutines.

c. Determines the amount and pattern of memory. A page frame number (PFN) bitmap is constructed. Unless inhibited by a boot flag, memory is tested for gross, uncorrectable parity errors. VMB.EXE contructs, in the RPB, a table indexed by nexus number of all memory controller and I/O adapter types.

d. Based on register values, one of the following occurs:

   (1) A boot block at the designated logical block number (LBN) will be read into memory and given control.

   (2) A file named [SYSEXE]SYSBOOT.EXE will be read into memory and given control.

   (3) A file named [SYSMAINT]DIAGBOOT.EXE will be read into memory and given control.

   (4) A file specified by the user in response to a prompt will be read into memory and given control.

6. SYSBOOT is the standard secondary bootstrap program. It performs initialization suitable for the unmapped environment. SYSBOOT performs the following steps:

   a. Reads current parameter settings from SYS.EXE.

   b. Looks up the bootstrap device driver file and stores information about it.

   c. If register values so indicate, prompts the user to modify current system parameter settings. The user can change the start-up command procedure name and modify system parameters using SET or a previously created parameter file. New parameters become the "current" parameters on the next bootstrap operation.

   d. Sets up SPT, SYSPHD, SCB, and PFN data structures.

   e. Reads the resident executive into high physical memory.

   f. Locates and transfers to INIT code.

7. The system initialization process consists of four stages: INIT, SYSINIT, STARTUP.COM, and SYSTARTUP.COM.

   a. INIT is part of SYS.EXE. It performs the following:

      (1) Enables mapping and sets the PC to system space.

      (2) Prints the system announcement message

(3) If requested by means of the boot flag, stops at the XDELTA breakpoint.

(4) Initializes the system for paging.

(5) Deallocates available physical pages (PFN bitmap set up by VMB) to the free page list.

(6) Initializes the system page table for paged and nonpaged pools.

(7) Initializes I/O adapters using the list of present adapters generated by VMB.EXE. Initialization consists of mapping adapter register space (only the number of pages actually used are mapped) and calling adapter-specific routines to allocate and set up data structures and to initialize the adapter hardware. In addition, for UNIBUS adapters, the 8K byte I/O page of the UNIBUS is mapped.

Data structures allocated are:

MASSBUS -- adapter control block
channel request block
interrupt descriptor block

UNIBUS -- adapter control block

(8) Performs additional process initialization tasks.

(9) Transfers the primitive VMB.EXE system device driver into nonpaged pool; and saves the driver entry and boot device control/status register (CSR) as virtual addresses (rather than physical addresses) in the RPB.

(10) Loads the CPU-dependent code image into nonpaged pool and links it into the system.

(11) Loads the terminal handler into non-paged pool, and connects the interrupt vectors. Loads the driver image for the system device into nonpaged pool, connects its interrupt vector, and derives the name of the system disk. The rule for the system disk device name is as follows:

device name	Examine the primitive driver, where the device name is stored.
controller	The controller designator is "A," "B," or "C" for the first, second, or third occurrence of this kind of adapter. For example, if the adapter of the system device is the second MASSBUS, the controller is B. (Note that for a generally configured system, it is possible to use the AUTOCONFIGURE command procedure to derive the controller name incompatibly with INIT. Consequently, some care is required when configuring multiple controllers of possible system disks across multiple buses.)
unit	Passed from VMB.EXE input, register R3.

(12) Adds the prologues of the resident drivers (for example, MB, NL) to the prologue list.

(13) Performs initialization of resident drivers.

(14) Moves completion code of INIT into the pool and executes it. The completion code deallocates space occupied by INIT (and optionally XDELTA) to the free page list. The completion code then jumps to the scheduler, which ultimately results in SYSINIT being swapped in and started.

b. SYSINIT performs the following:

(1) If necessary or requested, prompts for the time of day.

(2) Writes back system parameters to SYS.EXE.

(3) Creates some logical names.

(4) Sets up swapping and paging files.

(5) Installs the VAX-11 RMS image and system message file as pageable system sections.

(6) Mounts the system disk (ACP process created).

(7) Creates the job controller, OPCOM, and ERRFMT.

(8) Creates the STARTUP process.

c. STARTUP reads input from the start-up command procedure, which causes it to:

(1) Create logical names.

(2) Run SYS$SYSTEM:SYSGEN to configure the I/O system.

(3) Install known images.

(4) Invoke [SYSMGR]SYSTARTUP.COM.

(5) Log out.

d. SYSTARTUP.COM is an empty command procedure distributed by DIGITAL. The system manager can edit SYSTARTUP.COM to perform site-specific start-up functions.

8. SYSGEN is run by STARTUP or at any other time. SYSGEN:

a. Provides for dynamic loading of and connecting to drivers. (The operator, null, and mailbox drivers are permanently part of the executive image.)

b. Provides for the creation of new parameter files (which have an encoded format).

c. Creates paging, swapping, and system dump files.

Instruction Decode

THIS IS AN ATTEMPT TO DEMONSTRATE THE FLOW OF A MACRO INSTRUCTION THROUGH THE 11/750 DATA PATHS.

INITIAL INPUT ARGUMENTS

```
>>>D/L/P 100 005261D0          MOVL (R1),R2
                               HALT

>>>D/G 1 1000                  SET UP ADDRESS OF 1000 IN R1

>>>D/L/P 1000 12345678         SOME DATA IN 1000

>>>S 100
```

AND WERE OFF... THE START COMMAND IS DECODED BY THE CONSOLE MICROCODE IN CCS AND WILL FIRST INITIALIZE THE MACHINE. WE KNOW THAT THE CPU WILL PERFORM AN XB FLUSH WHENEVER WE WRITE TO THE PC, AND SINCE WE SPECIFIED A NEW PC INSIDE THE START COMMAND, AN EXECUTION BUFFER FLUSH TAKES PLACE. AN XB FLUSH REMEMBER DOES NOT WRITE ALL ZERO'S TO THE XB'S! THAT WOULD BE SENSELESS.

ANY TIME THAT WE WRITE THE PC, THE PRK CHIP WILL PERFORM A DOUBLE PREFETCH OPERATION BY TAKING THE VALUE SPECIFIED IN THE PC AND PERFORMING A BUS READ FROM MEMORY. SINCE THIS FIRST PREFETCH HAS ONLY FILLED XB0, ANOTHER PREFETCH WILL OCCUR USING THE PC+4 AND THE I-STREAM DATA RETURNED WILL BE PUT IN XB1. NOW THAT WE HAVE THE XB'S FULL OF DATA, THE PRK WILL START MONITORING THE PC BITS 1:0 AND THE "XB SELECT" LINES FROM THE MDR CHIPS, AND THE BUT FIELD OF THE MICROCODE LOOKING FOR HIS TWO CONDITIONS TO BE MET.

1). IS THERE AN EMPTY XB? DETERMINED BY THE PC BITS <1:0> = 3
2). IS THERE A BUS CYCLE IN PROGRESS? MONITOR BUS FIELD

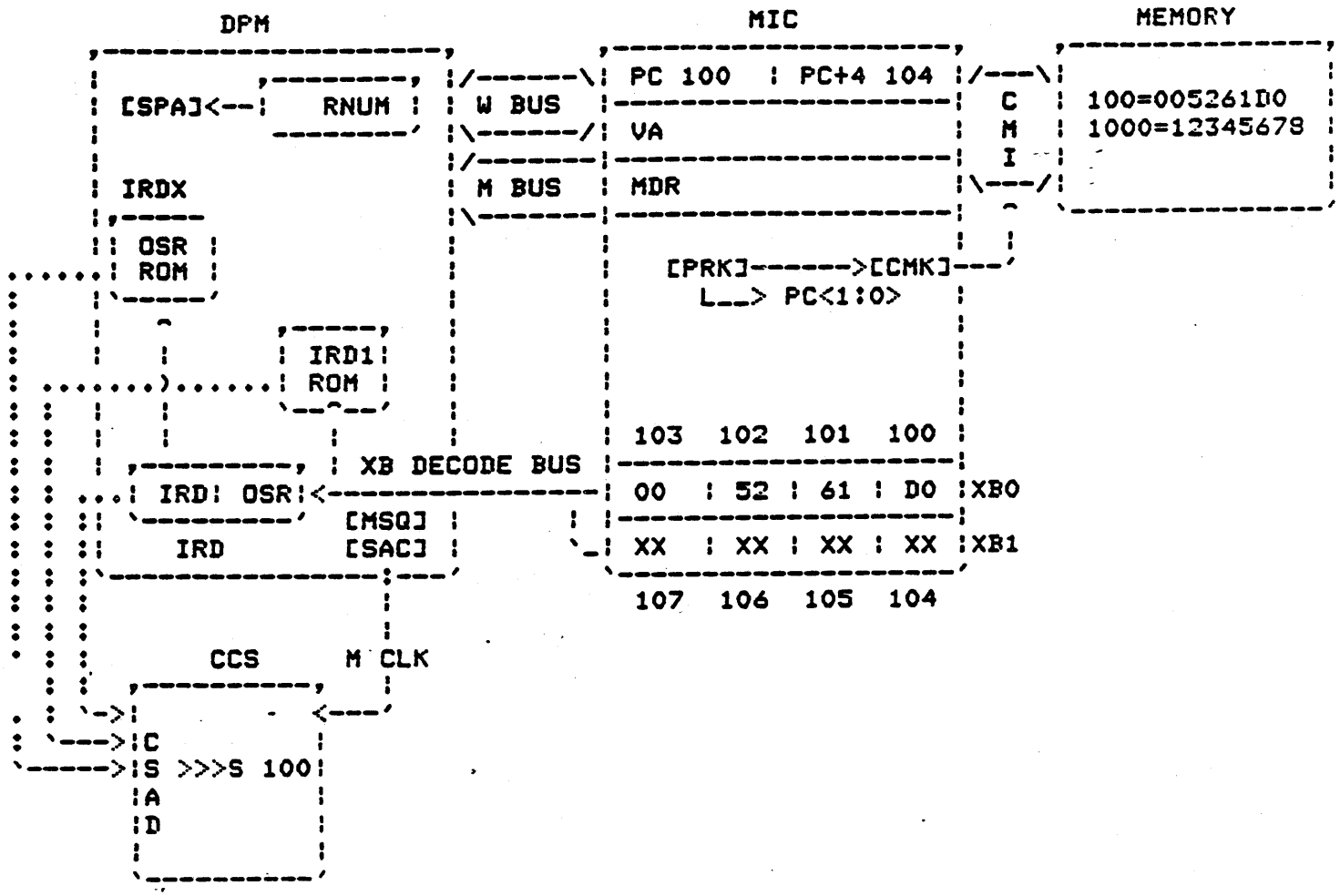
KEEP IN MIND THAT THE PRK IS WORKING TOTALY TRANSPARENT TO THE MICROCODE AND WILL INITIATE A PREFETCH WHENEVER IT'S CONDITIONS ARE MET OR THE PC GETS REPLACED BY THE USER OR THE USERS PROGRAM.

