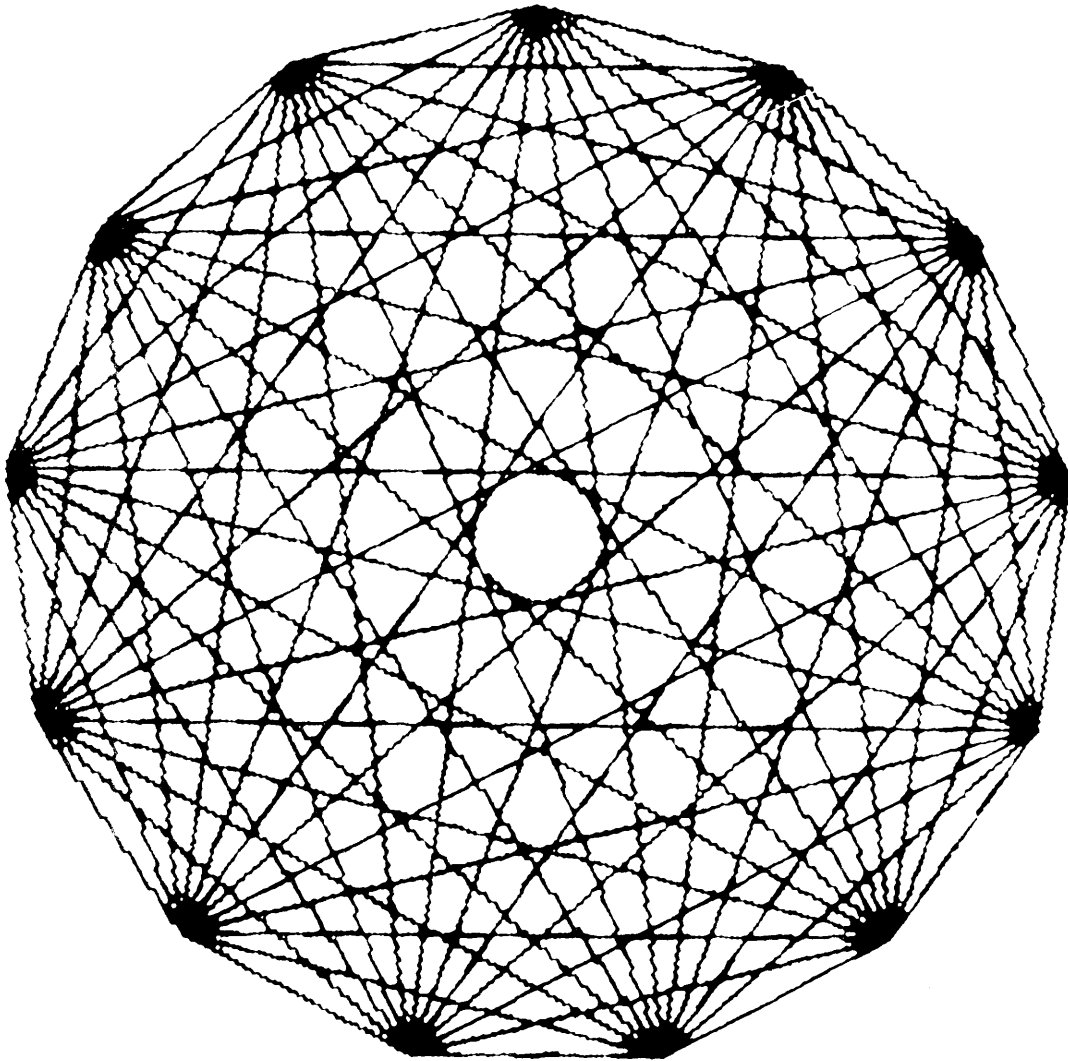


# VK100

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## TECHNICAL MANUAL

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digital

# VK100

## TECHNICAL MANUAL

1st Edition, April 1982

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## CHAPTER 1 INTRODUCTION

### 1.1 INTRODUCTION

The VK100 terminal is an interactive graphics terminal designed for use with a user supplied monitor. The terminal can operate in either an on-line or off-line mode and can execute programs written in GIGI BASIC.

This chapter provides a general overview of the VK100 terminal. The following chapters describe and summarize installation, operation, programming characteristics, theory of operation, and maintenance procedures for the VK100 terminal.

### 1.2 GENERAL DESCRIPTION

The VK100 or GIGI (General Imaging Generator and Interpreter) is designed as a terminal subsystem that connects to a host computer. The VK100 provides local (in terminal) processing using a microprocessor. The microprocessor supports two interpreters; a ReGIS graphics interpreter and the GIGI BASIC language interpreter. ReGIS (Remote Graphics Instruction Set) is a graphics language; GIGI BASIC is a BASIC language that uses VK100 unique graphics capabilities.

The VK100 is a separate keyboard which requires a user-supplied monitor for displaying screen images. Either black and white or color (RGB) monitors can be used. Also, the VK100 can display images on an optional LA34VA Graphics Printer which attaches directly to the terminal.

The VK100 can be used as a text terminal and as a graphics terminal. The VK100 terminal's basic mode of operation is as a text terminal. In this mode the terminal acts as a translator between the operator and the host computer. When the operator types a message or command on the keyboard, the terminal sends it immediately to the host computer. The host computer receives the message or command and executes it. Then the host computer sends an acknowledgement to the terminal, indicating the message or command was received and executed. The terminal receives the acknowledgement and displays it on the monitor screen. Figure 1-1 shows a simple diagram of the VK100 terminal operating in text mode.

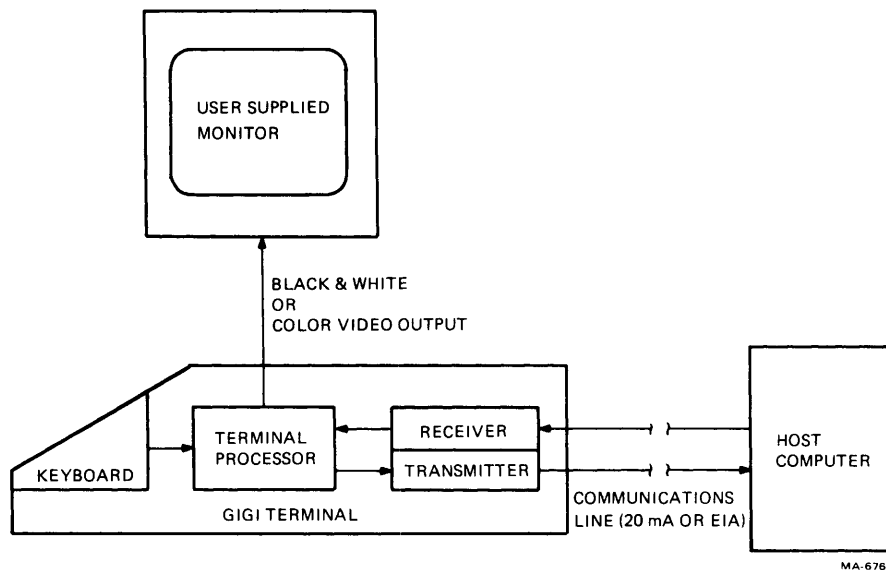


Figure 1-1 Text Mode Operation

The VK100 terminal always enters text mode when powered on or reset.

The VK100 (GIGI) terminal's primary operating mode is as a graphics terminal. The name GIGI derives from this capability as a General Imaging Generator and Interpreter.

Generally, the host computer places the terminal in graphics mode. In this mode the terminal interprets all data received from the host computer or the terminal keyboard as graphics commands and data. The interpreter and image generator translates the commands and data into the images displayed on the monitor screen. Figure 1-2 shows a simple diagram of the VK100 terminal operating in graphics mode.

The commands to the interpreter come from a new graphics command set called ReGIS (Remote Graphics Instruction Set). ReGIS command set consists of a few simple instructions and options.

Within the graphics mode is a locator mode. This mode helps the operator locate a point on the screen and report that point to the host computer. The VK100 terminal enters locator mode through the keyboard or a command from the host computer. When the terminal enters locator mode, a large cross-hair cursor appears on the screen. The point where the two lines cross is the point reported to the host computer.



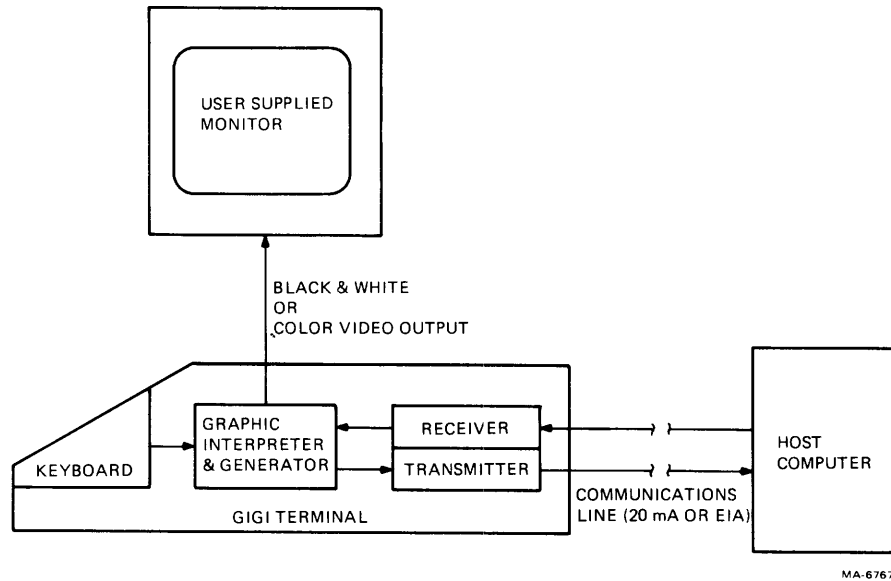


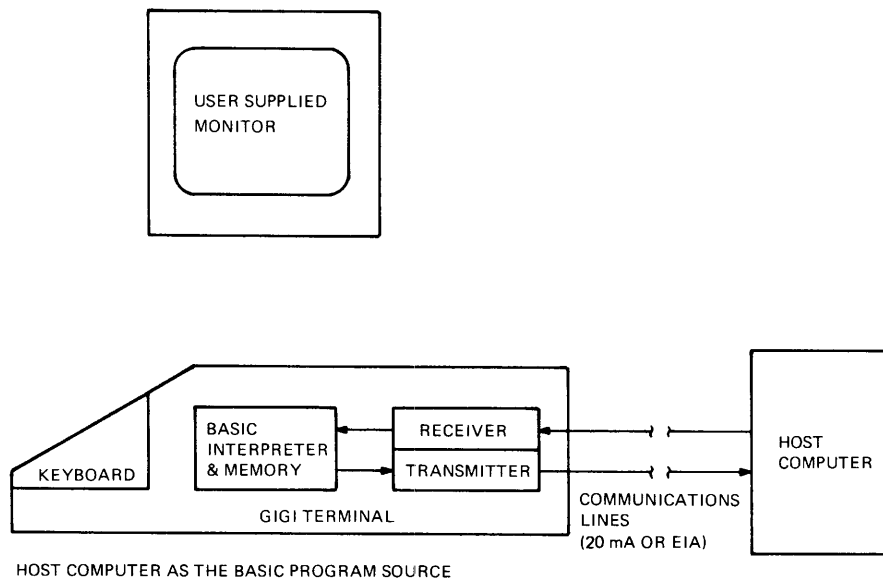
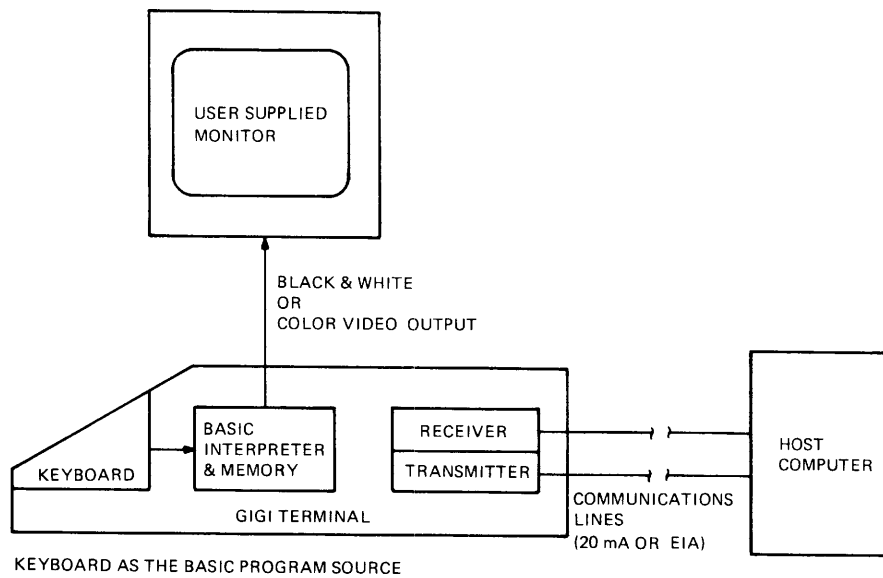
Figure 1-2 Graphics Mode Operation

The operator can return the terminal to the text mode at any time. When in text mode, the terminal interprets all graphics data and commands as text characters only and not as graphics.

The VK100 terminal also contains a BASIC language interpreter. This interpreter allows the terminal to run BASIC language programs. The terminal enters BASIC mode through the SET-UP mode (described in Chapter 3) or a command from the host computer.

The BASIC program comes from one of two places, the keyboard or the host computer. The operator selects the program source with a SET-UP parameter. If the keyboard is the program source, the operator types the BASIC program directly into the terminal memory. When the program runs, the output normally goes to the monitor screen. If the host computer is the program source, the program loads into the terminal memory from the host computer. When the program runs, the output normally returns to the host computer. Figure 1-3 shows a simple diagram of the VK100 terminal operating in both cases.

When the terminal enters the BASIC mode, the BASIC indicator above the keyboard lights. The operator can return the terminal to text mode at any time, either through the keyboard or the SET-UP mode. When the terminal is in text mode, it interprets all data as text only and not as BASIC language commands.



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Figure 1-3 BASIC Mode Operation

The VK100 terminal hardware is contained in a light weight plastic case. The terminal contains three major assemblies; the keyboard, the processor board, and the power supply, a color or monochrome (black and white) monitor is supplied by the customer.

### 1.3 ACCESSORIES AND SUPPLIES

DIGITAL offers the following accessories and supplies for the VK100 terminal.

#### 1.3.1 VK100 (GIGI) Carrying Cases (VK10K-CA)

These cases are specially designed to hold the VK100 terminal and all associated cables. They are constructed of high-density, charcoal brown, textured plastic and include two chrome-plated latches with locks.

#### 1.3.2 VK100 Keyboard Overlays

Two types of overlays are available with the VK100 terminal: preprinted keypad and keypad overlays. These overlays are easy-to-install, plastic key covers representing the VK100 terminal's special function keys or user-defined character sets.

Keypad overlays cover VK100's auxiliary keypad and are used with the following software packages.

- CAI Primer (VK10K-AA)
- Graphics Editor (VK10K-AB)
- ReGIS Illustrated Text Editor (VK10K-AC)
- Character Set Editor (VK10K-AD)

Keyboard overlays cover the VK100 terminal's entire keyboard, including the auxiliary keypad, and include the following.

- Preprinted APL character set overlays (VK10K-BB)
- Blank, full keyboard overlays for user-defined character sets (VK10K-BA)

#### 1.3.3 VK100 Cables and Connectors

Table 1-1 describes the cables and connectors used by the VK100 terminal.

In the future, additional options will be available. Contact the nearest DIGITAL Sales Office for further information.

**Table 1-1 VK100 Cables and Connectors**

Cable	Description
BC26M-05	RGB cable with BNC connectors for user-supplied monitor
BC26B-01	Y-cable for daisy-chaining the LA34VA graphics printer to multiple VK100 terminals
P/N 7015503-00	20 mA loopback connector
P/N 1215336-00	EIA loopback connector
BC22B-25	EIA extension to second VK100 terminal from Y-cable (BC26B-01)
BC05F-15 or BC05F-50,A0	20 mA cable with Mate-N-Lok connectors for connecting VK100 terminal (with 20 mA option) directly, to a line unit
BC22A-10 or BC22A-25	EIA null modem; connects VK100 terminal directly to a line unit (6 conductor cable)
BC22B-10 or BC22B-25	EIA extension to modem (14 conductor cable)

#### RELATED DOCUMENTATION

Table 1-2 lists the related documentation that is available from DIGITAL's Accessory and Supplies Group. For specific ordering information, see the end of this chapter.

#### 1.4 ORDERING ACCESSORIES AND SUPPLIES

You can order accessories and supplies (including documentation) either by mail or phone.

##### 1.4.1 Toll-Free Telephone Orders

Call DIGITAL Direct Catalog Sales from 8:30 a.m. to 5:00 p.m. at one of the following numbers.

Continental United States  
1-800-258-1710

New Hampshire, Alaska, and Hawaii  
1-603-884-6660

Canada  
1-800-267-6146

Northern California  
1-408-984-0200

Chicago  
1-312-640-5612

Outside North America  
contact your local A & SG business representative or local  
DIGITAL sales office.

The following information applies to all telephone orders.

Minimum order is \$35 unless charged to Master Card, Visa, or  
American Express.

Maximum order is \$5,000.

Phone orders are accepted at current list price only.

Phone orders are accepted per DIGITAL standard terms and  
conditions only.

#### 1.4.2 Direct Mail Orders

Mail all purchase orders directly to one of the following  
addresses.

For U.S. Customers  
Digital Equipment Corporation  
ATT: A&SG  
P.O. Box CS2008  
Nashua, New Hampshire 03061

For International Customers  
Digital Equipment Customers  
A&SG Business Manager  
c/o DIGITAL's local subsidiary

The following information applies to all direct mail orders.

Minimum order is \$35 unless paid by check, money order, or  
credit card (Visa, Master Card, or American Express accepted).  
No maximum order value.

Table 1-2 Related DIGITAL Documentation

Title	Document No.	Description
GIGI Terminal Installation and Owner's Manual	EK-VK100-IN	This manual describes the VK100 (GIGI) terminal. It provides information on installing the terminal and connecting the optional peripheral devices, performing terminal SET-UP, proper terminal operating specifications, and repair procedures. It also provides full specifications for all terminal outputs. A copy of this manual is shipped with each VK100 terminal.
GIGI Programming Reference Card	EK-0GIGI-RC	This pocket size reference card summarizes the programmable features of the VK100 (GIGI) terminal. It includes a summary of both the ReGIS and BASIC command sets. A copy is shipped with each VK100 terminal.
GIGI Terminal SET-UP Reference Card	EK-VK100-RC	This pocket size reference card summarizes the VK100 (GIGI) terminal SET-UP parameters. The card also contains the default SET-UP switch pack settings. A copy is shipped with each terminal.
VK100 Pocket Service Guide	EK-VK100-PS	This manual is a module-level repair manual. It provides troubleshooting information, testing information, and removal and replacement information for the VK100 terminal.

Table 1-2 Related DIGITAL Documentation (Cont)

Title	Document No.	Description
VK100 Technical Manual	EK-VK100-TM	This manual provides a detailed block-diagram-level discussion of the VK100 terminal. It also provides information on troubleshooting the terminal. The manual does not contain a set of schematic drawings. These drawings are a part of the VK100 print set, which must be ordered separately.
VK100 Illustrated Parts Breakdown (IPB)	EK-VK100-IP	This manual provides a detailed parts breakdown of the terminal. It does not provide part numbers for printed circuit board components. That information is contained in the VK100 print set, which must be ordered separately.
VK100 Print Set	MP-00893-00	This document provides a complete set of electrical and mechanical schematic diagrams for the VK100 terminal.
GIGI/ReGIS Handbook	AA-K336A-TK	This book provides user information to program the VK100 (GIGI) terminal, including system-dependent information. It provides comprehensive descriptions of ReGIS commands, organized alphabetically for easy reference. Extensive examples of the VK100 graphics capabilities are used throughout. A copy of this book is shipped with each VK100 terminal.

Table 1-2 Related DIGITAL Documentation (Cont)

Title	Document No.	Description
GIGI BASIC Manual	AA-K335A-TK	This is a BASIC language manual for the VK100 terminal. It provides comprehensive descriptions of the GIGI BASIC commands and functions, organized alphabetically for easy reference. A copy of this manual is shipped with each VK100 terminal.
GIGI Graphics Editor Manual	AA-J942A-TK	This manual describes the Graphics Editor software package within the entire VK100 package. The manual also includes descriptions of each Graphics Editor command. A copy of this manual is shipped with the GIGI Graphics Editor software package.
GIGI Data Plotting Package Manual	AA-J956A-TK	This manual describes the GIGI Data Plotting software package: the functional modes, the steps to create a table, defining and displaying plots from that table, and performing statistical analysis. It also describes each of the plot commands and file structures for the table data and statistical results. A copy of this manual is shipped with the GIGI Data Plotting software package.
GIGI Slide Projector Manual	AA-J943A-TK	This manual describes the GIGI Slide Projector software package. It describes the file formats and the use of the automatic and manual modes. It also describes each command and provides syntax and usage information. A



Table 1-2 Related DIGITAL Documentation (Cont)

Title	Document No.	Description
		copy of this manual is shipped with the GIGI Slide Projector software package.
GIGI Character Set Editor User Guide	AA-K337A-TK	This manual describes the GIGI Character Set Editor. It describes each command and provides syntax and usage information. A copy of this manual is shipped with the GIGI Character Set Editor software package.
GIGI ReGIS Illustrated Technical Manual	AA-J944A-TK	This manual describes the GIGI ReGIS Illustrated Technical Manual software package. It describes the ReGIS Illustrated Technical Manual its editing and graphics capabilities, and the use of picture files. It also describes the keypad commands. A copy of this manual is shipped with the GIGI ReGIS Illustrated Technical Manual software package.
GIGI/ReGIS CAI Primers Student Guide	SDC AA-K329A-TE	This manual is used with any of the GIGI/ReGIS CAI Primers. It provides an overall introduction to the primers, including their objectives and recommended course of study. It also tells new users how to start the course.
VAX/VMS GIGI/ReGIS CAI Primers	SDC BE-K391A-BC (TU58) SDC AS-K327A-BE (Floppy)	This computer-assisted instruction (CAI) course runs on VAX/VMS. It helps new VK100 users to begin using the terminal and ReGIS.

Table 1-2 Related DIGITAL Documentation (Cont)

Title	Document No.	Description
VAX/VMS GIGI/ReGIS CAI Primers Course Administrator Guide	SDC AA-K328A-TE	This manual provides an overview of the course administrator's role and describes how to install and maintain the CAI software on VAX/VMS.
RSTS/E GIGI/ReGIS CAI Primers	SDC BC-K346A-BC (RL02)	This computer-assisted instruction (CAI) course runs on RSTS/E. It helps new VK100 users to begin using the terminal and ReGIS.
	SDC AP-K392A-BC (Magtape 9-track 800 bits/in)	
	SDC BB-K393A-BC (Magtape 9-track 1600 bits/in)	
RSTS/E GIGI/ReGIS CAI Primers Course Administrator Guide	SDC AA-K347A-TC	This manual provides an overview of the course administrator's role and describes how to install and maintain the CAI software on RSTS/E.

## CHAPTER 2 INSTALLATION

### 2.1 INTRODUCTION

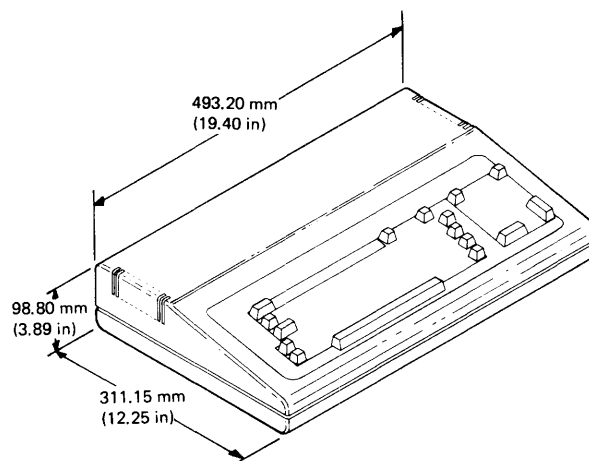
This chapter contains the following information.

- Site considerations
- Unpacking and inspection
- Repacking
- Installation
- Interface information

Included in the interface information are special programming considerations to observe for effective use of the interface.

### 2.2 SITE CONSIDERATIONS

The VK100 terminal is a lightweight, single-piece unit that fits on a desk or tabletop. Figure 2-1 shows the dimensions of the terminal.



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Figure 2-1 VK100 (GIGI) Terminal Dimensions

The VK100 terminal usually connects to a user-supplied monitor (display) device. The monitor always operates with the terminal and should be located close to the terminal. Be sure to consider the monitor's size and weight when planning the terminal's location.

The VK100 terminal places few limits on the operating environment. Avoid areas that have extremes in temperature and humidity or are subject to high levels of industrial contaminants. Appendix A describes the guaranteed operating conditions and terminal specifications.

A small fan in the VK100 terminal cools the terminal's electronic components. Keep all ventilation slots and an area of about six inches around the terminal clear. Do not place papers or similar materials on top of or under the terminal.

The terminal controls and cable connections are on the rear of the terminal. When installing the terminal, allow an adequate area to access the rear of the terminal.

#### NOTE

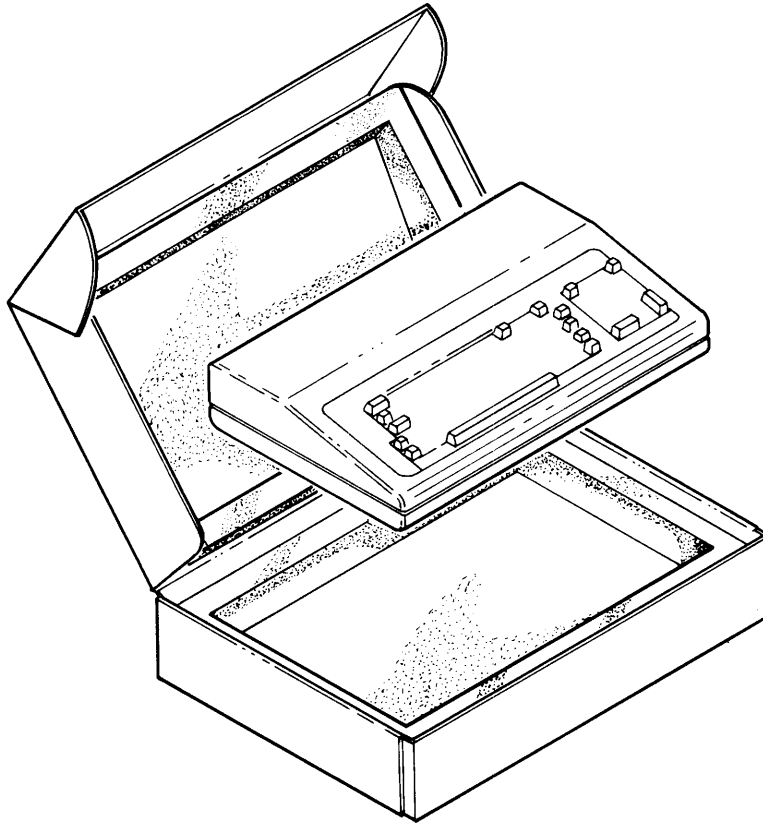
When installing the terminal, keep all power and signal cables free from obstructions, sharp bends, and stress.

### 2.3 UNPACKING AND INSPECTION

The VK100 terminal is packed in a reinforced shipping carton. The carton contains the following items.

- VK100 terminal
- VK100 terminal power cord
- VK100 terminal video cable
- GIGI Terminal Installation and Owner's Manual
- GIGI/ReGIS Handbook
- GIGI BASIC Manual
- GIGI Terminal SET-UP Reference Card
- GIGI Programming Reference Card
- GIGI Installation Card

Figure 2-2 shows the packaging used with the VK100 terminal. Use the following procedure to unpack the terminal from the shipping carton.



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Figure 2-2 VK100 (GIGI) Terminal Shipping Container

1. Carefully cut the shipping tape and open the shipping carton by pulling out the front flap and lifting the top of carton.
2. Remove the power cord, video cable, and documentation from the packing material.
3. Lift out the top piece of packing material and remove the terminal from the shipping carton. Save the packing material and shipping carton. They are needed to ship the terminal back to the repair center if the terminal ever fails.
4. Visually inspect the terminal for physical damage. If the terminal is damaged, notify your local DIGITAL Sales Office.
5. Install the terminal as described in the Installation section of this chapter.

## 2.4 REPACKING

Use the following procedure when repacking the VK100 terminal for shipment. Figure 2-3 shows all of the switch and cable locations.

1. Turn the ac power switch off.
2. Disconnect all cables from the rear of the terminal.
3. Locate the original packing material. If the original materials are not available, they can be ordered from DIGITAL. Refer to Chapter 1 for ordering information.
4. Repack the terminal in the shipping carton (Figure 2-2). Include the power cord and video cable in the shipping carton.
5. Seal the shipping carton with reinforced tape.

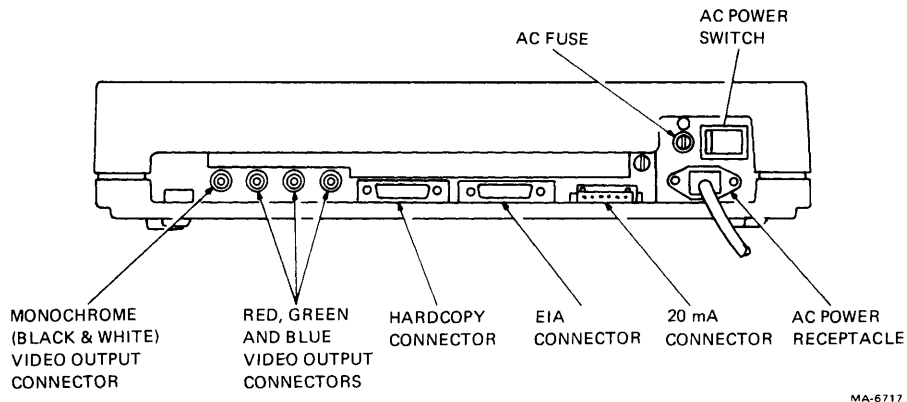
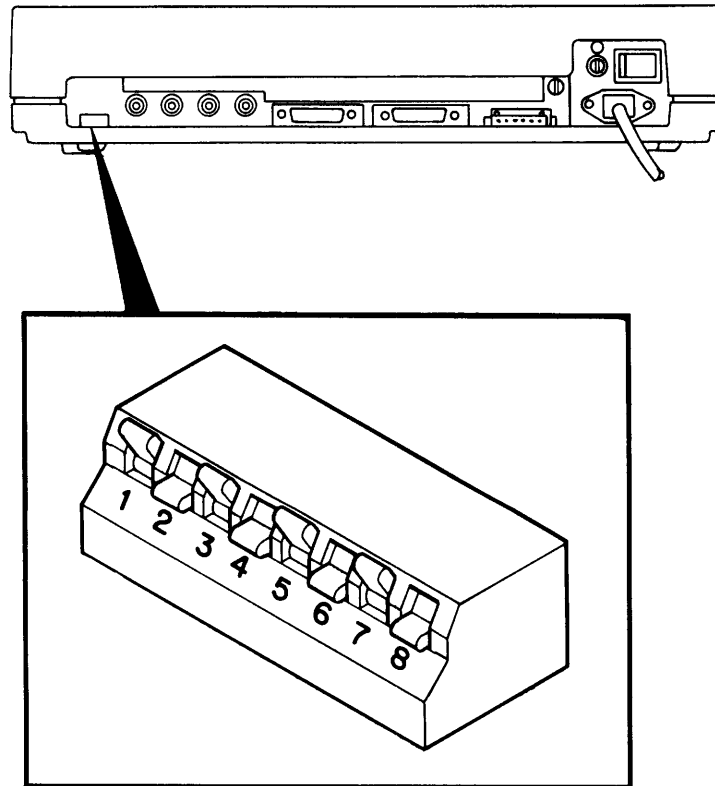


Figure 2-3 VK100 (GIGI) Terminal Switch and Cable Locations

## 2.5 INSTALLATION

The VK100 terminal is very easy to install. The only tool required is a flat blade screwdriver. Use the following procedure to install the terminal.

1. Remove the terminal from the shipping carton or optional carrying case and place in the desired work area.
2. Locate the access opening on the rear of the terminal (Figure 2-4). The eight-position default SET-UP switch pack will be visible in the opening.

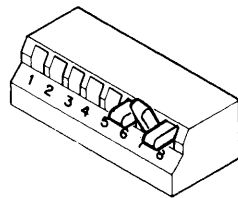


MA-6718

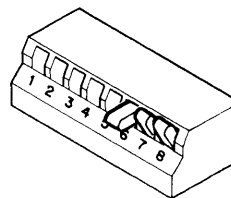
Figure 2-4 Default SET-UP Switch Pack Location

3. Note the switch positions and determine if the switch settings are correct for the host computer system. Figure 2-5 shows all the switch settings and what they mean to the host computer. Chapter 3 provides more detailed information on the SET-UP parameters.

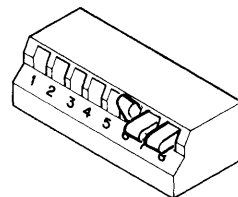
SET-UP FEATURE DEFAULT SETTINGS FOR BOTH TRANSMIT AND RECEIVE SPEEDS (TS AND RS) CONT.  
(SWITCHES 6, 7, & 8)



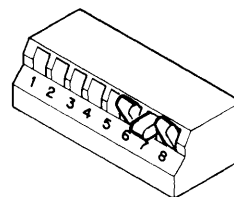
TRANSMIT AND RECEIVE SPEED FEATURES DEFAULT SET FOR 600 (RS2 AND TS2)



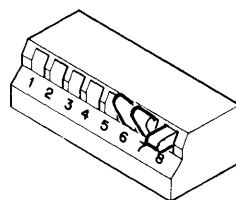
TRANSMIT AND RECEIVE SPEED FEATURES DEFAULT SET FOR 1200 (RS3 AND TS3)



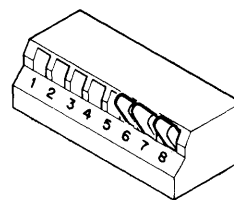
TRANSMIT AND RECEIVE SPEED FEATURES DEFAULT SET FOR 2400 (RS4 AND TS4)



TRANSMIT AND RECEIVE SPEED FEATURES DEFAULT SET FOR 4800 (RS5 AND TS5)



TRANSMIT AND RECEIVE SPEED FEATURES DEFAULT SET FOR 9600 (RS6 AND TS6)



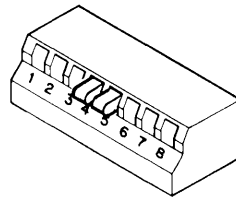
TRANSMIT AND RECEIVE SPEED FEATURES DEFAULT SET FOR 19,200 (RS7 AND TS7)

MA-6722

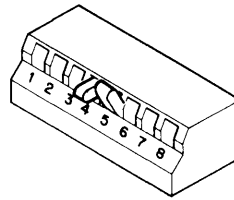
Figure 2-5 Default SET-UP Switch Pack Settings (Sheet 1 of 3)



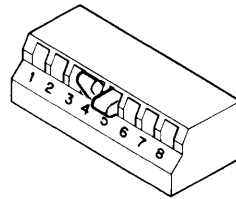
SET-UP FEATURE DEFAULT SETTINGS FOR PARITY ENABLE (PE)  
(SWITCHES 4 & 5)



PARITY ENABLE FEATURE  
DEFAULT SET FOR OFF (PE0)



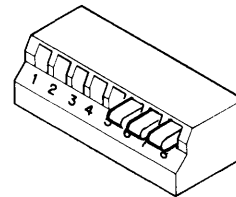
PARITY ENABLE FEATURE  
DEFAULT SET FOR EVEN (PE1)



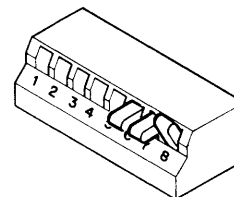
PARITY ENABLE FEATURE  
DEFAULT SET FOR ODD (PE2)

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SET-UP FEATURE DEFAULT SETTINGS FOR BOTH TRANSMIT AND RECEIVE  
SPEEDS (TS AND RS)  
(SWITCHES 6, 7, & 8)



TRANSMIT AND RECEIVE SPEED  
FEATURES DEFAULT SET FOR  
110 (RS0 AND TS0)

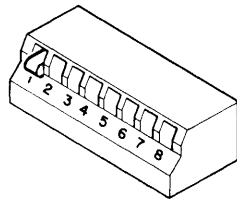


TRANSMIT AND RECEIVE SPEED  
FEATURES DEFAULT SET FOR  
300 (RS1 AND TS1)

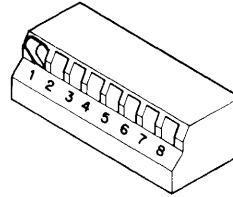
MA-6721

Figure 2-5 Default SET-UP Switch Pack  
Settings (Sheet 2 of 3)

SET-UP FEATURE DEFAULT SETTINGS FOR POWER FREQUENCY (PF)  
(SWITCH 1)



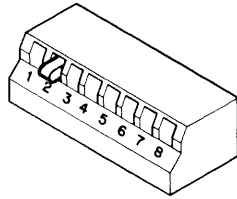
POWER FREQUENCY FEATURE  
DEFAULT SET FOR 60 Hz  
(PF0)



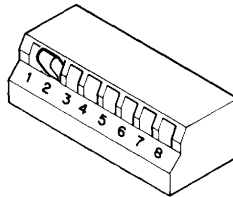
POWER FREQUENCY FEATURE  
DEFAULT SET FOR 50 Hz  
(PF1)

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SET-UP FEATURE DEFAULT SETTINGS FOR COMMUNICATIONS INTERFACE (CI)  
(SWITCH 2)



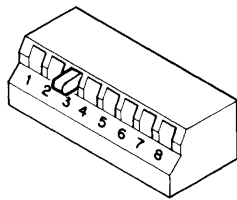
COMMUNICATIONS INTERFACE  
FEATURE DEFAULT SET FOR  
EIA (CI0)



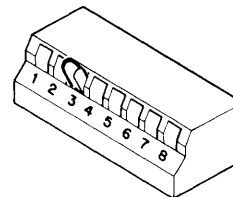
COMMUNICATIONS INTERFACE  
FEATURE DEFAULT SET FOR  
20 mA (CI1)

---

SET-UP FEATURE DEFAULT SETTINGS FOR UK CHARACTER SET (UK)  
(SWITCH 3)



UK CHARACTER SET FEATURE  
DEFAULT SET FOR US (UK0)



UK CHARACTER SET FEATURE  
DEFAULT SET FOR UK (UK1)

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Figure 2-5 Default SET-UP Switch Pack  
Settings (Sheet 3 of 3)

4. If the default SET-UP switch pack settings are incorrect for the host computer, carefully change the switch settings with a pencil or a similar object. Once the switches are set, verify the new settings. If the settings are wrong, the terminal may not be able to communicate with the host computer.
5. Remove the user-supplied monitor from its shipping carton and place in the desired work area. Perform the installation instructions packed with the monitor.
6. Connect the VK100 terminal to the user-supplied monitor. (The next section of this chapter provides specific instructions for connecting to the Barco Model GD33 monitor.)
7. Connect the communications cable to the appropriate communications connector. If you select EIA communications, connect the ground wire to the terminal communications connector. Figure 2-6 shows the cable connector with the ground wire connected.

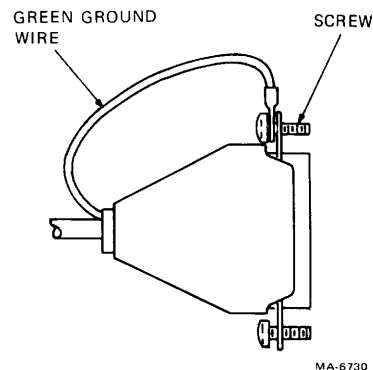


Figure 2-6 EIA Communications Cable Connector

8. Connect the VK100 terminal to the optional LA34VA graphics printer. There are two methods for this. Section 2.5.3 provides detailed instructions.
9. Connect the power cord to the power cord receptacle on the rear of the terminal. Plug the other end of the power cord into a nearby wall outlet.
10. Turn the monitor power switch on. Allow the monitor one or two minutes to warm up before performing the next step.
11. Turn the terminal power switch on. The terminal automatically performs the power-up self-test. Once the power-up self-test is successfully completed, the ON LINE indicator above the keyboard lights and the cursor appears in the upper left corner of the monitor screen. If any other indications are present, the terminal self-test may have found a fault in the terminal. Chapter 6 outlines the procedures to follow if this occurs.

NOTE

On some monitors the cursor does not appear immediately because of a monitor condition called overscan. To eliminate the overscan, set the HP or HM SET-UP parameters. Chapter 3 describes these parameters.

12. Select the terminal SET-UP parameters. Chapter 3 describes the SET-UP parameters and how to select them.
13. After selecting the SET-UP parameters, record their settings and keep them with the terminal for future reference.
14. Fill out the GIGI Installation Card and return it to DIGITAL. Postage is prepaid if mailed within the United States.

### 2.5.1 Connecting to the Barco Model GD33 Monitor

This section provides specific instructions for connecting the VK100 terminal to the Barco Model GD33 monitor. This monitor is not supplied by DIGITAL. The monitor must be purchased separately from a local Barco distributor. Monitor operating instructions are packaged with the monitor.

1. Locate the VK100 video cable. It is a single cable with three connectors on each end.
2. Connect the color-keyed red, green, and blue cable connectors to the RED, GREEN, and BLUE output connectors on the rear of the VK100 terminal.
3. Connect the color-keyed red, green, and blue cable connectors to the RED, GREEN, and BLUE input connectors on the rear of the Barco Model GD33 monitor (Figure 2-7).
4. Locate the white switches on the rear of the monitor above the input connectors. Slide the white switches to the 75 position. This switches in a 75-ohm cable impedance and provides the best possible monitor display.
5. Locate the G/X switch on the rear of the monitor. Slide the G/X switch to the G position. This sets the monitor synchronization for green signal sync.
6. Connect the monitor power cord.