EXAMPLE: 2$:: BRB 2$ THIS BRANCH INSTRUCTION WOULD REPLACE THE PC WITH THE PC PLUS THE BRANCH OFFSET.

FINALLY AFTER THE FIRST XB WAS FILLED, THE MICROCODE ROUTINE FOR THE START COMMAND WILL DO AN IRD1 AND THE WHOLE MESS BEGINS...

I THINK A BLOCK DIAGRAM WOULD BE NICE RIGHT ABOUT NOW...

BLOCK NUMBER 1



LETS BEGIN... AFTER THE START COMMAND INITIALIZES THE MACHINE AND WRITES THE PC, THE MICROCODED BUT FIELD GETS AN IRD1.

PC	PC+4
100	104

1. IRD1 OCCURS

ON AN IRD1 WE KNOW THAT TWO BYTES OF I-STREAM DATA WILL BE SOURCED FROM ONE OF THE XB'S OVER THE DECODE BUS TO THE IRD GATE ARRAY. SOURCING THIS DATA, MOVES AN OPCODE AND THE FIRST OPERAND SPECIFIER INTO THE IRD CHIP, AND THE OPCODE IS ALSO SENT TO THE IRD1 ROM FOR DECODING. SINCE TWO BYTES WERE SOURCED, WE BUMP THE PC BY 2.

PC	PC+4
102	106

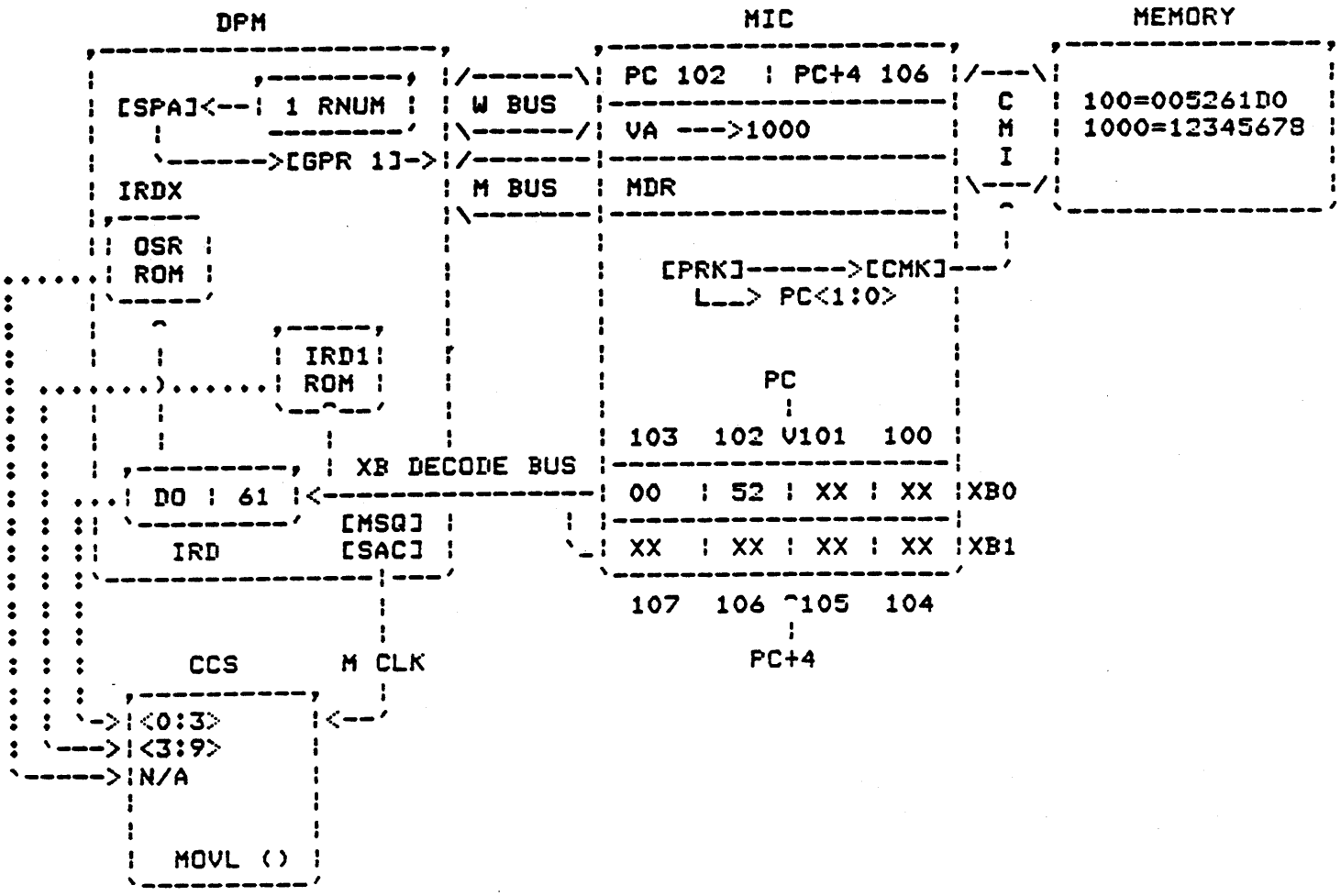
REFER TO BLOCK NUMBER 2

MICROWORD NUMBER 1

AT THIS TIME THE IRD1 ROM WILL LOOK AT THE OPCODE AND WHEN IT DECODES IT AS A MOVL INSTRUCTION, IT WILL OUTPUT BITS 3 THROUGH 9 OF THE BASE CONTROL STORE ADDRESS WHICH WHICH WILL TAKE US TO THE PROPER MICROCODE ROUTINE. ALSO AT THIS POINT THE IRD CHIP WILL EVALUATE THE 1st OPERAND SPECIFIER AND OUTPUT THE CONTROL STORE ADDRESS BITS 0 THROUGH 3 GIVING US A TOTAL CSAD FOR OUR MOVL INSTRUCTION IN REGISTER DEFFERRED MODE. THE IRD CHIP WILL OUTPUT THE ENCODED VALUE FOR GPR 1 INTO THE RNUM REGISTER.(OSR DECODE)
THE MDR WHICH CONTAINS GARBAGE WILL BE BACKED UP IN THE Q REGISTER.

*** SEE BLOCK NUMBER 2 ***

BLOCK NUMBER 2



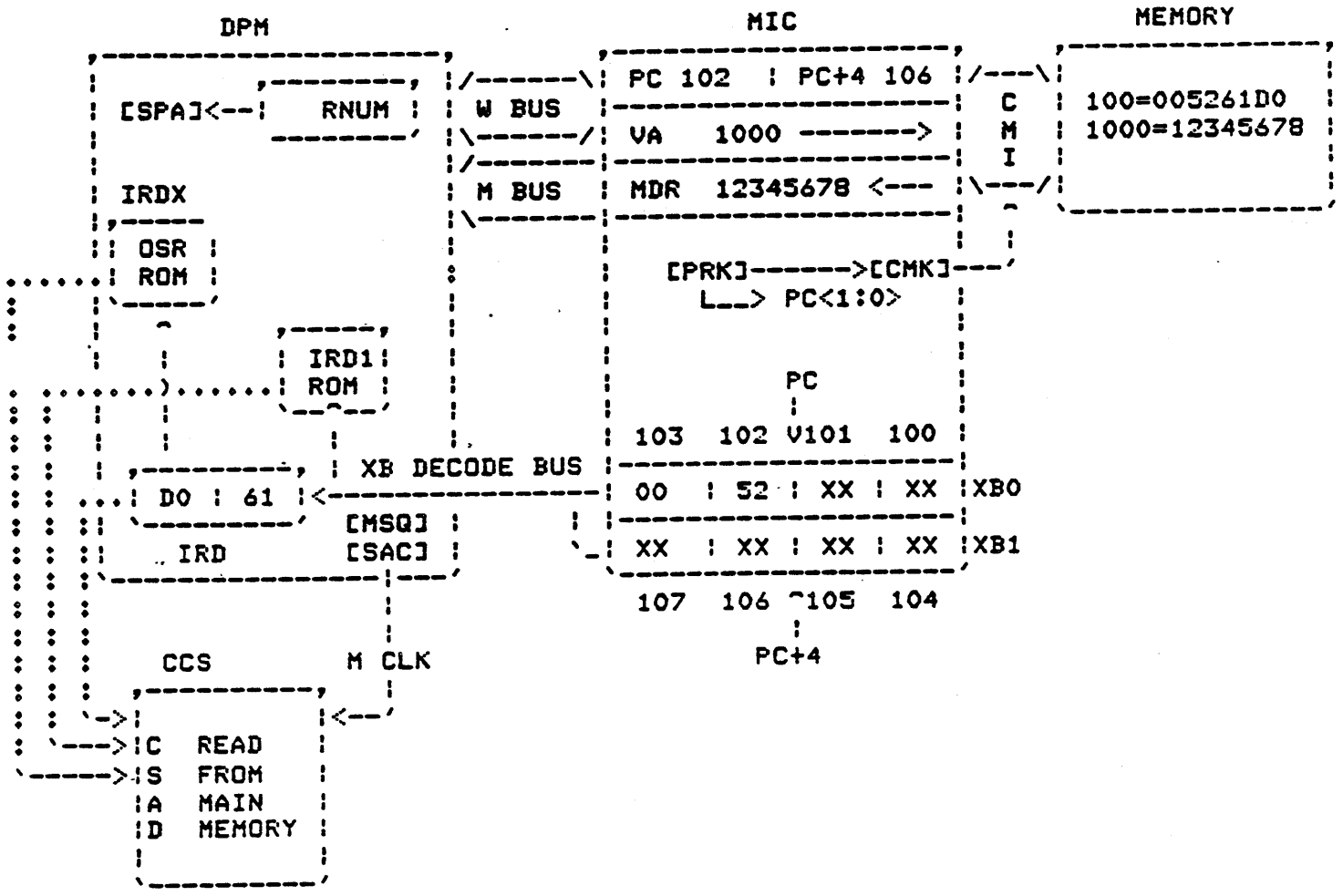
WHEN THE SPA GATE ARRAY SEE'S THE NUMBER IN RNUM, IT WILL SELECT THE CONTENTS OF R1 AND SEND IT OUT ONTO THE R BUS, THROUGH THE B LEG BYPASS OF THE ALU AND OUT ON THE W BUS. THE MICROWORD WILL SET UP THE VA REGISTER TO RECIEVE THE W BUS (WHICH IS CARRYING OUR ADDRESS OF 1000).

MICROWORD NUMBER 2

THE SECOND MICROWORD WILL CAUSE A BUS READ CYCLE TO OCCUR FROM MAIN MEMORY INTO THE MDR.

*** SEE BLOCK NUMBER 3 ***

BLOCK NUMBER 3



NOW THAT WE HAVE OUR DATA IN THE MDR, WE NEED SOMEPLACE TO PUT IT. NO MORE CAN BE DONE WITH THE 1st OPERAND, SO THE MICROCODE ROUTINE WILL DO AN IRDX TO BRING IN THE 2nd OPERAND.