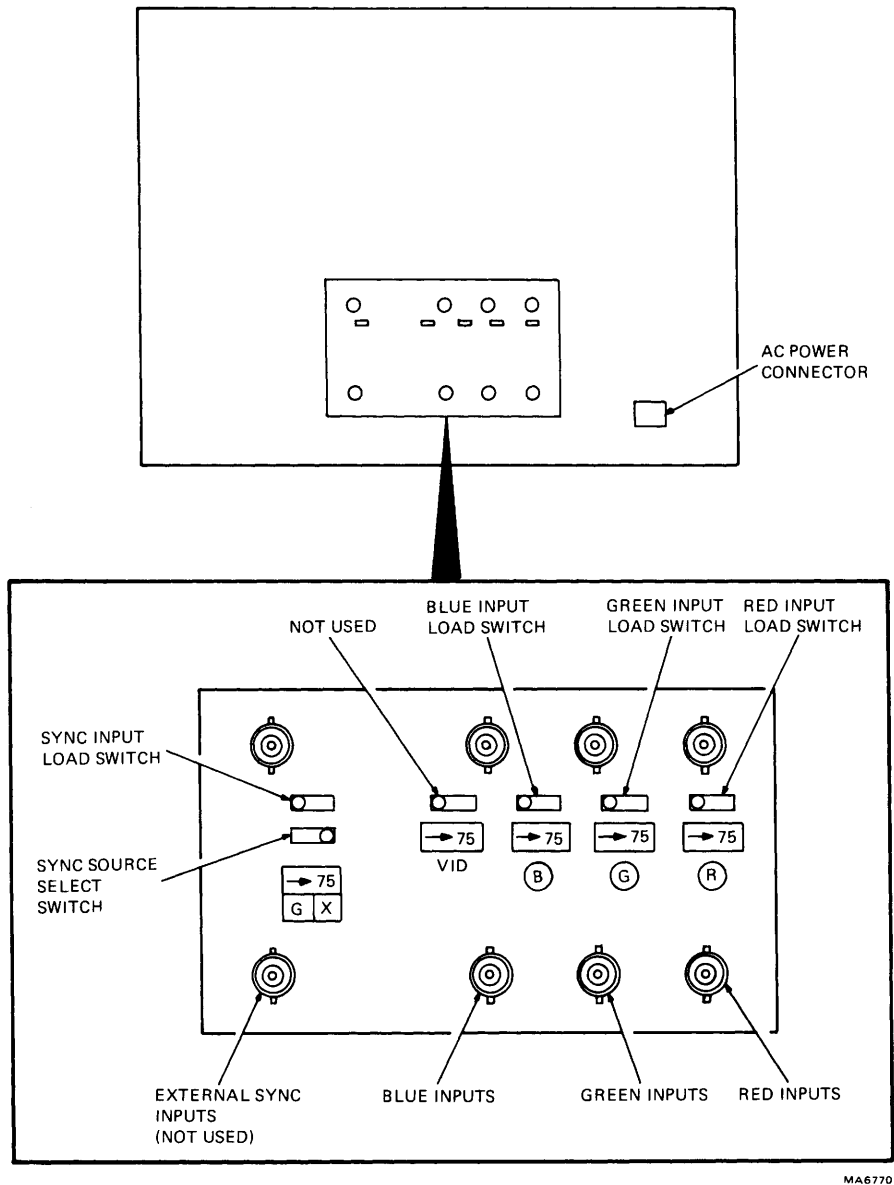


Figure 2-7 Barco Model GD33 Monitor Connections

### 2.5.2 Connecting to a Typical Black and White Monitor

The VK100 terminal can connect to a black and white (monochrome) monitor. DIGITAL does not supply a black and white monitor. Any black and white monitor must be obtained from local suppliers.

Use the following general instructions to perform the interconnection. Specific operating instructions for the monitor are packaged with the monitor.

1. Locate the VK100 video cable. It is a single cable with three connectors on each end.
2. Connect one of the three cable connectors to the MONO output connector on the rear of the VK100 terminal. Note the cable connector color key (red, green, or blue).
3. Locate the video input connector on the black and white monitor. This connector should be a BNC-type connector. If not, put a BNC adaptor on the connector.
4. Connect the video cable to the video input connector on the monitor. Be sure to use the same color-keyed cable connector that was used on the terminal end of the cable.

### 2.5.3 Connecting to the LA34VA Graphics Printer

The VK100 terminal connects to the LA34VA graphics printer in one of two ways.

1. The terminal connects directly to the printer.
2. The terminal is added to the end of a multiterminal string.

If the terminal connects directly to the printer, the printer is dedicated to that terminal. This means the printer is always available to the terminal.

In a multiterminal string, two or more VK100 terminals connect to one printer. Each terminal contains a hardcopy protocol. This protocol prevents problems when more than one terminal tries to use the printer. To request using the printer, press the SHIFT and PF1/HARDCOPY keys together. The terminal looks to see if the printer is busy. If the printer is not busy the terminal immediately sends its data to the printer.

If the printer is currently printing the terminal generates a print request and waits until the printer is available. The print request tells all other VK100 terminals that a terminal is waiting to use the printer. When the printer completes the copy the waiting terminal then sends its data to the printer.

When more than one terminal is waiting to use the printer an internal sequence system takes effect. The sequence system determines which terminal uses the printer next. The sequence system continues in effect until all of the waiting terminals have used the printer.

When using a multiterminal string, all terminals in the string must be powered on. If any terminal in the string is turned off, that terminal and all terminals after it in the string cannot use the printer. Figure 2-8 shows this point. Terminal 3 is turned off, so terminal 4 cannot use the printer. Disconnect any terminal that is turned off in a multiterminal string from the string. Paragraph 2.5.3.2 provides a disconnection procedure.

The following paragraphs provide the two procedures for connecting the VK100 terminal to the LA34VA graphics printer.

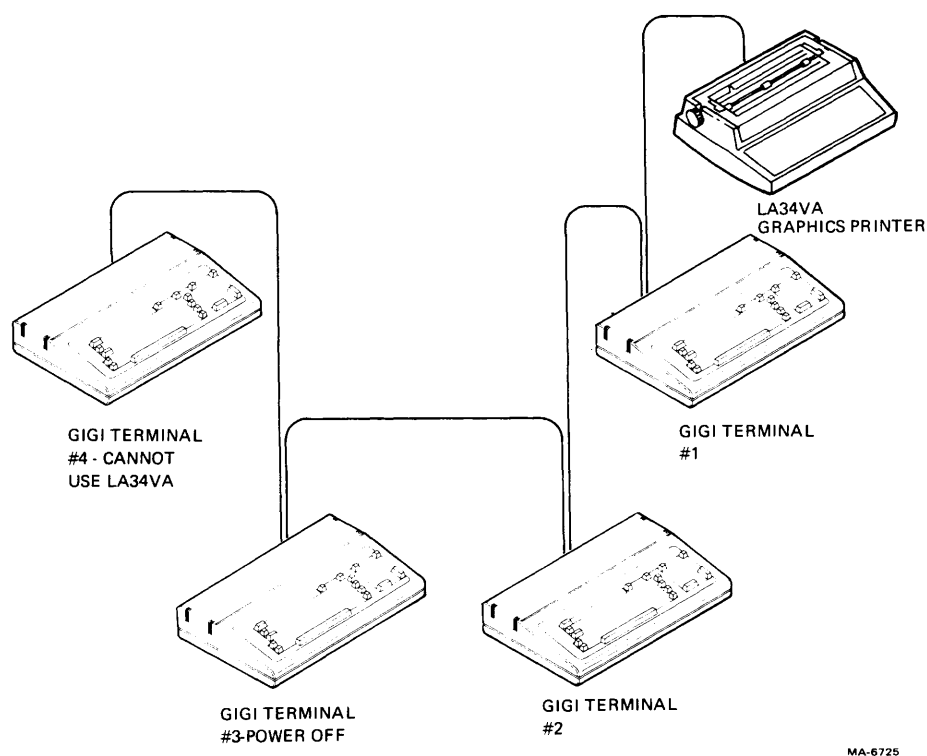


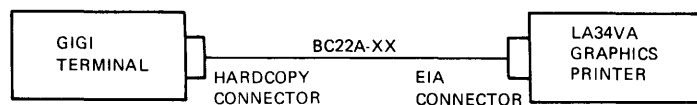
Figure 2-8 Multiterminal String with Terminal Turned Off



**2.5.3.1 Connecting Directly to the LA34VA Graphics Printer --** Use the following procedure for connecting a single VK100 terminal to the LA34VA graphics printer. Maximum cable length is 50 feet. Figure 2-9 shows a simple block diagram of this configuration.

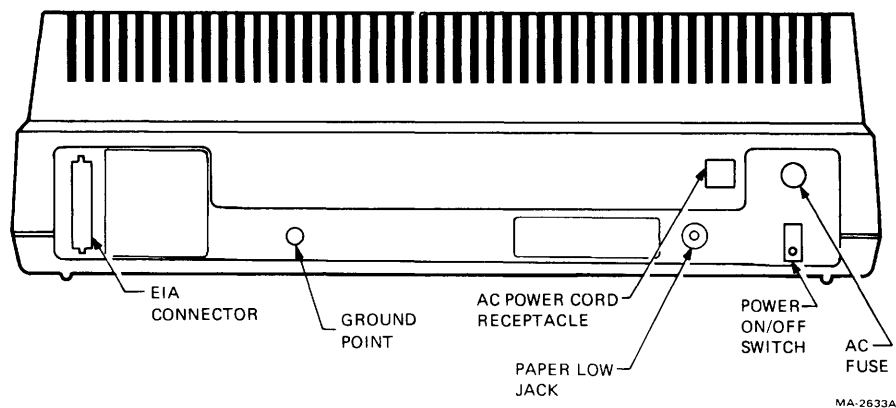
To perform the procedure use a flat blade screwdriver, a BC22A-xx interface cable, and one 8-32 X 5/8 inch screw.

1. Locate and connect the BC22A cable to the HARDCOPY connector on the rear of the VK100 terminal. The connector can only plug in one way. Connect the ground wire to the HARDCOPY connector. Figure 2-6 shows the cable connector with the ground wire connected.
2. Plug the other cable connector into the the EIA connector on the rear of the LA34VA graphics printer. This connector can only plug in one way (Figure 2-10).



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Figure 2-9 Single VK100 (GIGI) Terminal to LA34VA Graphics Printer Connection



MA-2633A

Figure 2-10 LA34VA Graphics Printer (Rear View)

3. Push the 8-32 X 5/8 inch screw through the ring terminal on the end of the ground wire coming out of the cable connector. Locate the grounding screw hole on the LA34VA graphics printer (about 3 inches to the right of the EIA connector). Attach the cable ground wire to the LA34VA graphics printer grounding point.
4. Perform the installation and SET-UP procedures outlined in the DECwriter IV Graphics Printer User Guide (EK-L34RO-UG).
5. Apply power to both terminals.
6. To verify the LA34VA graphics printer connection, place the screen alignment video pattern on the monitor screen. Do this by pressing the following keys in order: SET-UP, S, T, 4, and SET-UP again.
7. Print the screen alignment video pattern on the the LA34VA graphics printer. Do this by pressing the SHIFT and PF1/HARDCOPY keys together.

2.5.3.2 Adding a Terminal to a Multiterminal String -- Use the following procedure if one or more VK100 terminals are connected to the LA34VA graphics printer. Figure 2-11 shows a simple diagram of this configuration.

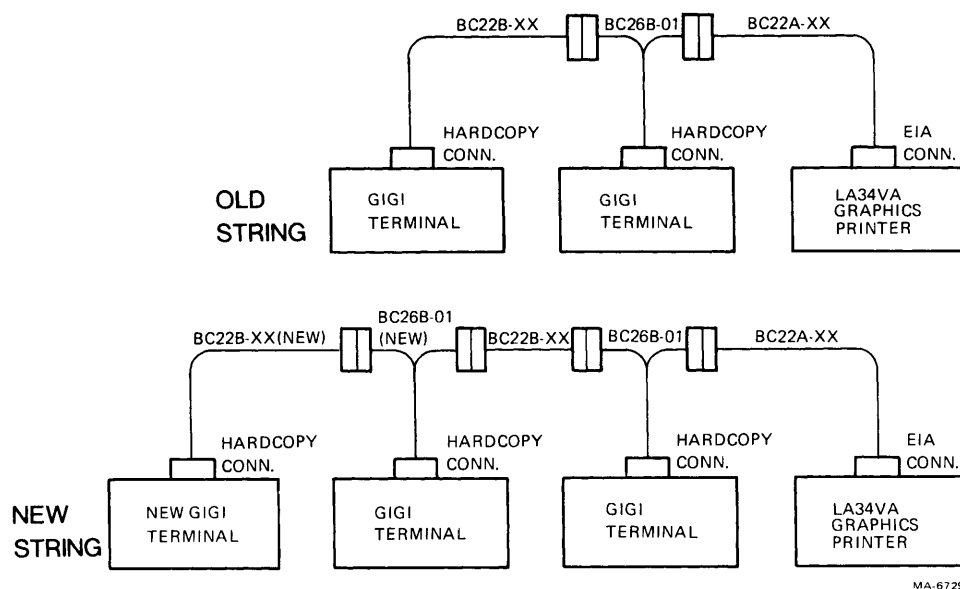


Figure 2-11 Adding a Terminal to a Multiterminal String

To perform the procedure use a flat blade screwdriver, a BC22B-xx interface cable, and a BC26B-01 Y-type cable.

1. Locate the last VK100 terminal in the string attached to the LA34VA graphic printer. Disconnect the cable connected to the HARDCOPY connector on the rear of this terminal.
2. Locate and connect the BC26B-01 Y-type cable to the HARDCOPY connector on the last VK100 terminal. The connector can only plug in one way. Connect the ground wire to the HARDCOPY connector. Figure 2-6 shows the cable connector with the ground wire connected.
3. Connect the cable disconnected from the terminal in step 2 to the female connector of the BC26B-01 Y type cable.
4. Locate the new BC22B cable. Plug one BC22B cable connector into the male BC26B-01 cable connector. The connector can only plug in one way. Connect the ground wire between the two connectors. Figure 2-6 shows the cable connector with the ground wire connected.
5. Plug the other BC22B cable connector into the HARDCOPY connector on the VK100 terminal being added to the string. The connector can only plug in one way. Connect the ground wire to the HARDCOPY connector. Figure 2-6 shows the cable connector with the ground wire connected.
6. Apply power to both terminals.
7. To verify the LA34VA graphics printer connection, place the screen alignment video pattern on the monitor screen. Do this by pressing the following keys in order: SET-UP, S, T, 4, and SET-UP again.
8. Print the screen alignment video pattern on the LA34VA graphics printer. Do this by pressing the SHIFT and PF1/HARDCOPY keys together.

2.5.3.3 Removing a Terminal from a Multiterminal String -- Use the following procedure if two or more VK100 terminals are connected to the LA34VA graphics printer. Figure 2-12 shows a simple diagram of the procedure.

1. Locate the VK100 terminal you want to disconnect.
2. Locate the BC26B-01 Y-type cable connected to the HARDCOPY connector on the rear of this terminal. Disconnect the two cables connected to the BC26B-01 Y-type cable.
3. Connect the two cables that were removed from the BC26B-01 Y-type cable. Be sure to connect the cable ground wires between the two connectors. Figure 2-6 shows the cable connectors with the ground wire connected.

The terminal is now disconnected from the multiterminal string.

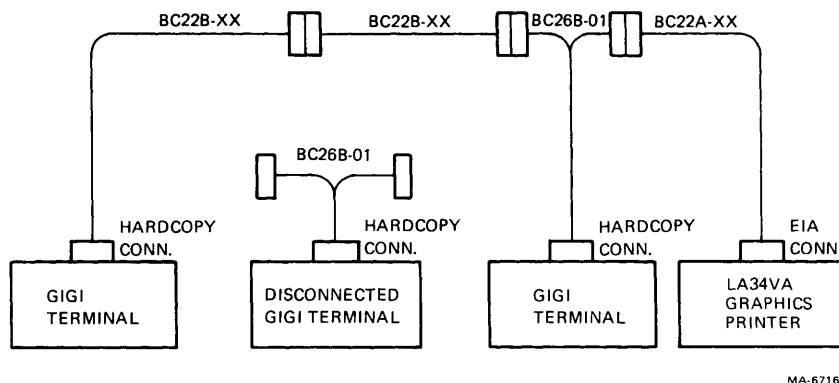


Figure 2-12 Removing a Terminal from a Multiterminal String

## 2.6        **HARDWARE INTERFACE INFORMATION**

### 2.6.1     **General Communications Interface Information**

The terminal operates on full-duplex, asynchronous communications lines. The physical interfaces are implemented using a 25-pin EIA connector and a 20 mA loop connector.

**2.6.1.1 Baud Rate** -- Transmit and receive baud rates are programmed through the keyboard using the SET-UP commands. Both transmit and receive baud rates can be set independently to: 110, 300, 600, 1,200, 2,400, 4,800, 9,600, or 19,200 baud.

The terminal (set up for jump scroll) supports text writing speeds up to 300 baud without using the XON/XOFF characters for synchronization.

**2.6.1.2 Character Format** -- The format of the asynchronous character is bit serial, consisting of a start bit (always SPACE), seven data bits (MARK equals binary 1, SPACE equals binary 0) an optional parity bit, and one or two stop bits (always MARK). The data bits are ASCII coded, and the least significant bit is transmitted or received first.

The parity bit can be programmed for odd or even parity. If parity is disabled, the eighth bit is set to SPACE and no parity checking occurs on input. If parity is enabled and parity errors are detected, the error character is displayed.

All baud rates have one stop bit per transmitted character, except 110 baud which has two stop bits per character.

The communication data format outlined here is programmed using SET-UP commands.

### 2.6.2     **EIA Interface**

**2.6.2.1 Physical Interface** -- The basic VK100 terminal operates on full-duplex, asynchronous communication lines. The terminal interfaces to the line with a 25-pin connector mounted on the back of the terminal. This connector meets the requirements of EIA Std RS-232-C. Table 2-1 summarizes the EIA connector signals. The following paragraphs explain how the basic VK100 terminal uses each signal.

**Protective Ground - Pin 1** -- This conductor connects to the terminal system ground via a jumper. The conductor cannot be used for reference potential purposes.

**Transmitted Data (from VK100 terminal) -- Pin 2** -- The VK100 terminal transmits serially encoded characters and break signals on this circuit. The circuit is held in the mark state when the terminal is not transmitting characters or break signals.

**Table 2-1 EIA Connector Signals**

Pin	Description	EIA/CCITT Circuit
1	Protective ground	AA/101
2	Transmitted data	BA/103
3	Received data	BB/104
4	Request to send	CA/105
5	(not used)	--
6	Data set ready	CC/107
7	Signal ground*	AB/102
8	(not used)	--
9	(not used)	--
10	(not used)	--
11	(not used)	--
12	(not used)	--
13	(not used)	--
14	(not used)	--
15	(not used)	--
16	(not used)	--
17	(not used)	--
18	(not used)	--
19	(not used)	--
20	Data terminal ready	CD/108.2
21	(not used)	--
22	(not used)	--
23	(not used)	--
24	(not used)	--
25	(not used)	--

\* Common return

Received Data (to VK100 terminal) -- Pin 3 -- The VK100 terminal receives serially encoded characters generated by the user's equipment on this circuit. The terminal is always ready to accept and interpret data after power-up, except in local mode.

Request To Send (from VK100 terminal) -- Pin 4 -- This signal is always asserted (SPACE state) when the terminal is powered up and in the on-line mode.

Clear To Send (from VK100 terminal) -- Pin 5 -- A circuit exists for this signal, but the signal is ignored at all times.

Data Set Ready (to VK100 terminal) -- Pin 6 -- A receiver exists for this signal, but the signal is ignored at all times.

Signal Ground -- Pin 7 -- This conductor establishes the common ground reference potential for all voltages on the interface. It connects to the VK100 terminal system ground.

Data Terminal Ready (from VK100 terminal) -- Pin 20 -- The data terminal ready (DTR) signal is always asserted, except under the following conditions.

1. When the terminal is not powered up
2. When the terminal is in local mode
3. During the 3.5 second interval following the pressing of SHIFT and BREAK.

#### NOTE

This use of data terminal ready (DTR) signal disconnects local and remote data sets when you press SHIFT and BREAK. It also prevents automatic answering when the terminal is in local mode or powered off. This use of DTR also causes the line to disconnect when the VK100 terminal switches from on-line to local mode.

2.6.2.2 Electrical Characteristics -- The EIA interface has the following characteristics. On all signals generated by VK100 terminal, the mark or unasserted state is -6 V to -12 V; the space or asserted state is +6 V to +12 V. On signals received by VK100 terminal, -25 V to +0.75 V or an open circuit is interpreted as a mark or unasserted state; and +25 V to +2.25 V is interpreted as a space or asserted state. Voltages greater than +25 V are not allowed. These levels are compatible with EIA Std RS-232-C and CCITT Recommendation V.28.

2.6.2.3 EIA Interface Cables -- Table 2-2 lists the recommended communication cables for use with the EIA interface.

Table 2-2 EIA Interface Cables

Cable Part Number	Cable Function
BC22A-10	EIA null modem; connects VK100 terminal directly to a line unit (6 conductor cable)
BC22A-25	EIA null modem; connects VK100 terminal directly to a line unit (6 conductor cable)
BC22B-10	EIA extension to modem (14 conductor cable)
BC22B-25	EIA extension to modem (14 conductor cable)

### 2.6.3 20 mA Current Loop Interface

The VK100 terminal current loop interface is a passive configuration, that is, current must be supplied to the VK100 terminal. The transmitter and receiver are both passive and optically isolated; the transmitter goes to the mark state when power is turned off. Table 2-3 lists the recommended 20 mA current loop characteristics.

Table 2-3 20mA Current Loop Characteristics

Condition	Transmitter		Receiver	
	Min	Max	Min	Max
Open circuit voltage	5V	50V	N/A	N/A
Voltage drop marking	0V	4V	—	2.3V
Spacing current		2mA		3mA
Marking current	20mA	50mA	15mA	50mA



2.6.3.1 Electrical Characteristics -- The 20 mA current loop interface has the following electrical characteristics.

2.6.3.2 20 mA Interface Cables -- Table 2-4 lists the recommended communication cables for use with the 20 mA interface.

#### 2.6.4 Buffer Overflow Prevention

The VK100 terminal can operate at transmission speeds up to 19,200 baud. However, the terminal may not be able to keep up with incoming data. The terminal stores incoming characters in a 253-character buffer and processes them on a first-in, first-out basis. When the contents of the buffer reaches 100 characters, the terminal transmits XOFF (023<sub>8</sub> or DC3). On this signal the host computer should stop transmitting to the terminal. If the host stops transmitting, the terminal eventually depletes the buffer. When 50 characters remain in the buffer, the terminal transmits XON (021<sub>8</sub> or DC1) to signal the host that it may resume transmission. If the host fails to respond promptly to the XOFF signal, the buffer continues to fill. When the buffer exceeds its 253-character capacity, a buffer overflow occurs. When the buffer overflows, the VK100 terminal ignores any incoming characters.

Table 2-4 20mA Interface Cables

Cable Part Number	Function
BC05F-15	20 mA cable with Mate-N-Lok connectors for connecting VK100 terminal directly to a line unit.
BC05F-50	20 mA cable with Mate-N-Lok connectors for connecting VK100 terminal directly to a line unit.
BC05F-A0	20 mA cable with Mate-N-Lok connectors for connecting VK100 terminal directly to a line unit.

The only indication of a buffer overflow is the loss of data on the monitor screen. The terminal does not display special characters on the screen to indicate this condition. Use the following formula to determine a possible buffer.

$$\text{Response time} = 153 \times 10 / \text{rec speed} -- 3 \times (\text{trans bits} / \text{trans speed})$$

where:

Rec speed = VK100 terminal receive speed in bits/second (baud).

Trans bits = 10, except at 110 baud where it is 11.

Trans speed = VK100 terminal transmit speed in bits/second (baud).

#### NOTE

The response time is less than 0 only when the receive speed is 19,200 baud and the transmit speed is 110 baud. Never use this combination of receive and transmit speeds.

#### Example 1

The VK100 terminal is transmitting at 1200 baud and receiving at 1200 baud. The terminal sends an XOFF signal which the host must respond to within 1.25 seconds to avoid the buffer overflow.

$$\text{Response time} = 153 \times (10/1200) -- 3 \times (10/1200) = 1.25 \text{ seconds}$$

#### Example 2

The VK100 terminal is transmitting at 300 baud and receiving at 1200 baud. The terminal sends an XOFF signal which the host must respond to within 1.175 seconds to avoid a buffer overflow.

$$\text{Response time} = 153 \times (10/1200) -- 3 \times (10/300) = 1.175 \text{ second}$$

The XON/XOFF synchronization scheme has an advantage over requiring the host to insert delays or filler characters in its data stream. Requiring a minimum of software support, XON/XOFF makes sure that every character or command sent to the VK100 terminal is processed in correct order. This scheme frees interface programs from all timing considerations and produces more reliable operation.

Software that does not support XON/XOFF signals from the VK100 terminal can still use the terminal in text or interactive mode. To do so limit the terminal receive speed to 300 baud in jump scroll mode, or 4800 baud in wrap scroll or scroll off modes. Set the receive higher only if the average line length of the data is known. Table 2-5 shows the maximum speeds (baud rates) for each scroll mode selection at different line lengths.

Table 2-5 Terminal Receive Speed Limits (No XON/XOFF Support)

Scroll Mode	Average Line Length in Characters								
	0	10	20	30	40	50	60	70	80
Smooth	0	600	1200	1200	1200	1200	2400	2400	2400
Jump	300	1200	2400	2400	2400	2400	2400	2400	2400
Wrap/Off	4800	4800	4800	4800	4800	4800	4800	4800	4800

Speeds are expressed as baud rates.

If XON/XOFF cannot be used, use fill characters after certain characters or character strings are sent to the VK100 terminal. Table 2-6 shows the number of fill characters required for these functions. Use either the NUL (000<sub>8</sub>) or the DEL (177<sub>8</sub>) as fill characters.

XON/XOFF support is required whenever the terminal is in the following modes.

- Auto Hardcopy (AH1)
- Graphics mode
- BASIC mode (BA1 or BA2)

If the host computer does not support XON/XOFF buffer synchronization, data will probably be lost. Fill characters and pauses after transmission do not prevent data loss due to the varying sequence execution times.

Table 2-6 Fill Character Requirements

Character or Sequence Received	Receive Speed							
	110	300	600	1200	2400	4800	9600	19200
TAB	--	--	--	--	--	--	1	2
Text	--	--	--	--	--	--	1	3
ED (char)	--	--	--	--	--	--	3	9
CAN	--	--	--	--	--	1	2	4
EL	--	--	--	--	2	6	15	32
FF	--	2	4	9	19	39	79	159
DECALN	--	3	9	21	45	93	189	381
ED (full)	1	9	20	42	86	175	353	709

Two terminal functions, reset and self-test, reinitialize the terminal and erase the buffer. This means characters received after the commands to perform these two functions are lost without being processed.

To compensate for this, the host computer may act in one of the two following ways.

1. Immediately after sending the terminal one of these commands the host may act as if it had received XOFF. Thus the host will not send additional characters until it receives XON. The terminal transmits XON only after it completes the specified operation and the XON/XOFF feature is enabled.
2. When the first method cannot be implemented, the host may use a delay of no less than 10 seconds to allow the terminal time to complete the invoked function. If the invoked function detects an error, there is no guarantee against loss of data. This delay is currently adequate, however, future options may require a change in the delay period.

The VK100 terminal always recognizes received XOFF and XON signals. Receipt of XOFF inhibits the VK100 terminal from transmitting any codes except XOFF and XON. Up to 253 keystrokes are stored in a keyboard buffer (some keys transmit two or three codes, e.g., cursor controls). If the keyboard buffer overflows, keyclicks stop. Transmission resumes upon receipt of XON.

Entering and exiting SET-UP clears all stored keyboard characters and the keyboard locked condition.

#### 2.6.5 Display Interface

The display interface provides the circuitry needed to drive one black and white monitor and one red, green, and blue (RGB) color monitor at the same time. Four separate BNC connectors are located on the rear of the terminal and are labeled as follows.

MONO  
RED  
GREEN  
BLUE

These connectors provide the signals needed to drive both black and white and color monitors.

**2.6.5.1 Composite Video Port (MONO)** -- This interface connector drives an external black and white monitor. The output conforms to EIA RS-330 and has the following nominal characteristics.

Output impedance	75 ohms, dc coupled
Sync level	0.0 V to 0.1 V
Black level	0.3 V +/- 10% when terminated with 75 ohms
White level	1.0 V +/- 10% when terminated with 75 ohms

**2.6.5.2 Color Monitor Port (RED, GREEN, BLUE) --** These interface connectors drive an external RGB color monitor. The RED, GREEN, and BLUE outputs have the following nominal characteristics.

Output impedance                75 ohms, dc coupled

Red and blue signal outputs

Signal level                    1.0 V +/- 10%

Green signal outputs

Signal level                    1.0 V +/- 10%  
 Sync level                    0.0 V to 0.1 V  
 Black level                    0.3 V +/- 10%

**2.6.5.3 Composite Sync Waveform Timing --** The composite sync waveform conforms to EIA RS-330 and has the following nominal characteristics.

Horizontal period	63.131 ~s (15.840 KHz)
Horizontal sync width	4.735 ~s
Front porch	0.789 to 7.891 ~s. The exact timing depends upon the HP SET-UP feature setting. When set to HP5 the front porch is 3.945 ~s.
Back porch	7.891 ~s minus front porch time
Active video time	50.505 ~s
Frame rate	
Noninterlaced (IL0)	60.00 Hz (PF0) or 49.97 Hz (PF1)
Interlaced (IL1)	29.94 Hz (PF0) or 24.95 Hz (PF1)
Vertical sync width	189.394 ~s
Serration during vertical sync	none
Vertical blank	1.262 ms minimum (PF0) 4.609 ms minimum (PF1)
Horizontal scans per frame	264 (PF0 and IL0) 317 (PF1 and IL0) 529 (PF0 and IL1) 635 (PF1 and IL1)

**2.6.5.4 Monitor Selection** -- The display interfaces to drive a number of commercially standard monitors. Monitors connected to the VK100 terminal should have the following capabilities.

Video bandwidth	8 MHz minimum
Horizontal flyback time	12 $\mu$ s maximum
Vertical flyback time	1.0 ms maximum (525-line monitor) 4.3 ms maximum (625-line monitor)
Line rate	15.840 KHz
Frame rate	60 Hz or 50 Hz
Aspect ratio	adjustable to 1:1.6
DC restoration	

To present the best possible display, the VK100 terminal contains a number of SET-UP selectable features to tailor the video output of the terminal to the monitor. These features are as follows.

Feature	Function
PF0	For 60 Hz, 525-line monitors
PF1	For 50 Hz, 625-line monitors
HP0 to HP9	For horizontal centering
HM0 to HM9	To horizontally limit the text display area for monitors with overscan
VM0 to VM9	To vertically limit the text display area for monitors with overscan
EM1	For 40 characters per line display text on low resolution monitors
IL0	For a noninterlaced display to reduce flicker
IL1	For an interlaced display on a monitor with a slow phosphor, or for taking monitor screen photographs

**2.6.5.5 Video Interface Cables** -- Table 2-7 lists the recommended communication cables for use with the video interfaces.

**Table 2-7 Video Interface Cables**

Cable Part Number	Function
BC26M-05	RGB cable with BNC connectors for user-supplied monitor

### **2.6.6 Hardcopy Interface**

The terminal has a serial interface port for interfacing to a LA34VA graphics printer; this allows dumping of bit map information to obtain a hardcopy. A series-chaining scheme allows more than one VK100 terminal to share a single graphics printer.

**2.6.6.1 Physical Interface** -- The interface to an external hardcopy device uses a standard 25-pin female EIA connector. Table 2-8 lists the pin assignments.

**Table 2-8 Hardcopy Interface Pin Assignments**

Pin	Signal Name
1	Protective Ground
2	Downstream Transmitted Data (DTXD)
3	Downstream Received Data (DRXD)
4	Downstream Request To Send (DRTS)
5	Downstream Clear to Send (DCTS)
7	Signal Ground
13	Upstream Clear To Send (UCTS)
14	Upstream Transmitted Data (DTXD)
16	Upstream Received Data (DRXD)
19	Upstream Request To Send (URTS)

**2.6.6.2 Electrical Interface** -- The electrical characteristics of the hardcopy interface are as follows. On signals generated by the VK100 terminal, the mark or unasserted state is -6 V to -12 V; the space or asserted state is +6 V to +12 V. These levels are compatible with EIA Std RS-232-C and CCITT Recommendation V.28.

On signals received by the VK100 terminal, -25 V to +0.75 V or an open circuit is interpreted as a mark or unasserted state, and +25 V to +2.25 V is interpreted as a space or asserted state. Voltages greater than +25 V are not allowed. These levels are compatible with EIA Std RS-232-C and CCITT Recommendation V.28.

**2.6.6.3 Hardcopy Interface Cables** -- Table 2-9 lists the recommended communication cables for use with the hardcopy interface.

**2.6.6.4 Hardcopy Device Sharing** -- The VK100 terminal contains the necessary logic for series-chaining to another VK100 terminal to time share a single hardcopy device. For every series-chained VK100 terminal, a Y-cable (BC26B-01) and a modem cable (BC22B-x) are needed. Chapter 5 provides instructions on how to connect the terminal in a series chain.

There is no limitation on the number of VK100 terminals chained to the hardcopy device as long as the maximum cable length between adjacent terminals is 50 ft. The 50 ft maximum cable length conforms to RS-232-C/CCITT V.28 interface specifications. In practice the number of VK100 terminals served by a single printer is limited by the maximum response time users will accept.

When a VK100 terminal is powered off, all upstream terminals (those farther away from the hardcopy device) are broken off the chain. The cabling system allows downstream terminals to bypass the Y-cable on the powered-off terminal and remain in the chain. As a general practice disconnect all powered-off terminals from the chain. This eliminates the possibility of inducing noise pulses in the chain, which may cause an erroneous printout.



**Table 2-9 Hardcopy Interface Cables**

---

Cable	
Part Number	Function
<hr/>	
BC26B-01	Y-cable for daisy-chaining the LA34VA graphics printer to multiple VK100 terminals
BC22B-25	EIA extension to second VK100 terminal from Y-cable (BC26B-01)
BC22A-10	EIA null modem; connects VK100 terminal directly to a line unit(6 conductor cable)
BC22A-25	EIA null modem; connects VK100 terminal directly to a line unit (6 conductor cable)

---

### 3.3 KEYBOARD CONTROLS

The VK100 terminal has two keypads. The main keypad has a key arrangement and sculpturing styled like a standard office typewriter. The auxiliary or numeric keypad allows you to enter numeric data in a calculator-like fashion.

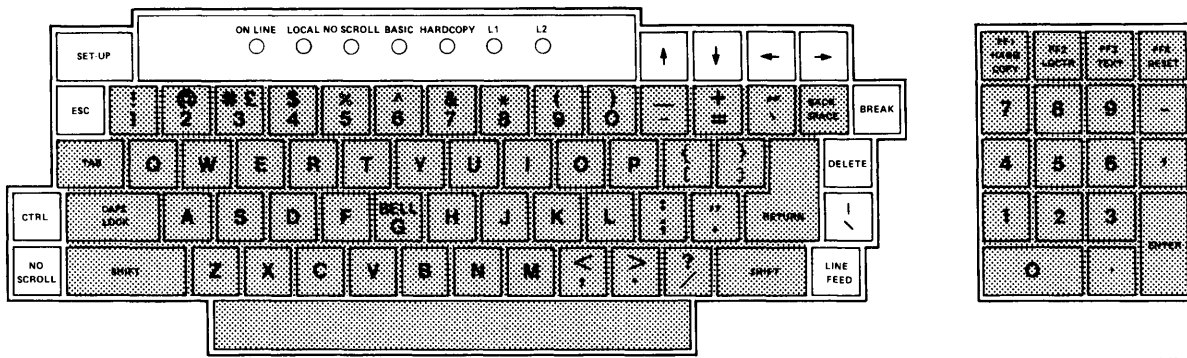
The following paragraphs describe the different VK100 terminal keyboard control groups and their functions.

- Standard keys
- Special function keys
- SET-UP mode keys
- Special mode keys

#### 3.3.1 Standard Keys

Figure 3-2 identifies the VK100 terminal keyboard keys that usually operate like standard typewriter and calculator keys. These keys generate ASCII codes which the terminal transmits to the host computer. The minus, comma, period, and numeric keys of the auxiliary keypad normally generate the same codes as the corresponding unshifted keys of the main keypad. The SHIFT key on the main keypad does not affect the codes generated by the keys on the auxiliary keypad.

The auxiliary keypad has two alternate modes of operation: keypad application mode and programmed keypad mode. The terminal can enter either mode through the SET-UP parameters or a command from the host computer. In both modes the auxiliary keypad generates control functions.



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Figure 3-2 Standard Keys



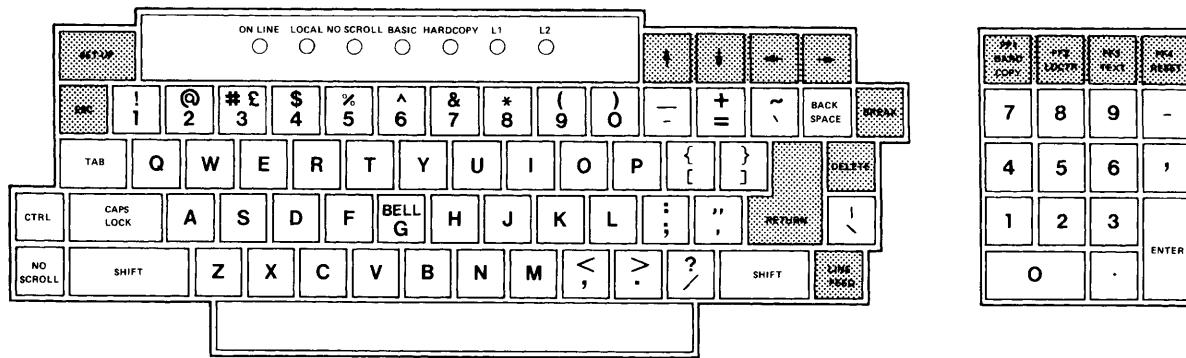
### CAPS LOCK

This key enables the uppercase function of alphabetic keys only. All numeric and special symbol keys remain in lowercase.



### SHIFT

This key enables the uppercase function of all keys. If a key does not have an uppercase function, the SHIFT key has no effect.



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Figure 3-3 Special Function Keys

### 3.3.2 Special Function Keys

Figure 3-3 identifies the special function keys on the VK100 terminal keyboard. The following paragraphs provide a general description.

**SET-UP**

#### SET-UP

Pressing this key causes the VK100 terminal to enter SET-UP mode. Terminal parameters such as scrolling can be changed in this mode.



#### Arrows

Each of these keys causes the VK100 terminal to transmit a control function code to the host computer. Usually the control functions are interpreted as commands to move the cursor in the direction of the arrow.

**BREAK**

#### BREAK

This key transmits a break signal. Pressing BREAK with either of the SHIFT keys transmits the long break signal.

**PF1  
HARD  
COPY**

#### PF1/HARDCOPY

Pressing this key by itself causes the VK100 terminal to transmit a control function code.

Pressing this key with either of the SHIFT keys causes the optional printer to copy the current contents of the monitor screen. During the copying process the screen is frozen. Once the

printer finishes the copy, the screen resumes normal operation. If a printer is not connected to the terminal, pressing this key freezes the screen for a short time just as if a printer was copying the screen.

Pressing the SHIFT and PF1/HARDCOPY keys a second time stops the printing of the screen contents. When this occurs the terminal returns to the previous operating mode.

PF2  
LOCTR

#### PF2/LOCATOR

Pressing this key by itself causes the VK100 terminal to transmit a control function code.

Pressing this key with either of the SHIFT keys causes the terminal to enter locator mode and display the locator cursor ( + ) on the screen. Section 3.3.4 provides more information on the locator mode.

PF3  
TEXT

#### PF3/TEXT

Pressing this key by itself causes the VK100 terminal to transmit a control function code.

Pressing this key with either of the SHIFT keys causes the terminal to enter text mode and disable graphics mode. When it enters text mode, the terminal cancels any special graphics display parameters that were selected. If the terminal was already in text mode, pressing this key resets any special text features.

PF4  
RESET

#### PF4/RESET

Pressing this key by itself causes the VK100 terminal to transmit a control function code.

Pressing this key with either of the SHIFT keys resets the terminal. This action is almost the same as turning the power switch off and on. All of the contents of memory are lost except the SET-UP parameter settings, soft character sets, BASIC program, graphics mode macrographs, and any special key definitions. This reset function does not change the SET-UP parameter settings.

DELETE

#### DELETE

This key causes the VK100 terminal to transmit a delete character code to the host system. The deleted character may or may not be erased from the screen.

A black rectangular key with the word "RETURN" printed in white capital letters.

RETURN

### RETURN

This key transmits either a carriage return (CR) code or a carriage return (CR) and line feed (LF) code. Select the desired function through the New Line (NL) SET-UP parameter.

A black rectangular key with the words "LINE FEED" printed in white capital letters.

LINE  
FEED

### LINE FEED

This key transmits a line feed (LF) code.

A black rectangular key with the words "NO SCROLL" printed in white capital letters.

NO  
SCROLL

### NO SCROLL

This key is controlled by the XO SET-UP parameter. If the XO parameter is on, pressing this key the first time stops data transmission from the host computer to the VK100 terminal. This also lights the NO SCROLL indicator above the keyboard, to show that the terminal is not sending or receiving data. Pressing the key a second time resumes transmission from where it stopped. This also turns off the NO SCROLL indicator. If the XO parameter is off, this key is inactive and has no effect on the terminal.

A black rectangular key with the word "CTRL" printed in white capital letters.

CTRL

### CONTROL

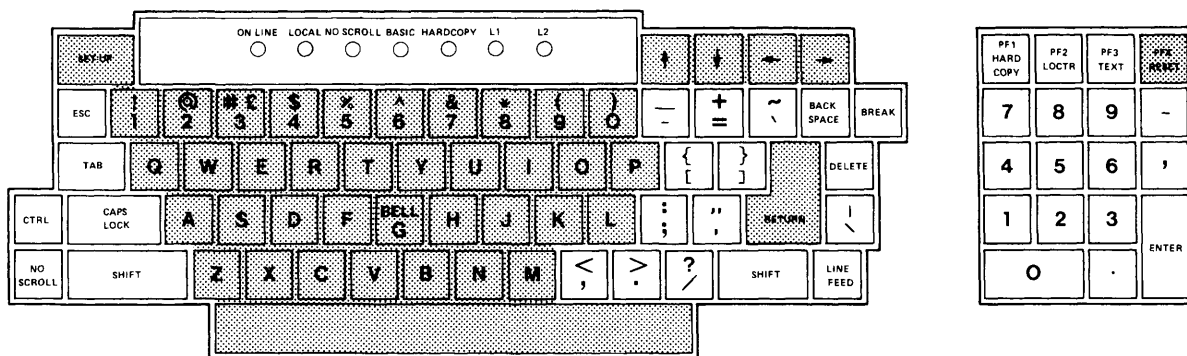
Pressing this key in combination with another key causes the VK100 terminal to transmit a control code.

A black rectangular key with the word "ESC" printed in white capital letters.

ESC

### ESCAPE

This key transmits an escape code.



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Figure 3-4 SET-UP Mode Keys

### 3.3.3 SET-UP Mode Keys

Figure 3-4 identifies the keys available in SET-UP mode. Section 3.5 provides a detailed description of the SET-UP mode.



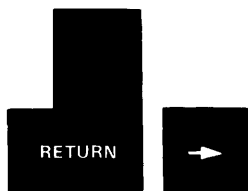
#### SPACE BAR or UP ARROW

Either key steps to the next higher setting for a SET-UP parameter. When the highest value is reached, the setting returns to 0 and starts the cycle over again. Each key performs the same function.



#### DOWN ARROW

This key steps to the next lower setting for a SET-UP parameter. When 0 is reached the setting returns to the highest value and starts the cycle over again.



#### RETURN or RIGHT ARROW

Either key steps the terminal to the next SET-UP parameter. When the last parameter appears on the screen, the terminal automatically returns to the first SET-UP parameter. Each key performs the same function.



#### LEFT ARROW

This key steps the terminal backwards to the previous SET-UP parameter. When the first parameter appears on the screen, the terminal automatically returns to the last SET-UP parameter.

**Alphabetic Keys --** These keys enter the two-letter code for each SET-UP parameter. This displays any SET-UP parameter without stepping through all the parameters. If the operator types an incorrect code, the terminal sounds the bell tone and displays the last correct parameter.