AN IRDX WILL SOURCE ONE BYTE FROM THE XB INTO THE IRD CHIP AND ALSO BUMP THE PC BY 1.

PC	PC+4
103	107

IRDX

MICROWORD NUMBER 3

WHEN THE OPERAND HITS THE IRD CHIP IT WILL BE DECODED TO FIND OUT IF REGISTER MODE IS USED AND WHICH REGISTER TO GIVE RNUM IF NEEDED. THE IRD CHIP WILL SEND THE OPCODE TO THE IRDX ROMS TO SUPPLY AN ADDRESS

THE IRDX (OSR) ROM WANTS TO KNOW TWO THINGS:

1. WHAT OP CODE IS IT? FOR A PARTIAL ADDRESS INTO THE ROM.

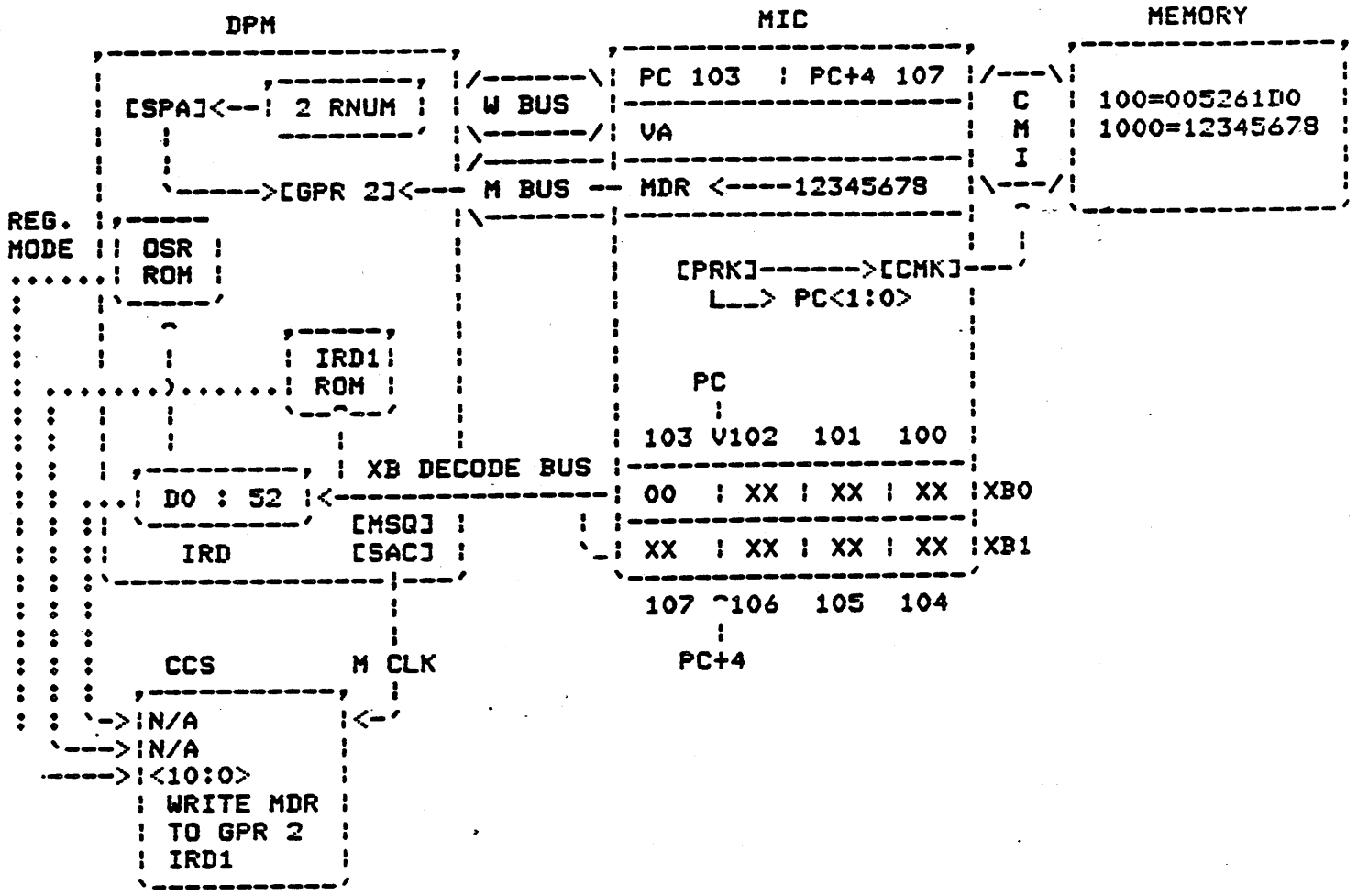
2). WHAT MODE ARE WE IN? REGISTER MODE DETERMINED BY THE UPPER 4 BITS OF THE OPERAND SPECIFIER FROM THE IRD CHIP.

AT THIS TIME THE IRDX ROM WILL OUTPUT AN ADDRESS THAT WILL PLACE US IN THE MICROCODE TO HANDLE THE NEEDED OPERAND SPECIFIER.

THE ENCODED VALUE FOR GPR 2 IS SENT TO THE RNUM REGISTER AND LIKE BEFORE, THE SPA SELECTS THAT REGISTER BUT THIS TIME WE WILL BE WRITING INTO IT.
THE CONTENTS OF THE MDR WILL BE SENT ACROSS THE M BUS, THROUGH THE ALP CHIPS AND ONTO THE WBUS TO BE WRITTEN INTO THE SELECTED GPR AND THE MICRO ROUTINE WILL END UP WITH ANOTHER IRD1 FOR THE NEXT INSTRUCTION.

*** SEE BLOCK NUMBER 4 ***

BLOCK NUMBER 4

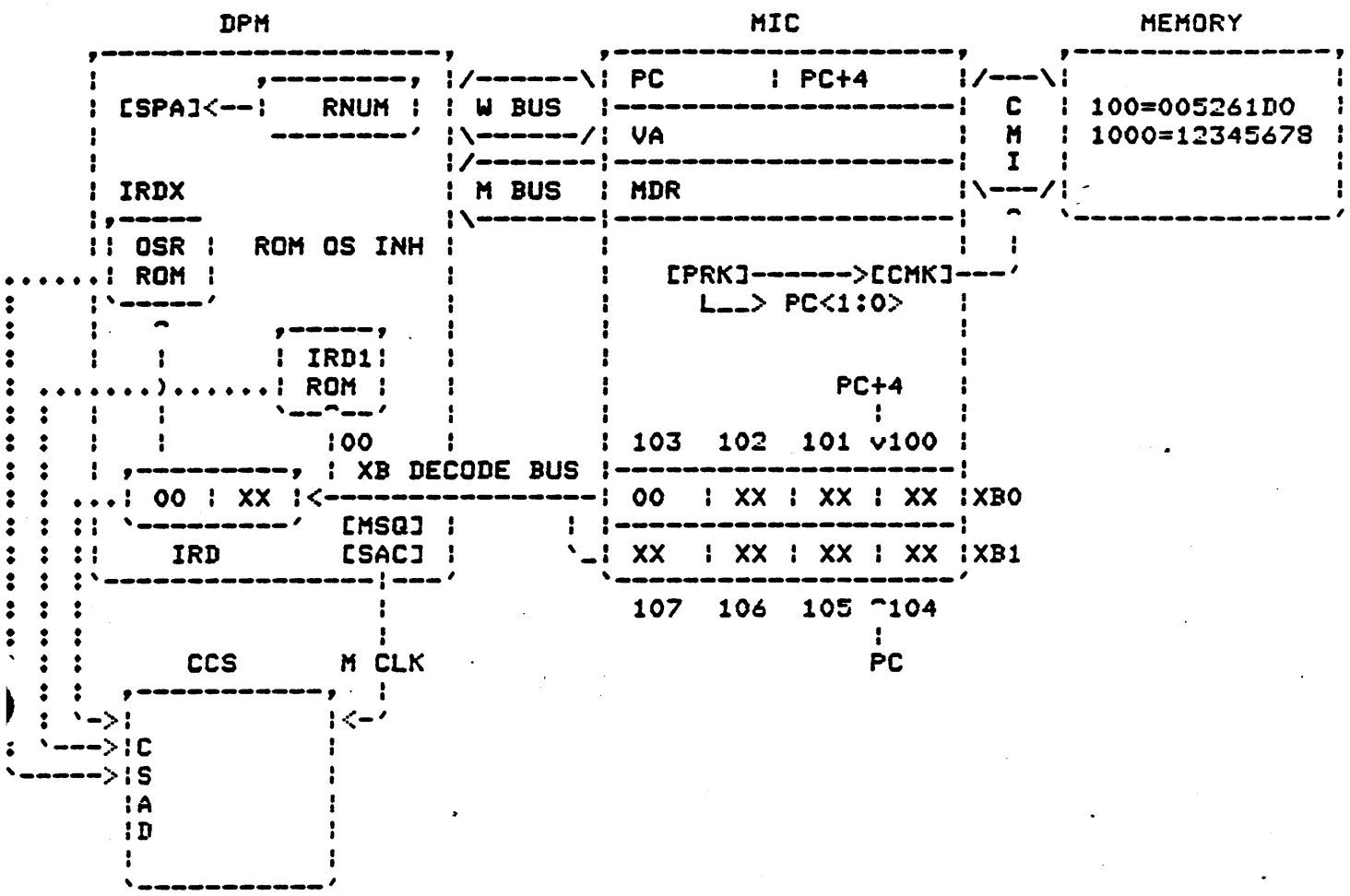


HAVING JUST FINISHED THE MOVL INSTRUCTION, THE MICROCODE ROUTINE LEFT US WITH ANOTHER IRD1. AS BEFORE AN IRD1 WILL SOURCE TWO MORE BYTES OF I-STREAM DATA OVER THE XB DECODE BUS, INTO THE IRD CHIP AND ALSO UP TO THE IRD1 ROM. AS BEFORE THE PC WILL BE BUMPED BY 2.