**Numeric Keys --** These keys enter the numeric parameter setting of a SET-UP parameter. This sets a parameter without stepping through all the parameter settings. If the operator types an incorrect setting, the terminal sounds the bell tone and displays the last correct parameter setting.

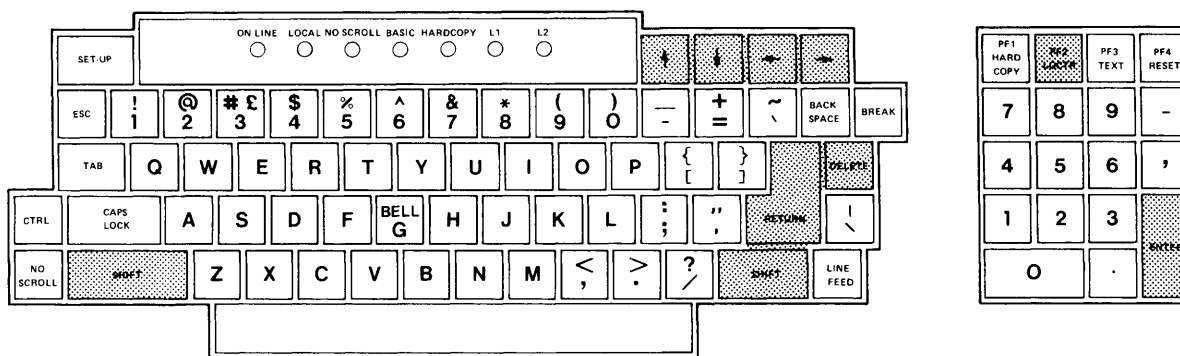


#### PF4/RESET

Pressing this key with either of the **SHIFT** keys resets the terminal to the power-up state. All the contents of memory, including the SET-UP parameter settings, are lost. Pressing these keys in SET-UP mode is the same as turning the terminal power switch off and on.

When the operator presses this key by itself, the terminal sounds the bell tone.





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Figure 3-5 Locator Mode Keys

### 3.3.4 Locator Mode Keys

Figure 3-5 identifies the keys that have a special meaning to the terminal in locator mode. The following paragraphs briefly describe the function of the locator keys in locator mode. If the operator presses any keys other than those described, the terminal exits locator mode, sends the code of the key pressed, and then sends the screen location of the locator cursor. If the terminal enters locator mode through the host computer, the terminal sends a carriage return (CR) code followed immediately by the key code.

PF2  
LOCTR

#### PF2/LOCATOR

Pressing this key with either of the **SHIFT** keys causes the terminal to enter locator mode and display the locator cursor ( + ) on the screen.



#### ARROWS

These keys move the locator cursor ( + ) around the screen. Each time the operator presses the key, the locator cursor moves one dot in the direction shown by the arrow on the key. Pressing **SHIFT** with one of the arrow keys moves the locator cursor ( + ) ten dots in the direction shown by the arrow on the key.



#### ENTER or RETURN

Either of these keys end the locator mode. The terminal sends the screen position of the locator cursor to the host computer.



#### DELETE

This key ends the locator mode; however, the terminal does not send the screen position of the locator cursor to the host computer. If the terminal enters locator mode through the host computer, the terminal sends a carriage return (CR) code.

### 3.4 VISUAL AND AUDIBLE INDICATORS

The VK100 terminal has two types of indicators: visual indicators above the keyboard, and audible alarms.

#### 3.4.1 Visual Indicators

Figure 3-6 shows the location of the keyboard indicators. The following paragraphs describe the function of each indicator.

##### ON LINE

This indicator lights to show that the VK100 terminal is on-line and ready to transmit or receive messages from the host computer. The ON LINE indicator can also show self-test errors.

##### LOCAL

This indicator lights to show that the terminal is off-line and cannot communicate with the host computer. In local mode the keyboard remains active and all typed characters appear on the screen. The LOCAL indicator can also show self-test errors.

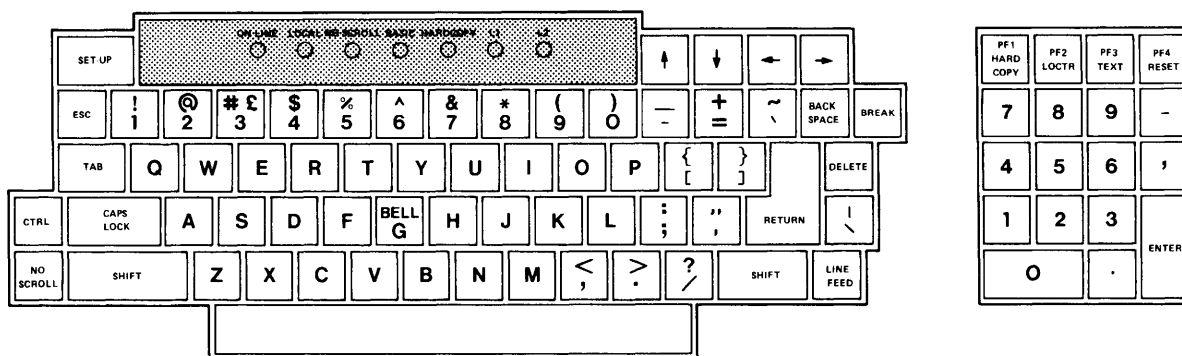


Figure 3-6 Keyboard Indicators

### NO SCROLL

This indicator lights to show that the NO SCROLL key was pressed and the terminal is no longer receiving or sending data to the host computer. The codes for any keys pressed while the NO SCROLL indicator is on are stored in the terminal and sent after the indicator turns off. To continue sending or receiving data, press NO SCROLL a second time. The NO SCROLL indicator is inactive if the XO SET-UP parameter is off (X00).

### BASIC

This indicator lights to show that the terminal is in the BASIC program mode. In this mode the terminal interprets all data entered on the keyboard or received from the host computer as BASIC language commands. The BASIC indicator also shows self-test errors.

### HARDCOPY

This indicator lights to show that the optional hardcopy printer is copying the screen. When the operation is complete, the terminal turns the indicator off. The HARDCOPY indicator also shows self-test errors.

### L1 and L2

These indicators are turned on and off by the host computer. The L1 and L2 indicators also show self-test errors.

### 3.4.2 Audible Indicators

The VK100 terminal has two audible alarms: a short tone (click) and a long tone (beep).

**Short Tone (click)** -- The terminal sounds the short tone whenever the operator presses a key, with the following exceptions.

1. SHIFT and CTRL keys do not generate a keyclick, because these keys do not transmit codes. These keys only modify the codes transmitted by other keys.
2. No key generates a keyclick if the keyclick parameter is turned off in SET-UP mode.

**Long Tone (beep)** -- The terminal sounds the long tone when one of the following conditions occurs.

1. The terminal enters SET-UP mode.
2. The terminal receives a bell code from the computer.
3. The cursor is eight characters away from the right margin, and the margin bell parameter is enabled.
4. The operator enters an incorrect parameter code or parameter setting in SET-UP mode.

### 3.5 SET-UP MODE DESCRIPTION

The VK100 terminal contains many features. Some of these features help the operator in the daily use of the terminal. Other features allow the terminal to talk to many different types of computers and computer programs. To change these features to the required settings the terminal contains a special mode of operation called SET-UP mode.

In SET-UP mode, the terminal displays the status of each parameter stored in the terminal memory individually on the monitor screen. Once the parameter code appears, the operator can change the parameter setting. Changing the parameter setting causes the terminal to operate according to the new setting. The effect is the same as turning a switch on or off.

Enter SET-UP mode by pressing SET-UP. The following events occur.

1. The monitor screen scrolls down six character lines.
2. The long tone sounds.
3. The monitor enters the expanded mode.
4. A message similar to the following appears at the top center of the screen.

SET-UP TS4 2400

The word SET-UP indicates the terminal is in SET-UP mode.

The next two characters are the SET-UP parameter code. This code represents the SET-UP parameter the operator can change. In this case the code is TS and stands for Transmit Speed.

Immediately following the SET-UP parameter code is its current setting (4 in this case). This parameter setting code changes when the parameter setting changes.

The last four characters in the message are an abbreviation of the current parameter setting. The abbreviation in this case is 2400, to show that the terminal transmit speed is set for 2400 baud (bits per second). The parameter setting abbreviation varies from setting to setting.

The parameter settings entered in SET-UP mode are not permanent. Every time the operator turns terminal power off, the parameter settings return to a condition known as default. The default conditions reside in two different physical locations in the terminal, the default SET-UP switch pack and the read only memory (ROM).

The default SET-UP switch pack controls the following parameters.

- Transmit (TS) and receive (RS) speed together
- Parity (PE)
- Default character (UK) sets
- Communications interface (CI)
- Power frequency (PF)

The operator can change the default values for these SET-UP parameters while installing the terminal. Refer to section 2.5 for the procedure to follow. This chapter discusses the specific function and possible settings for each SET-UP parameter.

All other default SET-UP parameter settings are controlled by the read only memory (ROM) in the VK100 terminal. These default parameter settings are permanent. For a parameter setting different from the default setting, change the setting each time terminal power is turned on.

### 3.5.1 SET-UP Parameter Summary

The VK100 terminal contains all the SET-UP parameters listed in Table 3-1. The first column in the table lists the SET-UP parameters in the order they appear on the monitor screen. The second column lists the parameter codes, and the third column lists the possible setting codes for each parameter. The next column lists the exact message that appears on the screen, and the last column briefly describes what the parameter does for that setting.

This table serves only as a brief summary of the SET-UP parameters and how they affect the VK100 terminal. See the SET-UP Parameter Descriptions section of this chapter for a more complete description of each parameter.

Table 3-1 SET-UP Parameter Summary

SET-UP Parameter	Para Code	Set Code	Displayed Message	Function
Transmit Speed	TS	0	TS0 110*†	Set transmit speed to 110 baud.
	TS	1	TS1 300	Set transmit speed to 300 baud.
	TS	2	TS2 600	Set transmit speed to 600 baud.
	TS	3	TS3 1200	Set transmit speed to 1,200 baud.
	TS	4	TS4 2400	Set transmit speed to 2,400 baud.
	TS	5	TS5 4800	Set transmit speed to 4,800 baud.
	TS	6	TS6 9600	Set transmit speed to 9,600 baud.
	TS	7	TS7 19.2	Set transmit speed to 19,200 baud.
Receive Speed	RS	0	RS0 110*†	Set receive speed to 110 baud.
	RS	1	RS1 300	Set receive speed to 300 baud.
	RS	2	RS2 600	Set receive speed to 600 baud.
	RS	3	RS3 1200	Set receive speed to 1,200 baud.
	RS	4	RS4 2400	Set receive speed to 2,400 baud.
	RS	5	RS5 4800	Set receive speed to 4,800 baud.
	RS	6	RS6 9600	Set receive speed to 9,600 baud.
	RS	7	RS7 19.2	Set receive speed to 19,200 baud.
Local/ Line	LL	0	LL0 Loc1	Local mode.
	LL	1	LL1 OnLn*	On-line mode.

Table 3-1 SET-UP Parameter Summary (cont)

SET-UP Parameter	Para Code	Set Code	Displayed Message	Function
BASIC	BA	0	BA0 Off*	BASIC disabled.
	BA	1	BA1 Loc1	BASIC enabled in local mode.
	BA	2	BA2 Host	BASIC enabled in host mode.
Parity Enable	PE	0	PE0 Off*+	Parity off, bit 8 set to SPACE.
	PE	1	PE1 Even	Even parity on, bit 8 set to even parity and checked.
	PE	2	PE2 Odd	Odd parity on, bit 8 set to odd parity and checked.
XON/XOFF	XO	0	XO0 Off	XON/XOFF not sent automatically.
	XO	1	XO1 On*	XON/XOFF sent automatically.
Scroll	SM	0	SM0 Off	No scrolling.
	SM	1	SM1 Jump	Jump scroll.
	SM	2	SM2 Smth*	Smooth scroll.
	SM	3	SM3 Wrap	Wrap scroll.
Reverse Video	RV	0	RV0 Off*	Normal video.
	RV	1	RV1 On	Reverse video.
Horizontal Margins	HM	0	HM0*	No horizontal margins.
	HM	1--9	HM(1--9)	Horizontal margins one to nine characters from left and right.
Vertical Margins	VM	0	VM0*	No vertical margins.
	VM	1--9	VM(1--9)	Vertical margins one to nine characters from top and bottom.
Expansion Mode	EM	0	EM0 Norm*	Normal display.
	EM	1	EM1 Expn	Expanded mode (double-width text characters).
Horizontal Position	HP	0--9	HP(0--9)	Horizontal display position.
	HP	5	HP5*	Normal horizontal display position.

\* Indicates the default value of the parameter.

+ This default value is determined by the settings of the default SET-UP switch pack. Refer to Chapter 2 section 2.5 for the procedure to change these settings.

**Table 3-1 SET-UP Parameter Summary (cont)**

SET-UP Parameter	Para Code	Set Code	Displayed Message	Function
Overstrike	OS	0	OS0 Off*	Normal text replacement.
	OS	1	OS1 On	Overlay text writing.
Visual Cursor	VC	0	VC0 Off	Disable visual cursor.
	VC	1	VC1 Text	Enable text visual cursor.
	VC	2	VC2 Grph	Enable graphics visual cursor.
	VC	3	VC3 Both*	Enable both cursors.
Text Display	TD	0	TD0 Norm*	Normal processing of text display.
	TD	1	TD1 Text	Display all characters as text (transparency mode); all characters are displayed as text and not processed, except LF which is displayed as next line.
	TD	2	TD2 Ctrl	Process all characters normally, display all unrecognized characters as text.
Graphics Display	GD	0	GD0 Norm*	Normal processing of graphics.
	GD	1	GD1 Text	Display graphics commands as text.
	GD	2	GD2 Top	Display last line of ReGIS at top of screen.
	GD	3	GD3 Bot	Display last line of ReGIS at bottom of screen.
Graphics Prefix	GP	0	GP0 Off*	Disable graphics prefix mode.
	GP	1	GP1= "!"	Enable graphics prefix mode; character shown in quotes is prefix character.
Single Character	SC	0	SC0 Off*	Normal communications operation.
	SC	1	SC1 On	Single character operation.
Local Echo	LE	0	LE0 Off*	No local echo.
	LE	1	LE1 On	Local echo every key stroke.
New Line	NL	0	NL0 Off*	New line mode disabled.
	NL	1	NL1 On	New line mode enabled.



**Table 3-1 SET-UP Parameter Summary (cont)**

SET-UP Parameter	Para Code	Set Code	Displayed Message	Function
Auto Hard- copy	AH	0	AH0 Off*	Disable auto hardcopy mode.
	AH	1	AH1 On	Enable auto hardcopy mode.
Auto Wrap- around	AW	0	AW0 Off	Disable auto wraparound.
	AW	1	AW1 On*	Enable auto wraparound.
Key Repeat	KR	0	KR0 Off	Disable key repeat parameter.
	KR	1	KR1 On*	Enable key repeat parameter.
Keyclick	KC	0	KC0 Off	Disable keyclick.
	KC	1	KC1 On*	Enable keyclick.
Margin Bell	MB	0	MB0 Off	Disable right margin bell.
	MB	1	MB1 On*	Enable right margin bell.
Terminal Mode	TM	0	TM0 VT52	VT52 mode.
	TM	1	TM1 ANSI*	ANSI mode.
Keypad Mode	KP	0	KP0 Norm*	Numeric keypad mode.
	KP	1	KP1 Appl	Application keypad mode.
Cursor Key Mode	CK	0	CK0 Norm*	Cursor key mode.
	CK	1	CK1 Appl	Cursor key application mode.
Programmed Keypad Mode	PK	0	PK0 Off*	Programmed keypad disabled.
	PK	1	PK1 On	Programmed keypad enabled.
Tablet Locator Mode	TL	0	TL0 Off*	Only four cursor keys control locator mode.
	TL	1	TL1 On	Tablet or cursor keys control locator mode.
UK Character Set	UK	0	UK0 U.S.* †	US character set.
	UK	1	UK1 U.K.	UK character set.
Comm. Interface	CI	0	CI0 EIA*†	EIA comm. interface selected.
	CI	1	CI1 20 mA	20 mA comm. interface selected.

\* Indicates the default value of the parameter.

† This default value is determined by the settings of the default SET-UP switch pack. Refer to Chapter 2 section 2.5 for the procedure to change these settings.

**Table 3-1 SET-UP Parameter Summary (cont)**

SET-UP Parameter	Para Code	Set Code	Displayed Message	Function
Hardcopy Speed	HS	0	HS0 110	Set hardcopy speed to 110 baud.
	HS	1	HS1 300	Set hardcopy speed to 300 baud.
	HS	2	HS2 600	Set hardcopy speed to 600 baud.
	HS	3	HS3 1200	Set hardcopy speed to 1,200 baud.
	HS	4	HS4 2400	Set hardcopy speed to 2,400 baud.
	HS	5	HS5 4800	Set hardcopy speed to 4,800 baud.
	HS	6	HS6 9600*	Set hardcopy speed to 9,600 baud.
	HS	7	HS7 19.2	Set hardcopy speed to 19,200 baud.
Power Frequency	PF	0	PF0 60 Hz*†	60 Hz power frequency.
	PF	1	PF1 50 Hz	50 Hz power frequency.
Interlace	IL	0	IL0 Off*	Interlace turned off.
	IL	1	IL1 On	Interlace turned on.
Self-Test	ST	1	ST1 PwUp	Select power-up self-test.
	ST	2	ST2 ExCm	Select external comm. test.
	ST	3	ST3 HcCm	Select hardcopy comm. test.
	ST	4	ST4 Dspl	Select display pattern test.
	ST	5	ST5 CBar	Select color bar test pattern.
	ST	9	ST9 Rept	Repeat selected test(s) until failure.
	ST	0	ST0 Clr	Clear all selected test(s).

\* Indicates the default value of the parameter.

† This default value is determined by the settings of the default SET-UP switch pack. Refer to Chapter 2 section 2.5 for the procedure to change these settings.

### 3.5.2 Changing a SET-UP Parameter (Operator)

To change any or all of the SET-UP parameters perform the following simple procedure.

1. Enter SET-UP mode by pressing SET-UP.
2. Select the SET-UP parameter you want to change. Use one of the four following methods.
  - a. Type the two-character SET-UP parameter code on the keyboard.
  - b. Press RETURN until the SET-UP parameter code appears on the screen. This key is pressed, the code advances by one.
  - c. Press the > key until the SET-UP parameter code appears on the screen. Each time this key is pressed, the code advances by one.
  - d. Press the < key until the SET-UP parameter appears on the screen. Each time this key is pressed, the code advances by one.
3. Change the parameter setting. Use one of the four following methods.
  - a. Type the single-digit parameter setting. This changes the parameter setting to the typed-in value without stepping through all the possible parameter settings.
  - b. Press the SPACE BAR. Each time the SPACE BAR is pressed the parameter setting advances to the next possible value.
  - c. Press the ↑ key. Each time this key is pressed, the parameter setting advances to the next possible value.
  - d. Press the ↵ key. Each time this key is pressed, the parameter setting goes back to the previous setting.

To change more than one SET-UP parameter, just repeat steps 2 and 3 as often as needed. Pressing either the RETURN or > key advances the terminal to the next parameter and displays the new parameter and its current setting. Pressing the < key steps the terminal back to the previous parameter and displays that parameter and its setting. The terminal always returns to the first parameter (TS) after stepping through all the parameters.

If the operator presses any keys other than SPACE, RETURN, <, >, ↑, ↓, a parameter code letter, or a parameter value, the terminal bell sounds and the last correct parameter or parameter setting appears on the screen.

When all the SET-UP parameters are set, exit the SET-UP mode by pressing SET-UP once. The screen then scrolls back to its original position and the normal viewing area appears again.

### 3.5.3 Changing a SET-UP Parameter (Host Computer)

The host computer can change all VK100 terminal SET-UP parameters. It has this capability because the SET-UP parameters directly affect how the terminal acts with specific programs. To change the SET-UP parameters, the host computer sends escape sequences to the terminal. The terminal then changes the SET-UP parameters and acts according to the new settings.

The Device Control Strings (DCS) section in Chapter 4 describes the specific escape sequences and message formats that change the terminal SET-UP parameters.

## 3.6 SET-UP PARAMETER DESCRIPTIONS

This section describes each SET-UP parameter in detail and explains how each parameter affects the terminal. The SET-UP parameters are listed in the order they appear on the screen.

### NOTE

Unless otherwise stated, entering SET-UP mode and changing parameters does not result in the loss of data on the screen.

### 3.6.1 Transmit Speed (TS)

Set the transmit speed to match the computer receive speed. The VK100 terminal can transmit at any one of the following preselected speeds: 110, 300, 600, 1,200, 2,400, 4,800, 9,600, and 19,200 baud.

Transmit speed is independent of receive speed; the terminal can transmit data at one speed and receive data at a different speed.

Select the default value of both this parameter and the receive speed (RS) parameter with the same default SET-UP switch pack settings.

### NOTE

Setting this parameter to 110 baud (TS0) selects two stop bits; all other settings select one stop bit.

### 3.6.2 Receive Speed (RS)

Set the receive speed to match the computer transmit speed. The VK100 terminal can receive at any one of the following preselected speeds: 110, 300, 600, 1,200, 2,400, 4,800, 9,600 and 19,200 baud.

Receive speed is independent of transmit speed; the terminal can receive data at one speed and transmit data at a different speed.

Select the default value of both this parameter and the transmit speed (TS) parameter with the same default SET-UP switch pack settings.

### 3.6.3 Line/Local (LL)

The line/local parameter allows the operator to enter the terminal into either an on-line or a local (off-line) mode. When the terminal is on-line (the ON-LINE indicator lights), all characters typed on the keyboard are sent directly to the computer and messages from the computer appear on the screen. In local mode (the LOCAL indicator lights), the terminal is disconnected from the computer; messages are not sent to or received from the computer. Characters typed on the keyboard are echoed directly to the screen.

#### NOTE

When the terminal is on-line (LL1), the data terminal ready (DTR) signal on the EIA communications line is asserted. When the terminal enters local mode (LL0), DTR is deasserted and the LOCAL indicator lights.

### 3.6.4 BASIC (BA)

The BASIC mode parameter allows the operator to select the BASIC programming capability of the VK100 terminal. If the BASIC mode is off (BA0), the terminal operates normally. The line/local parameter (LL) determines if the terminal is on-line or local to the host computer.

When the operator selects BASIC local (BA1), the standard BASIC programming capability of the terminal turns on and the terminal keyboard acts as the input device to BASIC. In this mode, to enter a BASIC program into the terminal type it on the keyboard. The BASIC indicator lights when the parameter is set to BA1.

When the operator selects BASIC host (BA2), the BASIC programming capability of the terminal turns on and the host computer acts as the input device to BASIC. In this mode the host computer normally loads a BASIC program in the VK100 terminal through the communications line. The BASIC indicator lights when the parameter is set to BA2.

### 3.6.5 Parity Enable (PE)

The parity enable parameter defines the type of parity bit that the VK100 terminal generates for transmitted characters and checks for received characters. All characters contain eight bits -- seven data bits and one parity bit. Select the parity bit from one of the three following options.

1. Space parity, which ignores the parity bit for all received characters (PE0)
2. Even parity, with even parity checking for all received characters (PE1)
3. Odd parity, with odd parity checking for all received characters (PE2)

Select the default value of this parameter with the default SET-UP switch pack settings. Section 2.5 provides information on how to set these switches.

### 3.6.6 XON/XOFF (XO)

The VK100 terminal can automatically generate the synchronizing codes XON (DC1) and XOFF (DC3). The synchronizing codes prevent data loss when the host computer sends characters to the terminal faster than the terminal can process them. The XOFF control code stops data transmission from the host computer to the terminal; the XON code signals the host computer to resume transmission.

When the parameter is on, and the receive buffer contains 100 unprocessed characters, the VK100 terminal automatically generates the XOFF code. The receive buffer fills to that point when one of the following events occur.

1. The operator presses NO SCROLL.
2. The operator enters the SET-UP mode.
3. The terminal receives characters faster than it can process them.

The buffer empties only after the operator presses NO SCROLL again or takes the terminal out of SET-UP mode. The terminal then takes characters out of the buffer and processes them one at a time. When 50 characters remain in the buffer, the terminal transmits the XON code to resume transmission from the computer to the terminal.

If the XON/XOFF parameter is off, NO SCROLL is disabled.

If the host computer software does not support the XON/XOFF codes, data sent during buffer-full conditions may be lost.

#### NOTE

The VK100 terminal always stops transmission when it receives an XOFF (DC3) code and resumes transmission when it receives an XON (DC1) code, regardless of the auto XON/XOFF parameter setting.

#### 3.6.7 Scroll Mode (SM)

Scrolling describes the movement of existing lines on the monitor screen to make room for new lines on the screen. The scroll mode function has four possible settings: scroll off, jump scroll, smooth scroll, or wrap scroll.

In scroll off mode (SM0), the text cursor always remains on the top or bottom line of the display. The display does not move up or down. The terminal adds new lines to the screen by writing over the top or bottom line.

In jump scroll mode (SM1), the text cursor immediately moves to the next line. In this mode the existing lines on the screen move up or down to make room for new lines. The new lines appear on the screen as fast as the computer sends them to the terminal. At the higher baud rates, the data is very difficult to read due to the rapid movement of the lines.

#### NOTE

Jump scroll mode allows the terminal to add a maximum of thirty lines per second at the top or bottom of the screen. The XON/XOFF parameter must be enabled and supported by the host computer to make sure that data is not lost when jump scroll mode is enabled.

In smooth scroll mode (SM2), the terminal receives new lines of data at a limited speed. The movement of lines occurs at the smooth, steady rate of eight lines per second, allowing the operator to read the data as it appears on the screen.

#### NOTE

Smooth scroll mode allows the terminal to add a maximum of eight lines per second at the top or bottom of the screen. The XON/XOFF parameter must be enabled and supported by the host computer to make sure that data is not lost when smooth scroll mode is enabled.

In wrap scroll mode (SM3), the terminal adds new lines to the screen by writing over the old lines. When the operator reaches the end of the screen, (bottom or top) the cursor automatically moves to the beginning of the screen, and the terminal writes new lines over the old lines on the screen. Existing data on the screen does not move.

### 3.6.8 Reverse Video (RV)

The reverse video parameter allows the operator to select the background of the screen. In normal screen mode (RV0), the screen contains light (or colored) characters on a dark background. In reverse screen mode (RV1), the screen contains dark characters on a light (or colored) background.

### 3.6.9 Horizontal Margins (HM)

This parameter allows the operator to tailor the video output of the VK100 terminal to the monitor. If the monitor cannot display 84 characters per line, insert margins on both sides of the screen. The width of each margin is in characters.

If the horizontal margin parameter is set for HM0, the monitor can display 84 characters on a line (42 characters if the expansion mode parameter is set for EM1). If the parameter is set for a one-character margin (HM1), both the left and right margins are one character wide. This setting allows only 82 characters per line (40 characters in EM1).

The maximum margin width is nine characters for both the left and right margins. This setting provides space for 66 characters per line (24 characters in EM1).

### 3.6.10 Vertical Margins (VM)

This parameter allows the operator to tailor the video output of the VK100 terminal to the monitor. If the monitor cannot display 24 lines of data, insert vertical margins at the top and bottom of the screen. The height of each margin is in lines.

If the vertical margin parameter is set for VM0, the terminal sends 24 lines of data to the monitor before scrolling the screen. If the parameter is set for VM1, both the top and bottom margins are set for one line. This setting allows the terminal to send 22 lines of data to the monitor before scrolling the screen.

The maximum margin height is nine lines for both the top and bottom margins. This setting allows the terminal to send six lines of data to the monitor before scrolling the screen.

### 3.6.11 Expansion Mode (EM)

This parameter allows the operator to expand characters on the screen to twice their normal width. In normal mode (EM0), characters are seven pixels wide and are spaced two pixels apart. In expanded mode (EM1), characters are 14 pixels wide and are spaced 4 pixels apart.

The EM1 setting allows a maximum of 42 characters per line.

### 3.6.12 Horizontal Position (HP)

This parameter allows the operator to tailor the video output of the VK100 terminal to the monitor. The horizontal position parameter lets the operator center the entire display on the



screen. The normal setting for this parameter is HP5. If the display is left of center, increase the value of the parameter setting. This moves the entire display to the right. If the display is right of center, decrease the parameter setting value. This moves the entire display to the left.

### 3.6.13 Overstrike (OS)

This parameter allows the operator to create special graphics on the screen by typing over characters. If the overstrike parameter is off (OS0), typing over a character replaces the old character with the new character. If the parameter is on (OS1), typing over a character places the new character over the old character without destroying the old character. For example, this parameter allows you to create the "not equal to" sign ( $\neq$ ) by pressing the = key, BACKSPACE key, and / key.

### 3.6.14 Visual Cursor (VC)

This parameter allows the operator to change the visual cursor displayed. The cursor is the visual indicator that shows the active position, where the next character will appear on the screen. The text cursor is a solid block character (■); it only appears when the terminal is in text mode. The graphics cursor is a diamond cross hair (⋄) at the current drawing position; it only appears when the terminal is in graphics mode. Only one cursor appears on the screen at any one time.

The visual cursor parameter has four settings.

In VC0, neither the text cursor nor the graphics cursor appears on the screen.

In VC1, the text cursor appears in text mode, and no cursor appears in graphics mode.

In VC2, no cursor appears in text mode, but the graphics cursor appears in graphics mode.

In VC3, both the text and graphics cursors appear in their respective modes.

### 3.6.15 Text Display (TD)

This parameter controls how characters sent to the display are processed by the terminal.

In TD0, normal processing of both text and ReGIS graphics occurs.

In TD1, all characters appear as graphics text, including all control and escape sequences. No normal processing of these characters occurs, except for line feed (LF) which causes a next-line function. The XON/XOFF codes are still interpreted for synchronization, but also appear as graphics text. Control codes appear as the proposed ANSI standard two-character mnemonics.

In TD2, normal processing occurs; those control codes which are not normally processed appear as graphics text. Unrecognized escape and control sequences do not appear.

### 3.6.16 Graphics Display (GD)

This parameter controls how characters sent to the terminal's ReGIS interpreter are processed.

In GD0, normal ReGIS processing occurs.

In GD1, ReGIS commands appear as text, and no graphics display occurs. When the operator enters ReGIS mode while in GD1, the message "GON" appears on the screen, and "GOFF" appears when the ReGIS string is done.

In GD2 and GD3, normal processing of ReGIS graphics commands occurs. The last line of the ReGIS commands appears as text on the top display line (GD2) or bottom display line (GD3). This line appears only when there are no more ReGIS commands to process, or when you freeze the display by pressing NO SCROLL.

### 3.6.17 Graphics Prefix (GP)

This parameter allows the terminal to enter graphics mode by receiving a single unique character from the host computer. When the graphics prefix character parameter is off (GP0), no graphics prefix character operations can occur. When the parameter is on (GP1), the line feed (LF) character followed by the graphics prefix character enters the terminal into graphics mode. The terminal interprets any characters received after the prefix character as graphics data. The next LF character received returns the terminal to normal text mode. If the graphics prefix character follows the second LF character, the terminal remains in graphics mode for the next line. The terminal does not perform a line feed function when it receives the second LF character.

Use the following procedure to set the graphics prefix character.

1. Enter SET-UP mode and place the graphics prefix character parameter on the screen. If the parameter has not been set, the default character (!) appears as the prefix character.
2. Press the = key.
3. Press the key for the prefix character. The prefix character may be any one of 95 graphic text characters (space thru ~).

The graphics prefix character is now set in the terminal.

### 3.6.18 Single Character (SC)

When this parameter is on (SC1), the terminal sends a carriage return (CR) character after each code or set of codes generated by a single keystroke. The CR character is also sent after a terminal report.

### 3.6.19 Local Echo (LE)

When this parameter is on (LE1), every character sent to the host computer is automatically echoed on the screen. The host computer does not have to transmit the character back to the terminal.

If double characters appear on the screen, turn the local echo parameter off, since the host computer is echoing characters back to the terminal.

### 3.6.20 New Line (NL)

This parameter enables the RETURN key on the terminal to function like the RETURN key on an electric typewriter. When the new line parameter is on (NL1), pressing RETURN generates the carriage return (CR) and line feed (LF) codes. When the terminal receives a LF code, it interprets the code as a carriage return and line feed.

When the parameter is off (NL0), pressing RETURN generates only the CR code; a LF code causes the terminal to perform a line feed only.

If double line feeds occur consistently, turn this parameter off since the computer is performing this function.

### 3.6.21 Auto Hardcopy (AH)

This parameter allows the operator to make a continuous hardcopy record of all text that appears on the screen. When the auto hardcopy parameter is on (AH1), the printer copies the screen:

1. Just before the screen is cleared
2. Each time an entire display of new lines scrolls onto the screen.

### 3.6.22 Auto Wraparound (AW)

This parameter determines where the next character will appear on the screen after reaching the end of the current line. When the auto wraparound parameter is off (AW0), all characters received after reaching the end of the line appear in the last character position of that line. For example, take an 84-character line. With the parameter off, the eighty-fifth text character received appears at the end of the current line and replaces the character already located there. This continues until the terminal receives a carriage return character.

When the parameter is on (AW1), the eighty-fifth text character received appears in the first character position on the next line.

### 3.6.23 Key Repeat (KR)

This parameter allows a key to automatically repeat when you hold the key down for more than 0.5 seconds. The repeat rate speeds up to about 30 characters per second when you hold the key down for more than 1.5 seconds. The key repeat parameter affects all but the following keyboard keys.

BREAK  
ESC  
NO SCROLL  
SET-UP  
RETURN  
CTRL and any other key  
PF1 to PF4  
SHIFT

### 3.6.24 Keyclick (KC)

The keyclick is a tone generated every time the operator presses a key. The keyclick may be turned on or off to suit the operator's needs. However, research and experience have shown that an operator is more accurate when there is an audible feedback from the keyboard.

The keyclick volume is not adjustable.

### 3.6.25 Margin Bell (MB)

This parameter acts like the bell in a typewriter. When the margin bell parameter is on (MB1), the VK100 terminal sounds a tone to alert the operator that the cursor is nine characters from the end of the current line.

### 3.6.26 Terminal Mode (TM)

The VK100 terminal follows two different programming standards -- American National Standards Institute (ANSI) and VT52. In ANSI mode (TM1), the VK100 terminal generates and responds to coded sequences per ANSI standards X3.41-1974 and X3.64-1977. In VT52 mode (TM0), the VK100 terminal is compatible with previous DIGITAL software used on the VT52 video terminal. Chapter 4 summarizes both ANSI and VT52 modes.

### 3.6.27 Keypad Mode (KP)

In normal (numeric) mode (KP0), the auxiliary keypad keys transmit the ASCII codes for the characters engraved on the keycaps, (for example 0 to 9). The ENTER key acts like the RETURN key on the main keyboard. In application mode (KP1), these keys transmit unique escape sequences. Chapter 4 provides the exact escape sequences.

### 3.6.28 Cursor Key Mode (CK)

In normal (cursor) mode (CK0), the four cursor keys send the ANSI cursor movement escape sequences. In application mode (CK1), the cursor keys transmit unique control sequences. Chapter 4 provides the exact escape sequences. In VT52 mode (TM0), this parameter has no effect; the four cursor keys send the codes listed in Table 4-1.

### 3.6.29 Programmed Keypad Mode (PK)

The VK100 terminal can be programmed to send special sequences for any or all of the auxiliary keypad keys. When the programmable keypad parameter is on (PK1), keys that are programmed to send special code sequences send those sequences. Keys not programmed are not affected. If the parameter is off (PK0), all cursor and auxiliary keypad keys transmit their normal sequences as selected by the TM, KP, and CK parameters.

### 3.6.30 Tablet Locator Mode (TL)

This parameter defines how to move the locator mode cross-hair cursor. When the parameter is off (TL0), move the cross-hair cursor by pressing one of the four arrow keys on the keyboard. The cross-hair cursor moves in the direction of the arrow on the key.

When this parameter is on (TL1), an optional tablet pen or cursor positions the cross-hair cursor.

The optional tablet connects to the VK100 terminal at the Hardcopy connector. When the tablet is connected, the terminal cannot be connected to a printer.

### 3.6.31 United Kingdom Character Set (UK)

The VK100 terminal contains two different character sets: the United States ASCII character set and the UK (United Kingdom) character set. The difference between the two sets is one character, the # or £ sign. When this parameter is on (UK1), the UK pound sign £ appears instead of the # sign.

Setting this parameter does not immediately change the character that appears on the screen. To obtain the desired character set reset the terminal.

The default SET-UP switch pack settings determine the default value of this parameter. Section 2.5 of Chapter 2 provides information on how to set these switches.

### 3.6.32 Communications Interface (CI)

This parameter selects the communications interface (EIA or 20 mA current loop) used to connect the terminal to the host computer. A parameter setting of CI0 selects EIA communications. CI1 selects the 20 mA communications. This parameter must be set correctly for the VK100 terminal to communicate with the host computer.

The default SET-UP switch pack settings determine the default value of this parameter. Section 2.5 of Chapter 2 provides information on how to set these switches.

### 3.6.33 Hardcopy Speed (HS)

Set the hardcopy speed to match the hardcopy printer's transmit and receive speed. The VK100 terminal can transmit data to the hardcopy printer at any one of the following preselected speeds: 110, 300, 600, 1,200, 2,400, 4,800, 9,600 and 19,200 baud.

#### 3.6.34 Power Frequency (PF)

This parameter matches the terminal's video output signals to the monitor characteristics affected by the power line frequency. During the terminal installation, set this parameter for the power line frequency, 50 or 60 Hertz. In the US, the correct setting is 60 Hertz (PF0).

The default SET-UP switch pack settings determine the default value of this parameter. Section 2.5 of Chapter 2 provides information on how to set these switches.

#### 3.6.35 Interlace (IL)

Interlace describes a method of displaying characters on the screen. When the interlace parameter is on, every other scan line (row of horizontal dots) appears on the screen. After a complete scan of the screen, the terminal returns to start and scans the lines that were skipped. When the parameter is off, every scan line appears on the screen in order.

Using the interlace parameter with a monitor that does not need an interlaced video input causes the screen to flicker. When using the Barco Model GD33 monitor with the VK100 terminal, turn the interlace parameter off (IL0).

#### 3.6.36 Self-Test (ST)

This parameter selects the internal test programs the terminal performs. The following programs are available.

Clear all selected test(s) (0)  
Power-up test (1)  
External communications test (2)  
Hardcopy communications test (3)  
Display pattern test (4)  
Color bar test pattern (5)  
Repeat the selected test(s) until failure (9)

The self-test parameter allows the operator to select more than one test program. To do this type the number of each test program to be run. The terminal performs the test(s) after exiting SET-UP mode by pressing SET-UP.

#### **4.1 INTRODUCTION**

This chapter summarizes the programming characteristics of the VK100 terminal. The summary covers the following topics.

Codes generated by the keyboard

Character sets

Terminal actions to control sequences in both ANSI and VT52 modes

ReGIS command structure

BASIC command structure

#### **4.2 KEYBOARD CODES**

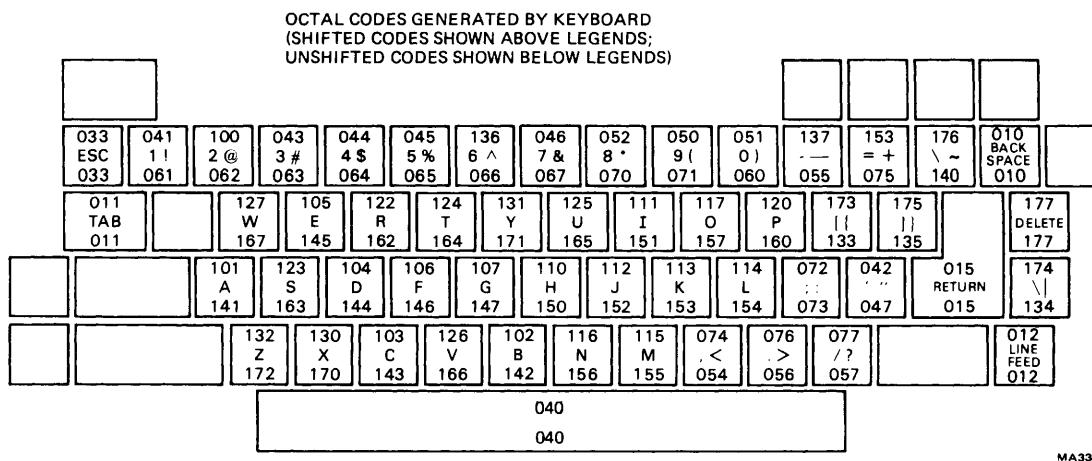
The following paragraphs describe the codes generated by the VK100 terminal keyboard.

##### **4.2.1 Standard Key Codes**

The VK100 terminal keyboard resembles a standard office typewriter. In addition to the standard typewriter keys, the terminal has keys to generate control functions and cursor control commands. Figure 4-1 shows the VK100 terminal keyboard layout and the ASCII codes generated by each key.

##### **4.2.2 Cursor Control Key Codes**

The VK100 terminal's main keyboard contains four cursor control keys. Table 4-1 lists all the possible codes generated by these keys. The operator selects the ANSI/VT52 mode with the terminal mode (TM) SET-UP feature, and the cursor key application mode with the set mode (SM) and reset mode (RM) control functions.



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Figure 4-1 Keyboard-Generated ASCII Codes

Table 4-1 Cursor Control Key Codes

Cursor Key (Arrow)	VT52 Mode	ANSI Mode/Cursor Key Mode Reset	ANSI Mode/Cursor Key Mode Set (Application)
Up	ESC A	ESC [ A	ESC O A
Down	ESC B	ESC [ B	ESC O B
Right	ESC C	ESC [ C	ESC O C
Left	ESC D	ESC [ D	ESC O D



### 4.2.3 Auxiliary Keypad Codes

The VK100 terminal contains an auxiliary or numeric keypad to the right of the main keyboard. Table 4-2 shows all the possible codes generated by the numeric keys. Table 4-3 shows all the possible codes generated by the program function (PF) keys. The operator selects the ANSI/VT52 mode with the terminal mode (TM) SET-UP feature, and the keypad applications mode with the set mode (SM) and reset mode (RM) control functions.

Table 4-2 Auxiliary Keypad Numeric Key Codes

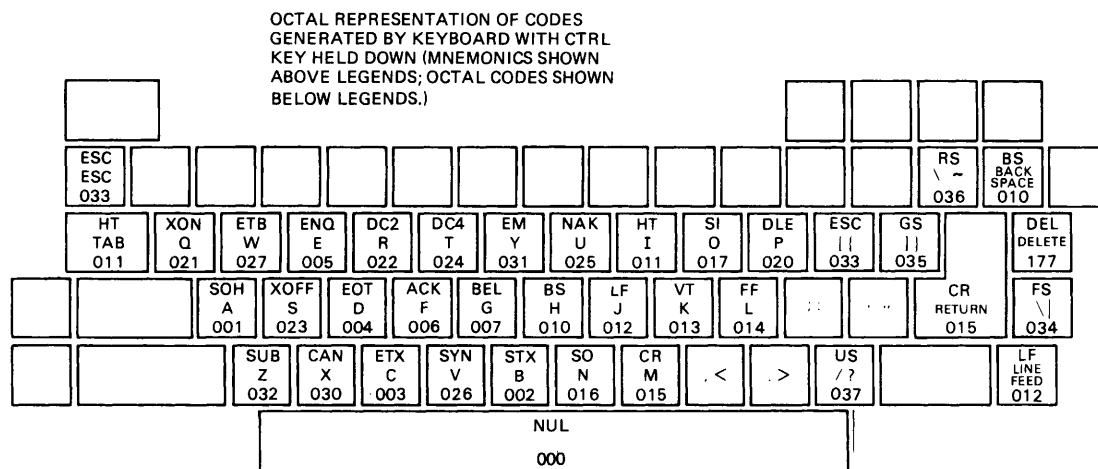
Key	Keypad Numeric Mode	Keypad Application Mode	
		ANSI	VT52
0	0	ESC O p	ESC ? p
1	1	ESC O q	ESC ? q
2	2	ESC O r	ESC ? r
3	3	ESC O s	ESC ? s
4	4	ESC O t	ESC ? t
5	5	ESC O u	ESC ? u
6	6	ESC O v	ESC ? v
7	7	ESC O w	ESC ? w
8	8	ESC O x	ESC ? x
9	9	ESC O y	ESC ? y
-	-	ESC O m	ESC ? m
,	,	ESC O l	ESC ? l
.	.	ESC O n	ESC ? n
ENTER	Same as RETURN	ESC O M	ESC ? M

Table 4-3 Auxiliary Keypad PF Key Codes

Key	Keypad Numeric Mode/ Keypad Application Mode	
	ANSI	VT52
PF1/HARDCOPY	ESC O P	ESC ? P
PF2/LOCTR	ESC O Q	ESC ? Q
PF3/TEXT	ESC O R	ESC ? R
PF4/RESET	ESC O S	ESC ? S

#### 4.2.4 Control Characters

The VK100 terminal generates and supports certain control characters. Figure 4-2 shows the control characters generated by the terminal keyboard. Table 4-4 lists the control characters supported by the VK100 terminal, and the action the terminal takes when it receives each control character. The terminal ignores control characters that it does not support.



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Figure 4-2 Keyboard-Generated Control Codes

**Table 4-4 Terminal-Supported Control Character Functions**

Control Code	Octal Code	Terminal Action
BEL	007	Ring the terminal bell.
BS	010	Backspace the cursor by one position; if at left margin, then no operation.
HT	011	Horizontal tab; move the cursor to next fixed tab position (fixed at eight character intervals). The cursor will not move if at right margin.
LF	012	Line feed; move cursor to next line down. If at bottom margin, the cursor position remains unchanged. If new line mode is enabled, perform carriage return function.
FF	014	Form feed; clear screen and move cursor to home position (upper left corner).
CR	015	Carriage return; move cursor to left margin.
SO	016	Shift out; invoke G1 character set.
SI	017	Shift in; invoke G0 character set.
DC1 (XON)	021	Allows terminal to resume transmitting.
DC3 (XOFF)	023	Causes terminal to stop transmitting all characters except XOFF and XON.
CAN	030	If sent during an escape sequence the sequence is immediately terminated and not executed. Causes the error character (⌘) to be displayed.
SUB	032	Same effect as CAN.
ESC	033	Subsequent character(s) are interpreted as part of an escape sequence.

### 4.3 CHARACTER SETS

The VK100 terminal can contain up to five character sets.

1. United Kingdom (UK)
2. United States (USASCII)
3. Soft character set 1
4. Soft character set 2
5. Soft character set 3

The soft character sets 1 through 3 are the same character sets referenced in the ReGIS mode of operation. The contents of these character sets can be specified to meet specific requirements. The character sets are loaded by using the ReGIS L command. (See the ReGIS command summary in section 4.4.3.)

Using multiple character sets in the VK100 terminal is a simple, two-step operation. Simply define the active character sets and select one of those sets for use.

From the five character sets select one or two active character sets. This is done with the select character set (SCS) control sequence. The SCS control sequence defines the active character sets as G0 and G1. Table 4-5 summarizes the SCS control sequences. It lists the exact sequence needed to define any character set as G0 or G1.

Table 4-5 Select Character Set Sequences

Character Set	G0	G1
UK	ESC ( A	ESC ) A
US ASCII	ESC ( B	ESC ) B
Soft Set 1	ESC ( 0	ESC ) 0
Soft Set 2	ESC ( 1	ESC ) 1
Soft Set 3	ESC ( 2	ESC ) 2

The shift in (SI) and shift out (SO) control characters select the actual character set used. When the terminal receives the shift in (SI,  $\text{017}_8$ ) control character, the character set defined as G0 by the SCS control sequence becomes the active character set. The shift out (SO,  $\text{016}_8$ ) control character activates the character set defined as G1 by the SCS control sequence. The following examples show how the multiple character sets are used.

#### Example 1

You want to use the United States character set and soft character set 3 in the terminal. To select these two character sets as the active character sets, the host computer sends the following control sequences to the terminal.

ESC ( B      To define the United States character set as G0

ESC ) 2      To define soft character set 3 as G1

The shift in and shift out control characters then control the selection of the active character sets. Shift in (SI,  $\text{017}_8$ ) selects the US character set and shift out (SO,  $\text{016}_8$ ) selects soft character set 3.

#### Example 2

You want to use soft character set 1 and the United States character set in the terminal. To define these two character sets as the active character sets, the host computer sends the following control sequences to the terminal.

ESC ( 0      To define soft character set 1 as G0

ESC ) B      To define the United States character set as G1

The shift in and shift out control characters then control the selection of the active character set. Shift in (SI,  $\text{017}_8$ ) selects soft character set 1, and shift out (SO,  $\text{016}_8$ ) selects the US character set.

As the two examples show, any character set can be defined as G0 and any other character set as G1. In those cases only one character set is used, it can be defined as both G0 and G1.

At either power-up or master reset, the terminal defines the default character set as both G0 and G1. The default SET-UP switch pack selects the specific default character set. See Chapter 2 section 2.5 for information on changing the default character set.

#### 4.4 CONTROL FUNCTIONS

The VK100 terminal is an upward and downward software compatible terminal. Previous DIGITAL terminals have DIGITAL private standards for control sequences. The American National Standards Institute (ANSI) has since standardized control sequences in terminals. The VK100 terminal is compatible with both the previous DIGITAL standards and current ANSI standards.

##### NOTE

The ANSI standards allow the manufacturer flexibility in implementing each function. This manual describes how the VK100 terminal responds to the implemented ANSI control functions.

Customers may use existing DIGITAL software designed around the VT52, or new VK100 terminal software designed to meet ANSI standards. The VK100 terminal has a "VT52 compatible" mode in which the VK100 terminal responds to control sequences like a VT52. In this mode, the operator cannot use many VK100 terminal features.

Throughout this chapter references are made to "VT52 mode" or "ANSI mode". These two terms indicate the VK100 terminal's software compatibility. All new software should be designed around the VK100 terminal's ANSI mode. The VT52 mode is included only to provide continuity for existing operating systems support.

The following paragraphs briefly summarize the control sequences implemented by the VK100 terminal. The GIGI ReGIS Handbook, AA-K366A-TK, contains detailed descriptions of the control sequences and the action they perform.

The following ANSI standards were used in implementing the VK100 terminal.

X3.16-1976	Character Structure and Character Parity Sense
X3.4-1977	USA Standard Code for Information Interchange (ASCII)
X3.41-1974	Code Extension Techniques for Use with ASCII
X3.64-1977	Addition Controls for Use with ASCII

The VK100 terminal implements a subset of these standards.

In the list of control functions in this chapter, the characters are shown using the ASCII character set. The case (upper or lower) of the characters sent is significant and must be sent exactly as documented. These characters are spaced apart for clarity only. The SPACE character (040<sub>8</sub>) never appears in any of the VK100 terminal's recognizable control or escape sequences. The ESCAPE character (033<sub>8</sub>) is defined as ESC. All graphics characters shown in bold are integral to the control or escape sequence. Characters not in bold indicate variable parameters (Ps and Pn) or a possible sequence of parameters (...). Where a variable parameter is indicated, the possible values appear immediately after the sequence.

#### 4.4.1 ANSI Control Functions Summary

The following escape and control sequences are transmitted from the host computer to the VK100 terminal unless otherwise noted. The control sequences are listed according to the generic function they perform.

##### 4.4.1.1 Cursor Movement Commands

Sequence	Function
ESC [ Pn A*	Cursor up
ESC [ Pn B*	Cursor down
ESC [ Pn C*	Cursor forward (right)
ESC [ Pn D*	Cursor backward (left)
ESC [ Pl ; Pc H†	Direct cursor addressing
ESC [ Pl ; Pc f	
ESC D	Index
ESC E	New line
ESC M	Reverse index
ESC 7	Save cursor and attributes
ESC 8	Restore cursor and attributes

---

\* Pn is a decimal number expressed as a string of ASCII digits. Multiple parameters are separated by the semicolon character (073<sub>8</sub>). If a parameter is omitted or specified as 0, the default parameter value is used. For the cursor movement commands, the default parameter value is 1.

† Pl equals the line number; Pc equals the column number.

#### 4.4.1.2 Character Attributes

ESC [ Ps ; Ps ; Ps ;...; Ps m

Ps is a selective parameter. Multiple parameters are separated by the semicolon character (073<sub>8</sub>). The parameters execute in order and have the following functions.

Parameter	Function
0 or none	Exit graphic mode and select writing color (same as SHIFT/PF3)
2	Half bright (or green)
4	Underscore on
5	Blink on
7	Reverse video on
30	Black
31	Red
32	Green
33	Yellow
34	Blue
35	Magenta
36	Cyan
37	White
40	Black
41	Red
42	Green
43	Yellow
44	Blue
45	Magenta
46	Cyan
47	White

writing colors

screen colors

Any other parameter values are ignored.

#### 4.4.1.3 Erasing Commands

Sequence	Function
ESC [ K or ESC [ 0 K	From cursor to end of line
ESC [ 1 K	From beginning of line to cursor
ESC [ 2 K	Entire line containing cursor
ESC [ J or ESC [ 0 J	From cursor to end of screen
ESC [ 1 J	From beginning of screen to cursor
ESC [ 2 J	Entire screen

#### 4.4.1.4 Programmable Indicators

ESC [ Ps ; Ps ;...Ps q

Ps is a selective parameter. Multiple parameters are separated by the semicolon character (073<sub>8</sub>). The parameters execute in order and have the following functions.



Parameter	Function
0 or none	All indicators off
1	Indicator 1 on
2	Indicator 2 on

#### 4.4.1.5 Select Character Sets (SCS)

Character Set	Sequence
	G0                      G1
UK	ESC ( A            ESC ) A
US ASCII	ESC ( B            ESC ) B
Soft set 1	ESC ( 0            ESC ) 0
Soft set 2	ESC ( 1            ESC ) 1
Soft set 3	ESC ( 2            ESC ) 2

#### 4.4.1.6 Enter Graphics Mode

Sequence	Function
ESC Pp	Enter and remain in graphics mode until next escape sequence
Line Feed (LF)!	Enter and remain in graphics mode until next line feed character if GP1 is selected

#### 4.4.1.7 Modes

SET-UP parameters are affected by these modes.

		To Set		To Reset	
SET-UP Para	Mode Name	Mode	Sequence	Mode	Sequence
NL	Line Feed/ New Line	New Line	ESC [ 20 h	Line Feed	ESC [ 20 l*
CK	Cursor Key	Appl	ESC [ ? 1 h	Cursor	ESC [ ? 1 l*
TM	ANSI/VT52	ANSI	n/a	VT52	ESC [ ? 2 l*
SM	Scrolling	Smooth	ESC [ ? 4 h	JUMP	ESC [ ? 4 l*
RV	Screen	Reverse	ESC [ ? 5 h	Normal	ESC [ ? 5 l*
AW	Auto Wrap-around	On	ESC [ ? 7 h	Off	ESC [ ? 7 l*
AR	Auto Repeat	On	ESC [ ? 8 h	Off	ESC [ ? 8 l*
OS	Overstrike	On	ESC [ ? 20 h	Off	ESC [ ? 20 l*
BA	Local BASIC	Local	ESC [ ? 21 h	BASIC Off	ESC [ ? 21 l*
BA	Host BASIC	Host	ESC [ ? 22 h	BASIC Off	ESC [ ? 22 l*
PK	Programmed Keypad	Programmed	ESC [ ? 23 h	Normal	ESC [ ? 23 l*
AH	Auto Hardcopy	On	ESC [ ? 24 h	Off	ESC [ ? 24 l*
KP	Keypad	Appl	ESC =	Numeric	ESC >

\* The last character of the sequence is a lowercase l (154<sub>8</sub>).

#### 4.4.1.8 Reports

There are three types of reports with the following escape and control sequences.

##### Cursor Position Report

Invoked by: ESC [ 6 n  
Response is: ESC [ P1 ; Pc R

P1 equals the line number; Pc equals the column number.

##### Status Report

Invoked by: ESC [ 5 n  
Response is: ESC [ 0 n (terminal ok)

##### What Are You

Invoked by: ESC [ c or ESC [ 0 c  
Response is: ESC [ ? 5 ; 0 c or  
ESC [ ? 5 c  
(Meaning: I am GIGI terminal.)

Alternately invoked by ESC Z (not recommended). Response is the same.

#### 4.4.1.9 Reset

ESC c

Reset executes the reset routine. The SET-UP parameters, BASIC program, and soft character sets are not destroyed. This is the same as pressing SHIFT and PF4.

##### 4.4.1.10 Print Commands

Sequence	Function
ESC # 7	Print display image (same as pressing SHIFT and PF1.)
ESC [ Pn ; Pn !q	Print partial image

Pn is a numeric parameter; these parameters specify start and stop line numbers inclusive.

##### 4.4.1.11 Confidence Tests

Sequence	Function
ESC # 8	Generate crosshatch pattern on display
ESC [ 3 ; Pn ;...y	Perform self-tests

Pn selects the test to be performed as follows.

Pn	Test Selected
1	All power-up tests
2	External communications test
3	Hardcopy communications test
4	Display pattern test
5	Color bar test
9	Repeat selected tests until failure

#### 4.4.1.12 Device Control Strings

Sequence	Function
ESC P p (host to terminal)	ReGIS data to follow
ESC P r (host to terminal)	SET-UP data to follow
ESC P key ID code s (host to terminal)	Auxiliary keypad data to follow
ESC P q (terminal to printer)	Hardcopy data to follow*
ESC \	String terminator

---

\* This string is generated by the VK100 terminal and sent to the LA34VA graphics printer. The VK100 terminal does not process the string.

All device control strings must be terminated with a string terminator. For example:

ESC P r ... SET-UP data ... ESC \

#### 4.4.2 VT52 Control Functions Summary

Sequence	Function
ESC A	Cursor up
ESC B	Cursor down
ESC C	Cursor right
ESC D	Cursor left
ESC F	Select soft character set 1
ESC G	Select ASCII character set
ESC H	Cursor to home
ESC I	Reverse line feed
ESC J	Erase to end of screen
ESC K	Erase to end of line
ESC Ylc*	Direct cursor address

---

\* l equals line number, c equals column number. Line and column numbers for direct cursor address are single character codes whose values equal the desired number plus 37<sub>8</sub>. Line and column numbers start at 1.

Sequence	Function
ESC Z†	Identify
ESC =	Enter alternate keypad mode
ESC >	Exit alternate keypad mode
ESC <	Enter ANSI mode
ESC ]	Dump hardcopy
ESC Pp	Enter graphics mode (ReGIS)
ESC \	Exit graphics mode

† Response to ESC Z is ESC / Z. This is not recommended; use What Are You report in ANSI mode.

#### 4.4.3 ReGIS Summary

The following summary of ReGIS commands serves as a quick reference guide. Refer to the software documentation for more information on any command or command argument. Chapter 1 provides a complete list of all the documentation available along with ordering information.

#### ReGIS Commands (graphics mode only)

Command	Function
S c r e e n      d	Screen scroll offset, quantified to [12,8].
[x,y]	Move this address to upper left corner.
[dx,dy]	Scroll screen by this amount.
(W )	Writing controls.
(E r a s e)	Clear data and set foreground color.
(A ddressing [x1,y1] [x2,y2])	Compatibility with other ReGIS devices.
(A ddressing)	Restore native addressing.
(N e g a t e 1)	Reverse video.
(N e g a t e 0)	Restore video to normal mode.
(T i m e nnn)	In 60ths (PF0) or 50ths (PF1) of a second.
(H a r d c o p y [,Y1] [,Y2])	Print hardcopy between Y coordinates.
(I n t e n s i t y	Screen background intensity/color.
0 to 7)	Dark to bright.
(D)) dark	
(B l u e))	
(R e d))	
(M a g e n t a))	Red + blue.
(G r e e n))	
(C y a n))	Green + blue.

## Command

## Function

	(Y ellow))	Red + green.
	(W hite))	Red + green + blue.
	(H ue 0 to 360))	Angle on color wheel.
	(L ightness 0 to 100))	Percentage.
	(S aturation 0 to 100))	Percentage.
W rite	(I ntensity ... 0 to 7) (D)) dark (B lue)) (R ed)) (M agenta)) (G reen)) (C yan)) (Y ellow)) (W hite)) (H ue 0 to 100)) (L ightness 0 to 100)) (S aturation 0 to 100))	Writing intensity/color null; change colors. Dark to bright.
	(A lternate 1) 0)	Red + blue.
	(S hade from [,Y]) (S hade with "c") (S hade 1)  0)	Green + blue. Red + green. Red + green + blue.
	(M ultiplier nnn)	Angle on color wheel.
	(N egate 1)  0)	Percentage.
	(C omplement)	Percentage.
	(oV erlay)	Flashing on. Flashing off. Set shading axis. Set shading character.
	(E rase) (R eplace)	Shade on, line pattern shading. Shade off. Pixels per offset vector.
		Negative writing (invert pattern bits). Positive writing. Exclusive OR pattern with bit map. Logical OR pattern with bit map. Write "negate" setting. Replace, ignore bit map data.

Command		Function
	(P attern bbbbbb)	Binary bit pattern, fills to 8 places.
	(Md))	Multiply each bit pattern.
	l)	Solid line.
	p)	Digits 2--9 specify standard patterns.
P osition	[X,Y] [dx,dy] d	Absolute position. Relative position, d is offset vector, 0--7.
	(W )	Temporary write controls.
	(B egin)	Begin position sequence -- save position
	(E nd)	(up to 7 levels). End and restore starting position.
V ector	[ ] [X,Y] [dx,dy] d	Write point at current cursor position. Absolute position. Relative position, d is offset vector, 0--7.
	(W...)	Temporary write controls.
	(B egin)	Begin closed polygon sequence.
	(E nd)	Draw to starting position.
C urve	[X,Y] [dx,dy] d	Absolute coordinates Relative coordinates Offset vectors, 0--7.
	(B egin)	Begin closed curve.
	(S tart)	Start open curve.
	(E nd)	End curve.
	(W... )	Temporary writing controls.
C ircle	[X,Y] [dx,dy] d	Absolute coordinates. Relative coordinates, offset vectors, 0--7.
	(C ircumference)	Position is on the circumference.
	(A ngle d)	d = degrees resolution, signed.
	(W... )	Temporary writing controls.

Command		Function
T ext	'string'	Display 'string' (includes BS, CR, LF, TAB).
	"string"	Display "string" (includes BS, CR, LF, TAB).
	d	Offset text line by 1/2 character, d = 0--7.
	[dx,dy]	Set spacing between characters.
	(A lphabet 0 to 3)	Select character set 0 to 3.
	(B egin)	Begin temporary text attributes (saves 1 level).
	(D irection d)	d = 45 degrees resolution, signed.
	(E nd)	Restore permanent text attributes.
	(H eight 0 to 16)	Height times base character size (affects S[r,c]).
	(I talic + degrees) - degrees)	Right slant, no. of degrees. Left slant, no. of degrees.
	0)	No slant.
	(M ultiplier [r,c])	No. of times to repeat bits in character. ([1,2] used for standard size.)
	(S ize [r,c])	Dimensions of character area. [9,20] is standard size.)
	(S ize 0 to 16)	Select one of 17 predefined character sizes.
	(W... )	Temporary writing controls.
L oad	(A lphabet 1 to 3)	Select character set 1 to 3.
	'name')	1 to 10 character name for character set; see R(L).
	"c" <10 hex pairs >	Load specific letter with pattern.

Command	Function									
'c' <10 hex pairs >	Load specific letter with pattern.									
@ letter	Invoke macrograph "letter".									
:l etter ... @;	Load macrograph "letter".									
.	Clear all macrographs.									
R eport (L oaded)	Currently loaded character set name.									
(M acrographs (letter ,... ))	Report contents of macrograph "letter".									
(=)	Report macrograph space usage.									
(P osition)	Current position.									
(I nteractive))	Enter locator mode.									
[+dx,+dy))	Arrow increments.									
(M acrographs (letter))	Report contents of macrograph 1.									
(=)	Report macrograph space usage.									
;	Resynchronization character.									
Offset vectors are:	<table><tr><td>3</td><td>2</td><td>1</td></tr><tr><td>4</td><td>*</td><td>0</td></tr><tr><td>5</td><td>6</td><td>7</td></tr></table>	3	2	1	4	*	0	5	6	7
3	2	1								
4	*	0								
5	6	7								
To initialize ReGIS:	;S (I 0 N 0 A) W (V I 7A 0 S 0 M 1 N 0 P 1 M 2) T (I 0 A 0 D 0 S 1) P[0,0]									



#### 4.4.4 BASIC SUMMARY

The following summary of the BASIC commands serves as a quick reference guide. Refer to the software documentation for more information on any command or command argument. Chapter 1 provides a complete list of all the documentation available along with ordering information.

##### 4.4.4.1 Commands/Statements

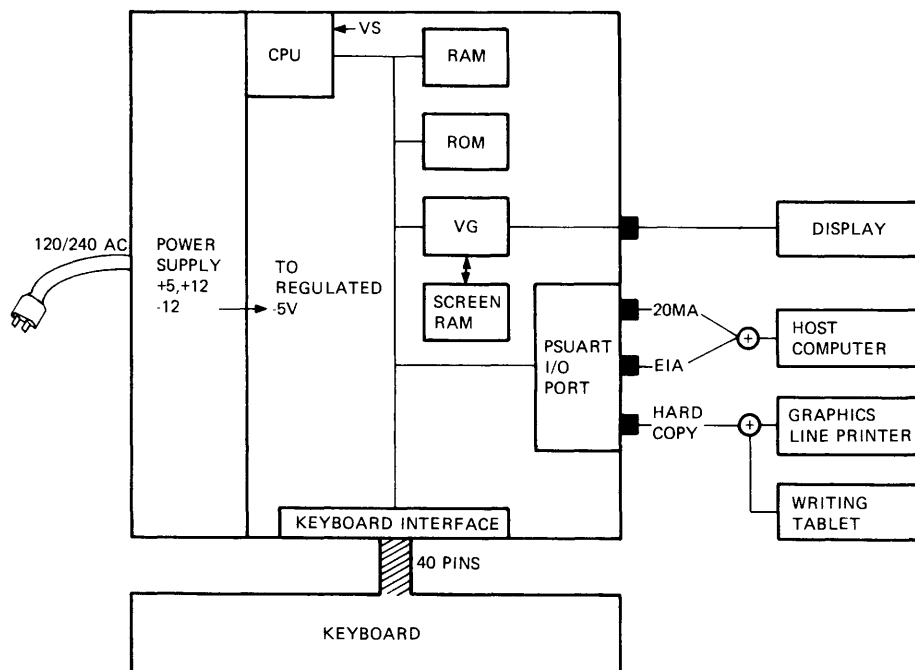
AUTO	CLEAR	CONT	CTRLC
CTRLO	DATA	DEF FN	DELETE
DIM	ECHO	EDIT	END
ERASE	ERL	ERR	ERROR
FOR...NEXT	GOSUB...RETURN	GOTO	HOST
IF...THEN[...ELSE]	IF...GOTO	INPUT	LET
LINPUT	LIST	MID	NEW
NEXT	NO ECHO	OLD	ON ERROR GO TO
ON...GOSUB	ON...GOTO	OPTION BASE	OUT
PRINT	RANDOMIZE	RCTRLC	RCTRL
READ	REM	RESTORE	RESUME
RUN	SAVE	STOP	SWAP
TRON/TROFF	WAIT	WHILE...WEND	WIDTH

##### 4.4.4.2 Functions

ABS	ASC	ATN	CHR\$
COS	EXP	FRE	GOFF\$
GON\$	HEX\$	INKEY\$	INP
INSTR	INT	LEFT\$	LEN
LOG	MID\$	OCT\$	POS
RIGHT\$	RND	SGN	SIN
SPACE\$	SPC	SQR	STR\$
STRING\$	TAB	TAN	

### 5.1 INTRODUCTION

The VK100 terminal is a graphics terminal which displays information from the keyboard in local mode or displays information from the host computer in on-line mode. The system prints the display data on the Graphic Line Printer (LA34VA). A writing tablet can also be connected to the hardcopy port. Only one type of device may be connected to the hardcopy port, graphics line printer or the writing tablet. Figure 5-1 shows the block diagram of the VK100 system.



MA-8150

Figure 5-1 VK100 (GIGI) Block Diagram

## 5.2 TERMINAL CONTROLLER MODULE

This chapter describes the functional theory of the VK100 (GIGI) Terminal. The terminal controller module is divided into five sections (Figure 5-2):

1. CPU
2. Vector Generator
3. I/O Ports
4. Keyboard
5. Power Supply

### 5.2.1 Central Processing Unit (CPU)

The CPU is an 8085 chip; 8-bit general purpose microprocessor capable of accessing up to 64K bytes of memory. Figure 5-3 shows a functional block diagram of the CPU.

The microprocessor (8085A) performs the following functions.

- Clock generation
- Interrupt priority selection
- System bus control
- Executing the instruction

The CPU transfers data on an 8-bit bidirectional Tri-State Bus (AD0--AD7) that is time multiplexed to transmit the eight low ordered address bits. Address bits A8--A15 expand the address capability to 16 bits, allowing the CPU to directly access 64K bytes of memory.

The CPU generates signals telling peripheral devices what type of information is on the multiplexed address/data bus. Figure 5-4 shows the basic CPU blocks. The CPU is a single chip that performs the following machine cycles.

- Memory write
- Memory read
- I/O write
- I/O read
- Opcode fetch
- INT ACK (interrupt acknowledge)
- Bus idle

Table 5-1 shows the machine cycle status and control signals.

The execution of any CPU program is a sequence of read and write operations. Each operation transfers a byte of data between the CPU and a specific memory or I/O address.

Each read or write operation is referred to as a machine cycle. The execution of each instruction by the CPU includes a sequence of from one to five machine cycles. Each machine cycle contains a minimum of from three to six clock cycles (also referred to as T states). Figure 5-5 shows an instruction cycle for Store Accumulator Direct (STA).

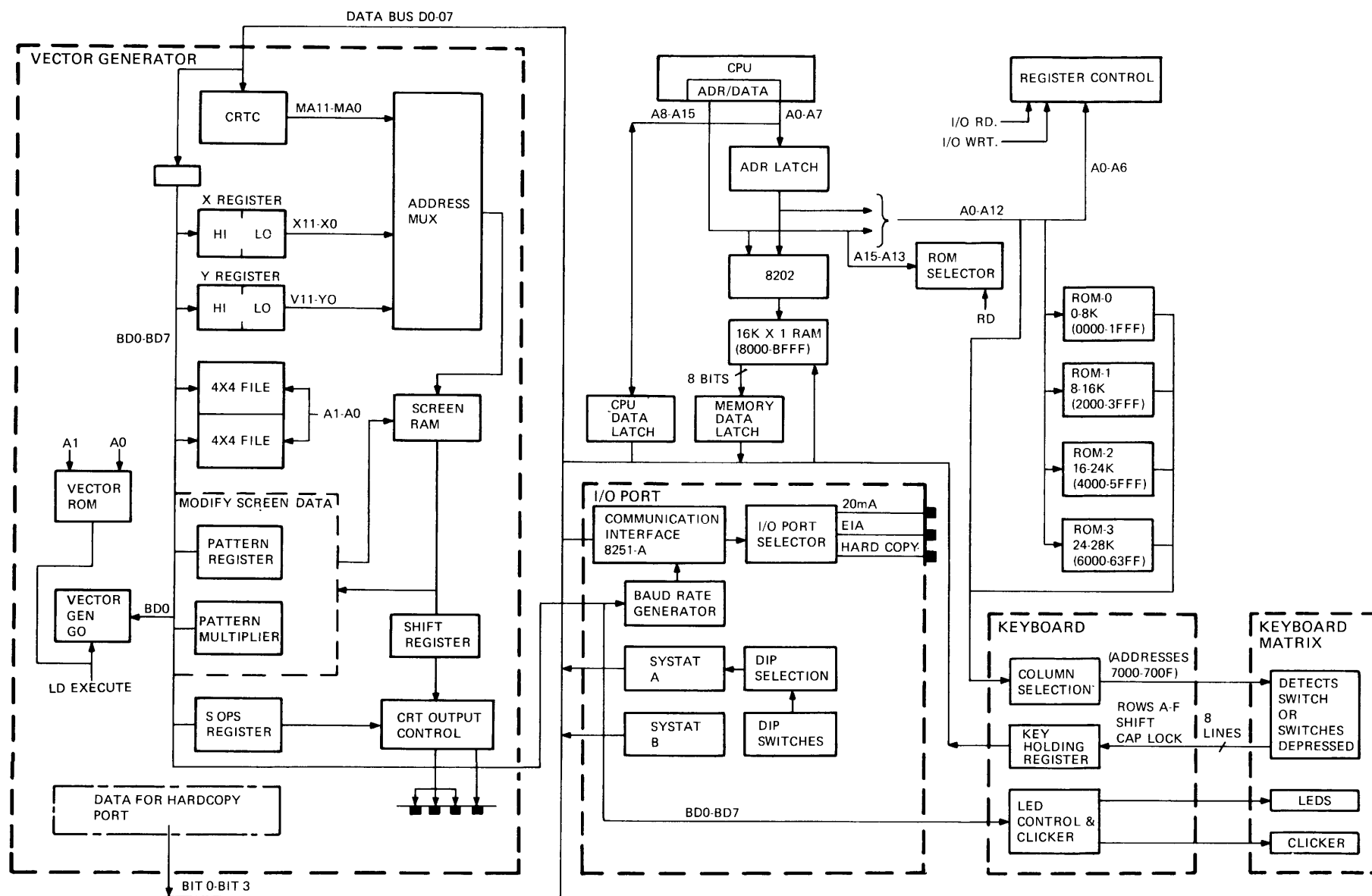


Figure 5-2 System Overview Block Diagram

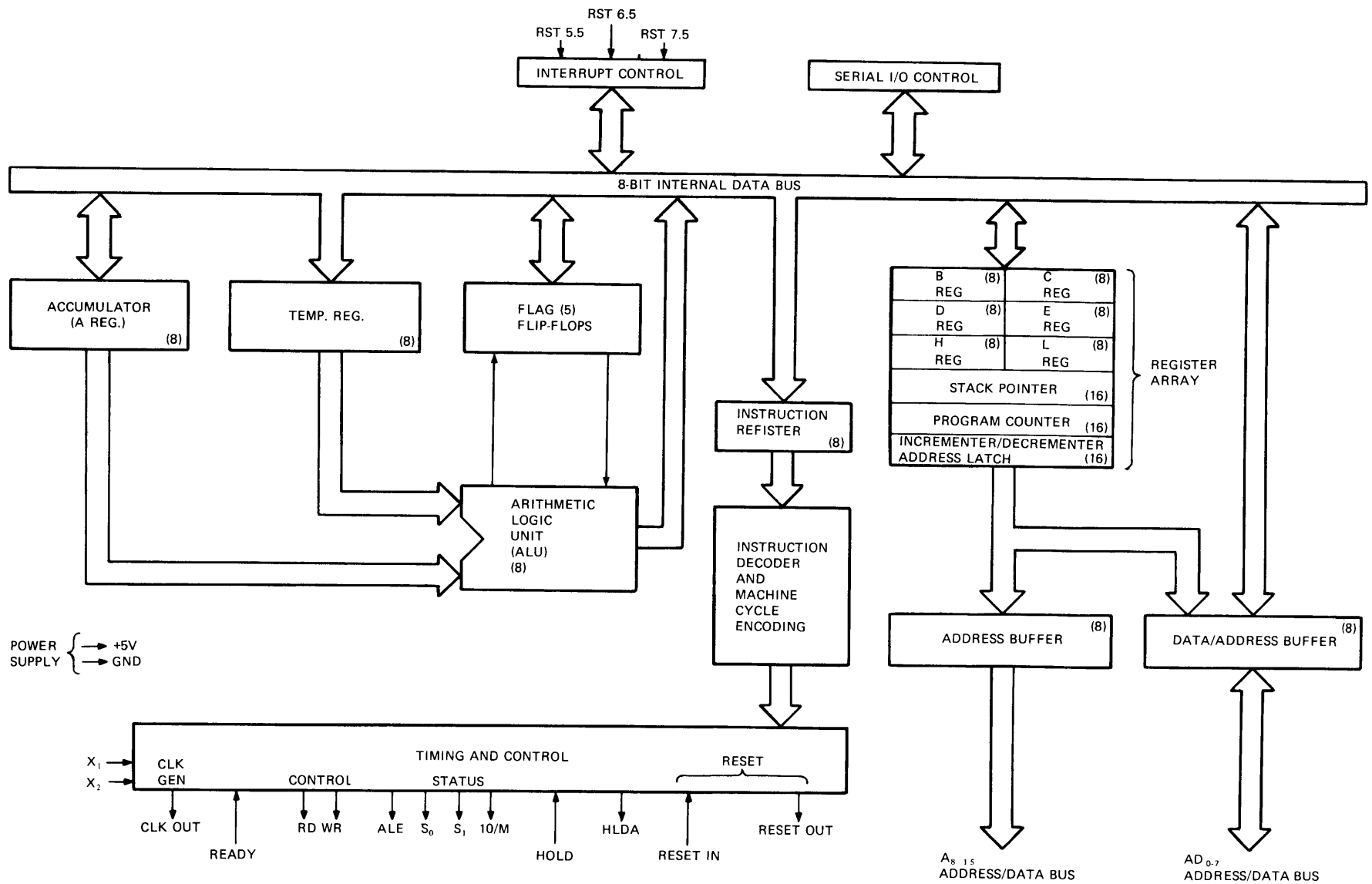


Figure 5-3 CPU Functional Block Diagram

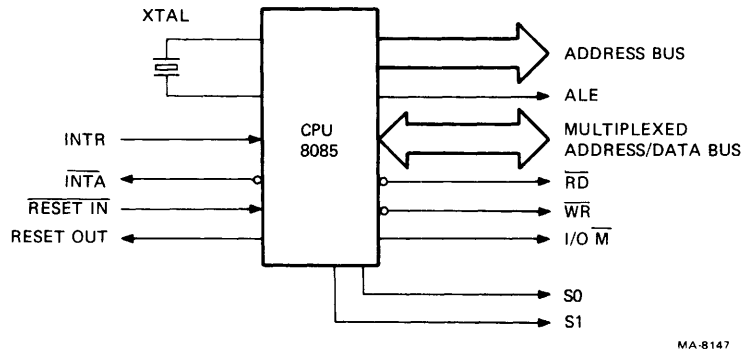


Figure 5-4 Basic CPU Block Diagram

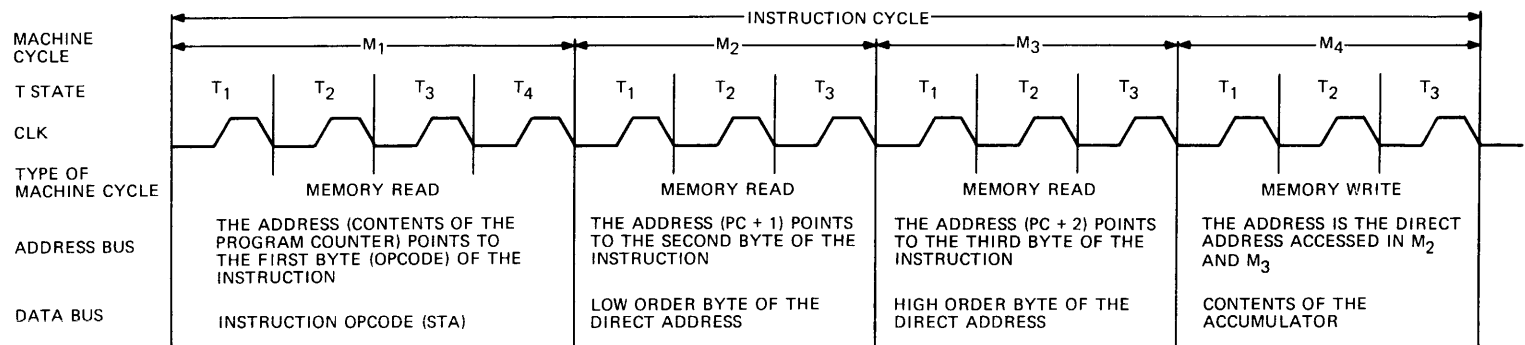
Table 5-1 Machine Cycle Status and Control

Machine Cycle		Status			Control		
		I/O	M	S1	S0	RD	WRT INTA
Op Fetch	(OF)	0	1	1	0	1	1
Memory Read	(MR)	0	1	0	0	1	1
Memory Write	(MW)	0	0	1	1	0	1
I/O Read	(IOR)	1	1	0	0	1	1
I/O Write	(IOW)	1	0	1	1	0	1
INTR Acknowledge	(INA)	1	1	1	1	1	0
Bus Idle*	(BI):DAD	0	1	0	1	1	1
	INA (RSTS/TRAP)	1	1	1	1	1	1
	HALT	TS	0	0	TS	TS	1

0 = Logic "0", 1 = Logic "1", TS = High Impedance

\* Bus idle (BI) only occurs in response to:

1. DAD instructions
2. During an acknowledge of RSTS, TRAP, or HALT instructions.



MA-8192

Figure 5-5 Instruction Cycle for Store Accumulator Direct

The CPU can address up to 256 different I/O addresses. These addresses have the same numerical values (00 through FF Hex) as the first 256 memory addresses. The 256 I/O locations are selected by the I/O M output.

The status signals, I/O M, S1, and S0, define what type of machine cycle is about to occur. The I/O M signal identifies the machine cycle as either a memory reference or input/output operation. The S1 status signal identifies whether the cycle is a read or write operation. S0 and S1 can be used together (see Table 5-1) to identify read, write, opcode fetch, or halt machine cycles. Figure 5-6 shows the timing and control for an opcode fetch.

**5.2.1.1 Address** -- When the CPU generates a 16 bit address, the lower byte is latched and the upper byte is held active by the CPU. Bits A0--A15 address the following:

RAM Memory

A0--A7 -- Row address bits

A8--A15 -- Column address bits

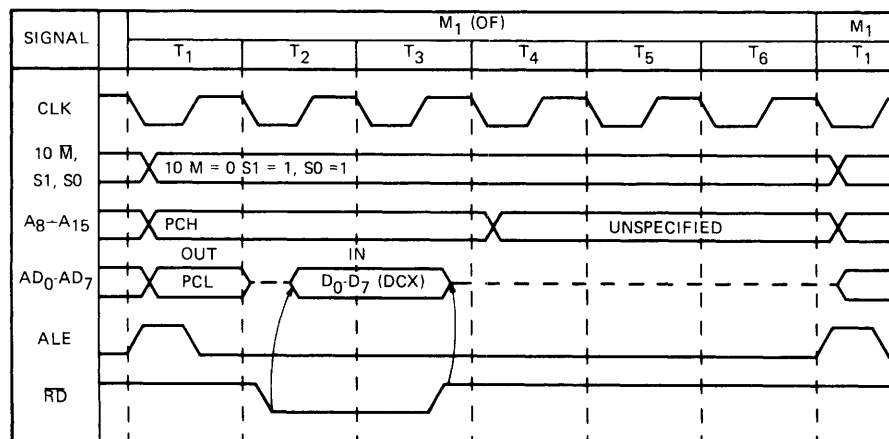
ROM Memory

Address bits A13, A14, and A15 generate ENA ROM 0, ENA ROM 1, and ENA ROM 2. Address bits A0--A12 address the selected ROM.

Register Control

Address bits A0--A6 address and generate register load pulses.

Table 5-2 shows an address map.



MA-8193

Figure 5-6 Opcode Fetch Machine Cycle



Table 5-2 8202 Pin Description

Pin Name	No.	I/O	Pin Description
AL <sub>0</sub>	6	I	Low-Order Address. These Address inputs generate the ROW Address for the Multiplexer. If AL <sub>6</sub> /OP <sub>3</sub> is pulled to +12V through a 5K $\Omega$ resistor, the 8202 configures itself for 4K RAMs. If AL <sub>6</sub> /OP <sub>3</sub> is driven with TTL levels, the 8202 configures itself for 16K RAMs.
AL <sub>1</sub>	8	I	
AL <sub>2</sub>	10	I	
AL <sub>3</sub>	12	I	
AL <sub>4</sub>	14	I	
AL <sub>5</sub>	16	I	
AL <sub>6</sub> /OP <sub>3</sub>	18	I	
AH <sub>0</sub>	5	I	High-Order Address. These Address inputs generate the Column Address for the Multiplexer. If the 8202 is configured for 4K RAMs, use AH <sub>6</sub> as an active high chip select for memory controlled by 8202. For 16K RAM operation, AH <sub>6</sub> becomes the most significant column address bit.
AH <sub>1</sub>	4	I	
AH <sub>2</sub>	3	I	
AH <sub>3</sub>	2	I	
AH <sub>4</sub>	1	I	
AH <sub>5</sub>	39	I	
AH <sub>6</sub>	38	I	
OUT <sub>0</sub>	7	O	Output of the Multiplexer. These outputs drive the addresses of the Dynamic RAM array. For 4K RAM operation, OUT <sub>6</sub> drives the 2104A CS input. (Note that the OUT <sub>0-6</sub> pins do not require inverters or drivers for proper operation.)
OUT <sub>1</sub>	9	O	
OUT <sub>2</sub>	11	O	
OUT <sub>3</sub>	13	O	
OUT <sub>4</sub>	15	O	
OUT <sub>5</sub>	17	O	
OUT <sub>6</sub>	19	O	
WE	28	O	Write Enable. This output drives the Write Enable inputs of the Dynamic RAM array.
CAS	27	O	Column Address Strobe. This output latches the Column Address into the Dynamic RAM array.
RAS <sub>0</sub>	21	O	Row Address Strobe. These outputs latch the ROW Address into the bank of dynamic RAMs selected by the 8202 Bank Address pins (B <sub>0</sub> , B <sub>1</sub> /OP <sub>1</sub> ).
RAS <sub>1</sub>	22	O	
RAS <sub>2</sub>	23	O	
RAS <sub>3</sub>	26	O	

Table 5-2 8202 Pin Description (Cont)

Pin Name	No.	I/O	Pin Description
B <sub>0</sub>	24	I	Bank Address. These inputs select one of four banks of dynamic RAM via the RAS <sub>0-3</sub> outputs. If the B <sub>1</sub> /OP <sub>1</sub> input is pulled to +12V through a 5K $\Omega$ resistor, the 8202 configures itself to the Advanced Read mode. This mode changes the function of the 8202 RD/S <sub>1</sub> and REFRQ/ALE inputs and disables the RAS <sub>0</sub> and RAS <sub>1</sub> outputs.
B <sub>1</sub> /OP <sub>1</sub>	25	I	
RD/S <sub>1</sub>	32	I	Read/S <sub>1</sub> input. This input requests a read cycle. In normal operation, a low on this input informs the arbiter that a read cycle is requested. In the Advanced Read Mode, this input accepts the S <sub>1</sub> status signal from the 8085A (fully decoded for a read). The trailing edge of ALE informs the arbiter that a read cycle is requested by latching S <sub>1</sub> .
WR	31	I	Write Input. This input requests a write cycle. A low on this input informs the arbiter that a write cycle is desired.
PCS	33	I	Protected Chip Select. A low on this input enables the WR and RD/S <sub>1</sub> inputs. PCS is protected against terminating a cycle in progress.
REFRQ/ ALE	34	I	Refresh Request/Address Latch Enable. During normal operation, a high on this input indicates to the arbiter that a refresh cycle is being requested. In the Advanced Read Mode, this input latches the state of the 8085 S <sub>1</sub> signal into the RD/S <sub>1</sub> input. If S <sub>1</sub> is high at this time, a Read Cycle is requested. In this mode, transparent refresh is not possible.
XACK	29	O	Transfer Acknowledge. This output is a strobe indicating valid data during a read cycle or data written during a write cycle. XACK can latch valid data from the RAM array.