PC	PC+4
105	109

*** SEE BLOCK NUMBER 5 ***

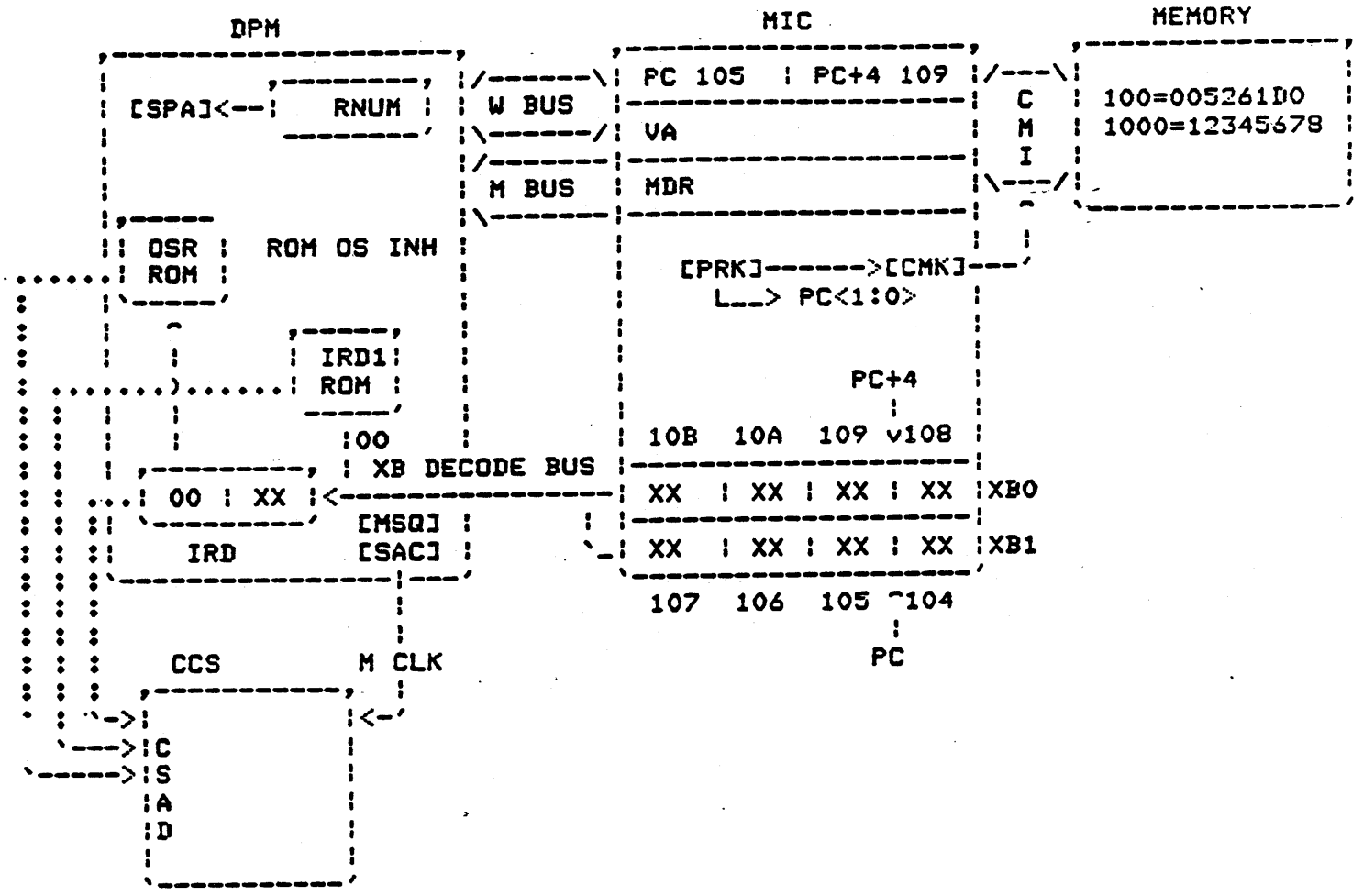
BLOCK NUMBER 5



NOTICE WHAT HAPPENED TO THE PC AND PC+4... THE PC HAS BEEN BUMPED TO 105 WHICH TELLS THE PRK CHIP THAT WE HAVE USED ALL THE DATA IN XB0. A PREFETCH CYCLE WILL OCCUR USING THE PC+4 AS OUR ADDRESS TO FETCH DATA FROM MAIN MEMORY. IF WE SEND THE ADDRESS OF 109 OVER THE CMI WE WILL GET BACK THE LONGWORD ADDRESS CONTAINING 109. THIS IS DUE TO THE FACT THAT THE CMI IGNORES BITS 0 AND 1 OF THE ADDRESS THUS GIVING US A LONGWORD ADDRESS OF 108 WHICH IS EXACTLY WHAT WE WANT.

*** SEE BLOCK NUMBER 6 ***

BLOCK NUMBER 6



EXECUTION OF THE NEW INSTRUCTION TAKES PLACE SIMUTANIOUSLY WITH THE PREFETCH, BUT NOTICE WHAT INSTRUCTION WE ARE USING... IT IS A HALT INSTRUCTION. WE KNOW THAT A HALT INSTRUCTION HAS NO OPERANDS ONLY AN OPCODE, THEREFORE SOMETHING MUST BE DONE TO PREVENT THE IRD CHIP FROM EVALUATING THE SECOND BYTE AS A 1st OPERAND SPECIFIER. WHAT HAPPENS IS WHEN THE IRD1 ROMS DECODE THE HALT OPCODE, (OR ANY ONE BYTE INSTRUCTION) A SIGNAL NAMED 'ROM OS INHIBIT' IS OUTPUTED FROM THE ROM ITSELF AND SENT TO THE MSQ AND SAC CHIPS WHERE IT DISABLES ANOTHER SIGNAL CALLED 'LOD OSR A' WHICH WILL PREVENT THE UPDATING OF THE OSR COUNTER. THE SAME SIGNAL TELLS THE SAC CHIP TO TELL THE PHB CHIP NOT TO GENERATE THE SIGNAL 'IRD LOD RNUM' WHICH WILL PREVENT THE SPA CHIP FROM LOOKING AT RNUM, AND FINNALY THE 'LOD OSR A' SIGNAL TELLS THE IRD CHIP NOT TO DECODE THE DATA ON THE OSR SECTION OF XB DECODE AS IT IS NOT REALLY AN OPERAND.

THE HALT MICROCODE FLOW WILL NOW TEST THE CURRENT MODE TO SEE IF WE ARE IN KERNAL MODE AS YOU MUST BE TO HALT THE CPU.

ASSUMING THAT WE ARE IN KERNAL MODE, THE MICROCODE ROUTINE WILL ...

1). SET UP A HALT CODE OF 06 IN A TEMPORARY REGISTER
2). ADD 1 TO THE CURRENT PC GIVING US PC=106 AND PC+4=10A
3). VARIOUS OTHER TASKS REQUIRED TO SHUTDOWN THE CPU
4). AND FINALLY SEND THE PC TO THE PRINT ROUTINE

THE MICROCODE PRINT ROUTINE WILL ALWAYS SUBTRACT 2 FROM ANY GIVEN PC BEFORE ACTUALLY SENDING IT TO THE CONSOLE.

```
PC= 106          00000104 06
  -   2          >>>
    ---
    104
```

THIS LEAVES US AT A PC OF 104 WHICH IS ONE BYTE AHEAD OF THE ACTUAL OPCODE OF THE HALT INSTRUCTION.

THE REASON FOR THIS IS BECAUSE NOW WE CAN SIMPLY TYPE...

```
>>> C
```

AND CONTINUE ON WITH THE NEXT OPCODE FOLLOWING THE HALT INSTRUCTION.

ONE FINAL NOTE: DURING EXECUTION OF MACRO INSTRUCTIONS, IF ANY GIVEN INSTRUCTION BLOWS UP AFTER BEING DECODED ON AN IRD1, THE PC WOULD HAVE ALREADY BEEN UPDATED BY 2... SO THE PRINT ROUTINE CALLED IF WE WERE TO HALT THE CPU, WOULD SUBTRACT 2 FROM THE PC GIVING US THE CORRECT OPCODE ADDRESS OF THE FAILING INSTRUCTION.

THIS ALSO CLARIFIES WHY WE HAVE TO ADD 2 TO A MICRO-VERIFY ERROR HALT TO GET THE CORRECT FAILURE CODE. THE MICRO-VERIFY ROUTINE IS RESIDENT IN SCS ROM AND IS NOT A MACRO PROGRAM AT ALL! THUS IT DOES NOT UPDATE THE PC IN ANY WAY, BUT IT STILL USES THE SAME PRINT ROUTINE FOR THE ERROR DISPLAY.

THINK YOU'VE GOT THAT DOWN??? NOW TRY TO EXPLAIN IT TO A CLASS FULL OF BEWILDERED ENGINEERS!!!

GOOD LUCK.

Machine and Bugchecks

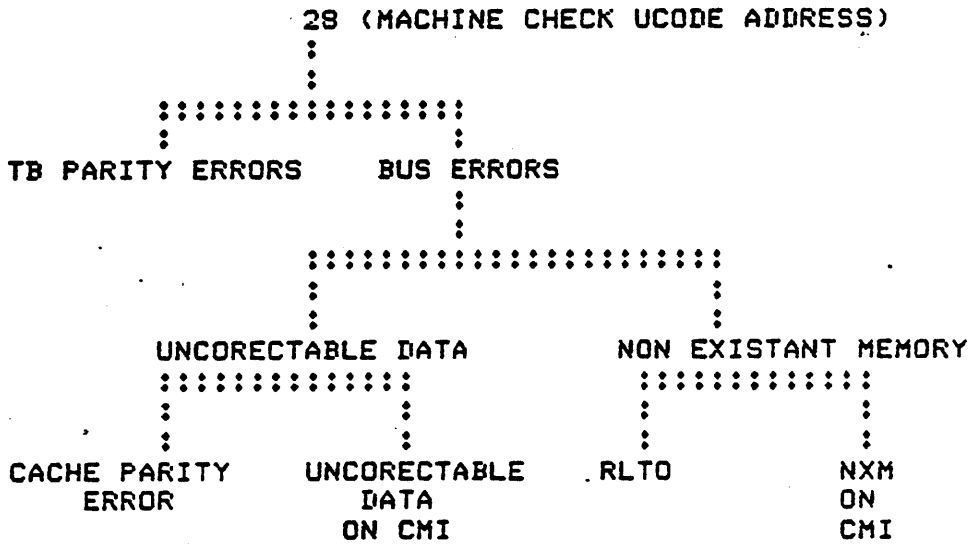
11/750 MACHINE CHECK INTERPRETATION

TO HELP ALIVIATE ANY PROBLEMS HAVING TO DO WITH MACHINE CHECKS IN THE 11/750 BELOW IS AN EXPLANATION OF WHY AND HOW THEY OCCUR ALONG WITH AN EXPLANATION OF HOW TO READ THE MACHINE CHECK LOGOUT.

A MACHINE CHECK IS A UTRAP TO LOCATION 28 IN THE MICROCODE. THIS IS CAUSED ONLY BY TWO CONDITIONS WITHIN THE LOGIC OF THE UTR CHIP. THESE CONDITIONS ARE AS FOLLOWS;

1. TRANSLATION BUFFER PARITIY ERRORS IN DATA OR TAG
2. BUS ERROR

THIS SOUNDS EASY BUT WHAT CAN CAUSE A BUS ERROR IS THE PROBLEM. PLEASE LOOK AT THE FOLLOWING CHART AND READ THE EXPLANATION BELOW IT.



WE WILL USE THE ABOVE CHART TO INTERPERT THE MACHINE CHECK LOGOUT THAT IS ON PAGE 25 IN THE VAX 11/750 DIAGNOSTIC MINI REFERENCE GUIDE. ATTACHED TO THIS SHEET IS A COPY OF THE LOGOUT AND A BREAKOUT OF THE NEEDED REGISTERS IF YOU HAVE NO MINI REFERENCE GUIDE.