**Table 5-2 8202 Pin Description (Cont)**

Pin Name	No.	I/O	Pin Description
SACK	30	O	System Acknowledge. This output indicates the beginning of a memory access cycle. It is also an advanced transfer acknowledge to eliminate wait states. (Note: If a memory access request is made during a refresh cycle, SACK is delayed until XACK occurs in the memory access cycle).
X <sub>0</sub> /IO <sub>2</sub>	36	I	Crystal Inputs. These inputs are designed for a quartz crystal to control the frequency of the oscillator. If X <sub>0</sub> /OP <sub>2</sub> is pulled to +12V through a 1K $\Omega$ resistor, X <sub>1</sub> /CLK becomes a TTL input for an external clock.
X <sub>1</sub> /CLK	37	I	
TNK	35		Tank. This pin provides a tank circuit connection.
V <sub>cc</sub>	40		+5V $\pm$ 10%
V <sub>ss</sub>	20		Ground

#### 5.2.1.2 ROMs -- Four ROMs hold the firmware to run the system:

Three 8K by 8 ROMs  
One 4K by 8 ROMs

This means there are 28K of firmware space, however, the system uses only 26K.

When the CPU reads the ROMs, it sends out an address (A12--A0) to the ROM. Address bits A13 and A14 select one of the four ROMs. A15 is high for all memory addresses. The ROM addresses follow:

0000--1FFF	(ROM 0)	E53
2000--3FFF	(ROM 1)	E52
4000--5FFF	(ROM 2)	E51
6000--63FF	(ROM 3)	E50

The CPU sends out the control signals RD and I/O M. Both these signals are active low.

The data from the selected ROM is placed on the data bus and sent to the CPU.

### 5.2.1.3 RAMs -- There are two RAMs in the system:

#### System RAM

Contains the CPU stacks, work areas and User's programs

#### Screen RAM

Stores the CPU data and attributes to be displayed on the CRT.

The System RAM and the Screen RAM both are 16K by 1 RAMs. The Screen RAM is described in the Vector Generator section. The following paragraphs describe the system RAM.

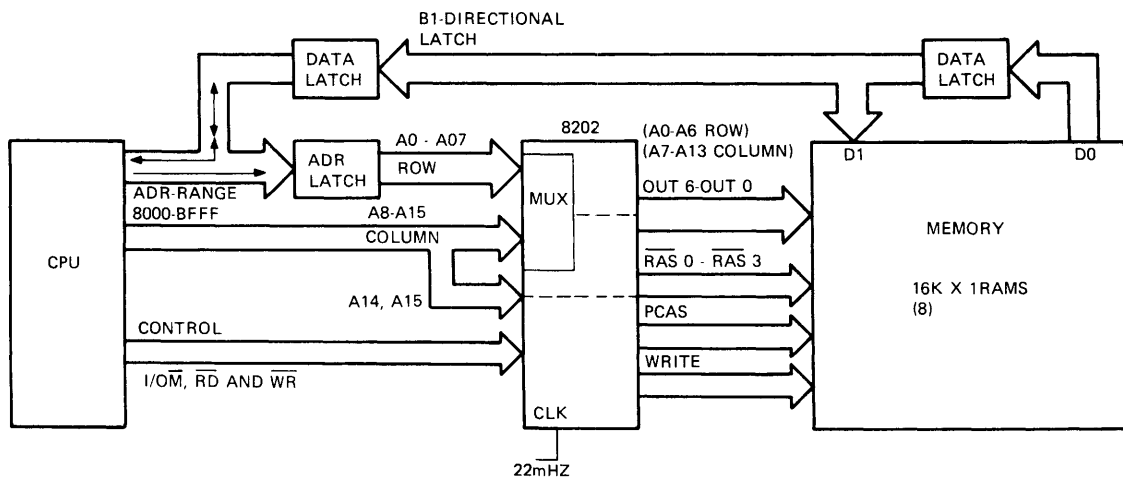
For any memory operation to occur, the CPU generates the following actions.

Address  
Control  
Data

Figure 5-7 shows how the CPU controls the System RAM.

**Address --** The address range of the memory is 8000--BFFF. The address bits, A0--A15 go to the Dynamic RAM Controller (8202). The address bits contain the following information:

1. Row Address (A0--A6)
2. Column Address (A7--A15)
3. Row Address Selection (RAS0--3) (A14, A15).



MA8146

Figure 5-7 CPU to RAM Memory Block Diagram

Memory addresses within the 8000--BFFF range have A15=1, A14=0. This combination selects RAS2.

**Control** -- The control signals are I/O M, RD and WRT. When low the I/O M signal enables the 8202 to receive RD or WRT commands. If high the I/O M signal prevents the 8202 from starting a memory cycle. The address at this time an I/O address.

**Data** -- The data path to and from the memory is shown in Figure 5-6.

Figure 5-8 shows the block diagram of the 8202 and its pin configuration. Refer to Table 5-2 for the 8202 pin description.

**5.2.1.4 Data Bus** -- The data bus is a Tri-State bus that connects the CPU to the following.

- RAM (memory)
- ROM
- I/O Port
- Keyboard

Figure 5-9 shows the data bus.

The CPU time multiplexes the low byte of the Data/Address Buffer. When the CPU reads a valid address, the data is gated onto the Tri-State Data Bus. When active, the direction signal RD allows the data in the data latch. The CPU then loads the data into the Data/Address buffer. When the CPU writes a valid address, WRT determines the data flow direction. This implies RD is high and the data is gated on the Tri-State Data Bus.

**5.2.1.5 Control Functions** -- The CPU control functions are divided into two groups.

1. Memory control
2. Register control

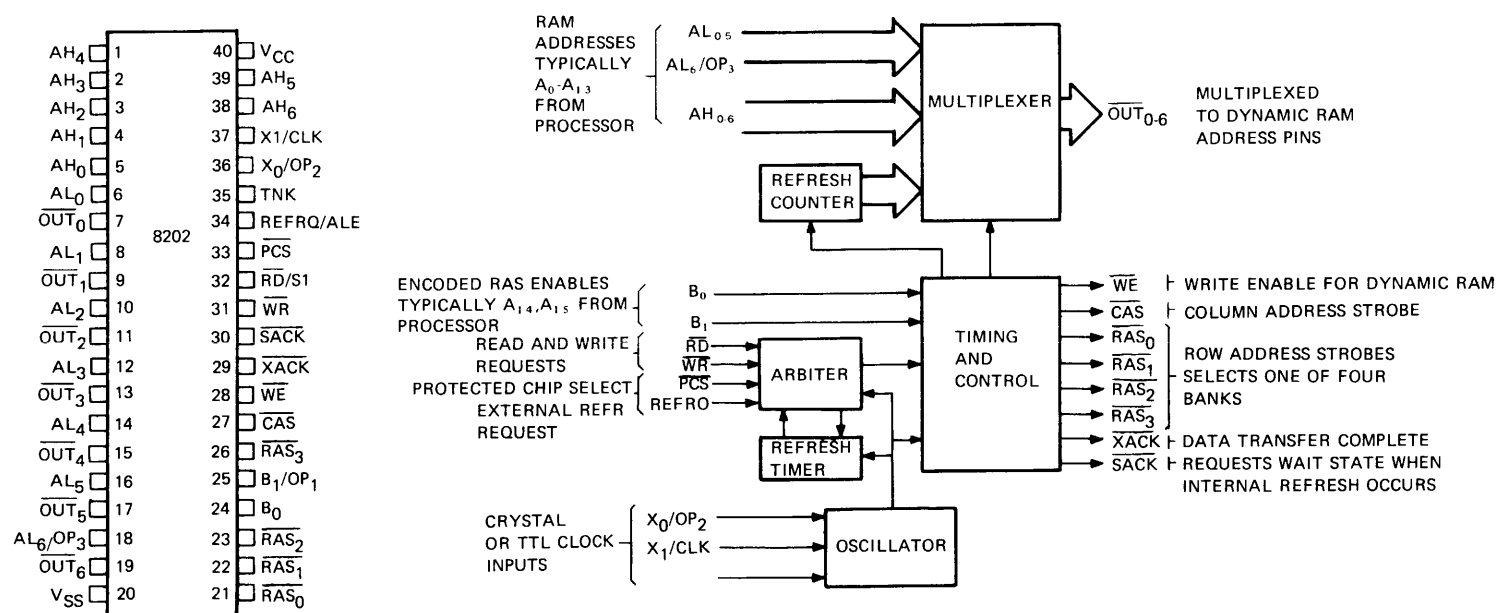
Memory control generates memory reads, writes and opcode fetches. Table 5-1 shows the memory control for these operations.

The registers that the system uses as control registers are I/O addresses.

This means the CPU generates the following sequence.

1. Address (of register)
2. Data
3. Control
  - a) I/O M H (The address is an I/O Address)
  - b) RD
  - c) WRT

Address bits A0--A6 generate the appropriate register control signals (Tables 5-3, 5-4 and 5-5).



MA-8144

Figure 5-8 8202 Block Diagram and Pin Description

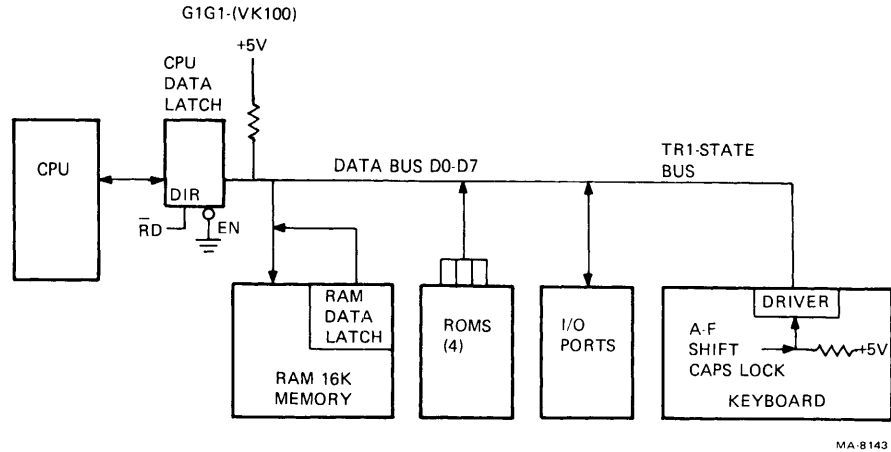


Figure 5-9 DATA Bus

Table 5-3 I/O Register Addresses

Address Bits																Signals			Address Hex	Function
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	I/O	RD	WT		
0	1	0	0	0	0	0	0	0	1	0	0	0	0	0	0	1	0	1	40	LD X LO
0	1	0	0	0	0	0	1	0	1	0	0	0	0	0	1	1	0	1	41	LD X HI
0	1	0	0	0	0	1	0	0	1	0	0	0	0	1	0	1	0	1	42	LD Y LO
0	1	0	0	0	0	1	1	0	1	0	0	0	0	1	1	1	0	1	43	LD Y HI
0	1	0	0	0	1	0	0	0	1	0	0	0	1	0	0	1	0	1	44	LD ERR
0	1	0	0	0	1	0	1	0	1	0	0	0	1	0	1	1	0	1	45	LD SOPS
0	1	0	0	0	1	1	0	0	1	0	0	0	1	1	0	1	0	1	46	LD PAT
0	1	0	0	0	1	1	1	0	1	0	0	0	1	1	1	1	1	1	47	LD PMUL
0	1	1	0	0	0	0	0	0	1	1	0	0	0	0	0	1	0	1	60	LD DU
0	1	1	0	0	0	0	1	0	1	1	0	0	0	0	1	1	0	1	61	LD DVM
0	1	1	0	0	0	1	0	0	1	1	0	0	0	1	0	1	0	1	62	LD DIR
0	1	1	0	0	0	1	1	0	1	1	0	0	0	1	1	1	0	1	63	LD WOPS
0	1	1	0	0	1	0	0	0	1	1	0	0	1	0	0	1	0	1	64	EX MOV
0	1	1	0	0	1	0	1	0	1	1	0	0	1	0	1	1	0	1	65	EX DOT
0	1	1	0	0	1	1	0	0	1	1	0	0	1	1	0	1	0	1	66	EX VEC
0	1	1	0	0	1	1	1	0	1	1	0	0	1	1	1	1	0	1	67	EX ER
0	1	1	0	1	0	0	0	0	1	1	0	1	0	0	0	1	0	1	68	
0	1	1	0	1	1	0	0	0	1	1	0	1	1	0	0	1	0	1	6C	LD BAUD
0	1	1	1	0	0	0	0	0	1	1	1	0	0	0	0	1	0	1	70	LD COMD
0	1	1	1	0	0	0	1	0	1	1	1	0	0	0	1	1	0	1	71	LD COM
0	1	1	1	0	1	0	0	0	1	1	1	0	1	0	0	1	0	1	74	
0	1	1	1	1	0	0	0	0	1	1	1	1	0	0	0	1	0	1	78	KYBDW
0	1	1	1	1	1	0	0	0	1	1	1	1	1	0	0	1	0	1	7C	
																I/O WRT				
0	1	0	0	0	0	0	0	0	1	0	0	0	0	0	0	1	1	0	40	SYSTAT A
0	1	0	0	1	0	0	0	0	1	0	0	1	0	0	0	1	1	0	48	SYSTAT B
0	1	0	1	0	0	0	0	0	1	0	1	0	0	0	0	1	1	0	50	UART O
0	1	0	1	0	0	0	1	0	1	0	1	0	0	0	0	1	1	0	51	UAR
0	1	0	1	1	0	0	0	0	1	0	1	1	0	0	0	1	1	0	58	
0	1	1	0	0	0	0	0	0	1	1	0	0	0	0	0	1	1	0	60	
0	1	1	0	1	0	0	0	0	1	1	0	0	1	1	0	1	1	0	68	NOT USED
0	1	1	1	0	0	0	0	0	1	1	1	0	0	0	0	1	1	0	70	
0	1	1	1	1	0	0	0	0	1	1	1	1	0	0	0	1	1	0	78-7F	
																I/O RD				

Table 5-4 Program RAM Addresses

CPU Address Bits																
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	8000 Hex
								"								↑
								"								16K of Address Space
								"								↓
1	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1	B FFF Hex
1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	C 000 Hex
								"								↑
								"								16K of Address Space
								"								↓
1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	F F F F Hex

## NOTE

CPU Address Bits 15 and 14 are inputs to the M8202 and are used to generate RAS0 through RAS3

RAS 0 0 0 -- Enables refresh flip-flop to be cleared

RAS 1 0 1 -- Not Used

RAS 2 1 0 -- Used with address range 8000 Hex to BFFF Hex

RAS 3 1 1 -- Used with address range C000 Hex to FFFF Hex

Table 5-5 I/O ROM Microcode Address

	Address Bits																Address Space	Hex Address Range
	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0		
ROM 0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0	8K of Address Space	0000 HEX
	0	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1		01FF HEX
ROM 1	0	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	8K of Address Space	2000 HEX
	0	0	1	1	1	1	1	1	1	1	1	1	1	1	1	1		3FFF HEX
ROM 2	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	8K of Address Space	4000 HEX
	0	1	0	1	1	1	1	1	1	1	1	1	1	1	1	1		5 FFF HEX
ROM 3	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	0	2K of Address Space	6000 HEX
	0	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0		63 FF HEX
*	0	1	1	1	0	0	0	0	0	0	0	0	0	0	0	0		700 HEX
	0	1	1	1	0	0	0	0	0	0	0	0	0	1	1	1	16 Addresses	

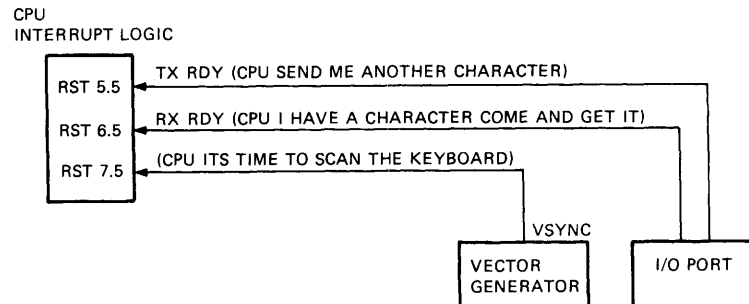
\* ROM 3 and Bit 12 equal to a 1 implies Keyboard address



5.2.1.6 Memory Refresh Cycle -- A read cycle causes a refresh to occur. The memory refresh is controlled internally by the dynamic RAM Controller (8202). Figure 5-8 shows the components used for the refresh cycle. 128 memory refresh occurs every 2 ms. The refresh logic has 2 sections.

1. Internal Counter -- contains the RAS address used during the refresh. The counter is incremented after each refresh resetting to zero after all RAS addresses have been refreshed.
2. Arbitration -- timing and control logic allows either a read, write or refresh cycle to occur. After any read or write cycle request, SACK (System Acknowledge) goes active if the cycle was not requested during a refresh cycle. If it was requested SACK is delayed until XACK (Transfer Acknowledge) thereby requesting wait states from the cycle requestor.

5.2.1.7 Interrupts -- Hardware interrupts are generated from two sources: (the vector generator and I/O port (Figure 5-10)).



NAME	PRIORITY	ADDRESS BRANCHED TO WHEN INTERRUPT OCCURS	TYPE TRIGGER
RST 7.5	1	3CH	RISING EDGE LATCH
RST 6.5	2	34H	HIGH LEVEL UNTIL SAMPLED
RST 5.5	3	2CH	HIGH LEVEL UNTIL SAMPLED

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Figure 5-10 Interrupt Block Diagram

These interrupts change the flow of the executing program (ROM control).

The interrupts are sampled on the descending edge of the clock, one cycle before the end of the instruction in which the interrupt input is activated. The CPU saves the contents of the program counter before it branches to the subroutine.

Refer to Table 5-6 for the interrupt priority structure.

The vector generator and I/O port sections describe how the system generates the interrupts. The software controls the interrupt logic by using the RIM (Read Interrupt Masks) and SIM (Set Interrupt Mask) instructions.

#### 5.2.1.8 CRT Sweep Overview

The CPU sets the horizontal and vertical timing registers in the CRT controller to control the horizontal and vertical sweep circuits. The horizontal timing registers are R0--R3 and the vertical timing registers are R4--R9. The register functions are as follows.

Horizontal Total Register (R0) -- This 8-bit write-only register determines the horizontal frequency of the horizontal sweep.

Horizontal Displayed Register (R1) -- This 8-bit write-only register determines the number of displayed characters per horizontal line.

Horizontal Sync Position Register (R2) -- This 8-bit write-only register determines the horizontal sync position on the horizontal line.

Horizontal Sync Width Register (R3) -- This 4-bit write-only register determines the width of the horizontal sync pulse.

The horizontal registers are programmed in "character times" units with respect to the reference.

**Table 5-6 Interrupt Priority, Restart Address, and Sensitivity**

Name	Priority	Address Branched To When Interrupt Occurs	Type Trigger
RST 7.5	1	3CH	Rising edge latch
RST 6.5	2	34H	High level until sampled
RST 5.5	3	2CH	High level until sampled

Vertical Total Register (R4) and Vertical Total Adjust Register (R5) -- These two registers determine the vertical frequency of vertical sync. The calculated number of character line times is usually an integer plus a fraction to get exactly 50 or 60 Hz vertical refresh rate. The integer number of character line times minus one is programmed in the 7-bit write-only vertical total register; the fraction is programmed in the 5-bit write only vertical scan adjust register as a number of scan lines.

Vertical Displayed Register (R6) -- This 7-bit write-only register determines the number of displayed character rows on the CRT screen and is programmed in character row times.

Vertical Sync Position (R7) -- This 7-bit write-only register determines the vertical sync position with respect to the reference. It is programmed in character row times.

Interlace Mode Register (R8) -- This 2-bit write-only register controls the raster scan mode. These bits are zeros which means non-interlace raster scan mode is selected.

For 60 Hz the CPU initializes the registers in the CRT controller (CRR) as follows.

R0 (horizontal total)	= 4F	80-1=79
R1 (horizontal displayed)	= 40	64
R2 (horizontal sync position)	= 44	68
R3 (horizontal sync width)	= 41	65 (value can be 60--69 ticks depending on HP)
R4 (vertical total)	= 41	66-1=65
R5 (vertical total adjust)	= 0	0
R6 (vertical displayed)	= 3D	61
R7 (vertical sync position)	= 3E	62
R8 (interlace mode)	= 0	0

5.2.1.8.1 Horizontal Sweep -- The horizontal sweep time is 63.131 ~s. This is the time needed for the beam to move from the left side of the screen to the right side of the screen (display time) and return to the left side (retrace time).

The display time is 50.505 ~s and the retrace time is 12.626 ~s. These times are converted into tick values for the CRTC registers. One tick value is the time needed for the horizontal sweep to pass twelve pixels. One tick occurs every 0.789144 ns.

The horizontal sync pulse triggers the horizontal sweep. The horizontal sync pulse has three components.

1. HS pulse width
2. HF horizontal front porch
3. HB horizontal back porch

The HS pulse width is constant. The HF can be changed by the HP command. If the HF is increased by one tick then the HB is decreased by one tick. This action controls the horizontal sweep start time, which allows for positioning of the display area in the horizontal direction on the face of the CRT.

**5.2.1.8.2 Vertical Sweep** -- The vertical sweep is 50 or 60 Hz. The total vertical sweep is 16.666 ms. A horizontal sweep rate of 63.131 ~s provides 264 available scan lines of which 244 scan lines are used. The remaining 20 scan lines include retrace time from the last active scan line.

The vertical registers used are

R4 (vertical total)	= 41	66-1=65	Character row
R5 (vertical total adjust)	= 0	0	Scan line
R6 (vertical displayed)	= 3D	61	Character row
R7 (vertical sync positive)	= 3E	62	Character row
R8 (interlace mode)	= 0	0	

The CPU loads the vertical registers with scan line and character row values.

The total sweep time is 66 characters. A character row by definition is four scan lines, which means there are 264 scan lines in a vertical sweep.

The display time is 61 character rows (0--60). The screen remains blank during display time. The screen blank time is five character rows. These rows are divided into:

- Vertical sync front porch -- one character row
- Vertical sync pulse width -- four character rows
- Vertical sync back porch -- zero

## 5.2.2 Vector Generator Overview

The vector generator interfaces the VK100 to the CRT display (Figure 5-11). The vector generator performs four functions.

1. Generates a timing chain
2. Generates display refresh sequence
3. Generates the hardcopy output
4. Generates status

The vector generator, under ROM control, places characters and vectors on the CRT display. The system, using a crystal control clock (45.692 Hz), synchronizes the display sequence and generates the timing for the vector generator and the CRT monitor (Figure 5-12). Time states control the vector generator, sync ROM and the vector ROM.

The system uses a crystal control clock (45.692 Hz) to synchronize the display sequence and generate the timing for the vector generator and the CRT monitor (Figure 5-12).

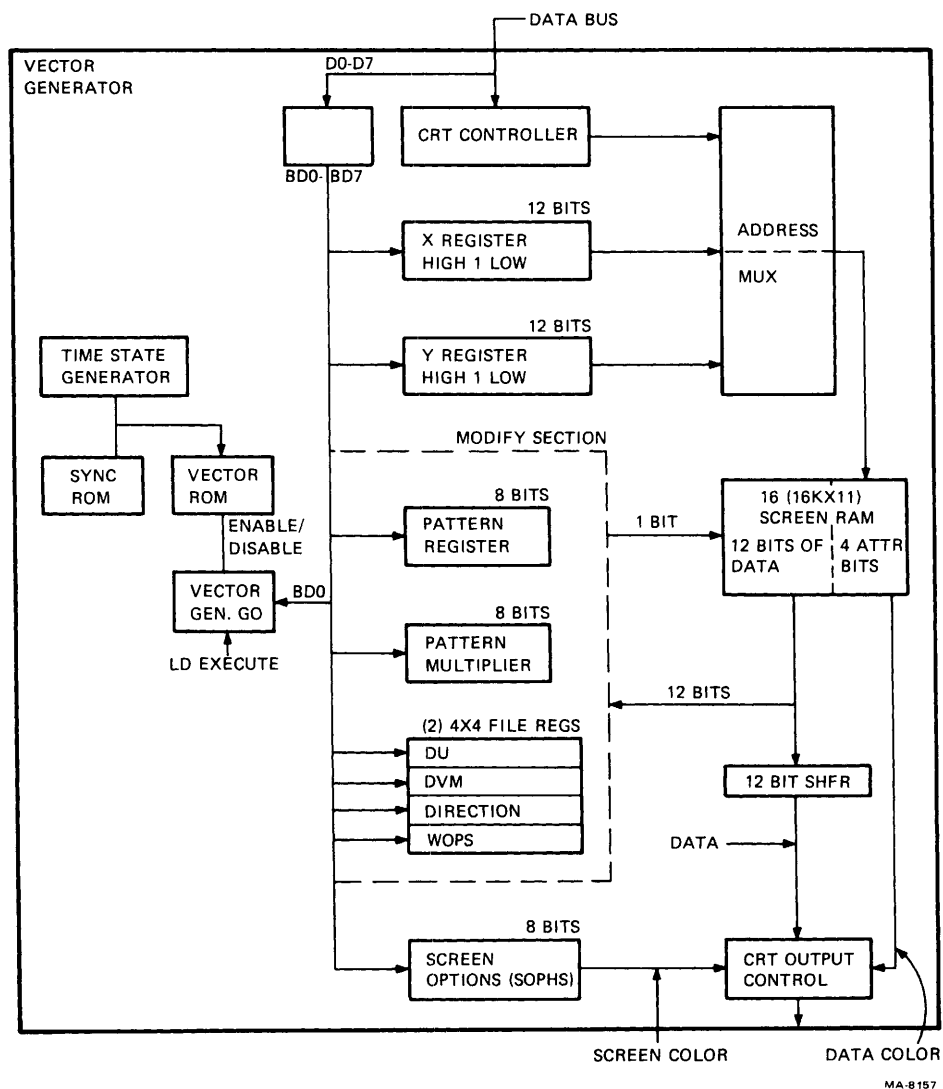
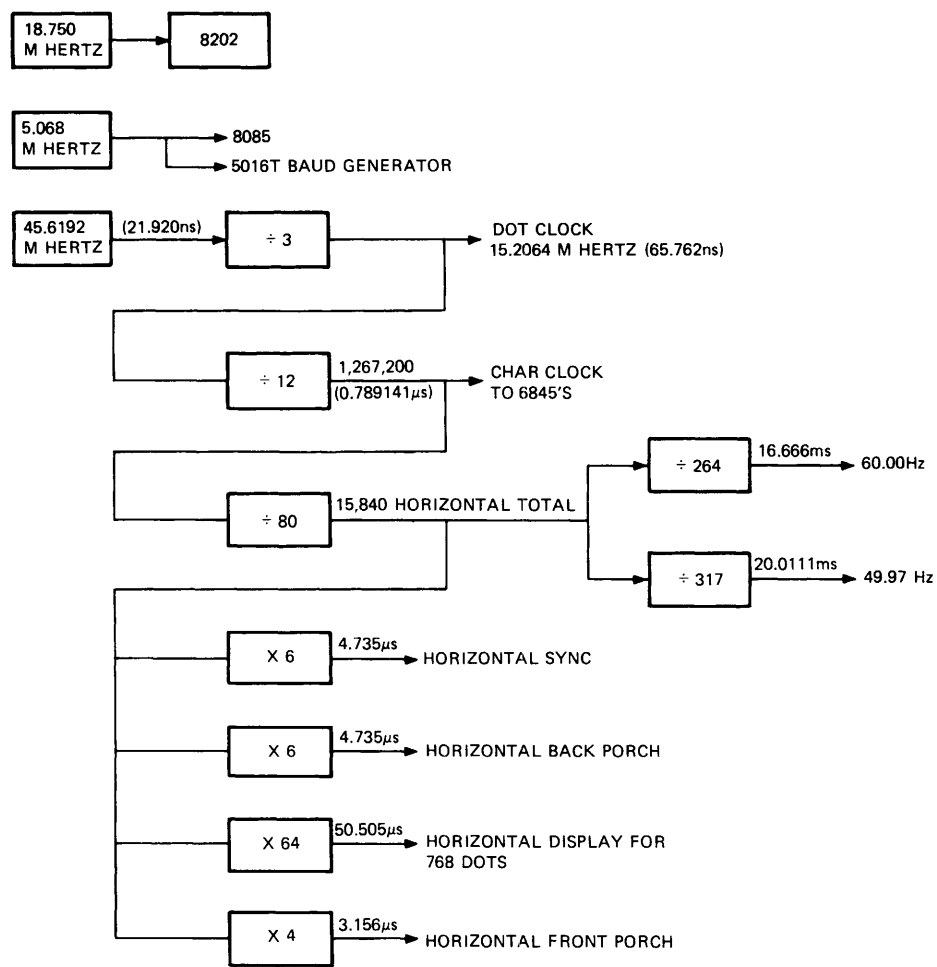


Figure 5-11 Vector Generator Block Diagram



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Figure 5-12 System Timing

The vector generator performs two separate time shared operations.

1. Modify screen RAM data
2. CRT display

A read modify write operation modifies the screen RAM. The screen RAM is addressed and 16 bits are read (12 bits of data and 4 attribute bits). Only one of the twelve data bits can be modified at a time. Then the modified data bit is written into the screen RAM.

The CRT refresh holds the display for a limited amount of time. If the CRT is not refreshed the contents of the screen RAM fade and then disappear.

The CRT refresh is a continuous action. The screen RAM is addressed sequentially. For each address twelve bits of data are loaded into the shift register. Then the data is shifted one bit at a time to the CRT display. The data that appears on the CRT is an image of the data in the screen RAM.

**5.2.2.1 Addressing the Screen RAM** -- The screen RAM is addressed through a two to one multiplexer (Figure 5-16). When the modify screen RAM function is taking place, the address comes from the X and Y register. The WRT/RD signal when high allows the contents of the X and Y register to pass through the multiplexer to address the screen RAM.

When the CRT refresh function is taking place, the address used comes from the sequential counter (MA) of the CRT controller. The low WRT/RD signal when low allows the contents of the MA register to pass through the multiplexer to address the screen RAM.

The address bit breakdown is shown in Figures 5-13 and 5-14. The outputs of the address multiplexer are divided into two groups, the RAS and CAS bits.

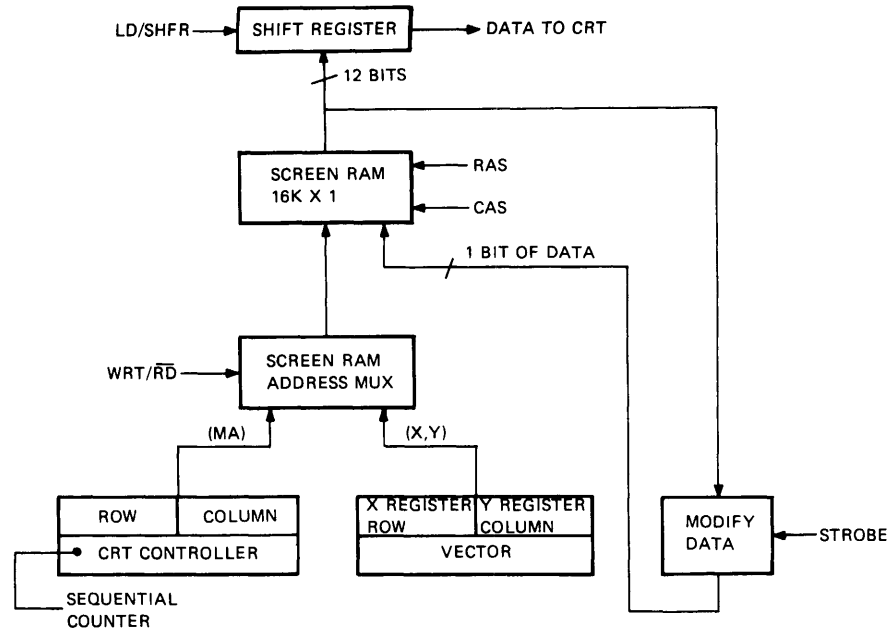
The RAS, CAS bits used when modifying the screen RAM are (Figure 5-15):

RAS -- Y1, X9--X4  
CAS -- Y8--Y2

The RAS, CAS bits used when doing a CRT refresh are:

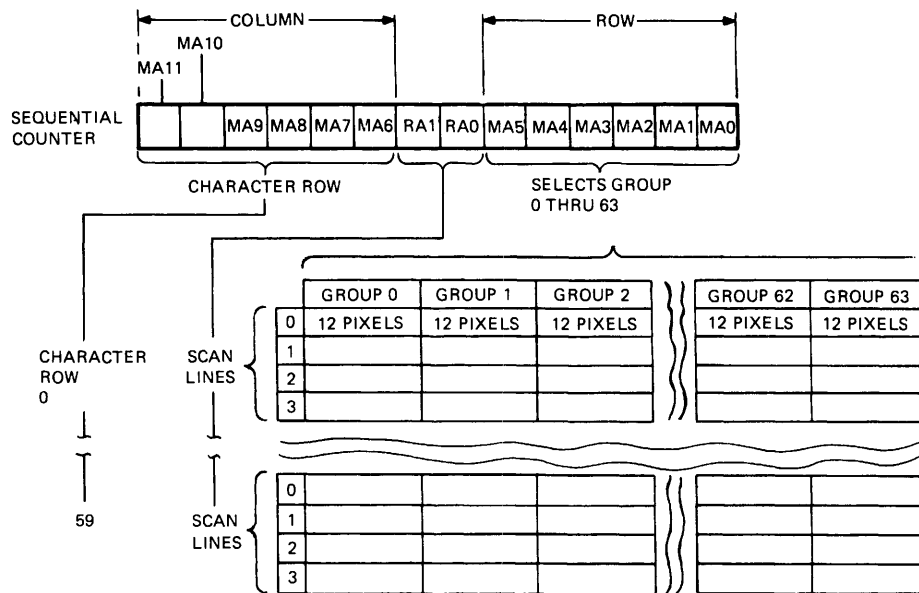
RAS -- RA0, MA5--MA0  
CAS -- MA11--MA6, RA1

The address bits X9--X2 go through a translator, which makes sure that the output bits X3 and X2 are never equal to a binary three. Bank three in the screen RAM does not exist (Figure 5-16).



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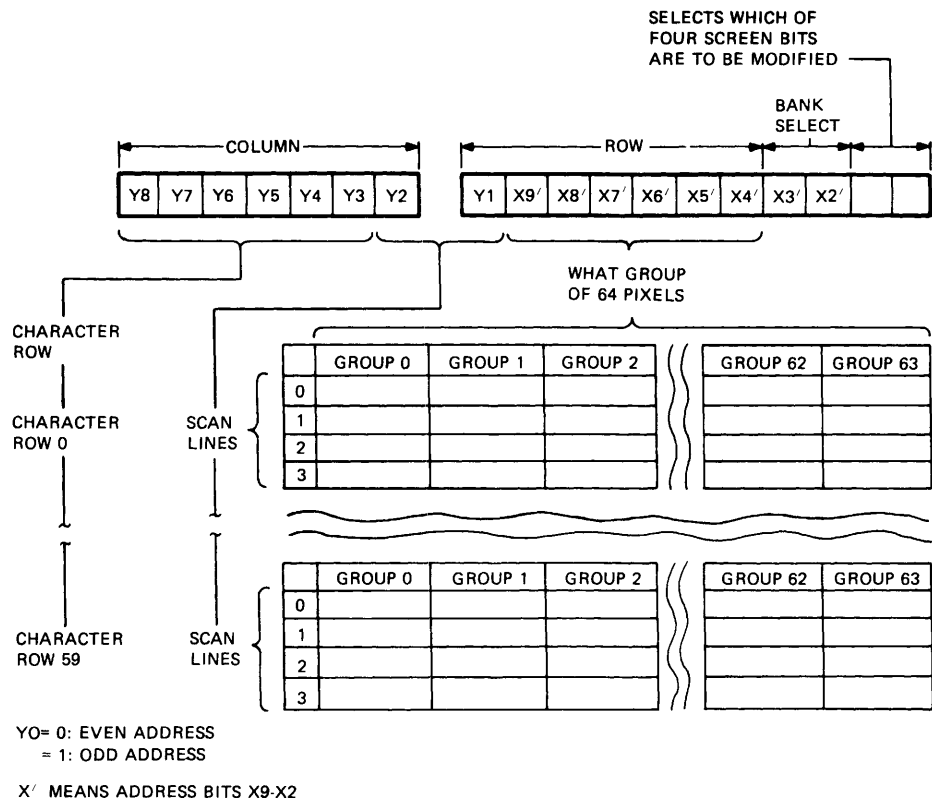
Figure 5-13 Basic Overview of Address and Data Path



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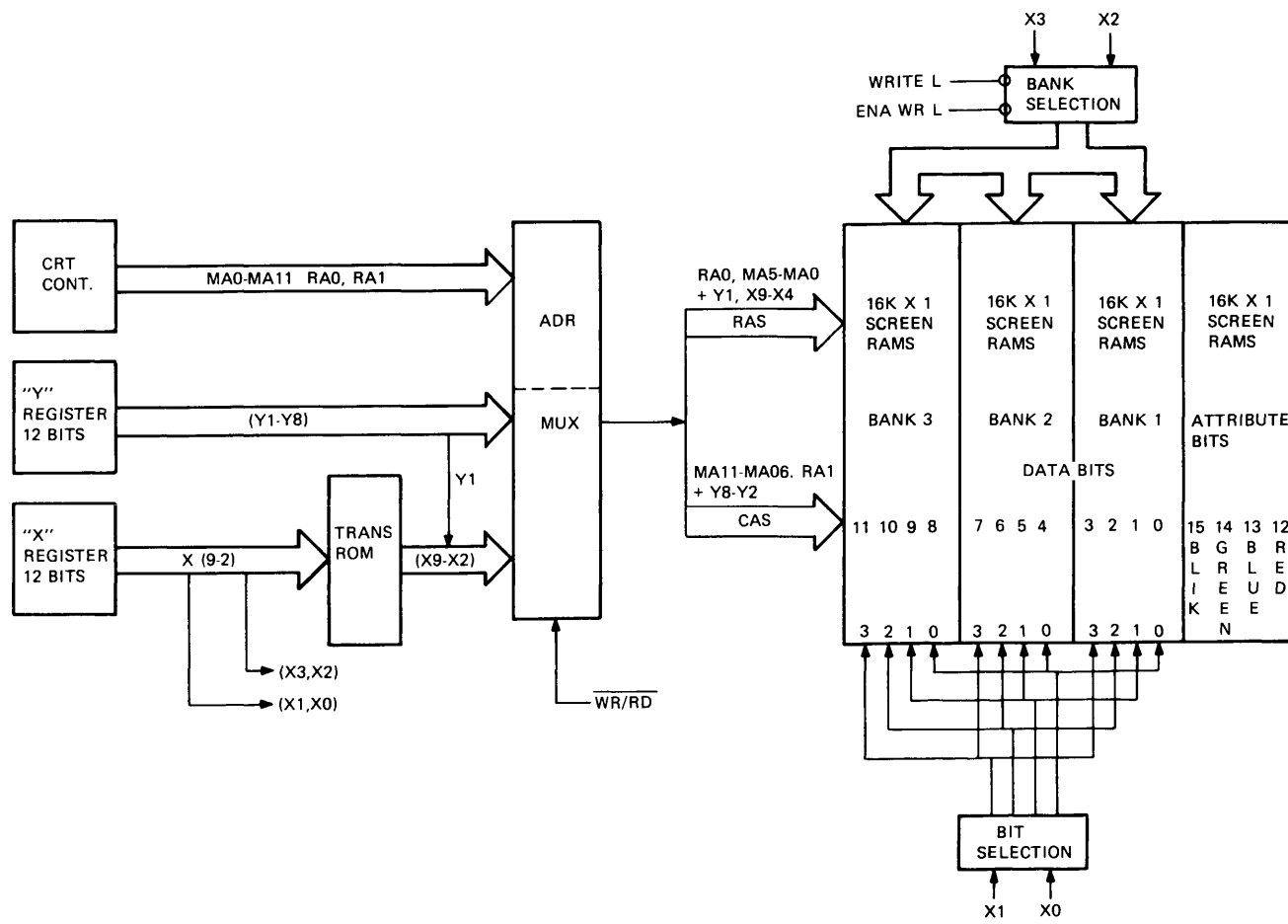
Figure 5-14 Screen Update, Screen RAM Address Breakdown





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**Figure 5-15 Modify Data, Screen RAM Address Breakdown**



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Figure 5-16 Addressing the Screen RAM

5.2.2.2 Modification of Data in the Screen RAM -- The system sets up registers in the vector generator to place a character or vector on the screen. These registers control how the data is written into the screen RAM. The registers are as follows.

- Pattern register
- Pattern multiplier register
- Write options (WOPS) register

These registers, and the bit selected for update, control how the data is modified.

The CPU decodes the following write commands and then loads the commands into the pattern, pattern multiplier and the WOPS register.

- Write Pattern
- Write Multiplier
- Write Negate
- Write Complement
- Write Intensity

The CPU loads the pattern register with the pattern to be written into the screen RAM.

The contents of the pattern multiplier register (2's complement of the value) indicates how many times the pattern register output is used before allowing the pattern register to be shifted. The default value of the pattern multiplier is one. If the default value is loaded into the pattern multiplier, the pattern register output is used once before shifting. If the pattern multiplier is two the pattern register output is used twice before shifting.

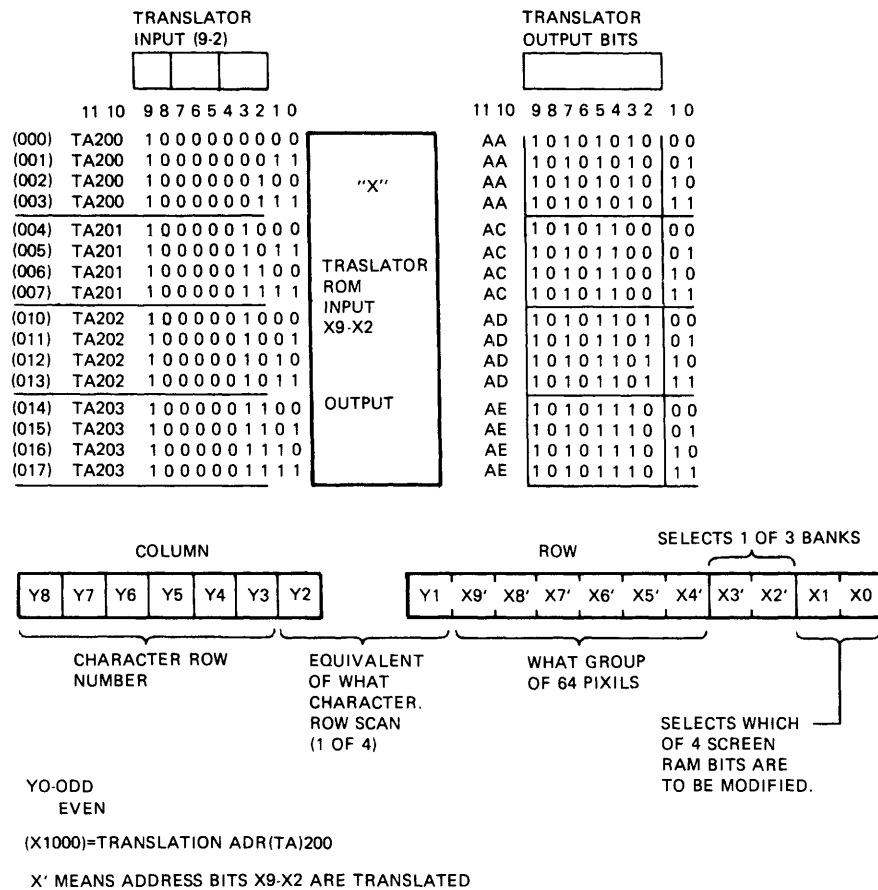
The CPU loads the Write Negate, Complement and Intensity commands into the WOPS register.

The CPU loads the x and y registers with an address to modify data in the screen RAM. This address accesses a location in the screen RAM. The twelve bits of data are read and bits X3 and X2 select four of the twelve bits. This is called bank selection. Bits X1 and X0 select which of the four bits is to be modified (bit selection) (Figure 5-17). At this time the contents of the pattern register and WOPS determine how the selected data bit will be modified (Figure 5-18).

The following example shows how the selected bit is modified for a complement function.

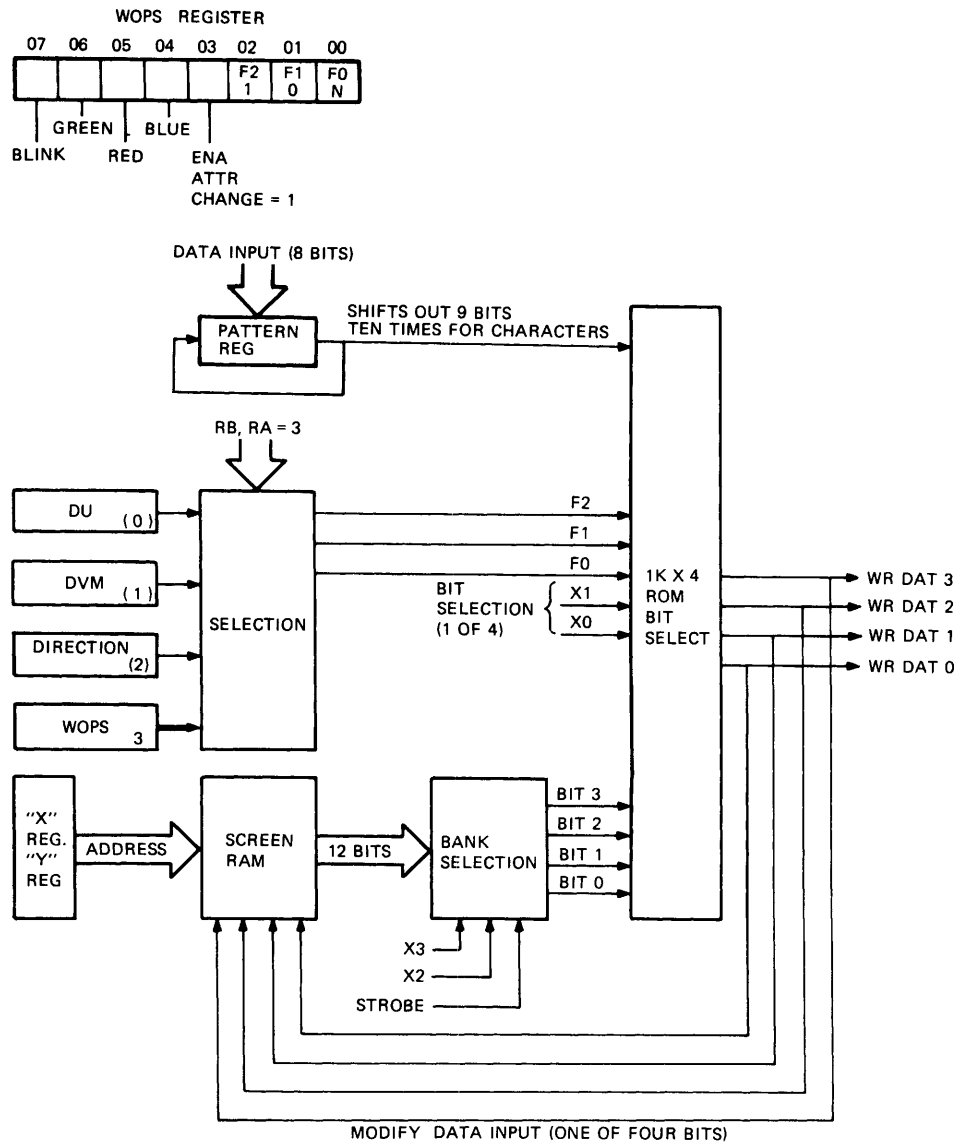
GIVEN:

- The output of screen RAM -- selected bank = 0010 binary
- The output of WOPS register - bits 2--0 = 100 binary
- The output of the pattern register = output bit = 1 binary



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Figure 5-17 Translation of X Bits



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Figure 5-18 Modify Data Bits

The output of the WOPS register equals 4 binary, a complement with no negate function. Refer to the complement equation in Table 5-7.

Complement  $M = A + (P + N)$   
 Complement = 0010 + (1 + 0) (0010 is selected bank)  
 Complement = 1 + 1 (1 is selected bit)  
 Complement = 0

The complement bit zero is written into the selected bank of the screen RAM. Initially, the value of the selected bank was 0010 binary. After modification the value changes to 0000 binary.

5.2.2.3 Refresh the CRT -- The display area of the video monitor contains 240 scan lines (horizontal sweeps) with each sweep having 768 picture elements called pixels. A pixel is the smallest picture element that can display data. The display area contains a total of 184,320 pixels. The color of the characters or vectors represents foreground information. The color of the screen represents background information.

The characters, vectors and screen can be different shades of black and white or color. Two separate control circuits are used for CRT color control.

1. Foreground control
2. Background control

Table 5-7 Screen RAM Write Control

WOPS BITS  
 2 1 0

F2	F1	F0	Function	Equation
0	0	N	Overlay	$M=A+(P+N)$
0	I	N	Replace	$M=P+N$
I	0	N	Complement	$M=A+(P+N)$
I	I	N	Erase	$M=N$

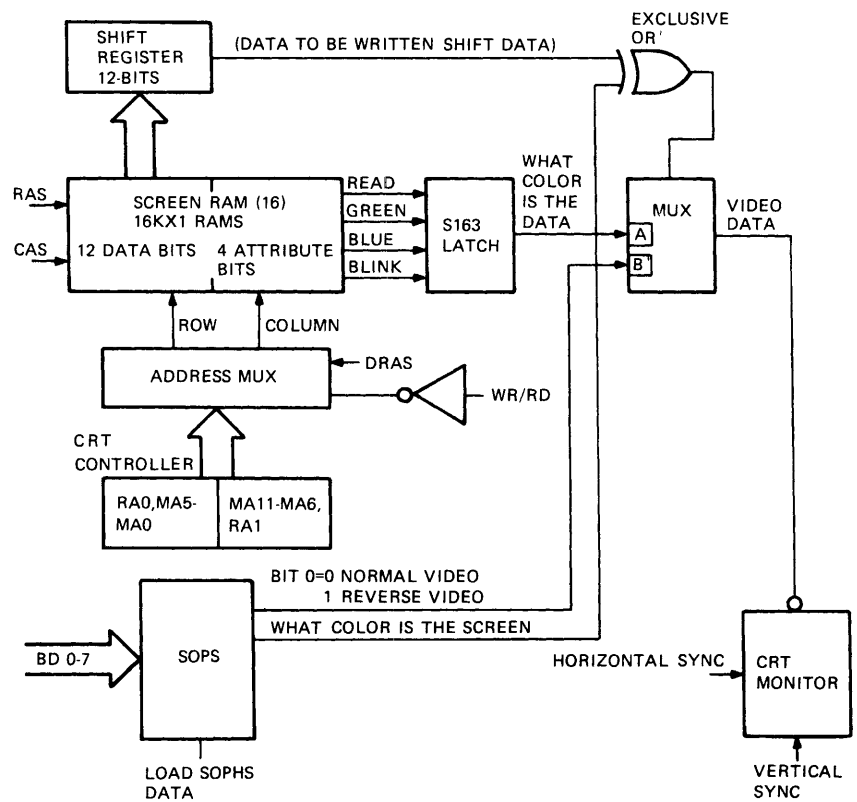
Legend for Equations

M = Data to be written into memory  
 A = Data now in memory  
 P = Output of pattern register  
 N = Negate bit  
 T = OR  
 + = XOR

**Foreground Control** -- The CPU loads the WOPS register with a value that defines the color of the character or vector. The output of the WOPS register bits F7 (blink), F6 (green), F5 (red), and F4 (blue) are inputs to the screen RAM attribute section. Every time the screen RAM is modified, the contents of bits F7--F4 if enabled are written into the screen RAM attribute section.

When the screen RAM is addressed, sixteen bits are read from memory. Twelve bits of data are loaded into the shift register and the four attribute bits are loaded into the S163 latch (Figure 5-19). The data output of the shift register is exclusively ORed with bit 0 of the screen option register (SOPS).

The exclusive OR selects the foreground or background colors. When the video control bit is zero (normal video) and the shifted data bit is a one, the attribute bits from the latch determine the video data color (foreground).



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Figure 5-19 Color Control

When the output of the shift register is zero and the video control bit is zero (normal video), the attribute bits from the SOPS register determine the video data color (background).

When the SOPS register bit is a one (reverse video), the SOPS register attribute bits are used for the foreground color and the latch attribute bits are used for the background color.

**Background Control** -- The ReGIS screen command, through the CPU, loads the SOPS register with a value that determines the background color. The SOPS register holds the background attribute bits. The SOPS register attribute bits are; bit 6 (green), bit 5 (blue), and bit 4 (red). These bits are inputs to the multiplexer that in a normal video condition furnishes the background color. The background color is displayed when the output of the shift register is zero and bit 0 of the SOPS register is 0.

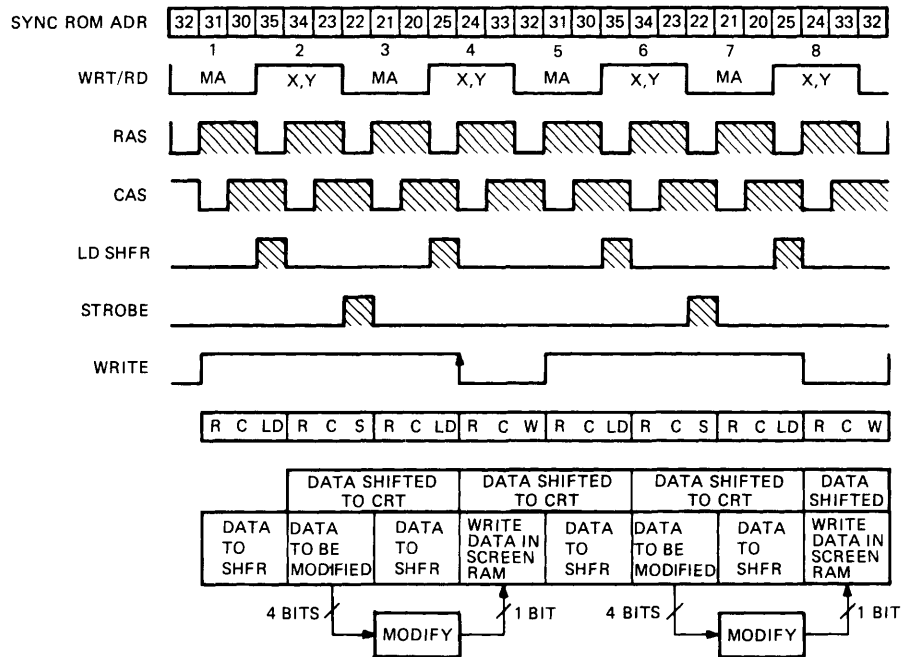
**5.2.2.4 Modify Screen RAM and CRT Refresh Timing** -- The sync ROM in the vector generator runs continuously. Figure 5-20 shows the sync ROM addresses which are a function of the Time State Generator (Figure 5-21) and other bits. Twelve addresses are used before repeating the sequence again. The WRT/RD signal controls the screen RAM address multiplexer. If the WRT/RD signal is low, the address from the mA sequential counter passes through the screen RAM address multiplexer.

If the WRT/RD signal is high, the address from the x and y register passes through the screen RAM address multiplexer.

The WRT/RD signal changes levels every third sync ROM address. For every WRT/RD time frame a RAS and CAS signal are generated. Depending on the sync ROM address, a load shift register or strobe pulse occurs (Figure 5-19). Strobe pulse loads the four-bit holding register with data from memory (X3, X2). The following sequence of events occur.

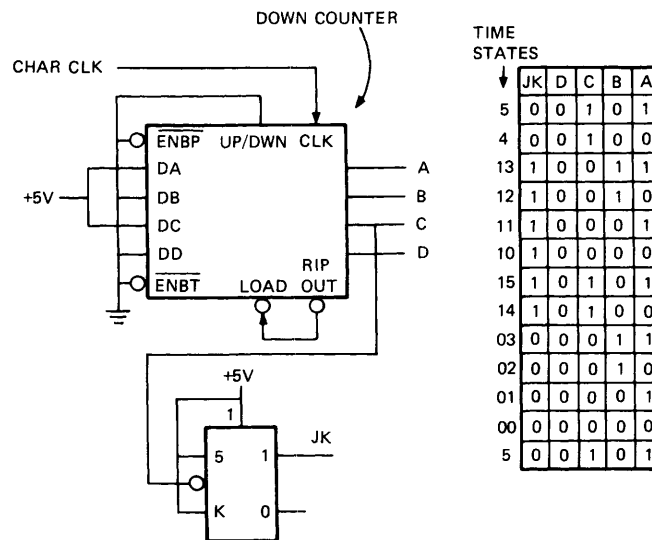
1. Data is loaded into the shift register.
2. While the data is shifted is out, the x,y address reads the data to be modified. In another read cycle, X3 and X2 selects the data to be modified and strobes the four bits into the holding register. Only one bit is modified.
3. While the data is shifted to the CRT, another RAS, CAS, LOAD function is performed. At the proper time another twelve bits are loaded in the shift register and shifted to the CRT.
4. During the continuous shifting of data from the shift register to the CRT, the modified data is written into the screen RAM. The screen RAM data is modified by the execute point, erase and the execute vector commands. During sync ROM address 32, the execute vector command turns on the vector ROM. This activates the write signal.





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Figure 5-20 Screen RAM Data Timing



MA-8151

Figure 5-21 Time State Generator

5.2.2.5 Generation of Vectors -- The VK100 system can draw both characters and vectors. Section 5.2.2.5 describes characters. The following paragraphs describe vectors. There are two kinds of vectors.

1. Basic vectors
2. Arbitrary vectors

Basic vectors fall under the following conditions:

1. If coordinates  $X=0$  and/or  $Y=0$
2. If the absolute value of  $x$  = absolute value of  $y$  [ $X$ ]=[ $Y$ ]

There are eight basic directions for vectors (Figure 5-22). All other conditions are arbitrary vectors.

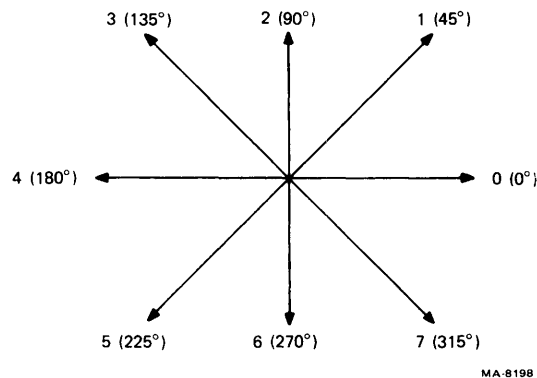
The terminal operator can type a character and rotate it in any of the basic directions (Figure 5-22). For example the operator types in:

```
"FORMAT" TEXT (DIRECTION) "Character to Print"  
"EXAMPLE" T(D45) "A"
```

**NOTE**

The above must be in ReGIS command mode to work.

The T(D45) command displays the A character along the one basic direction, or 45° direction. This character is a basic vector.



**Figure 5-22 Basic Vectors**

The CPU has to set up registers in the vector generator to display characters or vectors on the CRT. The following are the registers that are loaded.

- X and Y
- DU--Length of major axis
- DVM--Length of minor axis
- Pattern
- Pattern multiplier
- Direction
- Write options (WOPS)
- Screen options (SOPS)
- Execute vector
- Error register (only used with arbitrary vectors)

The function of these registers follows.

**X and Y** -- These registers are loaded with the starting address of the character or vector. The X and Y register contents address the screen RAM when modifying data. The address control increments or decrements the x and Y individually or both at the same time.

The X coordinate is X0 through X767. If the direction of the character or vector is ROM coordinate X0 through X767, X is positive. If the direction is from X767 to X0, X is negative.

The Y coordinate is Y0 through Y240. If the direction of the character or vector is from coordinate Y0 to Y240, Y is positive. If the direction is Y240 to Y0, Y is negative.

If both X and Y = 0 during a screen RAM modify, the CRT displays the data in the top left corner of the screen. This corner is the first pixel of the CRT during display time.

**DU** -- The length of the major axis is loaded into this register. For character displays, the width of a character is loaded into the DU.

For vectors, the firmware knows the vector starting point and how far the vector moves in the X and Y position. The larger of the two values is placed in the DU register.

**DVM** -- The length of the minor axis is loaded into this register. For character displays, the width of a character is loaded into the DVM.

For vectors, the DVM receives the smaller of the X and Y values.

**Pattern** -- The pattern register is an eight-bit shift register that is parallel loaded and shifted out one bit at a time to a 1K by 4 PROM. This register controls the pattern of the data written into the screen RAM.

If the pattern = 1, a modify function is performed. If the pattern = 0, the pass data is modified. This does not apply in replace mode.

**Pattern Multiplier** -- The contents of this four bit register can increase the width of a character or vector by a factor of one to sixteen. If the pattern multiplier register is loaded with all binary ones, the pattern register shifts every write time. If the pattern multiplier is loaded with 1110 binary, the pattern register shifts every two write times.

**Direction** -- The direction register is an eight bit register. Only four bits are used. Bits 0--2 tell the vector direction and bit 3 tells if the vector is a basic or arbitrary vector. If bit 3 equals zero, the vector is a basic vector. If bit 3 equals one, the vector is an arbitrary vector.

**Write Options (WOPS)** -- WOPS is an eight-bit register. Bit 7 is blink control. Bits 6--4 tells the color of data (12 pixels) when in normal video mode. Bit 3 (equal to a one) enables attributes. Enable attributes is an address bit to the WRT ROM. This allows the contents of WOPS register bits 7--4 to be written into the screen RAM.

Bits 1 and 2 describe how the data being modified is controlled; If it is overlayed, replaced, complemented or erased. Bit 0, the negate bit, controls the output of the pattern register. If bit 0 equals a one, the pattern register output is complemented.

**Screen Options (SOPS)** -- The SOPS register is an eight-bit register which controls the following three functions.

1. Blink
2. Background color
3. I/O port control (EIA, 20 mA, hardcopy and self-test)

**LD Execute** -- The execute instructions set the Go flip flop ( $GO_{FF}$ ) which enables the vector ROM to run. This is necessary for writing the modified data in the screen RAM and reading the file register contents (DU, DVM, DIR, and WOPS).

**5.2.2.6 Writing a Character on the Screen** -- Writing a character on the CRT is the same as writing a vector. The main difference is that a character is a series of parallel vectors. When you press a key the following events occur:

1. At the next occurrence of VSYNC the CPU recognizes the keyboard interrupt.
2. In response to the interrupt, the CPU enters the keyboard scan routine, reads the keyboard and determines which key was pressed. The processor then translates the key location code into an ASCII code and stores it in the keyboard line.

3. The processor reads the ASCII character in the keyboard line to determine what character to place on the CRT.
4. The processor translates the ASCII character code into a dot pattern. To do this, the processor reads a character look-up table located in RAM. The look-up table consists of a series of character cells, one cell for each ASCII code. Each character cell contains 10 patterns to be written as vectors on the screen. These pattern vectors compose the character on the CRT screen.

#### NOTE

The look-up table is filled with the dot patterns for each displayable character during the ROM power-up sequence. The look-up table can also be filled from the host computer using the Load Character Cell command in the graphics mode.

There are 10 pattern vectors for each character. To write a character into the screen RAM, the DU, DVM, WOPS, and direction registers are initially loaded. The following sequence of events must occur 10 times.

1. The X and Y registers are loaded. The pattern of the character is loaded into the 8-bit pattern shift register.
2. The CPU issues the Execute Vector command. The Execute Vector command sets the GO bit enabling the vector ROM to output. The address for Execute vector is 66. This means address bits A1 and A0 are equal to a binary two. These address bits, A1 and A0, are part of the vector ROM address bits which allows the vector ROM sequence for the Execute Vector command.
3. It takes three cycles (or nine time states) to modify the data in the screen RAM.
  - a. Read cycle -- The X and Y register contents read a location of the screen RAM. The twelve bits of data that are read from the screen RAM go to the bank select logic. Bits X3 and X2 select which four bits will be strobed into the holding register.
  - b. Modify cycle -- The logic uses the pattern output WOPS, X and holding register to determine which bit will be modified by addressing a 1K by 4 ROM. The address of the 1K by 4 ROM is determined by the following.

Pattern register output bit -- (A9)  
WOPS register output bits (F2,F1,F0) -- (A8--A6)  
X register output bit (X1,X0) -- (A5--A4)  
Holding register output bits (3,2,1,0) -- (A3--A0)

- c. Write cycle -- When the write pulse occurs the output of the bit select ROM (WR DAT 3--WR DAT 0) is written into the same bank in the screen RAM.
4. The down counter whose value is initially nine bits gets decremented every time a write takes place. The logic checks to see if the down counter equals zero. This indicates a pattern or vector has been stored in the screen RAM.
  5. The X register is incremented or decremented according to the contents of the direction register.
  6. If the down counter is not equal to zero, steps three through five are repeated.

If the down counter is equal to zero a pattern (vector) with nine bits is stored in the screen RAM. This resets the Go flip-flop and disables the vector ROM outputs.

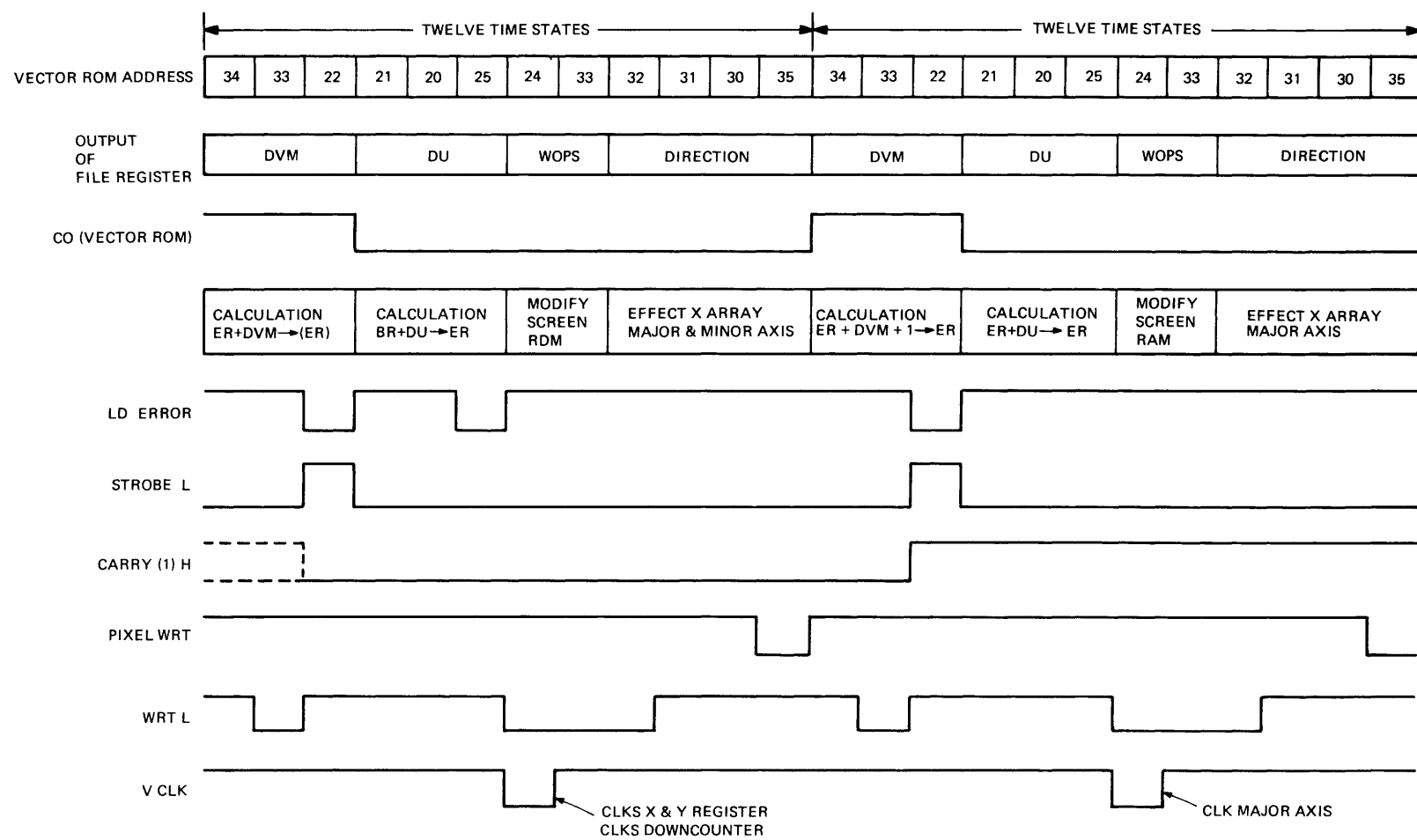
Steps one through six are performed for each pattern. The character appears on the CRT after the ten patterns are written into the screen RAM and those locations addressed by the CRT Controller (CRR).

**5.2.2.7 Arbitrary Vectors** -- The vector generator produces basic and arbitrary vectors in the VK100 system. The basic vectors are shown in Figure 5-23. There are eight basic vector directions 45° apart. Vectors drawn in between the eight basic vectors are called arbitrary vectors.

The Bresenham algorithm is a series of calculations (Appendix B) that allows an arbitrary vector to light a pixel close to the ideal vector path. A staircase effect takes place when arbitrary vectors are drawn. This staircase effect can be seen by looking closely at the screen when it is displaying arbitrary vectors.

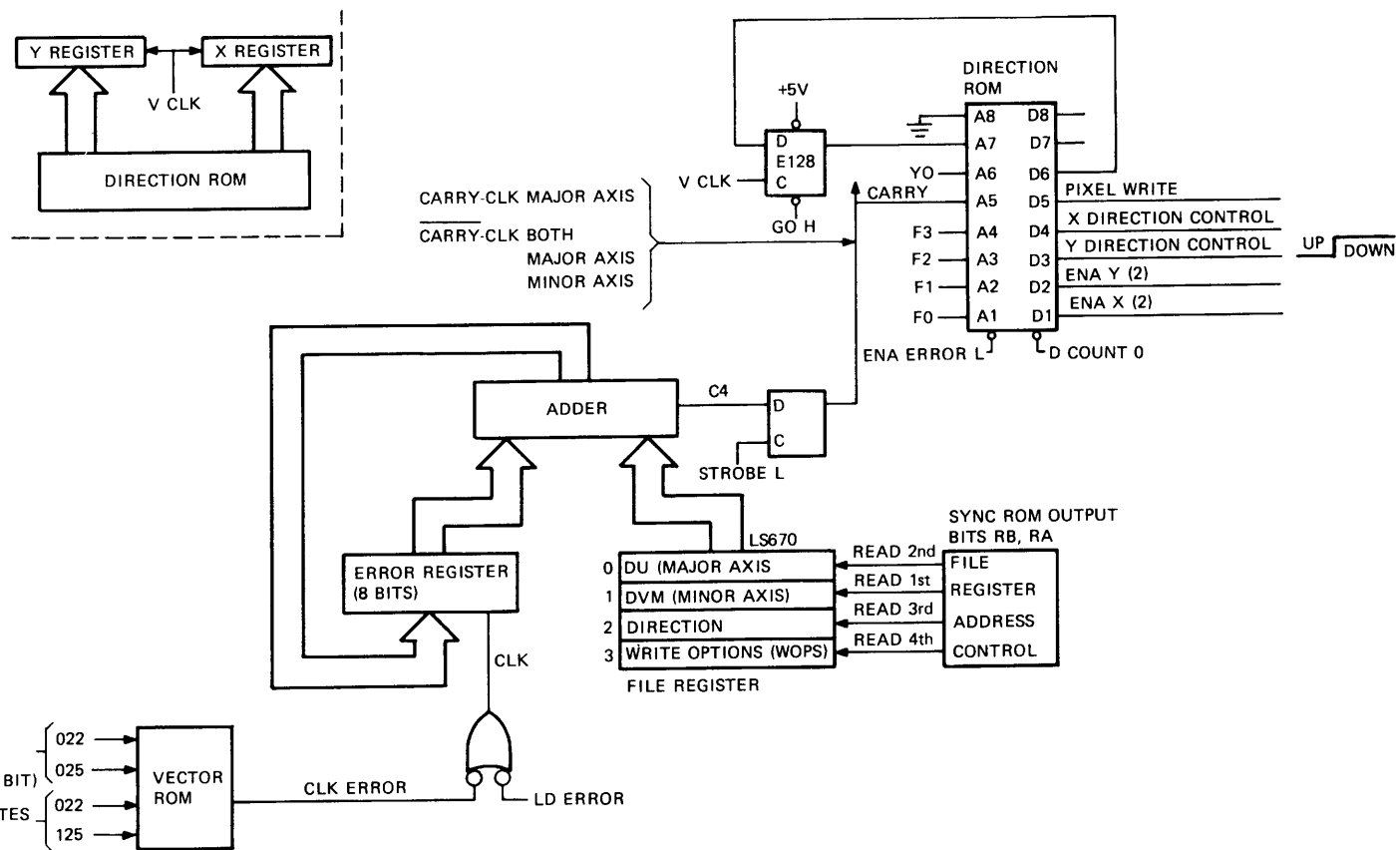
A calculation requires twelve time states (Figure 5-24). These twelve time states are divided into four groups. The four groups are repeated until the vector is drawn. The four sequential groups are:

1. DVM time (length of minor access)
2. DU time (length of major access)
3. WOPS time
4. Direction time



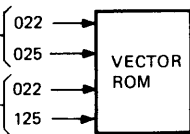
MA-8331

Figure 5-23 Arbitrary Vector Timing



VECTOR ROM  
GENERATES 2  
CLK ERROR PULSES  
(CARRY IS AN ADDRESS BIT)

VECTOR ROM GENERATES  
1 CLK ERROR PULSE



CLK ERROR

LD ERROR

MA-8172

Figure 5-24 Carry Control



When writing a vector, the firmware loads the following registers:

DVM -- with the length of the minor access. For an example use the value of 3 (Appendix B).

DU -- with the length of the major access. For an example use the value of 5 (Appendix B).

Error Rec -- is loaded with a value that the firmware obtains by dividing 2 into the largest value. For an example the value 5 divided by 2 equals 2 with a remainder of 1 (Appendix B).

The following are the functions that occur in each group.

DVM Time -- The error register is added to the DVM register plus carry in. The error clock loads the sum into the error. The carry output of the add is strobed into the carry flip-flop.

DU Time -- The contents of the error register are added to the DU register. If the carry flip-flop is reset, the vector ROM allows an error clock pulse which loads the result of the add into the error register. If the carry flip-flop is set, the vector ROM does not allow an error clock pulse to occur. The contents of the error register remain unchanged.

WOPS Time -- The modified data bits are selected and written into the screen RAM location specified by the X and Y registers.

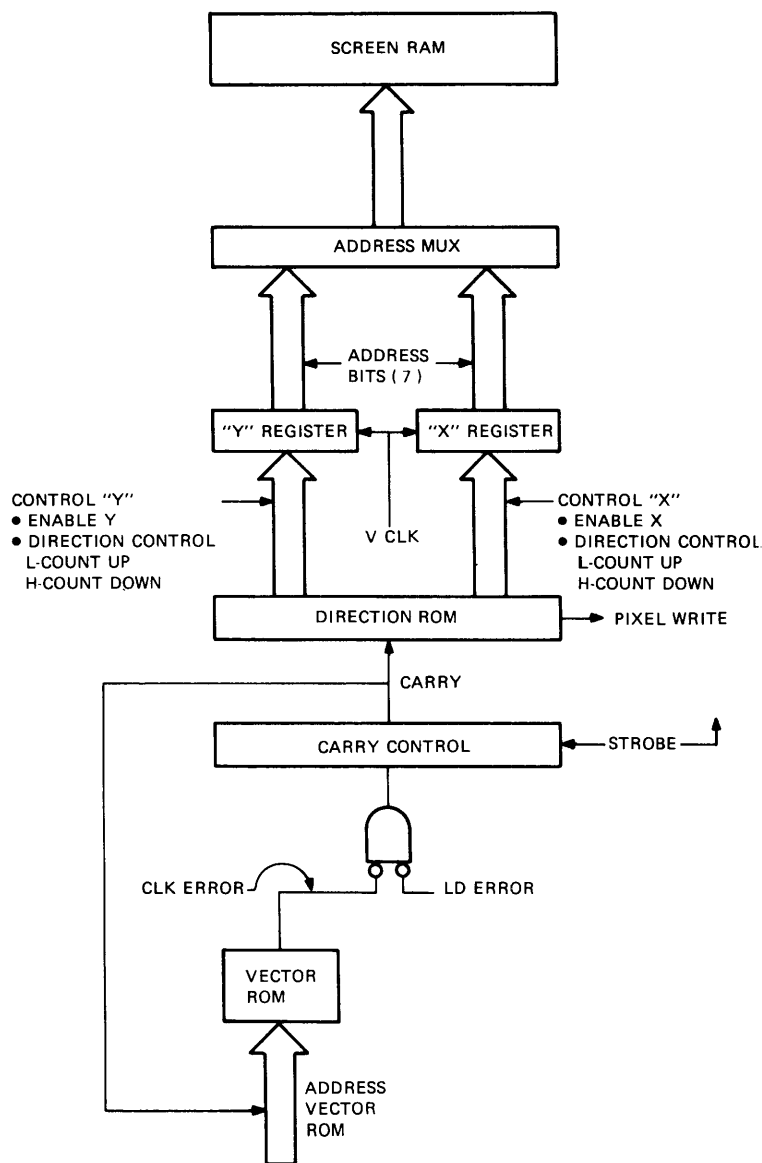
Direction Time -- The outputs of the direction register, bits F3--F0, are inputs to the direction ROM (Figure 5-25). An arbitrary vector is drawn in direction three when the input bits of the direction ROM equal "B" hex. The carry bit equal to a one indicates that the major axis register is only affected. The direction affected is determined by the direction ROM input bits F0--F2. Direction three is a negative direction. Therefore, the major access register decrements.

If the carry bit equals zero, the major and minor axis registers are effected. The direction effected is determined by the ROM input bits F0--F2. Direction three is a negative direction. Both the major and minor axis registers are decremented.

The vector sequence terminates when the V clock signal clocks the downcounter to zero. This resets the Go flip-flop.

The direction ROM produces the signal pixel write. The pixel write must be active to write data into the screen RAM. There are three conditions that prevent a write operation from occurring.

1. Do not write in direction: 2 from an odd line.  
6 from an even line.
2. Do not write if the direction is 5 or 7. The scan line is even (Y0) and the last direction was 6.
3. Do not write if the direction is 1 or 3. The scan line is odd and the last direction was 2.



MA-8174

Figure 5-25 Direction Control

### 5.2.3 I/O Port Overview

The VK100 interfaces to the host system through a serial data port. An 8251 programmable universal synchronous or asynchronous receiver-transmitter drives the port. This device translates between parallel and serial character formats. The 8251 adds or removes start and stops bits as needed. The data used are ASCII characters. Character parity may be enabled or disabled. The parity bit, if selected, takes the most significant bit position. The VK100 I/O system can connect the three CPU ports.

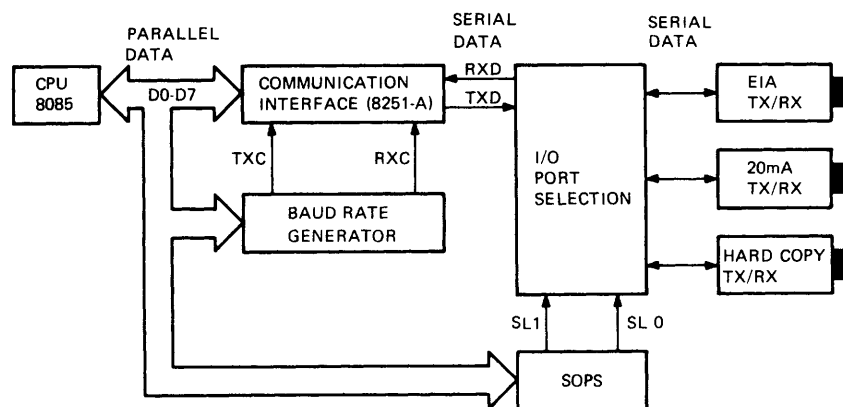
EIA  
20 mA  
Hardcopy

Figure 5-26 shows the Basic I/O Port block diagram.

The communication interface (8251A) is the main control of the I/O section. The baud rate generator allows firmware control of the baud rates to transfer data through the 8251A module.

The I/O port selection logic is controlled by the SL1 and SL0 bits of the screen option register (SOPS). Different combinations of SL1 and SL0 select the desired port or the self-test feature.

The self-test diagnostic feature is firmware controlled. A known value is sent to the I/O interface. The value goes through the 8251A chip as serial transmit data, to the I/O port selection (self-test). Then the data is serially routed to the RXD input of the 8251A chip. The chip assembles a data byte and sends the byte in parallel form to the CPU. The CPU compares the transmitted value to the received value.



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Figure 5-26 Basic I/O Port Block Diagram

5.2.3.1 Communication Interface (8251A) -- This interface (Figure 5-27) performs the following three functions.

- Modem Control
- Data Control
- Error Reporting

Mode Instruction Register -- After an internal reset, the CPU loads the mode instruction register. Then any control register writes will load the data into the command instruction register. To return the 8251A from command to mode instruction, the CPU sets the internal reset bit of the command register.

The mode instruction register defines the general operating characteristics of the 8251A (Figure 5-28). The following paragraphs describe these characteristics.

- Baud rate factor
- Character length
- Number of stop bits
- Parity control

The Baud Rate Factor (X16) -- The baud rate selected is times 16 (X16) because the TCLK and RCLK frequencies are 16 times the selected baud rates. To obtain the selected baud rate, divide the TCLK and RCLK frequencies by 16.

Character Length -- The length of a character transmission may be 5, 6, 7 or 8 bits. The unused bits are zeros (Figure 5-29).

Number of Stop Bits (1, 1-1/2, 2) -- If the baud rate is 310 or above, the CPU selects one stop bit. If the baud rate is under 310, the CPU selects two stop bits.

Parity Enable -- When set this bit enables parity generation and parity detection.

Parity Generation Bit -- When set this bit generates even parity for data transmission. Even parity means the character bits plus the parity bit have an even number of one bits. After receiving a data character the 8251A parity check logic counts the number of one bits in the character plus the parity bit. An odd number of one bits raises the parity error flag.

When clear this bit generates odd parity for data transmission. Odd parity means the character bits plus the parity bit have an odd number of one bits. After receiving a data character, the 8251A parity check logic counts the number of one bits in the character plus the parity bit. An odd number of one bits raises the parity error flag.