WE NEED TO CORRECT ONE AREA OF THE LOGOUT IN THE MINI REF. GUIDE BEFORE WE GO ON. AT LOCATION (SP)+28 IT SHOULD READ MACHINE CHECK ERROR SUMMARY REGISTER AND NOT MEMORY CONTROL REGISTER.

ALL RIGHT WE ARE OFF!!!! WHAT YOU SEE IN THE LOGOUT IS WHAT IS PUSHED ONTO THE STACK WHEN A MACHINE CHECK OCCURS WHILE NORMAL RUNNING OF VMS "AFTER" THE VECTOR ADDRESS IS BROUGHT IN IN FROM SCBB+4 AND THE VECTOR BITS 0 AND 1 ARE CHECKED. WE WILL ATTACK THE STACK DUMP FROM TWO AREAS;

1. INFORMATION RELATING TO LOCATION OF FAULT (PC ETC)

2. CAUSE OF THE FAULT.

LOCATION : AT (SP)+8 IS THE VIRTUAL ADDRESS REGISTER. THIS REGISTER IS USED TO FETCH THE OPERAND DATA NEEDED BY THE INSTRUCTION. SO IT CONTAINS THE OPERAND ADDRESS IF THE MACHINE CHECK OCCURRED WHILE FETCHING OPERAND DATA.

AT (SP)+C IS THE PC AT THE TIME OF THE EXCEPTION. THIS MAY BE USED WITH (SP)+2C WHICH IS THE ADDRESS OF THE OPCODE OF THE FAILING INSTRUCTION. EX: IF YOU ARE PREFETCHING AND USE AN INSTRUCTION AT ADDRESS 1000 AND THAT INSTRUCTION HAS 5 OPERAND SPECIFIERS THE ADDRESS OF THE OPCODE +2 IS STORED IN THE PC BACKUP REGISTER UNTIL THE NEXT OPCODE IS USED.(IRD1 TIME) AS YOU USE THE 5 OPERANDS IN THE INSTRUCTION THE PC (NOT PC BACKUP) IS INCREMENTED TO KEEP TRACK OF EXECUTION BUFFER USAGE. SO IF WE HAVE A MACHINE CHECK INVOLVED WITH EXECUTION BUFFER DATA, WE HAVE PUSHED ONTO THE STACK THE ACTUAL PC (SP+C) AND THE OPCODE OF THE INSTRUCTION (SP+2C).

AT (SP)+30 WE HAVE THE STANDARD PSL.

CAUSE: WE SHOULD FIRST LOOK AT THE SUMMARY PARAMETER CODE AT (SP)+4. GENERALLY SPEAKING YOU WILL ONLY HAVE NUMBERS 1,2,6 OR 7. 1,6 AND 7 ARE BASICALLY THE SAME THING. THESE MEAN A CONTROL STORE PARITY ERROR OCCURRED OR SOMEHOW THE MACHINE WAS SENT TO AN UNUSED IRD OR UNKNOWN ROM LOCATION. THIS COULD HAPPEN FOR A FEW REASONS, OF WHICH THE MOST LOGICAL IS THAT YOU HAVE A BAD CONTROL STORE, BAD MICROSEQUENCER ON THE DPM OR A BAD IRD DECODE ON THE DPM.

THE MOST COMMON AND HARDEST TO FIGURE OUT IS THE CODE OF 2. THIS RELATES TO MEMORY ERROR,TB PARITY TIMEOUT ETC. YOU LIKE THAT ETC. DO YOU. WELL LETS TAKE THE CONFUSION OUT OF THE STATEMENT. IF YOU EVER SEE A 2 FOR A SUMMARY PARAMETER CODE THE FIRST THING YOU SHOULD LOOK AT IS THE MACHINE CHECK ERROR SUMMARY REGISTER;(SP)+28. YOU CAN RELATE THIS REGISTER(MCESR) TO THE ABOVE CHART BECAUSE IT WILL TELL YOU WHAT CAUSED YOU TO GET TO UCODE ADDRESS 28. FIND THE BREAKOUT OF THE MCESR (PAGE 28 IN MINI REF.GUIDE) AND YOU WILL SEE A FOUR BIT REGISTER. LET US MAKE THE NEEDED CHANGE. THERE IS NO LONGER AN UNALIGNED UNIBUS REFERENCE THAT CAUSES A MACHINE CHECK, SO CROSS IT OFF. BIT 0 WILL TELL YOU IF THE MACHINE CHECK OCCURED WHILE DOING A PREFETCH OR OPERAND FETCH.(THIS MAY HELP YOU TO FIGURE ON USING THE VA OR PC FOR LOCATION)

IF BIT 0=0 THEN AN OPERAND FETCH WAS HAPPENING
IF BIT 0=1 THEN A PREFETCH OF AN INSTRUCTION CAUSED IT.

BITS 2 AND 3 WILL TELL YOU IF IT WAS A TB ERROR OR BUS ERROR AS AN EXAMPLE WE WILL USE THE TB ERROR FIRST.

TB PARITY ERROR WHILE FETCHING AN OPERAND WOULD CAUSE THE REGISTER TO LOOK LIKE THIS WHEN PUSHED ON THE STACK

00000004 BIT 2 SET AND 0 CLEAR.

IF A TB ERROR OCURRED WHILE PREFETCHING IT WOULD BE AS FOLLOWS;

00000005 BIT 2 SET AND 0 SET.

EITHER WAY IF IT IS A TB ERROR YOU SHOULD THEN LOOK AT(SP)+1C OR THE TRANSLATION GROUP REGISTER. THIS WILL TELL YOU WHICH GROUP (0 OR 1) AND IF IT WAS A TAG OR DATA ERROR.

YOU MAY ALSO LOOK AT (SP)+14 WHICH IS THE SAVED MODE REGISTER. THIS WILL TELL YOU THE PROCESSOR ACCESS MODE AND MEMORY MANAGEMENT STATES DURING THE LAST MICROCODE REFERENCE TO MEMORY.

FROM THIS YOU SHOULD KNOW WHAT CAUSED THE MACHINE CHECK AND THE LOCATION.

LET US RETURN TO THE MCESR AND ASSUME IT LOOKED LIKE THIS;

00000008 BIT 3 SET 0 CLEAR

THIS WOULD MEAN A BUS ERROR HAPPENED DURING AN OPERAND FETCH.

IF YOU LOOK AT THE CHART YOU WILL FIND THERE ARE TWO THINGS THAT CAN CAUSE A BUS ERROR. TO FIND OUT WHICH ONE IT WAS LOOK AT (SP)+24 THE BUS ERROR REGISTER. THE BUS ERROR REGISTER IS A FOUR BIT REGISTER IN THE MEMORY INTERCONNECT MODULE SLOT THREE.(NOT THE MEMORY CONTROLLER) THE EXAMPLE WE WILL USE FIRST IS UNCORECTABLE DATA CAUSED THE BUS ERROR.

THE BUS ERROR REG. WOULD LOOK LIKE THIS;

00000004

THIS SAYS UNCORECTABLE DATA CAUSED THE ERROR, THERE WERE NO LOST ERRORS(RECEIVED AN OTHER ERROR BEFORE THE LAST ONE WAS CLEARED)

!!!!CORRECTED READ DATA DID NOT OCCUR. CORRECTED READ DATA CAUSES AN INTERRUPT NOT A MACHINE CHECK!!!

IF YOU LOOK AT THE CHART YOU WILL FIND THAT UNCORRECTABLE DATA CAN BE CAUSED BY TWO THINGS;

1. CACHE PARITY ERROR

2. UNCORECTABLE DATA FROM THE CMI

TO DETERMINE WHICH OF THESE CAUSED THE BUS ERROR LOOK AT (SP)+20 WHICH IS THE CACHE ERROR REGISTER. THIS REGISTER CONTAINS INFORMATION ON THE DATA CACHE. IT IS A FOUR BIT REGISTER ON THE MIC MODULE THAT WILL TELL YOU IF THE LAST REFERENCE WAS A HIT; LOST ERROR AGAIN AS BEFORE AND IF YOU HAD A CACHE PARITY ERROR. IF THERE WAS NO CACHE PARITY ERROR SET IN THE REGISTER THEN THE BUS ERROR WAS CAUSED BY THE UNCORRECTABLE DATA FROM THE CMI.

SO; CONTINUING RIGHT ON LET US ASSUME THAT THE BUS ERROR WAS CAUSED BY A NON EXISTANT MEMORY. AS YOU CAN SEE BY THE CHART THAT TWO THINGS CAN CAUSE NXM. FIRST LETS LOOK AT THE BUS ERROR REGISTER. IT EQUALS;

00000008 BIT 3 SET = NXM

THEN WE WOULD LOOK AT THE READ LOCK TIME OUT REGISTER (RLTO) THIS IS A ONE BIT REGISTER THAT IF BIT 0 IS SET A READ LOCK TIME OUT CAUSED THE NXM. WHAT IS A READ LOCK TIME OUT? GOOD QUESTION. IF THE CPU ATTEMPTS TO ACCESS THE CMI DURING A READ LOCK CONDITION A TIMER IS STARTED IN THE CMK GATE ARRAY ON THE MIC MODULE. IF THE TIMER RUNS FOR 64 USEC (USEC IS CORRECT) THEN THE CMK CHIP GENERATES NXM TO THE UTRAP CHIP THAT WILL CAUSE A MACHINE CHECK. IF BIT 0 IS CLEAR IN THIS REGISTER AND THE BUS ERROR REGISTER SAYS A NXM CAUSED THE MACHINE CHECK THEN IT WAS CAUSED BY NXM ON THE CMI.

THE ONLY THING THAT WAS PUSHED ONTO THE STACK THAT WE HAVE NOT TALKED ABOUT IS (SP)+10, THE MEMORY DATA REGISTER (MDR). THIS WILL CONTAIN THE LAST DATA FETCHED FROM CACHE OR MAIN MEMORY.

HOPEFULLY THIS EXPANATION, CHART AND HANDOUT WILL CLEAR UP SOME MISCONCEPTIONS CONCERNING THE 11/750 MACHINE CHECK.