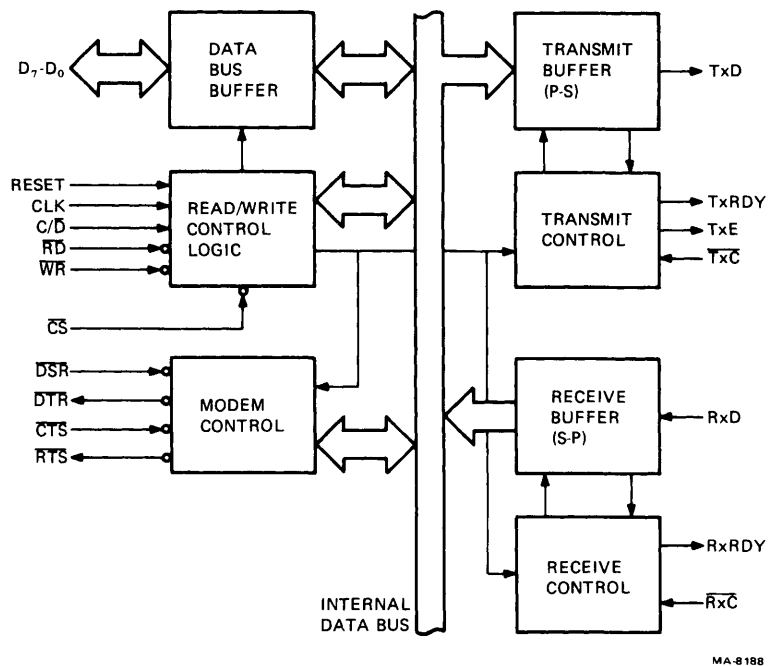


Figure 5-27 8251-A Block Diagram

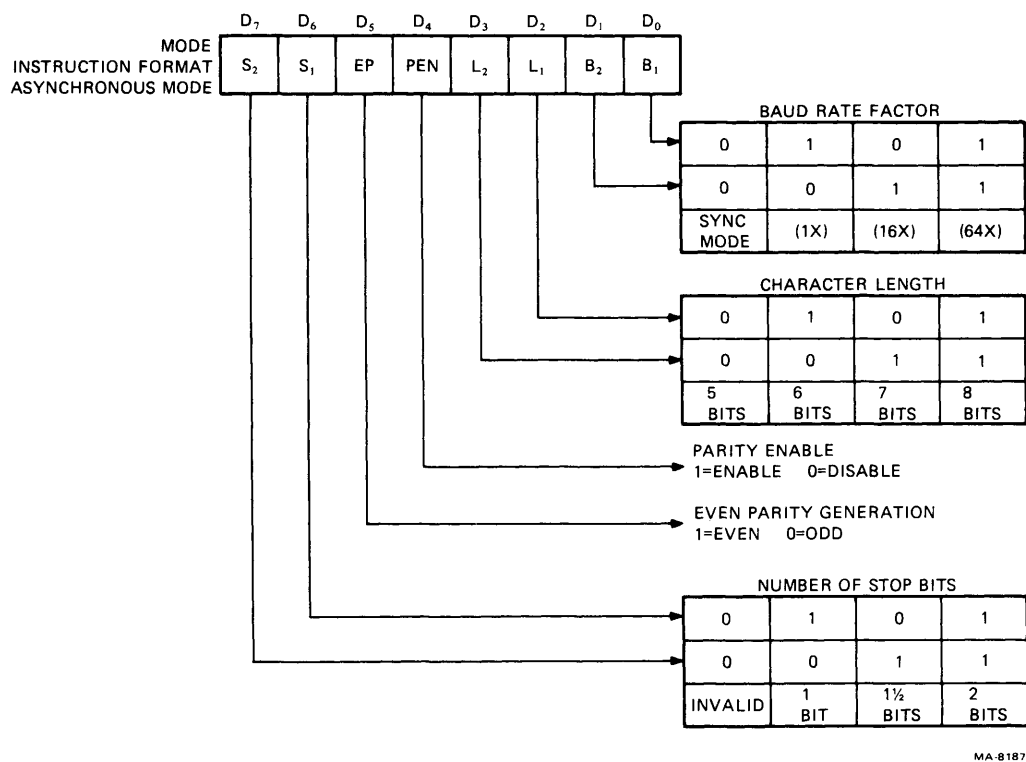


Figure 5-28 Mode Register

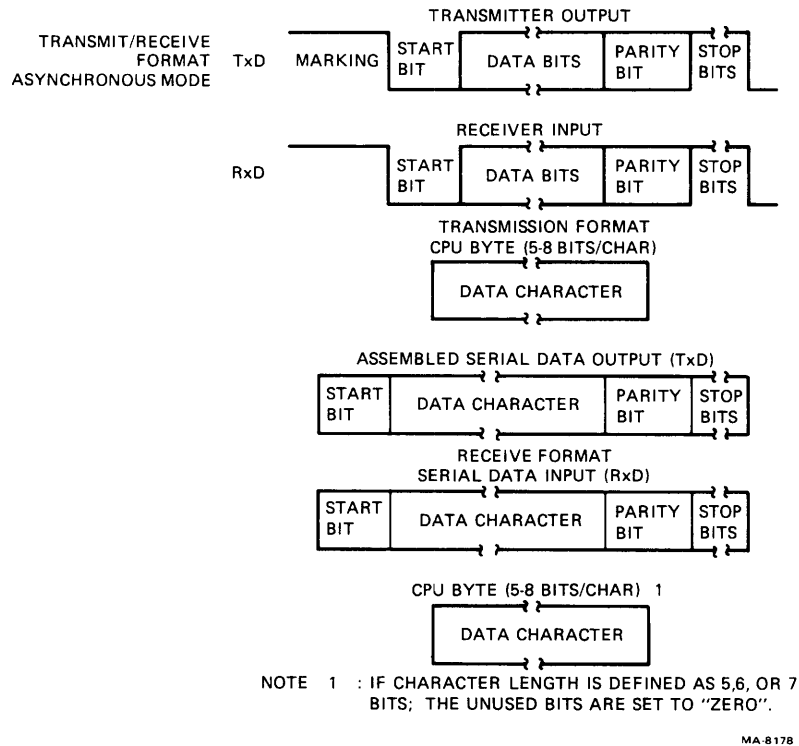


Figure 5-29 Transmit/Receive Format  
Asynchronous Mode

Command Instruction Register (Figure 5-30) -- The command instruction register defines the controls used in the operation of the 8251A. The following are the signals that control this operation.

- Transmit Enable
- Receive Enable
- Data Terminal Ready
- Request to Send
- Error Reset
- Internal Reset
- Send Break Character
- Enter Hunt Mode

Transmit Enable -- When the CPU sets this bit the 8251A can transmit data. Resetting this bit inhibits data transmission.

Receive Enable -- When the CPU sets this bit the 8251A can receive data. Resetting this bit prevents data reception.

The Transmit Enable and Receive Enable are both set in the VK100 system. This allows the 8251A to operate in full duplex mode.

Data Terminal Ready (DTR) -- The CPU sets this bit for loopback test.

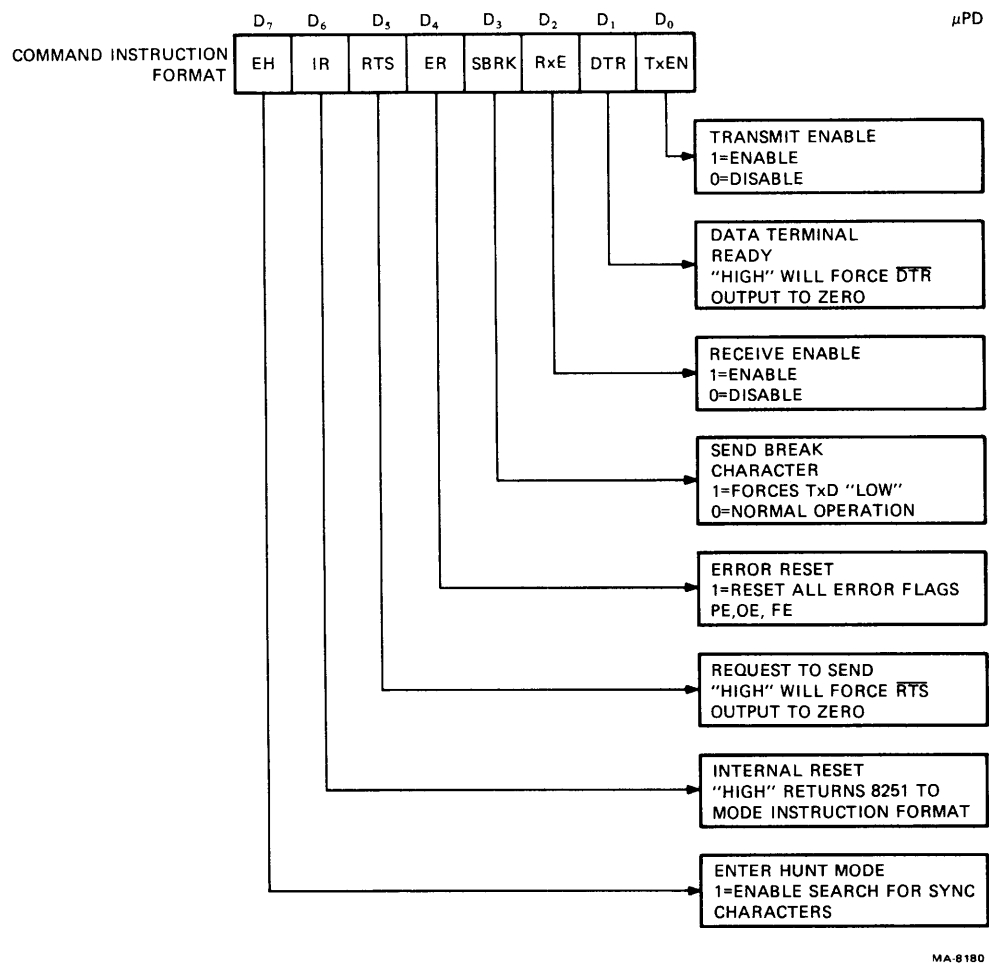
Request to Send -- The request to send signal is normally used for modem control.

Error Reset -- When the CPU sets this bit all error flags are reset. Parity Error (PE), Overrun Error (OE), and Framing Error (FE) are reset in the status register.

Internal Reset -- When set this bit returns the 8251A from Command instruction to Mode instruction.

Send Break Character -- When set this bit forces TxD to a low.

Enter Hunt Mode -- This bit is a zero. The VK100 system does not use the Hunt mode.



MA-8180

Figure 5-30 Command Instruction Format



Status Register -- Data Communication Systems require the status of the active device. To obtain the status, the CPU reads the status register. The following are the status register bits (Figure 5-31).

- Transmitter Ready (TxRDY)
- Receiver Ready (RxRDY)
- Transmitter Empty (TxE)
- Parity Error (PE)
- Overrun Error (OE)
- Framing Error (FE)
- SYNDET
- DSR

TxRDY -- This bit signals the CPU that the transmitter is ready to accept a data character. The CPU can use TxRDY for interrupt or polled operations. In polled operations the CPU checks TxRDY using a status read operation. TxRDY automatically resets when the CPU loads a character.

RxRDY -- This bit indicates that the 8251A contains a character ready to input to the CPU. RxRDY connects to the interrupt structure of the CPU or for polled operation. The CPU can check the condition of RxRDY using a status read operation. RxRDY is automatically reset when the CPU reads the character.

TxE -- When the 8251 has no characters to transmit, the TxE output goes high. TxE automatically resets after receiving a character.

The error conditions (PE, OE and FE) are covered in the asynchronous data transfer section.

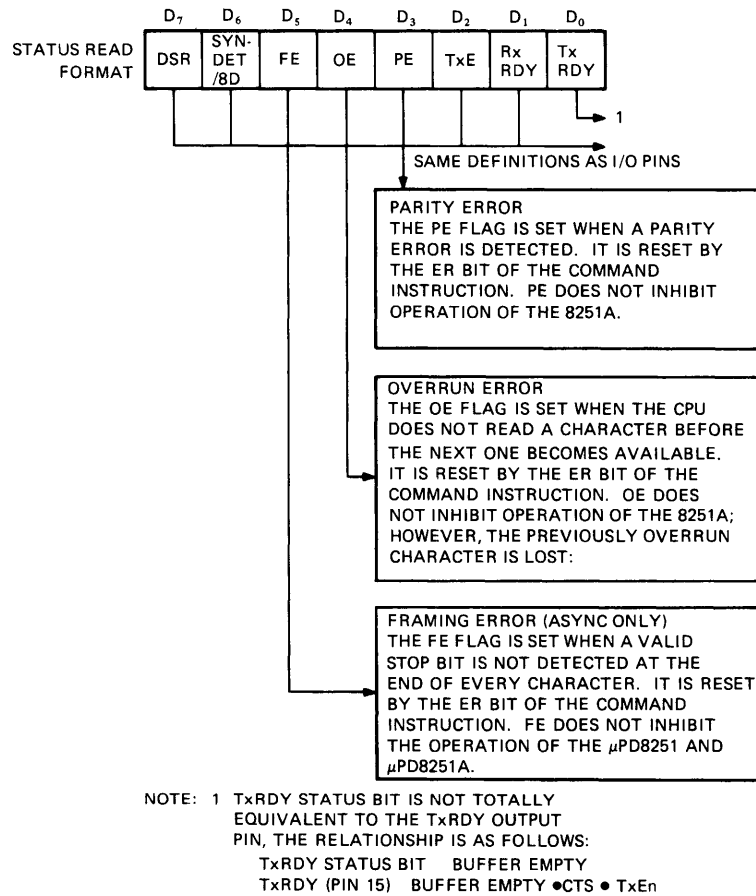
DSR -- The CPU uses this bit to monitor the hardcopy port. The usage of this bit is covered in the Hardcopy section (Paragraph 5.2.3.3).

Asynchronous Data Transfers -- In the VK100 system there are two modes of data transfers:

1. Data transmissions (TxD)
2. Data receptions (RxD)

Asynchronous Mode Transmissions -- Whenever the CPU sends a character the 8251 does the following.

- Adds a start bit (low level)
- Adds the required number of stop bits
- Adds the correct parity bit if parity is enabled



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Figure 5-31 Status Register

The character is then transmitted as a serial data stream on the TxD output (Figure 5-28). The serial data is shifted out on the trailing edge of TxC at a rate equal to 1/16 of the TxC as defined by the Mode Instruction. Break characters can be continuously sent to TxD if commanded to do so. If no data characters are loaded into the 8251A the TxD output remains high (marking) unless a break (continuously low) has been programmed.

**Asynchronous Mode Reception** -- The RxD line is normally high. When the line goes low this triggers the beginning of the start bit. The validity of the start bit is checked by strobing at the start bits nominal center. If a low is detected at the nominal center a valid start bit has been found. The bit counter then starts counting. The bit counter locates the center of the received bits, parity bits (if it exists) and the stop bits. The stop bits signal the end of a received character. The character is then loaded into the I/O buffer of the 8251A and the logic (RxDY) signals the CPU that data is available. The 8251A checks each character for errors. There are three types of errors.

1. Parity Error
2. Framing Error
3. Overrun Error

**Parity Error** -- The rising edge of RxC samples the receive inputs data and parity. If a parity error occurs, the parity error flag is set.

**Framing Error** -- Occurs if a low level is detected at the stop bit.

**Overrun Error** -- If a previous character has not been fetched by the CPU, the present character replaces it in the I/O buffer and the overrun flag is raised (the previous character is lost).

The occurrence of any of these errors will not stop the operation of the 8251A.

Table 5-8 shows the addressing of the 8251A.

**Table 5-8 Addressing the 8251-A**

Address Bits		Selection and Directive		
CD	RD	WR	CS	
0	0	1	0	8251A → Data Bus
0	1	0	0	Data Bus → 8251A
1	0	1	0	Status → Data Bus
1	1	0	0	Data Bus → Control
X	X	X	1	
X	1	1	0	Data Bus → 3 State

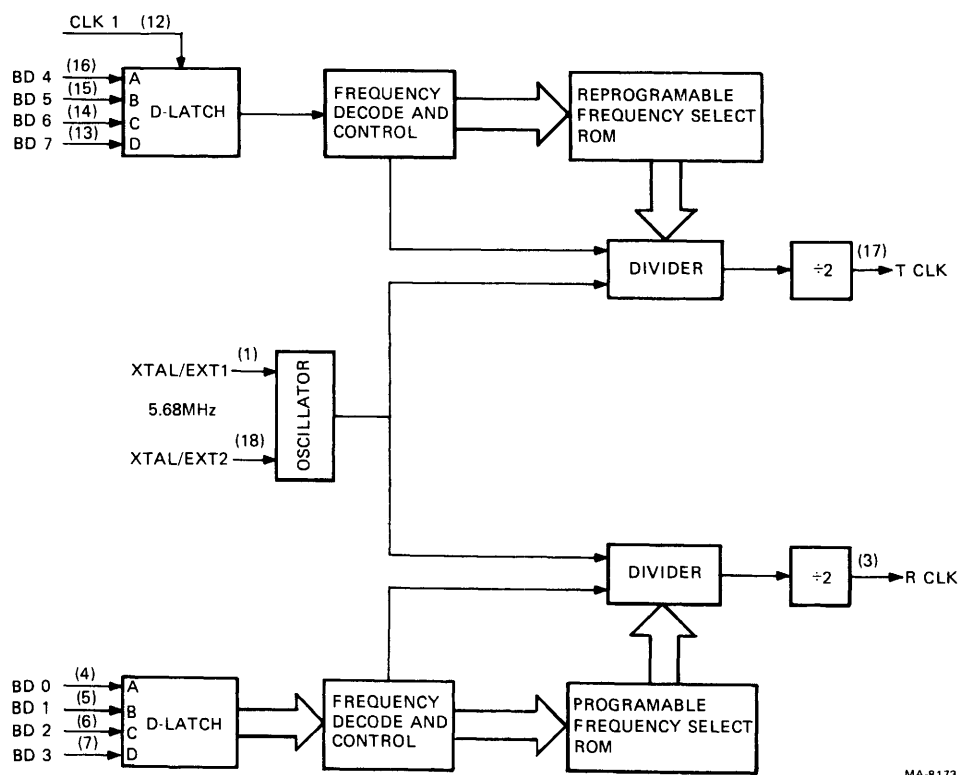
**5.2.3.2 Baud Rate Generator** -- The baud rate for a VK100 system is controlled by:

Default set up switch pack (switches S6--S8)  
 SET-UP mode (Refer to Chapter 4)  
 ReGIS command (Refer to Chapter 4).

On power up, or reset, the firmware uses default set-up switch pack (S6--S8) to load the baud rate generator with a byte value. This value selects the Tx clock and Rx clock frequency. The low four bits of the byte value select the baud rate for the Rx clock pulses and the high four bits select the baud rate of the Tx clock. Both the Tx clock and Rx clock frequencies are 16 times the selected baud rate. If the selected baud rate is 300 bits per second the clock frequencies are 4.8 kHz.

The baud rate generator sends the Tx clock or Rx clock frequency to the 8251A chip which divides the frequency by 16. The result is the device baud rate. Figure 5-32 shows the baud rate generator block diagram.

Table 5-9 shows how the CPU selects one of the eight possible baud rates used for the receive and transmit frequencies.



**Figure 5-32 Baud Rate Generator**

Table 5-9 Baud Rate Selection Crystal Frequency = 5.0688 M Hertz

Transmit/Receive Address D C B A	Baud Rate	Theoretical Frequency 16 X CLOCK	Actual Frequency 16 X CLOCK	Divisor
0 0 1 0	110	1.76 Hz	1.76 K Hz	2880
0 1 0 1	300	4.8	4.8	1056
0 1 1 0	600	9.6	9.6	528
0 1 1 1	1200	19.2	19.2	264
1 0 1 0	2400	38.4	38.4	132
1 1 0 0	4800	76.8	76.8	66
1 1 1 0	9600	153.6	153.6	33
1 1 1 1	19,200	307.2	316.8	16

#### 5.2.3.3 Selection of I/O Port -- The I/O ports are selected by:

Default SET-UP switch pack  
 SET-UP mode (Refer to Chapter 4)  
 ReGIS commands (Refer to Chapter 4).

When a power up or reset operation is performed, the CPU reads the default SET-UP switch pack. The condition of switch two (S2) determines if the CPU is connected to the 20 mA or EIA port. If S2 is open, the 20 mA port is used. If S2 is closed, the EIA port is used.

When an I/O port is selected the CPU modifies bits SL1 and SL0 of the screen option register (SOPS). The condition of these two bits connect the CPU to the selected port (5-33). Table 5-10 also shows this condition.

#### 5.2.3.4 Transferring Data Through the I/O Port -- The VK100 system uses the following three ports to connect the CPU to other devices.

20 mA  
 EIA  
 Hardcopy

20 mA Port -- The VK100 system has full-duplex capabilities. This includes a transmit and receiver channel (J1).

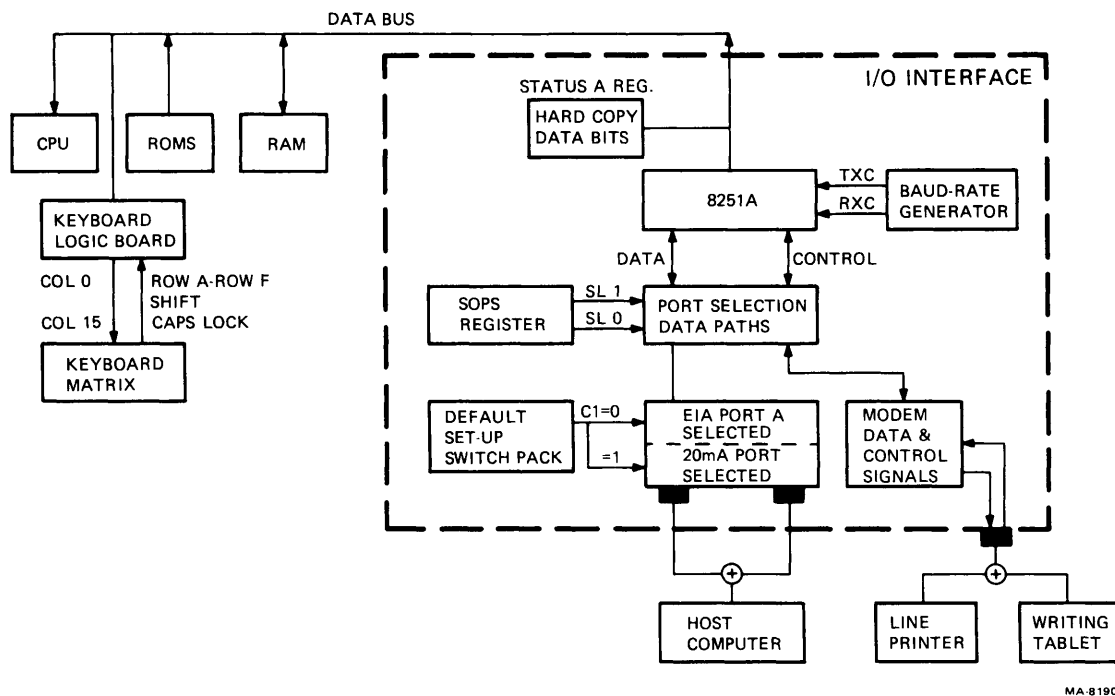


Figure 5-33 Port Selection Block Diagram

Table 5-10 I/O Port Selection

MUX Inputs	SL1	SL0	Port Selection
A	0	0	EIA
B	0	1	20 mA
C	1	0	Hardcopy
D	1	1	Self-test

Note -- 0 Level = L  
1 Level = H

Transmit Channel -- The CPU sends the data to the 8251A. This is where the transmission format is put together according to the mode instruction register. The data stream is shifted out of the 8251A serially on the TxD line. The data goes through the I/O port selected logic. The SOPS register bits SL1 and SL0 (L,H) selects the 20 mA drive circuitry to transmit the data to host computer (Figure 5-34).

The data that is transferred out to the 20 mA line goes through a photo transistor. When the photo transistor circuit receives the mark bit, the photo cell transistor is cut off. This allows Q7 to conduct which in turn causes Q8 to conduct. When Q7 and Q8 transistors are turned on the source current (18--50 mA) flows from pin 2, through Q7 and Q8, out to pin 5.

When the photo transistor circuit receives a space (start bit), the photo transistor turns on. This action cuts off Q7, which then cuts off Q8. The current that flows from pin 2 goes through the constant current diode. This keeps a constant current of 2 mA that goes through the photo transistor out to pin 5.

Receiver Channel -- The receiver channel monitors the current loop. If a mark is detected, the receiver channel changes the mark to a binary one. If a space is detected, the receiver channel changes the space to a binary zero.

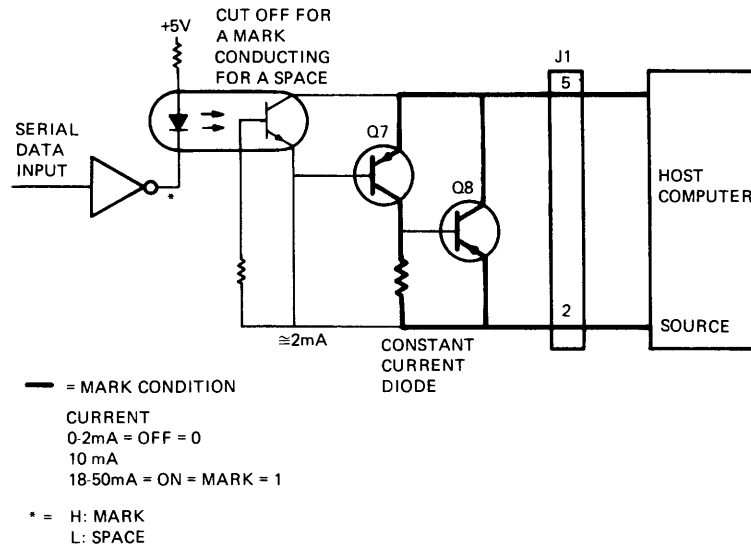
The receiver channel detects a mark and space in the following manner (Figure 5-35). The marking state is the initial condition.

The marking current causes the photo diode to conduct. When the photo diode passes 18 to 50 mA of current, the photo transistor turns on. The conduction of the photo transistor causes a positive voltage drop that turns on Q6. When Q6 conducts, a mark condition exists. The output of Q6 is inverted. The mark bit goes through the receiver multiplexer to the RxD input of the 8251A.

When a start bit is detected (space) the received current drops from (18 to 50 mA) to (0 to 2 mA). The space condition cuts off the photo transistor which cuts off Q6. The output of Q6 is inverted (0). The space signal goes through the receiver multiplexer to the RxD input of the 8251A.

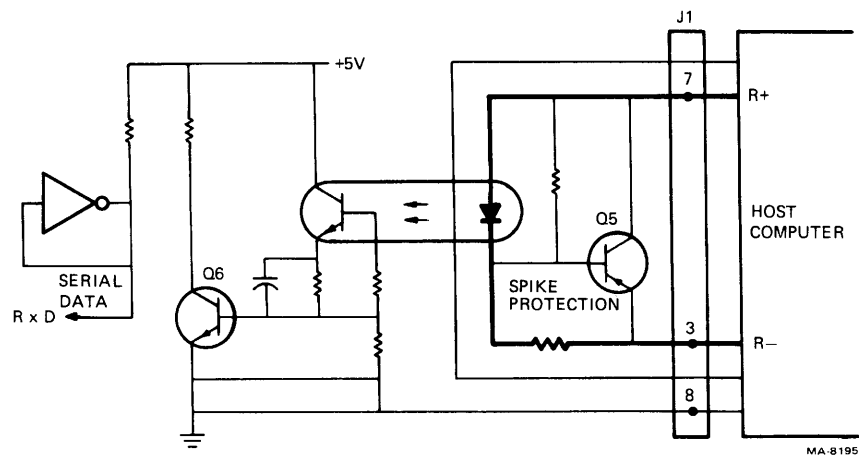
Table 5-11 shows the transmitter and receives interface specifications.

EIA Port -- The data transfer is the same as the 20 mA port except the EIA drivers or receivers are selected. Figures 5-36 and 5-37 show the block diagrams.



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Figure 5-34 20 mA Transmit Loop



MA-8195

Figure 5-35 20 mA Receive Loop

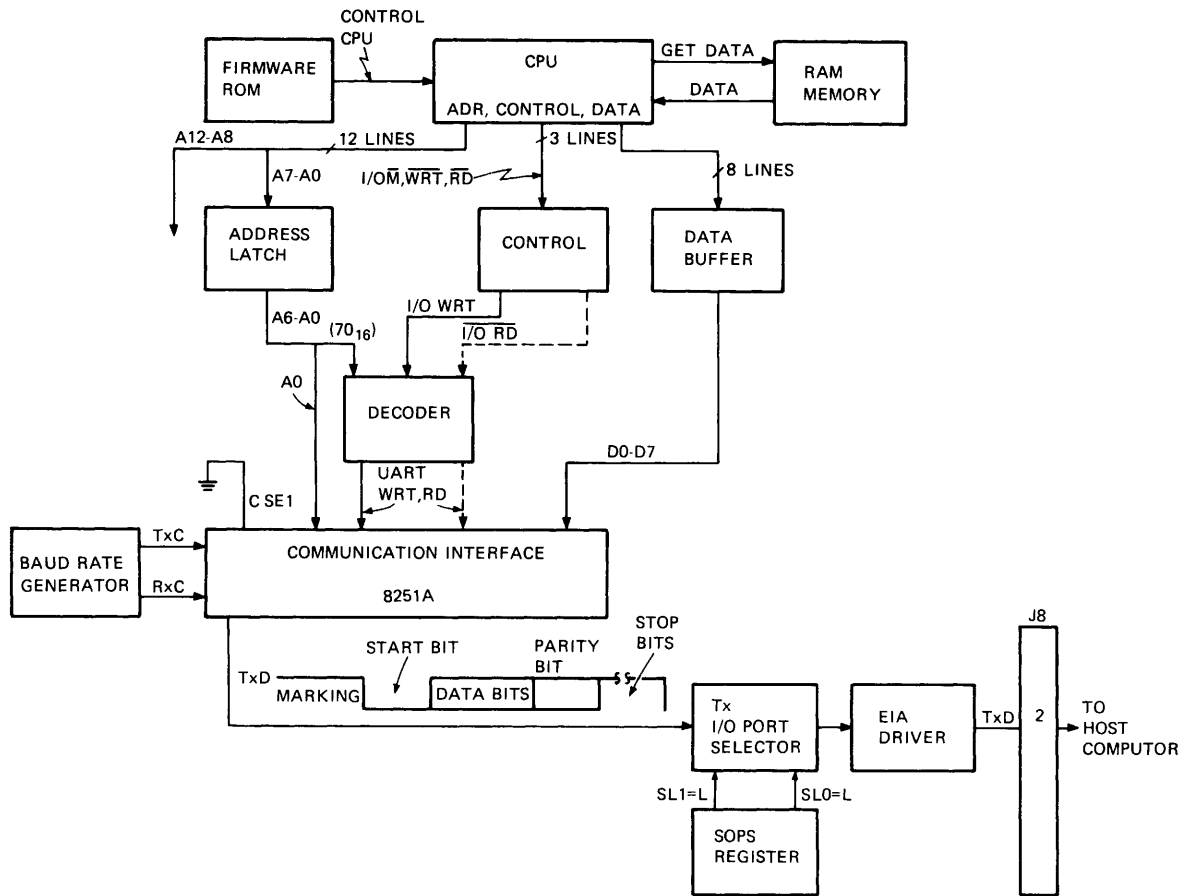


**Table 5-11 Interface Specifications**

Transmitter	Min	Max	Units
Open circuit voltage	5.0	50	Volts
Voltage drop marking	0.0	2.0	Volts
Spacing current	--	2.0	MA
Marking current	20	50	MA

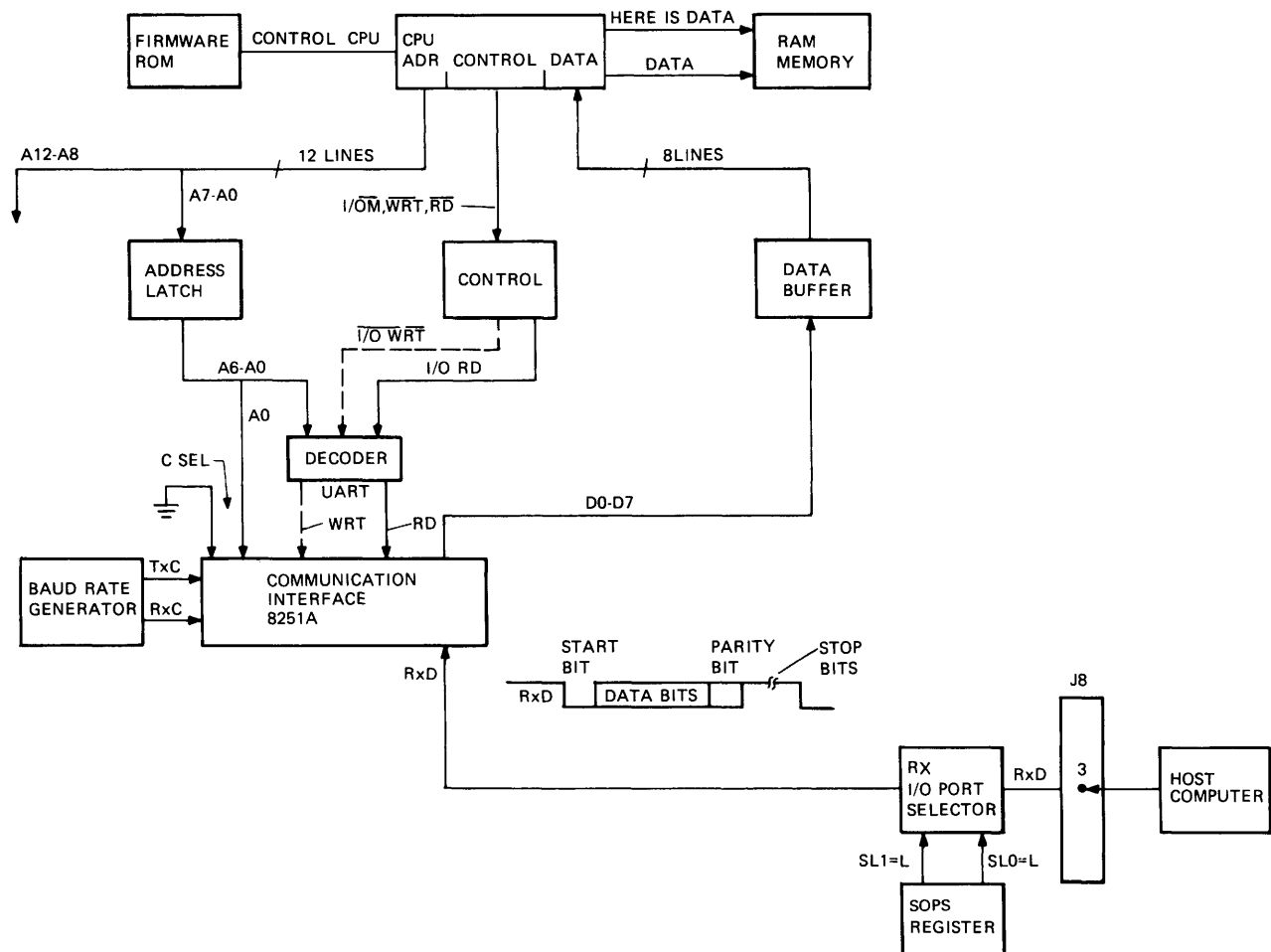
  

Receiver	Min	Max	Units
Voltage drop marking	--	2.3	Volts
Spacing current	--	3.0	MA
Marking current	15	50	MA



MA-8201

**Figure 5-36 EIA Transmit**



MA-8171

Figure 5-37 EIA Receive

**5.2.3.5 Hardcopy Overview** -- The hardcopy mode outputs screen image information to a hardcopy device (LA34-VA or another future compatible device) to obtain a permanent record on paper. Only the information in the bit map memory is sent to the device. The video attribute information is ignored. The four ways of entering hardcopy mode are:

1. Normal Screen Dump
2. Auto-Hardcopy
3. Partial-Hardcopy
4. Hardcopy Dump in Graphics Mode.

**Normal Screen Dump** -- Once initiated the screen is frozen and the entire image prints. Use SHIFT/PF1 keys or DECHP escape sequence (ESC #7) to enter this mode.

**Auto Hardcopy** -- This is similar to the normal screen dump but it is initiated automatically before the screen clears or scrolls an entire display of new text lines onto the display.

Auto Hardcopy is enabled using Set-Up (AH1) or SM escape sequence (ESC [ ? 24 h ] ), and disabled by AH0 or ESC [ ? 24 l ]. To abort hardcopy before completion, use the SHIFT/PF1 keys.

\* The last letter of the sequence is a lowercase l (154<sub>8</sub>).

**Partial Hardcopy** -- This prints the number of lines specified by the parameters in the following DEC PDH escape sequence

ESC [ Pn; Pn ! 8]

This escape sequence freezes the display and prints from the text line specified by the first parameter to the line specified by the second parameter.

**Hardcopy Dump in Graphics Mode** -- Hardcopy can be initiated using ReGIS screen command with hardcopy option:

S (H [, Y1] [, Y2])

If only one Y parameter is specified, the other Y parameter defaults to the current graphics cursor Y position. If neither Y parameter is specified, the whole screen is copied.

**Graphics Data Stream Format** -- The LA34-VA graphic printer accepts the hardcopy data from the VK100 in the following format:

```
CR SP SP SP SP
DCS Pn F . . . SD . . . ST PLO
DCS Pn F . . . SD . . . ST PLO
```

Where:

CR = Carriage Return  
SP = SPACE (ASCII 2/0)  
DCS = Device Control String: ESC P  
Pn = Parameter value for horizontal resolution selection:

Pn = 1 for horizontal resolution

F = q This final character donates the subsequent characters are encoded raster data to be printed.

SD = String Data

ST = String Terminator: ESC\ . Character processing returns to the method prior to the DCS.

PLO = Partial Line Down: ESC K moves to next line of graphic data.

The line printer connects to VK100 terminals in two ways.

1. Line printer connected only to a single terminal (Figure 5-38)  
(Line printer dedicated to one terminal)
2. Line printer connected to multi-terminals (Figure 5-39)  
(Line printer is shared by many terminals)

Figure 5-38 shows the cables used with both systems.

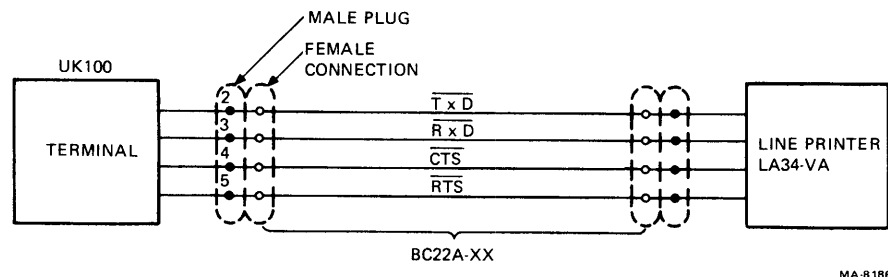


Figure 5-38 Line Printer Connected to Single Terminal

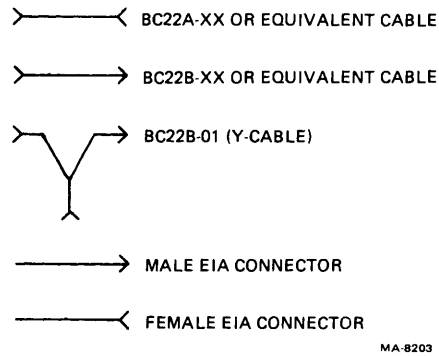


Figure 5-39 Printer Connection to Multiple  
Terminals and Connector Names

**Line Printer -- Connected to Multi-terminals --** The VK100 has the ability to organize multi-terminal demands for the hardcopy device. When the terminal outputs to the hardcopy device, all other terminals in the chain are locked out. The next terminal to be served depends on: the position of the currently printing terminal, its relation to other terminals in the chain, and the entering order of the hardcopy requests.

In general, the terminal farthest away from the printer has the higher priority and prints next. There is no limitation on the number of VK100 terminals that can connect to the line printer as long as the maximum distance between terminals is 50 feet. The number of VK100s serviced is limited by the users response time.

When a VK100 is powered off, all upstream terminals (farthest away from the hardcopy device) are broken off the chain. The upstream terminals are reconnected to the printer by bypassing the Y cable on the powered off terminal.

**5.2.3.5.1 VK100 Daisy Chain Bus Control --** The daisy-chain bus connecting the VK100s to the LA34-VA Graphic Line Printer is divided into data and control lines.

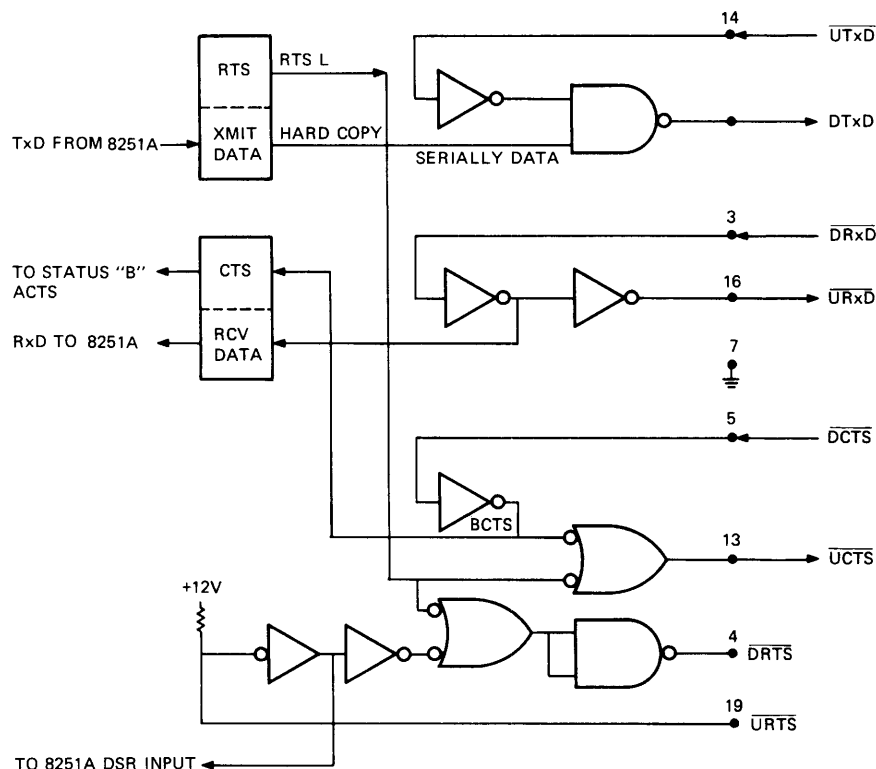
**Data Lines**

1. Transmit (TxD)
2. Receive (RxD)

**Control Lines**

1. Request to Send (RTS)
2. Clear to Send (CTS)

Figure 5-40 shows how each terminal interactively controls which terminal uses the VK100 daisy-chain bus.



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Figure 5-40 Logic for Hardcopy Bus Control

The signals that use the hardcopy daisy chain are:

- Upstream transmit data (UTxD)
- Downstream transmit data (DTxD)
- Upstream receive data (UPxD)
- Downstream receive data (DRxD)
- Upstream clear to send (UCTS)
- Downstream clear to send (DCTS)
- Upstream request to send (URTS)
- Downstream request to send (DRTS)

Terminals in the daisy-chain bus use an interconnecting dialogue that allows only one terminal at a time to use the bus. The following paragraphs describe this dialogue.

#### BUS NOT BUSY

When the bus is not busy each VK100 has as inputs, DCTS low and URTS high. The logic in each VK100 passes on the output signals, UCTS low and DRTS high. All VK100 are enabled to transfer data.

#### CPU WANTS TO USE BUS

A CPU that wants to transfer data reads two status registers.

1. Status Register B (checks ACTS bit)
2. Status Register 8251A (checks DSR bit)

The ACTS bit reflects the inverted condition of DCTS low (ACTS bit=1). The DSR bit reflects the condition of URTS high (DSR bit=0). The only time a VK100 can use the bus is when ACTS bit=1 and DSR bit=0.

When the CPU finds the ACTS bit=1 and DSR bit=0, it then clears the RTS bit in the command register in the 8251A. RTS switches the following signals.

1. UCTS goes high -- in the upstream terminal this signal name becomes DCTS high and is inverted changing the ACTS from a one to a zero. The upstream terminals have ACTS bits equal to zero to prevent the terminals from using the bus.
2. DRTS goes low -- in the downstream terminal this signal name becomes URTS low and is inverted changing the DSR bit from a zero to a one. The downstream terminals have DSR bits equal to one to prevent the terminals from using the bus.

#### CPU USING BUS

The terminal after gaining control of the bus transfers the data to the line printer (TxD).

#### BUS NOT BUSY

When the CPU finishes the data transfer the CPU sets RTS. RTS switches the UCTS and DRTS and the bus is no longer busy.

**5.2.3.5.2 Hardcopy Data Transfer** -- To transfer data to the line printer the following sequence takes place.

1. SET-UP
2. The DVM register is loaded. Direction equals 2.
3. The direction register is loaded. Direction equals 6.
4. The X and Y register is loaded.
5. The Baud Rate Generator is loaded.
6. The instruction format register is loaded.

For the following sequence of events refer to Figure 5-41.

SYSTAT A (X0, Y0) -- Firmware reads 4 bits from the screen RAM, (bits 0, 1, 2 and 3 of scan line zero) by issuing the instruction SYSTAT A. When the CPU receives the 4 bits it masks out bits 1, 2 and 3 and saves bit zero in a register X LSB in the CPU.

SYSTAT A (X0, Y2) -- Firmware reads 4 bits from the screen RAM, (bits 0, 1, 2 and 3 of scan line two) by issuing the instruction SYSTAT A. When the CPU receives the four bits it masks out bits 1, 2, and 3 and saves bit zero in a register X LSB + 1 position.

The above sequence continues until six reads are done (X0, Y12). At this time six-bit position zeros are stored in a register in the CPU.

The firmware makes an ASCII character by adding 077 octal to the contents of register X and sends the new value to the 8251A transmit buffer.