GENERAL 11/750 MICROCODE FLOW FOR A MACHINE CHECK

1. MACHINE CHECK EXCEPTION CONDITION OCCURS

THE VARIOUS TYPES ARE AS FOLLOWS:

A. BUS ERROR:----> NXM OFF CMI FROM: ----> CMC MODULE
(NON EXISTANT MEMORY) (MEMORY CONTROLLER)

---> UBI MODULE
(UNIBUS INTERFACE)

---> MBA MODULE
(MASBUSS ADAPTER)

---> UCE ----------> UCE FROM CMC
(UNCORRECTABLE ERROR) (OR OTHER DEVICE)

----> CACHE PARITY ERROR

---> RLTO
(READ LOCK TIME OUT)

B. TB ERROR:-----> TRANSLATION BUFFER TAG PARITY ERROR

---> TRANSLATION BUFFER DATA PARITY ERROR

THE TWO CATEGORIES OF MACHINE CHECK CONDITIONS CAN BE BROKEN DOWN INTO TWO MORE GROUPS:

A. SOURCING DATA FROM I-STREAM:--> MSRC XB TB ERROR

SEE NOTE

```
**********************************
* TRANSLATION BUFFER ERROR       *
* ENCOUNTERED WHEN SOURCING      *
* THE BAD DATA FROM THE          *
* EXECUTION BUFFER               *
**********************************
```

---> MSRC XB BUS ERROR

```
**********************************
* BUS ERROR ENCOUNTERED          *
* WHEN SOURCING THE BAD DATA     *
* FROM THE EXECUTION BUFFER      *
**********************************
```

NOTE: WHEN A TB OR BUS ERROR OCCURS DURING A PREFETCH, THE ERROR IS IGNORED UNTIL WE ATTEMPT TO SOURCE THE BAD DATA FROM THE EXECUTION BUFFER. THIS IS TO PREVENT UNNECCESSARY ERROR HANDLING OF DATA THAT MIGHT NOT GET USED ANYWAY.
THE DATA IN THE XB IS NOT ALWAYS THE RIGHT DATA TO BE EXECUTED, FOR EXAMPLE: IF THE CURRENTLY EXECUTING INSTRUCTION IS A BRANCHING INSTRUCTION IT WILL MODIFY THE PC THUS CAUSING AN EXECUTION BUFFER FLUSH WHICH CLEARS OUT THE XB AND FILLS IT WITH THE DATA FROM THE NEW PC AND PC+4.

8. ERROR DURING INSTRUCTION DECODE:----->BUT XB TB ERROR
   (IRD1/IRDX)
   ```
   ****************************
   * TB ERROR ENCOUNTERED     *
   * DURING AN IRD1 OR IRDX   *
   ****************************
   ```
   --->BUT XB BUS ERROR
   ```
   ****************************
   * BUS ERROR ENCOUNTERED    *
   * DURING AN IRD1 OR IRDX   *
   ****************************
   ```

2. MSQ, UTR AND SAC CHIPS SET UP A MICRO VECTOR OF 0028 AT THE OUTPUT OF THE MICROSEQUENCER, SENDING US TO THE PROPER MICRO ADDRESS AND THE MACHINE CHECK MICRO ROUTINE SETS UP OUR SCBB+4 AND BUILDS THE STACK.

3. SCBB+4 CONTAINS OUR MACRO VECTOR ADDRESS

4. USE THE LOWER TWO BITS TO SELECT A STACK:

VECTOR BITS <1>	<0>	
0	0	> USE KERNAL STACK UNLESS <IS> BIT IS SET IN PSL
0	1	> USE INTERUPT STACK
1	0	> TRAP TO WCS ADDRESS 2001 IF WCS IS NOT PRESENT, TRAP TO 0001 IN CCS
1	1	> HALT AT VECTOR PC POINTS TO INTERUPTED OR FAULTED INSTRUCTION.

```
00000000 07
>>>
```

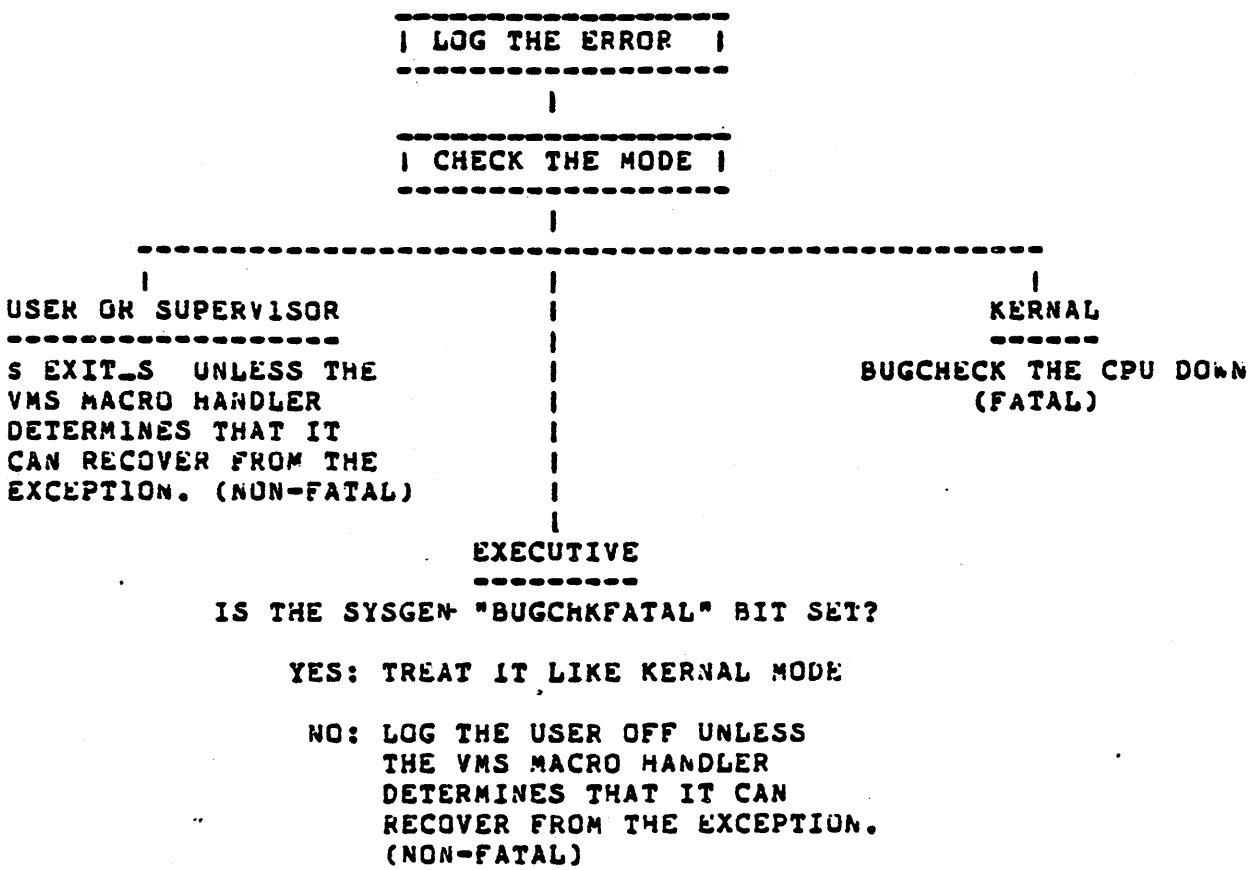
5. PUSH PSL, PC AND 11 OTHER LONGWORDS OF INFORMATION ON STACK.

6. LOWER TWO BITS OF VECTOR GET ZEROS WHEN CROSSING CMI ON ADDRESS CYCLE. THE ADDRESS POINTED TO BY THE VECTOR WILL BE THE START OF THE MACRO MACHINE CHECK HANDLER ROUTINE.

7. IRD1 OF MACRO ROUTINE TAKES PLACE.

GENERAL MACHINE CHECK MACRO FLOW

A MACHINE CHECK CAN BE HANDLED MANY DIFFERENT WAYS DEPENDING ON CERTAIN SYSGEN PARAMETERS AND THE CURRENT MODE OF OPERATION WHEN THE EXCEPTION OCCURRED. THE FOLLOWING CHART IS DESIGNED TO SHOW ONLY THE OVERALL SYSTEM RESPONSE TO A MACHINE CHECK.



IF THE MACHINE CHECK TURNS INTO A BUGCHECK, IT WILL HAVE THE FOLLOWING RESULTS:

	FATAL BUGCHECK CODE	NON-FATAL BUGCHECK CODE	
		BUGCHKFATAL BIT SET	BUGCHKFATAL BIT CLEAR
KERNAL MODE	SHUTDOWN THE CPU	LOG THE ERROR SHUTDOWN THE CPU	LOG THE ERROR THEN REI
EXECUTIVE MODE			

	PROCESS HAS BUGCHECK PRIV.	PROCESS DOES NOT HAVE BUGCHECK PRIV.	
SUPERVISOR MODE	LOG THE ERROR THEN SEXIT_S	DO NOT LOG THE ERROR BUT SEXIT_S	DISMISS THE ERROR THEN REI
USER MODE			

BUGCHECKS

A BUGCHECK is an internal inconsistency within a process or VMS, :n as a corrupted data structure or unexpected exception, detected by .S. Bugchecks can be the result of programming errors or hardware failures. Software related Bugchecks can be quickly isolated from the information saved in the system dump file on a system crash and from source listings. Hardware related Bugchecks are not so easy to isolate because the hardware failure can occur long before VMS detects it. Later on we will look at how to troubleshoot some of the common Bugcheck failures.

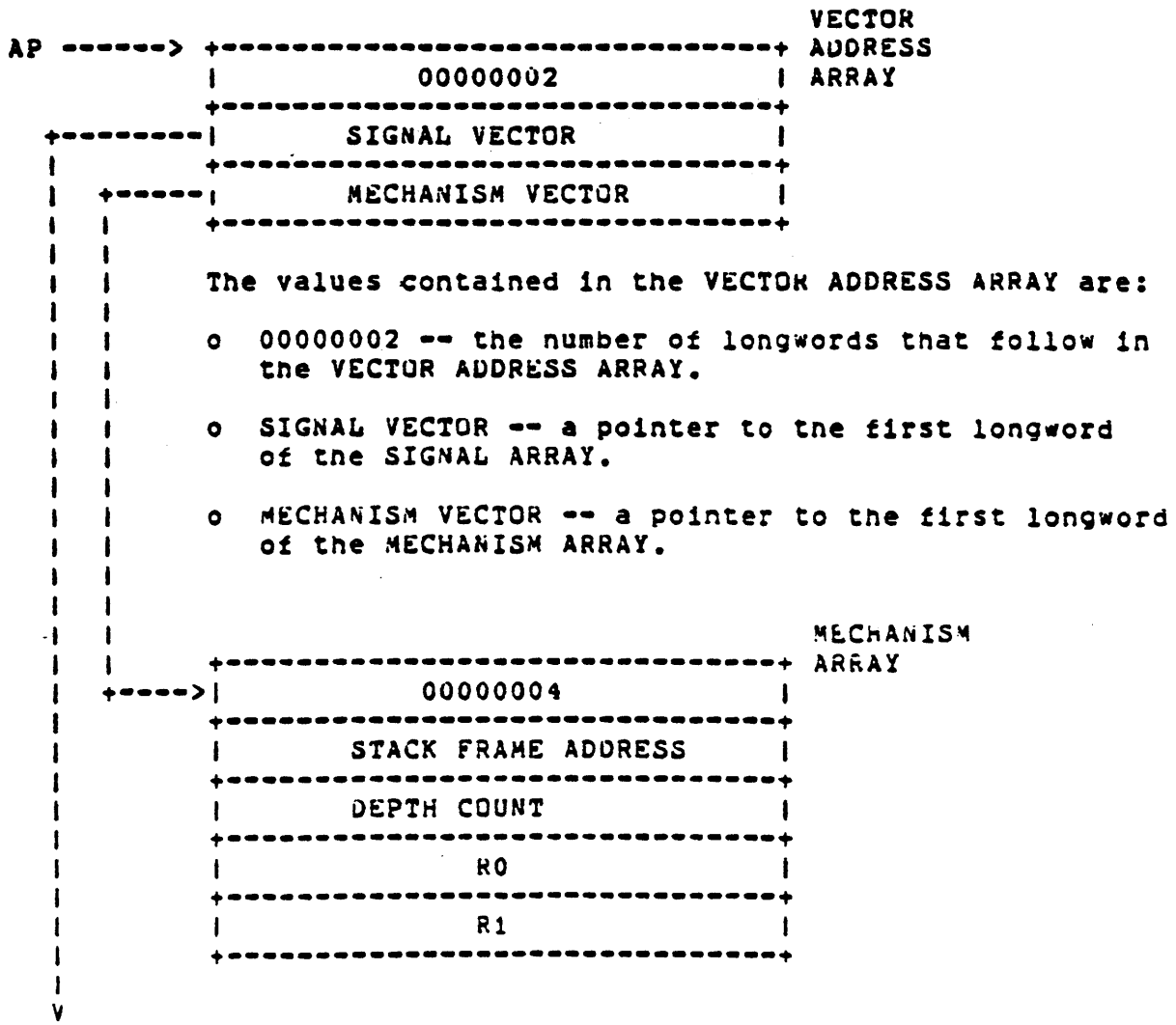
Bugchecks are not always fatal to the system. A Bugcheck that occurs while the CPU is in either User or Supervisor mode will result in termination of the process that incurred the Bugcheck, providing the process does not have privilege to cause a Bugcheck. If the Bugcheck is not fatal, VMS will dismiss it and allow the process to continue. Otherwise fatal Bugchecks will not crash the system from User or Supervisor mode.

VMS protects itself and its data structures by using the Bugcheck mechanism while in Executive or Kernel mode. Non-fatal Bugchecks which occur in Executive or Kernel mode are dismissed the same as those in Supervisor or User mode, unless the SYSBOOT parameter BUGCHECKFATAL is turned on. Non-fatal Bugchecks will be logged to the Error Log. Fatal Bugchecks will result in the orderly shutdown of the system. A small amount of information describing the Bugcheck is sent to the console terminal, a dump file is written to the disk and then a special code is sent to the CON chip's console transmit data buffer and a HALT instruction is executed. The system will then be rebooted unless the SYSBOOT parameter flag BUGREBOOT is cleared.

The crash dump file can be analyzed using the System Dump Analyzer (SDA). The size of the dump file must be four blocks larger than the number of physical pages in the system. If the space reserved on the disk for the dump file is too small, only the physical pages that can fit in the file will be written. A small dump file will not contain some of the most crucial contents of physical memory (the system page tables) which may make analysis with SDA impossible.

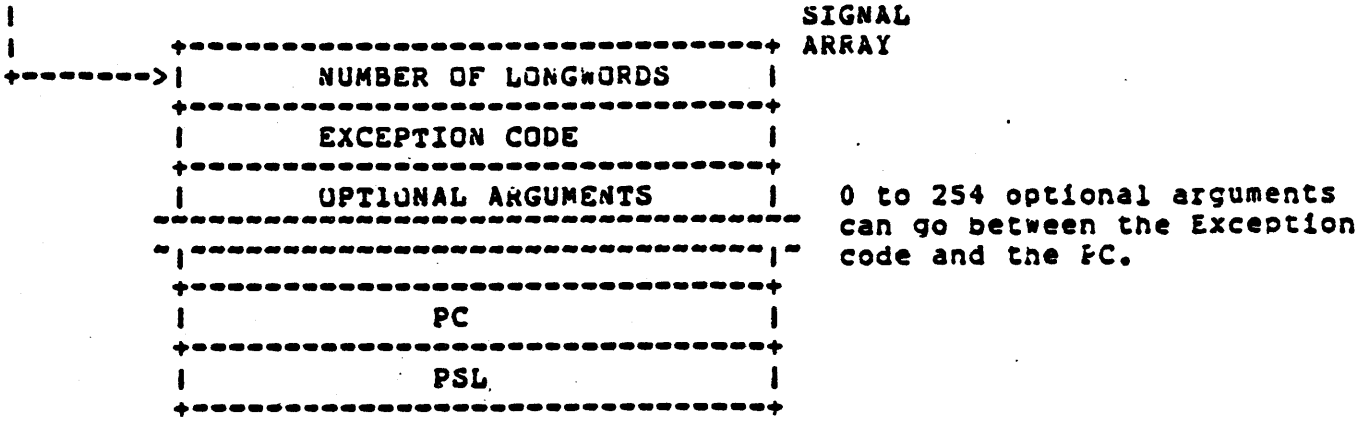
The tools you must know how to use to analyze a crash dump include the VMS microfiche listings and the System Dump Analyzer. This discussion assumes you also know the VAX instruction set and understand how to read a MACRO-32 listing. It is not necessary to understand the internals of VMS to troubleshoot some of the most common Bugchecks that are caused by hardware failures. Bugchecks caused by program errors are beyond the scope of this discussion.

When a Bugcheck occurs, information is left on the stack which is useful for isolating the area of code which caused the Bugcheck. This information is usually easy to identify. Note that this information is not always available on the stack. Sometimes a Signal Array can be found on the stack without a Vector Address array. The first item to locate is the Vector Address Array, though it is not always available. The AP will be pointing to the Vector Address Array if it is on the stack. This array will give you the address on the stack of the signal and mechanism arrays. The mechanism array contains the contents of R0 and R1 at the time of the Bugcheck. This information will be necessary for analyzing the code that Bugchecked.



The values contained in the MECHANISM ARRAY are:

- 00000004 -- the number of longwords in the MECHANISM ARRAY. In a MECHANISM ARRAY, this value is always four.
- FRAME -- the address of the stack frame.
- DEPTH -- the stack depth. (FFFFFFFD to FFFFFFFF) Look for this when the Vector Array is not on the stack.
- R0 -- the contents of R0 at the time of the exception.
- R1 -- the contents of R1 at the time of the exception.



As an Example:
The values contained in the SIGNAL ARRAY for an Access Violation Exception which caused a Bugcheck are:

- 00000005 -- the number of longwords contained in the SIGNAL ARRAY. For access violations this number is always five.
- EXCEPTION CODE -- a code which identifies the type of exception.
- REASON MASK -- the longword whose lowest three bits, if set, indicate that the instruction caused a Length Violation (bit 0), referenced the process page table (bit 1), and/or read/modify operation (bit 2).
- VIRTUAL ADDRESS -- the virtual address that the system tried to reference at the time of the exception.
- PC -- the Program Counter. The PC contains the address of the instruction that signaled the exception.
- PSL -- the processor status longword at the time of the exception.

Signal arrays differ in length, from 4 to 258 longwords, depending on the kind of exception the system detects. See the VAX-11 Run Time Library Reference Manual for details.

The Signal Array contains more interesting information about the Bugcheck. The format of the Signal Array varies for different Bugchecks. The Exception Code identifies what kind of error led to the Bugcheck. The Exception Code indicates such errors as Access Violation, Opcode Reserved to DEC, etc. Following the Exception Code are optional arguments. These arguments will vary in number and meaning for different Bugchecks. Next on the stack is the PC of the instruction that would have been executed next, if an Exception had not occurred.

Once you have located the Exception Code within the Signal Array, enter the following on a running VAX/VMS system:

```
$ @TT<cr>
$ _EXIT %X<exception code><cr>
```

For access violations the EXCEPTION CODE is 0000000C.

EXAMPLE:

```
$ @TT<cr>
$ _EXIT %X0C<cr>

%SYSTEM-F-ACCVIO, access violation, reason mask=00,
virtual address=0000000C, PC=7FFD3A58, PSL=0004034
```

Now that you know what the Exception Code means, you can look up a short explanation in the VAX/VMS System Messages and Recovery Procedures Manual. For instance, continuing with the Access Violation example, you would lookup ACCVIO on page 2-3 and find the following:

" ACCVIO, access violation, reason mask=xx, virtual address=location, PC=location, PSL=xxxxxxxx

Facility: VAX/VMS System Services

Explanation: An image attempted to read from or write to a memory location that is protected against the current mode. This message indicates an exception condition and is followed by a register and stack dump to help locate the error.

User Action: Examine the PC and virtual address displayed in the message and check the program listing to verify that instruction operands or procedure call arguments are correct. "

The explanation given in the VAX/VMS System Messages and Recovery Manual will give you an idea of what the software was attempting to do or a description of the Exception condition which led to the Bugcheck. The User Action may give you some idea of how to proceed in examining the crash dump. Remember that this manual was intended for programmers creating program errors and not for analyzing hardware failures, so some of the Explanations and User Actions will not be appropriate to a hardware failure.

Now that you have some idea where the Bugcheck error was detected and what type of an error caused the Bugcheck, you can attempt a bit of analysis using SDA. The above stack information may be available at the console or by using SDA and examining the stack. Exactly how you proceed with SDA will depend on your experience and the type of problem you are troubleshooting.

For instance, suppose you had an access violation caused by a length violation which led to a Bugcheck. The VA that failed can be found in the Signal Array. Try to examine this address using SDA. It will probably not be possible because the page may not have been mapped. Then check the process page table or system page table to find out if the address is mapped and what protection exists. If the VA is an 800xxxxx value, then you can use the system map (SYS.MAP) and locate the VMS module which contains the address. If the address is not mapped, it may indicate that the program calculated the address incorrectly or dropped/picked a bit in the data paths because of a hardware error. Try to figure out what the address should have been and if the VA that was generated is off by a single bit. Maybe one particular register dropped a bit. From a single failure you may not have enough information to isolate the problem to a small enough area of the system to warrant swapping a module. In these cases it is better to wait for additional crashes and collect more information.

Another possibility is that a device could cause an error, such as constant interrupts, which could cause a system crash or hang. Be especially suspicious of the system disk, MBA or Massbus if all of the failures happen while page faulting a page or swapping a process.

A customer written device driver, or for that matter a DEC device driver, could cause a Bugcheck. If the VA or PC which causes the failure is 800xxxxx and you cannot find the module which contains this address in the SYS.MAP, then the address may be within a device driver or other VMS component such as RMS. To find out if it is within a device driver, run SYSGEN and SHOW /DEVICES. The SHOW/DEVICES command will print out a list of address indicating where each device driver is loaded, and addresses where key structures within the I/O data base can be found. The SHOW DEVICE command under SDA could also be used. Just knowing that the address which caused the Bugcheck is associated with a particular device driver will give you some idea of where to start. In the case of a suspected customer written device driver, it would be wise to involve Software Support to help analyze the crash and look at the code of the device driver.

BUGCHECK ANALYSIS NUMBER ONE

Let's try looking at an example of one Bugcheck which was forced by hardware error and see if we can determine where the problem lies.

**** COMMENTS and SDA COMMANDS are indicated by "**" ****

```
SDA> SHOW CRASH
***************

VAX/VMS System dump analyzer

Dump taken on 13-JUL-1981 16:19:26.67
SSRVEXCEPT, Unexpected system service exception

Time of system crash: 13-JUL-1981 16:19:26.67

Version of system: VAX/VMS VERSION V2.3

Reason for BUGCHECK exception: SSRVEXCEPT, Unexpected system service exception

Process currently executing: SYSTEM

Current image file name: _DRA0:[SYSEXE]DIRECTORY.EXE;3    ** GETTING A DIRECTORY

Current IPL: 0  (decimal)

 neral registers:

      **** THE CONTENTS OF REGISTERS R0,R1,SP,PC,& PSL HAVE BEEN ****
      **** MODIFIED BY THE BUGCHECK HANDLER.  THE PC IS POINTING ****
      **** TO THE BUGCHECK HANDLER FOR SYSTEM SERVICE EXCEPTION. ****

      R0  = 7FFEFE35   R1  = 8000A122   R2  = 7FFEC200   R3  = 7FFEAE00
      R4  = 80070EA0   R5  = 7FFEA838   R6  = 7FFEA8EC   R7  = 00000000
      R8  = 7FFEF878   R9  = 7FFEF988   R10 = 7FFEA790   R11 = 7FFEA210
      AP  = 7FFECD84   FP  = 7FFECD6C   SP  = 7FFECD6C   PC  = 8000A128
      PSL = 00000000


Processor registers:

      P0BR   = 80097000     PCBB   = 0001A674     ACCS   = 00008001
      P0LR   = 00000000     SCBB   = 0007DA00     SBIFS  = 00040000
      P1BR   = 7F89B000     ASTLVL = 00000004     SBISC  = 00000000
      P1LR   = 001FFE87     SISR   = 00180000     SBIMT  = 00200200
      SBR    = 0007E400     ICCS   = 800000C1     SBIER  = 00008002
      SLR    = 00000700     ICR    = FFFFEE6B     SBITA  = 20000001
                            TODR   = 73BE01C0     SBIS   = 00000000

      ISP    = 8007F000   ** ON THIS SYSTEM, THIS IS AN EMPTY STACK **
      KSP    = 7FFECD6C   ** THIS IS THE CURRENT STACK **
      ESP    = 7FFEDDB0
      SSP    = 7FFEF818
      USP    = 7FFCC9C8
```

```
SDA> SHOW PROCESS
*****************

  ɔcess status:  00040001   RES,PHDRES

PCB address                 80070EA0    JIB address                 8007A980
Master PID                  00020016    Creator PID                 00000000
PID                         00020016    Subprocess count                 0
PHD address                 80096600    Swapfile disk address       00000000
State                          CUR      Termination mailbox              0000
Current priority                 4      AST's enabled                    KESU
Base priority                    4      AST's active                     NONE
UIC                         [001,004]   AST's remaining                    19
Mutex count                      0      Buffered I/O count/limit         12/12
waiting EF cluster               0      Direct I/O count/limit           12/12
Starting wait time          1A1B0000    BUFIO byte count/limit     20480/20480
Event flag wait mask        F7FFFFFF    # open files allowed left          20
Local EF cluster 0          C8000001    Timer entries allowed left         20
Local EF cluster 1          00000000    Active page table count             0
Global cluster 2 pointer    00000000    Process WS page count              40
Global cluster 3 pointer    00000000    Global WS page count               55
```

```
A> SHOW STACK
*************

rrent operating stack (KERNEL):

              7FFECD4C  7FFEF988
              7FFECD50  7FFEA790      CTLSAG_CLIDATA+580
              7FFECD54  7FFEA210      CTLSAG_CLIDATA
              7FFECD58  7FFECD84      CTLSGL_KSTKBAS+584
              7FFECD5C  7FFECD6C      CTLSGL_KSTKBAS+56C
              7FFECD60  7FFECD64      CTLSGL_KSTKBAS+564
              7FFECD64  8000A128      EXESEXCPTN+006
              7FFECD68  00000000

       SP =>  7FFECD6C  00000000
              7FFECD70  00000000
              7FFECD74  7FFEA956      MMGSIMGACTBUF+156
              7FFECD78  7FFECDC0      CTLSGL_KSTKBAS+5C0
              7FFECD7C  80000014      SYSSCALL_HANDL+004
              7FFECD80  80011265      EXESREFLECT+14E
              7FFECD84  00000002 <========================== *** THE VECTOR ARR.
              7FFECD88  7FFECDA4      CTLSGL_KSTKBAS+5A4
              7FFECD8C  7FFECD90      CTLSGL_KSTKBAS+590
              7FFECD90  00000004 <========================== *** THE MECHANISM
              7FFECD94  7FFECDC0      CTLSGL_KSTKBAS+5C0
              7FFECD98  FFFFFFFE
              7FFECD9C  00400005
              7FFECDA0  7FFEC000      CTLSA_DISPVEC
              7FFECDA4  00000005 <========================== *** THE SIGNAL ARR
              7FFECDA8  00000444 <========================== *** NOW FIND THE E
              7FFECDAC  00000000
              7FFECDB0  80011A00      EXESIMGSTA+5C2
              7FFECDB4  800119FD      EXESIMGSTA+5BF
              7FFECDB8  00400000
              7FFECDBC  8000E39F      EXESIMGACT+CAC
              7FFECDC0  00000000
              7FFECDC4  00CC0000
              7FFECDC8  7FFEDDC8      CTLSGL_KSPINI+FC8
              7FFECDCC  7FFECDE4      CTLSGL_KSTKBAS+5E4
              7FFECDD0  80007658      EXESCMKRNL+018
              7FFECDD4  00000000
              7FFECDD8  7FFEAE00      MMGSIMGACTBUF+600
              7FFECDDC  7FFEA8EC      MMGSIMGACTBUF+0EC
              7FFECDE0  00000000
              7FFECDE4  00000000
              7FFECDE8  00000000
              7FFECDEC  7FFEDDC8      CTLSGL_KSPINI+FC8
              7FFECDF0  7FFEDDB0      CTLSGL_KSPINI+FB0
              7FFECDF4  8000A130      EXESEXCPTN+00E
              7FFECDF8  80000096      SYSSCMKRNL+006
              7FFECDFC  01800000
```

**** If you have been following the crash so far, you should know that the Exception Code was a 444. Using the methods shown earlier, you should have been able to determine that the exception code indicates a PAGRDERR, that is a PAGRDERR. Now looking that up in the VAX/VMS System Messages and Recovery Procedures Manual you would find the following:

" PAGRDERR, page read error, reason mask=xx, virtual address=location, PC=location, PSL=xxxxxxxx

Facility: VAX/VMS system services

Explanation: The system failed to read a page from disk into memory during a page fault operation. This message indicates an exception condition and is usually followed by a display of the condition arguments, registers, and stack at the time of the exception.

User Action: Check the status of the device and repeat the request. If the failure persists, notify the system manager."

Now what do you think would be a good area to examine? While it is not possible from the information above to state conclusively that the Bugcheck was caused by a hardware failure in the disk subsystem, the available evidence is pointing in that direction. This Bugcheck was in fact caused by switching the system disk offline/online and then attempting to perform a DIR command. As you can see, this Bugcheck was fairly straight forward and could be isolated to the disk subsystem. If this Bugcheck occurred again and the hardware was available, you could look at the disk subsystem registers. You would find the Volume Valid bit reset. From this you would then be able to pursue the MBA or Disk drive to determine why the Volume Valid bit was reset on the system disk.

WORKSHEET A = 10.(1010) B = 11.(1011) C = 12.(1100) D = 13.(1101) E = 14.(1110) F = 15.(1111)

								31	30	29	28	27	26	25	24	23	22	21	20	19	18	17	16	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

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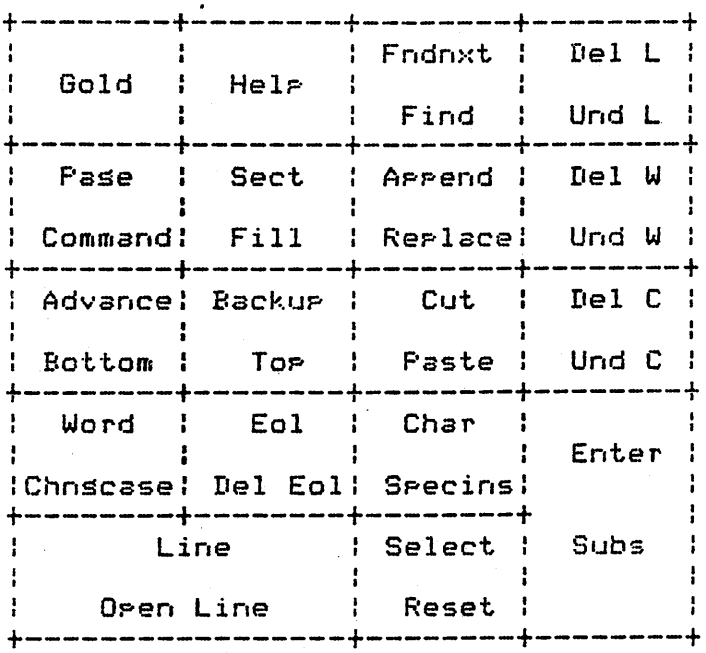
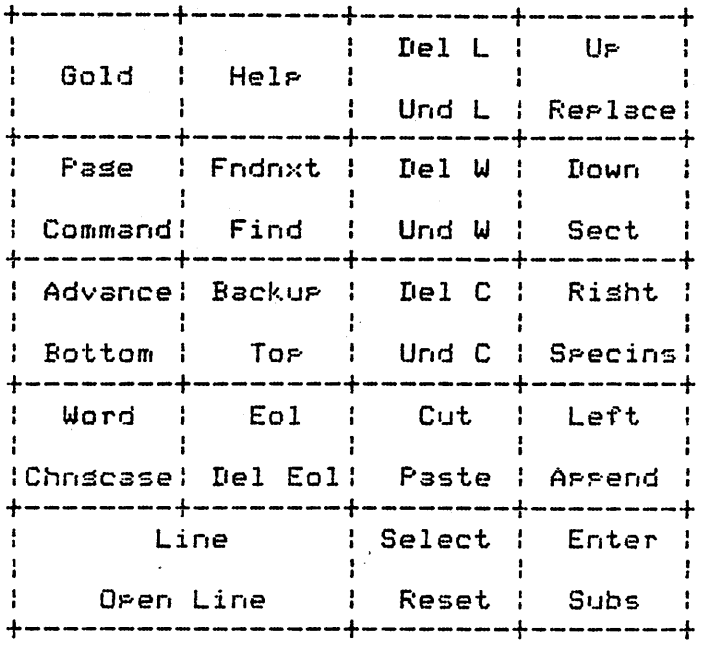
EDT Version 2 VT100 Keypad



Backspace	Go to beginning of line
Delete	Delete character
Linefeed	Delete to start of word
CTRL/A	Compute tab level
CTRL/D	Decrease tab level
CTRL/E	Increase tab level
CTRL/K	Define key
CTRL/L	Form feed
CTRL/T	Adjust tabs
CTRL/U	Delete to start of line
CTRL/W	Refresh screen
CTRL/Z	Return to line mode

EDT Version 2 VT52 Keypad



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