The 8251A assembles the data into the correct format, and transfers the data to the line printer.

The line printer receives and assembles the transmission, subtracts 077 octal from it and stores the result in a 256 byte buffer.

When its buffer is filled, the line printer transmits XOFF to the Receive Data buffer in the 8251A. This interrupts the CPU, signalling it to stop sending characters. When the buffer is able to receive more data it transmits XON to the CPU.

Starting at bit zero position the data is transferred as follows.

SCAN LINE 0--12 six bit zeros, six bit ones . . . . .  
six bit 767

SCAN LINE 12--26 six bit zeros, six bit ones . . . . .  
six bit 767

SCAN LINE 226--240 six bit zeros, six bit ones . . . . .  
six bit 767



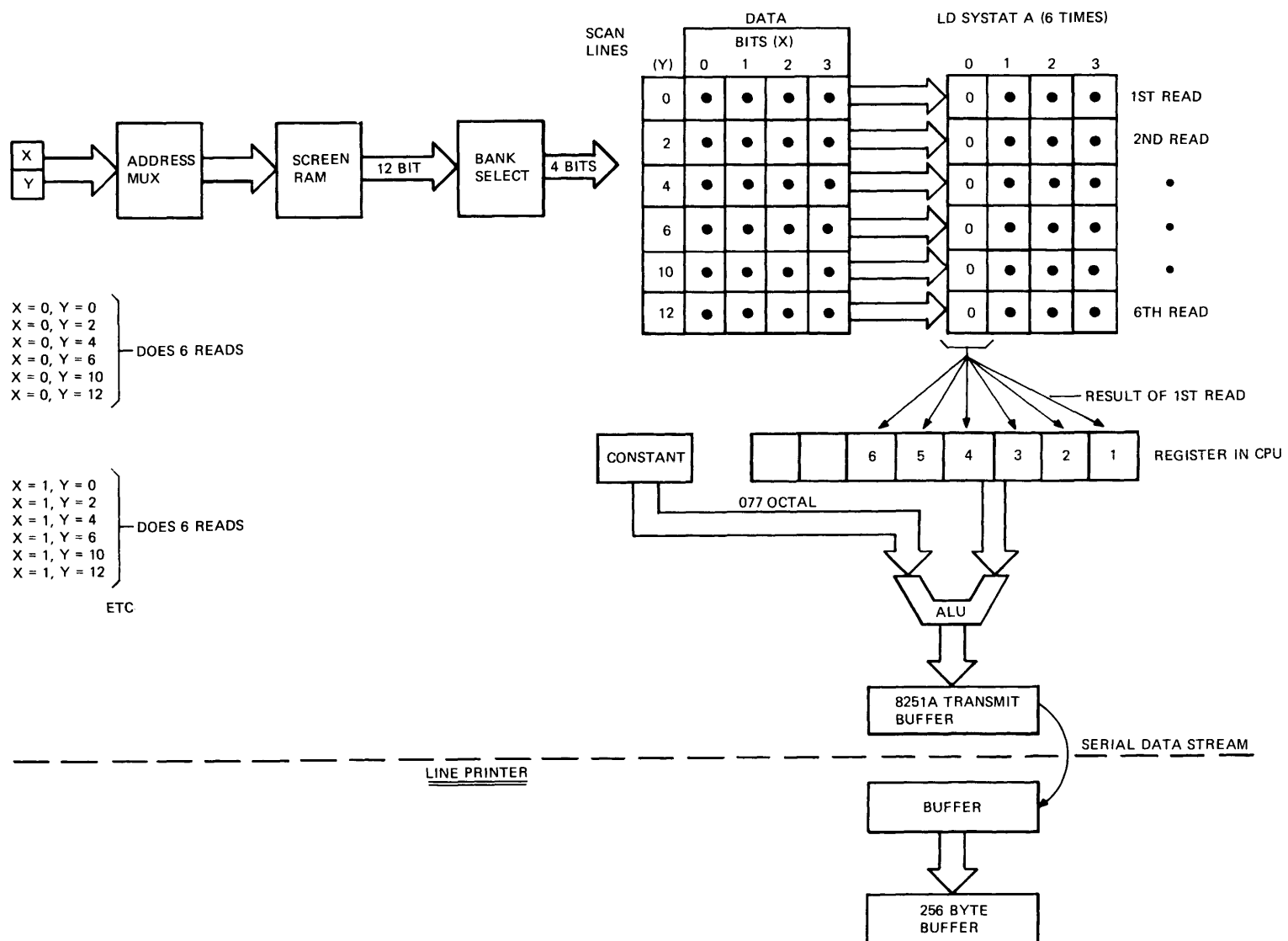


Figure 5-41 Hardcopy Data Transfer

#### 5.2.4 Keyboard

The keyboard is the user's input device to the terminal. The keyboard logic is divided into two sections.

1. Keyboard Matrix  
The keyboard switches are arranged like a typewriter with a numerical keypad. The keyboard matrix also provides light indicators.
2. Keyboard Interface  
The keyboard interface is on the terminal controller module and determines which keys have been pressed.

The keyboard is a firmware scanned key array, mapped into memory space (RAM). The CPU reads the keyboard array 16 times every 60th of a second to find out if any keys have been pressed. The keyboard logic consists of:

- Keyboard array
- Array column selector
- Indicators
- Audible section

The keyboard array consists of switches arranged in a column, row matrix. There are 15 columns (1--15) and 6 rows (A--F). Each switch has its own column and row position (Figure 5-42).

The CPU selects the column to read by using address bits A0--A3. When column one is selected, a ground (low) is present on one side of the following switches: SET-UP, ESC, TAB, ENTER and PF1. If one or more of the switches is pressed, the lows will be felt on the corresponding row bits. Then the CPU does a keyboard read (KBRD). Figure 5-43 shows column two addressed with the A switch pressed. The A switch pressed means the row C output is low and when the KBRD is active D2 goes low. All other bits are high. The code sent to RAM memory for an A is 11111011.

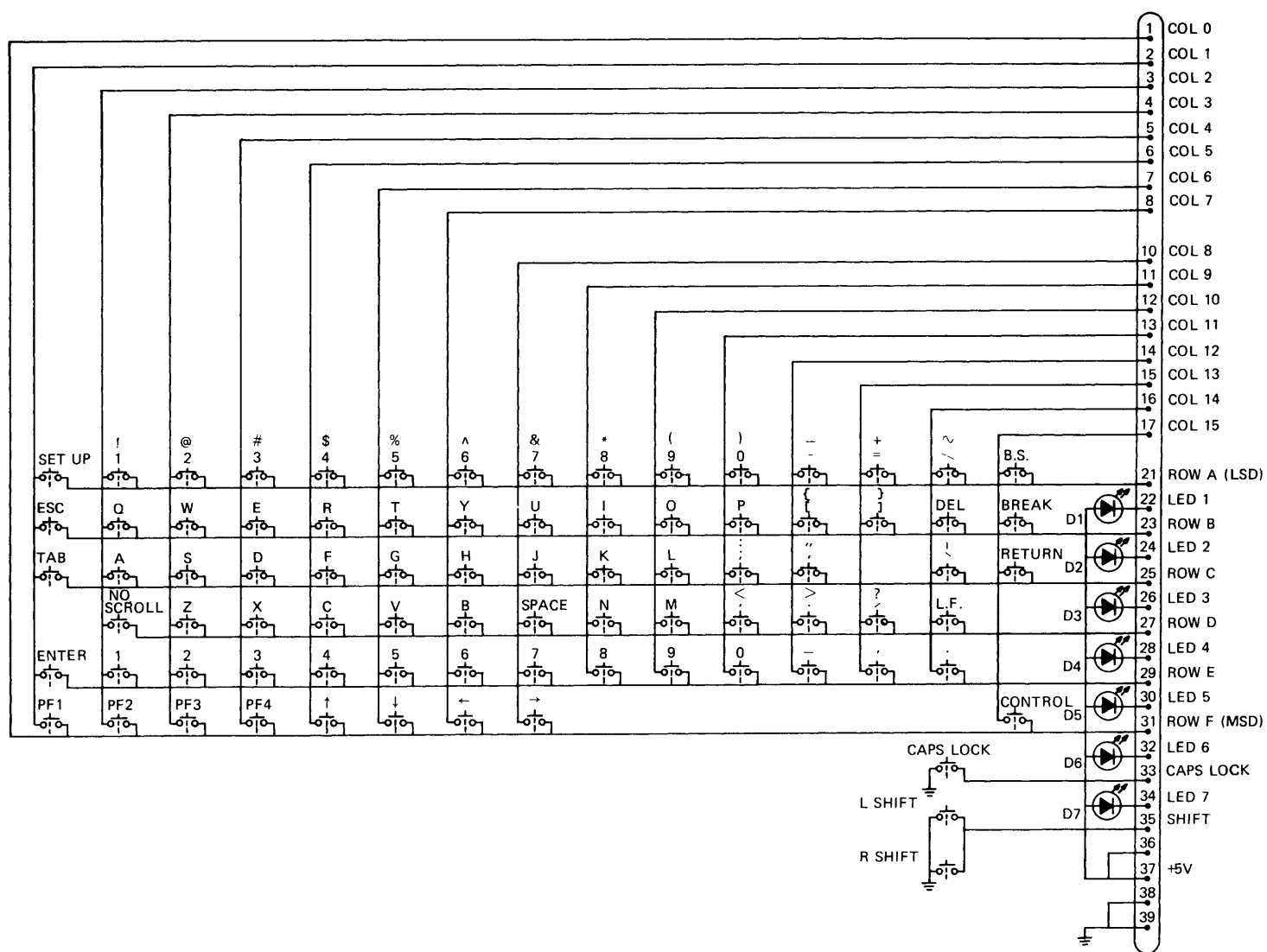
The keyboard write register controls the audible and indicator logic. Bits 1--6 control the indicators. Bit six output has two destinations:

1. ON-LINE LGD
2. Inverted bit six - LOCAL indicator

The following are the indicators.

- L2
- L1
- HARDCOPY
- BASIC
- NO SCROLL
- ON-LINE
- LOCAL

Bit six controls the ON-LINE/LOCAL signal.



MA-8204

Figure 5-42 Keyboard Matrix

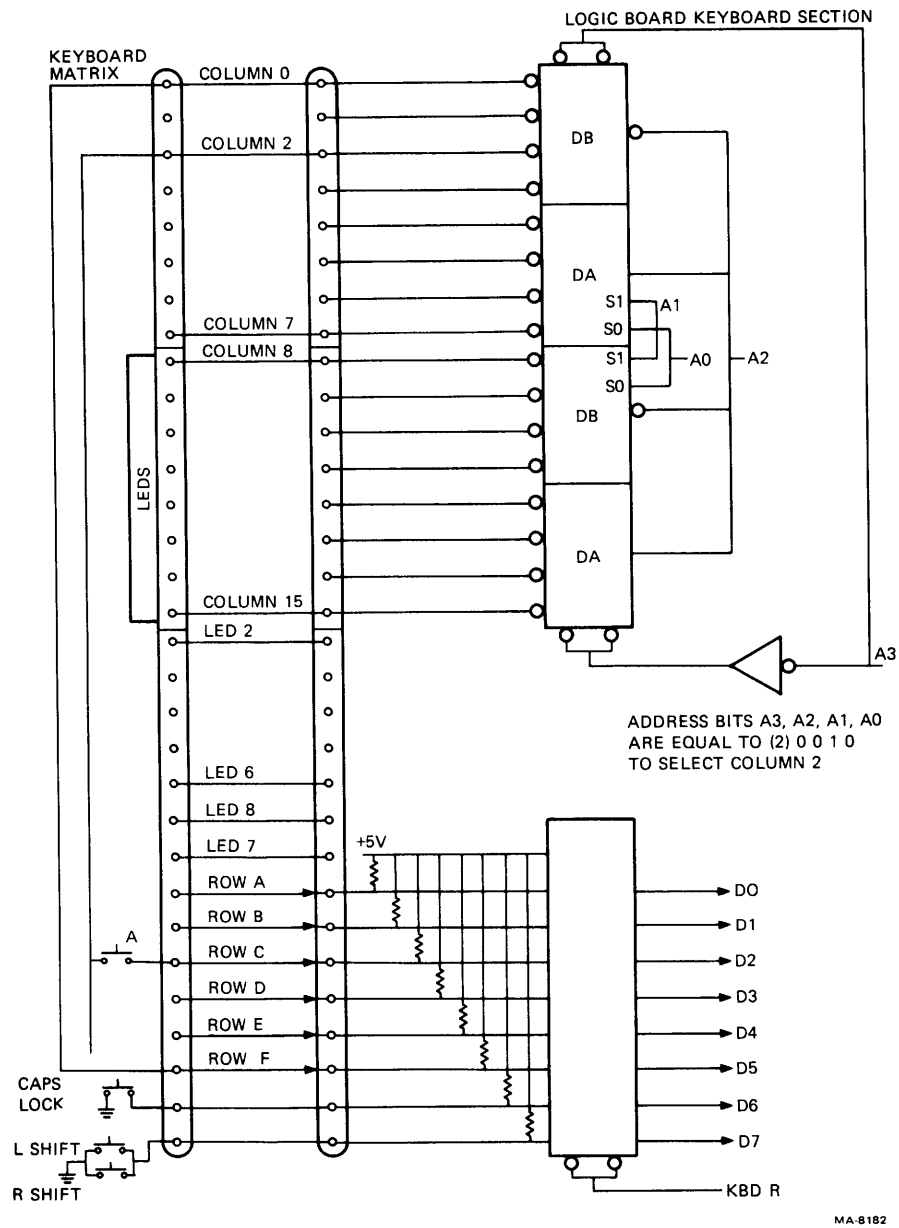


Figure 5-43 Keyboard Road with "A" Switch Pressed

Write register bits 77 and 8 control the two audible sounds emitted from the loudspeaker: the keyclick and beeper (Figure 5-44).

A one-shot multivibrator determines the keyclick signal. the output is high for 1.5 ms and low for 30.2 ms.

The beeper signal is high for 17.2 ms and low for 16.5 ms.

#### 5.2.5 Power Supply

The VK100 is driven by a free running, flyback mode, off-line switching power supply. It accepts either 115 or 230 Vac input and delivers three regulated dc outputs: +5 V, +12 V -5 V.

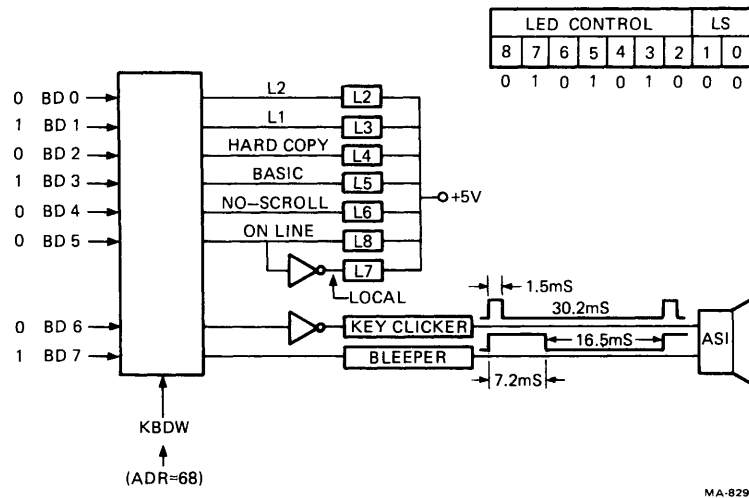


Figure 5-44 LED (Indicator) Keyclicks and Beeper Block Diagram

The power supply has the following protection.

Overcurrent Protection -- No damage to the power supply result from a short circuit of any duration across the output terminals. Normal operation resumes upon removal of the short circuit.

Overvoltage protection -- A crowbar circuit is provided to protect the load from damage. The crowbar activates if the +12 V output voltage range is between 13.0 V and 15.0 Vdc. No damage to the power supply results from activation of the crowbar for any duration and at any ambient temperature within specification limits.

Tolerance Band = +12 V: 11.4 to 12.6 dc  
-12 V: -11.4 to -12.6 dc

Output Current = +12 V: 0.2 to 0.9A dc  
-12 V: 0.2 to 0.075A dc

Voltage adjustments = none.

Figure 5-45 shows the power supply schematic. The explanation follows.

The mains are brought in through an EMI filter, (T1, C1, C2, and C3) rectified by BD1 and deliver approximately 300 Vdc across capacitive input filter C6, C7, C8, and C9. Current surge is limited by R1 and R2 and transient voltages are suppressed by VD1 and VD2. By turning on power transistor Q2, this voltage is applied across the primary of T2, charging its inductance with a linear current ramp. When Q2 is turned off, the energy stored in T2 is delivered from the secondary windings through rectifiers, capacitive input filters and smoothing filters to the outputs.

Initial turn-on Q2 is done by R1. Thereafter this task is performed by the feedback winding on T2 driving through R4 and C10. This winding initiates turn-on during the ring down following flyback. The operating frequency varies with line and load.

IC3 compares the output voltage level at the base of Q3. When the voltage created by L4 and R15 combination is sufficient to turn on Q3, T3 terminates Q2's drive..

Q2 can also be turned off when sufficient voltage is developed across R12 causing Q1 to turn on.

SCRI is used as a crowbar designed to protect against output overvoltage.

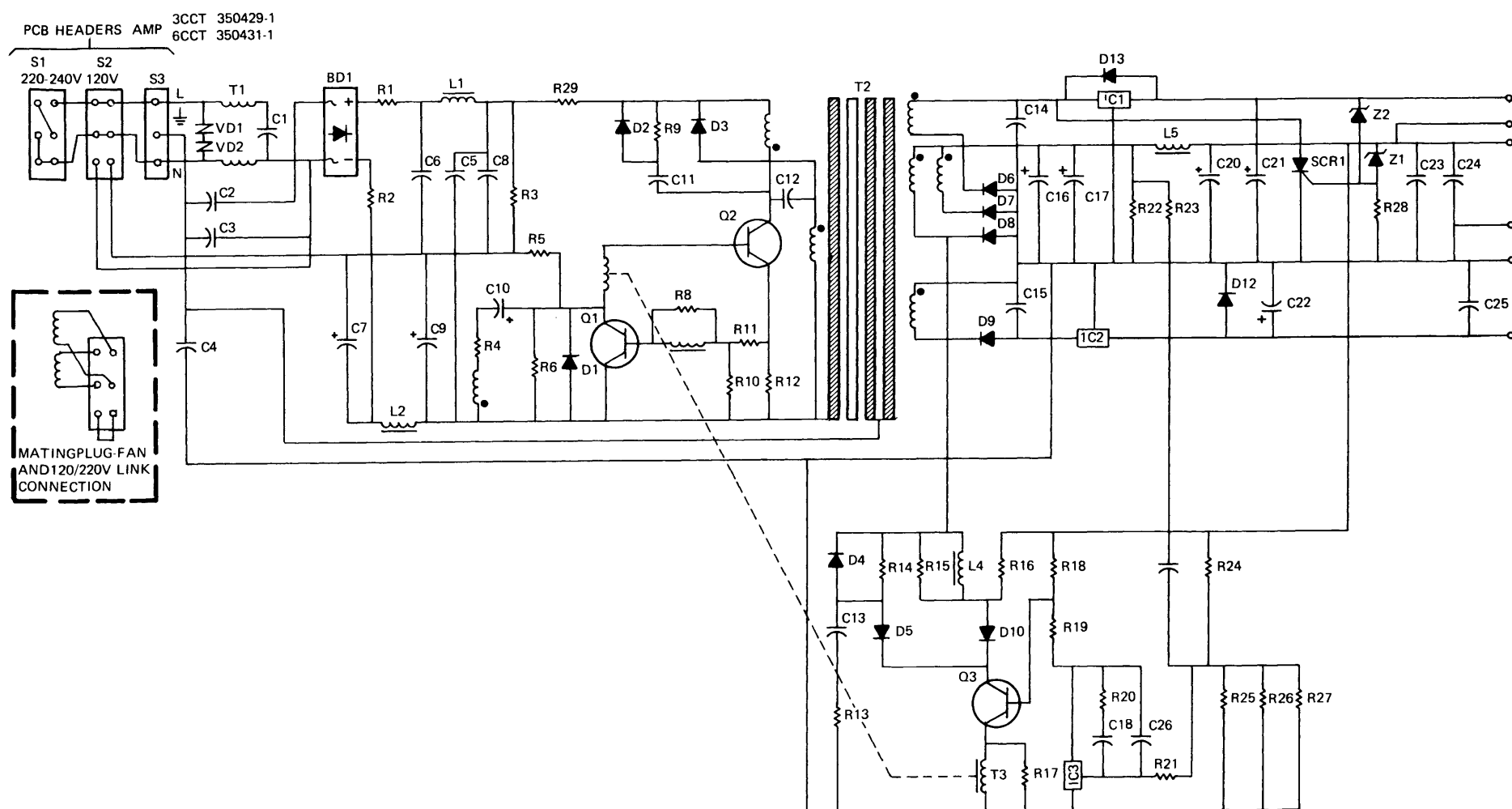


Figure 5-45 Power Supply Schematic

## CHAPTER 6

### TESTING AND TROUBLESHOOTING

#### 6.1 INTRODUCTION

The VK100 terminal contains a complete set of hardware self-test programs that check all of the major terminal functions. The self-test indicates that a problem exists and where the problem is.

Self-test mode has two tests power-up and diagnostic. Power-up tests automatically check the condition of the terminal every time terminal power is turned on. Diagnostic tests check the terminal outputs. Diagnostic tests require optional test connectors.

The self-test functions of the VK100 are invoked in one of three ways:

1. Automatic Tests (PUPTST)
2. Escape Sequences (CSITST)
3. SET-UP Mode (SETST)

6.1.1 Automatic Tests (PUPTST) -- The user has no control of the automatic confidence tests invoked when the terminal is powered on. The same tests may be invoked by doing a terminal reset (using SHIFT "-" key). These tests may also be called as a group through the various methods listed below.

6.1.2 Escape Sequences (CSITST) -- All tests are invoked by the escape sequence: ESC [3;Pn;Pn;...y] where Pn selects the test to be performed as follows:

Pn	Test Selected
1	All power-up tests
2.	External communication test
3	Hardcopy communication test
4.	Display pattern test
5.	Color bar test
6.	Repeat selected tests until failure

Any set of these tests may be selected in any order; however, they are always executed in numerical order.



The test select data is stored in a single byte (TSTSEL), with one bit for each test/option selected. While the CPU, ROM and RAM tests are running, these select bits are stored in register E, preserving this register.

6.1.3 SET-UP Mode (SETST) -- When the terminal is in SET-UP mode, setting the ST mode to any number has exactly the same effect as specifying the same parameter in the above escape sequence. The selected tests are executed when ST0 is set. Thus typing ST190 selects all the power-up tests and repeats these tests until failure. Every time the ST parameter set routine (STPPST) is called, it accumulates the test select data (TSTSEL).

6.1.4 Error Reporting -- Errors occurring during any test are reported in one of two ways:

1. Fatal errors
2. Non-fatal errors

6.1.4.1 Fatal Errors (TSTERROR) -- A fatal error (which causes the terminal to be useless) displays an error code in the indicators with the LOCAL indicator, alternating with a possible data item with the Line indicator, each for about 1/2 second. Table 6-1 shows the possible error codes.

Table 6-1 Possible Error Codes

Error Codes				Data	
Basic	Hard Copy	L1	L2		
0	0	0	0	CPU Register Error	Data=1111
0	0	0	1	ROM Error	Data=Bits 14,13,12 of ROM Address in Error
0	0	1	0	RAM Error	Data=Bit Number of RAM Error
0	0	1	1	Video Bit Map Error	Data=Bit Number of Screen RAM Error
0	1	0	0	Vector Generator Error	Data=1111
0	1	0	1	CRT Controller Register Error	Data=1111

**6.1.4.2 Non-Fatal Errors** -- Errors which allow some portion of the terminal to be useful display an error code in the center of the screen. The following are the possible error codes.

1. KB ERR -- Keyboard error
2. IC ERR -- Internal communication test error
3. EC ERR -- External communication test error
4. HC ERR -- Hardcopy test error

The two-byte mnemonic for the error is stored (TSTERM) and upon completion of terminal initialization is displayed in the center of the screen. The terminal always comes up in the local mode if any non-fatal errors are detected (only LOCAL indicator is lit).

## **6.2 POWER-UP SELF-TEST**

Power-up self-tests check the following terminal circuits.

Microprocessor  
Visual and audible indicators  
Read only memory (ROM)  
Random access memory (RAM)  
CRT controller  
CRT timing  
Vector timing  
Video bit map  
Vector generator  
Keyboard  
Communications (internal)

The power-up self-test can be started in four different ways.

1. Turn the terminal power switch to the on position.
2. Reset the terminal by pressing the shift and auxiliary keypad PF4 keys together in SET-UP mode.
3. Select the set-up self-test feature (ST1).
4. Receive a command from the host computer.

The power-up self-test takes about 15 seconds. While the test is running, the monitor displays various patterns that do not make sense. This is normal. Once the test is complete the cursor appears in the upper left corner of the monitor and only the ON-LINE indicator is turned on. If the self-test finds an error, it shows on either the keyboard or the monitor.

### 6.2.1 8085 CPU Test (CPUTST)

The microprocessor test checks the following registers: A, B, C, D, E, H, L, and SP by writing two patterns in the registers. The two patterns are:

1. 0 1 0 1 0 1 0 1
2. 1 0 1 0 1 0 1 0

The test is as follows:

PATTERN > A > B > C > D > E > H > L > SP

The pattern is loaded in the accumulator (A register) which is shifted to the B register ... shifted to the SP.

Firmware clears H L and then does a double add with the SP. The H L registers end up with the following.

H	L
0 1 0 1 0 1 0 1	0 1 0 1 0 1 0 1

The firmware compares the contents of the H and L register with the contents of the A register. If either test finds a difference, an error code is generated.

The error code = 0000

The data code = 1111

After the first pattern is checked, the second pattern is loaded and tested in the same manner.

### 6.2.2 Visual and Audible Indicators

The firmware when testing the indicators and bleeper circuits loads the accumulator with a value (0101010). This turns on the ON-LINE, NO SCROLL, HARDCOPY and L2 indicators and the bleeper for approximately 1/4 second (Figure 5-4).

### 6.2.3 ROM Test (ROM TST)

The ROM test verifies the addressability, order and data of all the ROMs present in the VK100. Only the CPU (8085A) and the ROMs are used in this test. There are four ROMs that are tested. If there is an error, the indicators blink.

	Basic	Hard copy	L1	L2	
with code equal to 0	0	0	0	1	= ROM failure
with data equal to					= address of ROM in error

To start the ROM test the following steps.

1. Each ROM has a check byte stored somewhere in each ROM and is a function of the ROM address.
2. Set initial value to high byte of ROM address + 1.
3. Rotate current check value left one bit.
4. Exclusive-OR current value with this ROM byte.
5. If value is zero, ROM is correct. Any other value indicates an error.

#### 6.2.4 Program RAM Test (RAM TST)

The program RAM checks to see if every bit can be written with ones and zeros and that every address is correct. This test uses only the 8085 CPU and the RAMs. The following patterns are written into the RAMs.

```
11111111
01010101
10101010
00000000
```

The ROM firmware writes the all ones pattern into the RAM memory. To start the RAM test perform the following steps for each RAM byte.

1. Read the first byte and compare with the old pattern (all ones). If the pattern is different, an error occurs.
2. If no error is found, write new pattern into the first byte location and continue this sequence until done.
3. If the error indicators blink with code = 0010, the data = the bit number of RAM bits in error.

#### 6.2.5 Video Bit Map RAM Test (VBM TST)

This test checks the entire video bit map for read/write of 0 and 1. A simple vector pattern is written throughout the entire memory (including the attribute memory) and then read back. The test uses CPU, ROM, Program RAM and the vector generator. To start the video bit map RAM test perform the following algorithm:

1. Set pattern = 01010101<sub>(2)</sub>, blink = off, color = green blue.
2. Set vertical position to zero.

3. Do 256 times:
  - a. Set horizontal position to zero.
  - b. Write 128 dot vector horizontal to the right. Repeat six times.
  - c. Increment vertical position by 2.
4. For pattern = 10101010(<sub>2</sub>), blink = on, color = red; pattern = 00000000(<sub>2</sub>), blink = off, color = dark; perform the following.
  - a. Set vertical position to zero.
  - b. Do 256 times:
    1. Set horizontal position to zero.
    2. Do 64 times:
      - a. Do 3 times  
Read 4 horizontal at current position  
  
Advance horizontal position by 4.  
  
Compare 4 bits just read with last pattern written. If pattern is different, an error is indicated.
    3. Read 4 attribute bits (blink, green, red, blue) at current position.
    4. Compare 4 bits just read with last pattern. If pattern is different an error is indicated.
    5. Decrement horizontal position by 12.
    6. Write a 12 dot vector to the right.
  - c. Increment vertical position by 2.

If error indicators blink with code = 0011, then the data = the bit number of data in error (bits 0--11 are bit map bits, 13--16 are attribute bits).

#### 6.2.6 Vector Generator Test (VGNTST)

The vector generator test writes a series of vectors from a single point and compares a small portion of the resultant bit map with an expected result. This test uses the 8085, ROM, Program RAM, and video bit map RAM.

To start the vector generator test perform the following steps:

1. Clear video bit map
2. Write the following sequence of vectors (Figure 6-1) starting at (-1,0)
3. Read and compare the 8 by 8 dot sample from (0,0),(7,0) to (0,7),(7,7) with the following pattern:

```
(0,0) 00100000 (7,0)
      00100000
      00100001
      10100000
      00100000
      00100000
      00100000
      00100000
(0,7) 00010000 (7,7)
```

If pattern is not identical an error occurs.

4. If an error occurs the indicators will blink the following patterns.

```
Code=0101
Data=1111
```

Vector Generator Test (to write sequence of vector)																																							
Sequence of Vector Test (8)																																							
DU								DVM								DIR								PMUL				PAT				WOPS							
7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	3	2	1	0	7	6	5	4	3	2	1	0				
0	0	0	0	1	0	0	0	1	1	1	1	1	0	1	0	0	0	0	1	1	1	1	1	1	1	1	1	1	0	0	1	1	1	1	0	0	0		
0	0	0	0	1	0	0	1	1	1	1	1	0	1	1	0	0	0	0	1	1	0	1	1	1	1	0	1	0	1	0	1	0	0	0	0	0	1		
0	0	0	0	0	1	1	1	1	1	1	1	1	0	0	0	0	0	0	1	0	1	0	1	1	0	1	1	1	1	0	0	0	0	0	0	0			
0	0	0	0	0	1	0	1	1	1	1	1	0	1	0	0	0	0	0	1	0	0	0	0	1	1	0	0	1	1	0	0	0	0	0	0	1			
0	0	0	0	1	0	0	1	1	1	1	1	1	0	1	0	0	0	0	1	1	1	0	1	0	1	1	1	1	1	0	0	0	0	0	0	1			
0	0	0	0	0	1	0	0	1	1	1	1	1	0	1	0	0	0	0	1	1	0	0	1	0	1	0	1	1	0	0	0	0	0	0	0	1			
0	0	0	0	0	0	0	1	1	1	1	1	1	1	0	0	0	0	0	1	0	1	1	1	0	0	1	1	0	0	0	0	0	0	0	0	1			
0	0	0	0	1	1	0	0	1	1	1	1	1	1	1	0	0	0	0	1	0	0	1	1	0	0	0	0	0	0	0	0	0	0	0	0	1			

Figure 6-1 Vector Generator Sequence

### 6.2.7 CRT Controller Test (CRTST)

This test makes sure that the CRT controller registers can be read and written. Only one register of the CRT controller, the cursor register, is read/write. This test uses the CPU and ROM. Two patterns are used in this test.

01010101(<sub>2</sub>), 10101010(<sub>2</sub>)

1. Write the cursor low register (register 15) and compare it with the pattern.
2. Read the cursor low register and compare with pattern. If the pattern is different or an error occurs.
3. If an error occurs the indicators will blink the following patterns.

Code=0101

Data=1111

### 6.2.8 CRT Timing

Firmware routine checks for the V SYNC signal from the CRT controller. If V SYNC is not received within 20 ms, a CRT timing error is generated.

Code 01001000 (Local and Hardcopy)

Data 10011111 (On-Line, Basic, Hardcopy, L1, L2)

## 6.3 DIAGNOSTIC TESTS

These tests are not normally executed by the terminal. They can be initiated via setup or escape sequences. They exist for diagnostic purposes and for error isolation in repair operations. The VK100 terminal contains five diagnostic tests.

External communications test  
Hardcopy communications test  
Display test  
Color bar test  
Screen alignment pattern

The following paragraphs describe Each test.

### 6.3.1 External Communications Test

This test is an extension of the internal communications test in the power-up test. In the external communications test the transmit and receive lines are connected through a special loopback connector. A predefined set of characters are then transmitted. The terminal receives the characters and compares them to the characters transmitted. If the characters do not match an error is indicated. This test is performed for all communications speeds.

This test requires an optional loopback connector.

To start the external communications test perform the following steps:

1. Turn terminal power off.
2. Disconnect the communications cable from the rear of the terminal.
3. Install the optional loopback connector on the terminal communications output connector. Loopback connector part number 12-13336-00 is for EIA communications; part number 70-13503-00 is for 20 mA current loop communications.
4. Turn terminal power on.
5. Place the terminal in SET-UP mode.
6. Verify CI SET-UP feature (CI0=EIA; CI1=20 mA).
7. Set the self-test SET-UP feature for selection 2 (ST2).
8. Exit SET-UP mode by pressing the SET-UP key. This starts the test.

If no error is found by the test the cursor is displayed on the monitor. Paragraph 6.4 lists the displayed error codes and their meanings.

#### 6.3.2 Hardcopy Communications Test

This test is similar to the external communications test described above. In the hardcopy communications test, the transmit and receive hardcopy output lines are connected through an EIA loopback connector. A predefined set of characters is then transmitted. The terminal receives the characters and compares them to the characters transmitted. If the characters do not match an error is indicated.

This test requires an optional loopback connector.

To start the hardcopy communications test perform the following steps:

1. Turn terminal power off.
2. Disconnect the hardcopy printer cable from the rear of the terminal.
3. Install the optional loopback connector on the terminal hardcopy connector. The loopback connector is part number 12-13336-00.
4. Turn terminal power on.
5. Place the terminal in SET-UP mode.



6. Set the self-test set-up feature for selection 3 (ST3).
7. Exit SET-UP mode by pressing the SET-UP key. This starts the test.

If no error is found by the test the cursor is displayed on the monitor. Paragraph 6.4 lists the displayed error codes and their meanings.

#### 6.3.3 Display Test

This test displays a full screen of blue, red, green, white, black, and a crosshatch pattern. Each display screen lasts for approximately one-half second and the crosshatch pattern remains on the screen at the end of the test. On a black and white monitor the test displays full screens of increasing intensity.

To start the display test perform the following steps.

1. Place the terminal in SET-UP mode.
2. Set the self-test set-up feature for selection 4 (ST4).
3. Exit SET-UP mode by pressing the SET-UP key. This starts the test.

An error in this test occurs if one of the display screens is not shown. If this happens the monitor attached to the VK100 terminal may have failed. Proceed with the color bar test.

To clear the monitor screen reset the terminal by pressing the SHIFT and PF4/RESET keys together.

#### 6.3.4 Color Bar Test

This test displays a color bar/grey scale pattern on the monitor. The color bar/grey scale pattern consists of eight equally spaced vertical bars. On a color monitor the bars are in the following order from left to right:

Black	Green
Blue	Cyan
Red	Yellow
Magenta	White

On a monochrome (black and white) monitor the bars show as different shades of grey. The bars start as black on the left and increase in intensity to a white bar on the right of the display.

To start the color bar test perform the following steps:

1. Place the terminal in SET-UP mode.
2. Set the self-test set-up feature for selection 5 (ST5).
3. Exit SET-UP mode by pressing the SET-UP key. This starts the test.

An error in this test occurs if the color bar/grey scale pattern is not displayed or a portion of the pattern is missing. Either error condition indicates that the attached monitor has failed, the video cable is not connected properly, or the VK100 terminal has failed. If you suspect that the terminal has failed, connect it to a different monitor and perform both the display and color bar/grey scale tests. If the same symptoms are present the second time the terminal has probably failed.

To clear the monitor screen reset the terminal by pressing the SHIFT and PF4/RESET keys together.

#### 6.3.5 Screen Alignment Pattern

This test fills the screen with a crosshatch pattern. The crosshatch pattern adjusts the display monitor connected to the VK100 terminal.

To place the screen alignment pattern on the monitor screen perform the following steps:

1. Place the terminal in SET-UP mode.
2. Set the self-test set-up feature for selection 4 (ST4).
3. Exit SET-UP mode by pressing the SET-UP key. This starts the display test. At the end of the display test the screen alignment pattern remains on the screen.

To clear the monitor screen reset the terminal by pressing the SHIFT and PF4/RESET keys together.

#### 6.4 ERROR CODES

There are two categories of errors: fatal and nonfatal. Fatal errors cause the terminal to immediately stop all operations. The monitor screen displays random patterns that do not make sense. In addition to the random pattern an error code is displayed on the keyboard indicators. Table 6-2 shows the possible error codes.

The fatal error code displayed on the keyboard light indicators contains two different messages: an error code and a data code. The error code lights the LOCAL indicator and displays a code in the BASIC, HARDCOPY, L1, and L2 indicators. The data code lights the ON-LINE indicator and is displayed in the BASIC, HARDCOPY, L1, and L2 indicators. The VK100 terminal alternates between each message about every one-quarter second.

Table 6-2 Possible Fatal Error Codes

Error Code Displayed							
On Line	Local	No Scroll	Basic	Hard Copy	L 1	L 2	Meaning
X	Ø	Ø	Ø	Ø	Ø	Ø	Microprocessor error
Ø	X	Ø	X	X	X	X	Data code
X	Ø	Ø	Ø	Ø	Ø	X	ROM error
Ø	X	Ø	Ø	?	?	?	Data code
X	Ø	Ø	Ø	Ø	X	Ø	RAM error
Ø	X	Ø	Ø	?	?	?	Data code
X	Ø	Ø	Ø	Ø	X	X	CRT controller error
Ø	X	Ø	X	X	X	X	Data code
X	Ø	Ø	Ø	X	Ø	Ø	CRT controller timeout
Ø	X	Ø	X	X	X	X	Data code
X	Ø	Ø	Ø	X	Ø	X	Vector timeout error
Ø	X	Ø	X	X	X	X	Data code

X = ON

Ø = OFF

? = variable condition

Nonfatal errors do not halt the terminal processor. Instead, the terminal displays an error code on the keyboard indicators and in the center of the monitor screen. The terminal may still be used if a nonfatal error occurs. In this case, the terminal remains in on-line or local mode with the appropriate indicator lit. The error is indicated by any of the BASIC, HARDCOPY, L1 or L2 indicators blinking. An example of this type of occurrence is a keyboard error. If the self-test detects a keyboard error, the L2 indicator blinks, and the message KB ERR is shown on the monitor screen.

Table 6-3 lists all of the nonfatal error codes the terminal displays and what they mean to the terminal.

Table 6-3 Possible Nonfatal Error Codes

Indicator Error Code						
No Scroll	Basic	Hard Copy	L 1	L 2	Screen Code	Meaning
0	0	B	B	0	ID Err	Vector generator and internal communications data loopback error
0	0	B	B	0	IT Err	Vector generator and internal communications timeout error
0	0	B	B	B	KC Err	Vector generator, keyboard and communications control signal error
0	0	B	B	B	KD Err	Vector generator, keyboard and internal communications data loopback error
0	0	B	B	B	KT Err	Vector generator, keyboard and internal communications timeout error

0 = Indicator FF

B = Indicator blinking

Table 6-3 Possible Nonfatal Error Codes (Cont)

Indicator Error Code						
No Scroll	Basic	Hard Copy	L 1	L 2	Screen Code	Meaning
0	B	0	0	0	None	Video RAM error
0	B	0	0	B	KB Err	Video RAM and keyboard error
0	B	0	B	0	IC Err	Video RAM and internal communications control signal error
0	B	0	B	0	ID Err	Video RAM and internal communications data loopback error
0	B	0	B	0	IT Err	Video RAM and internal communications timeout error
0	B	0	B	B	KC Err	Video RAM, keyboard and internal communications control signal error
0	B	0	B	B	KD Err	Video RAM, keyboard and internal communications data loopback error
0	B	0	B	B	KT Err	Video RAM, keyboard and internal communications timeout error
0	B	B	0	0	None	Video RAM and vector generator error
0	B	B	0	B	KB Err	Video RAM, vector generator and keyboard error

Table 6-3 Possible Nonfatal Error Codes (Cont)

Indicator Error Code						
No Scroll	Basic	Hard Copy	L 1	L 2	Screen Code	Meaning
Ø	B	B	B	Ø	IC Err	Video RAM, vector generator and internal communications control signal error
Ø	B	B	B	Ø	ID Err	Video RAM, vector generator and internal communications data loopback error
Ø	B	B	B	Ø	IT Err	Video RAM, vector generator and internal communications timeout error
Ø	B	B	B	B	KC Err	Video RAM, vector generator, keyboard and communications control signal error
Ø	B	B	B	B	KD Err	Video RAM, vector generator, keyboard and internal communications data loopback error
Ø	B	B	B	B	KT Err	Video RAM, vector generator, keyboard and internal communications timeout error

Ø = Indicator FF

B = Indicator blinking

## 6.5 TROUBLESHOOTING

The troubleshooting section consists of Tables 6-4 through 6-6. These tables show the indicators error code, screen code and the module to replace.

Table 6-7 shows the on-site recommended spares and their part numbers.

Table 6-8 lists the DIGITAL Servicenter Recommended Spares and their part numbers.

Table 6-4 Fatal Error Codes

Indicator Error Code

On Line	Local	No Scroll	Basic	Hard Copy	L 1	L 2	Meaning	Module to Replace
X	Ø	Ø	Ø	Ø	Ø	Ø	Microprocessor error	Logic
Ø	X	Ø	X	X	X	X	Data code	
X	Ø	Ø	Ø	Ø	Ø	X	ROM error	Logic
Ø	X	Ø	Ø	?	?	?	Data code	
X	Ø	Ø	Ø	Ø	X	Ø	RAM Error	Logic
Ø	X	Ø	Ø	?	?	?	Data code	
X	Ø	Ø	Ø	Ø	X	X	CRT controller error	Logic
Ø	X	Ø	X	X	X	X	Data code	
X	Ø	Ø	Ø	X	Ø	Ø	CRT controller timeout	Logic
Ø	X	Ø	X	X	X	X	Data code	
X	Ø	Ø	Ø	X	Ø	X	Vector timeout error	Logic
Ø	X	Ø	X	X	X	X	Data code	

X = ON

Ø = OFF

? = Variable condition

Table 6-5 Nonfatal Error Codes

Indicator Error Code						
No Scroll	Basic	Hard Copy	L 1	L 2	Screen Code	Module to Replace
Ø	Ø	Ø	Ø	B	KB Err	Keyboard
Ø	Ø	Ø	B	Ø	IC Err	Logic
Ø	Ø	Ø	B	Ø	ID Err	Logic
Ø	Ø	Ø	B	Ø	IT Err	Logic
Ø	Ø	Ø	B	Ø	EC Err	Logic
Ø	Ø	Ø	B	Ø	ED Err	Logic
Ø	Ø	Ø	B	Ø	ET Err	Logic
Ø	Ø	Ø	B	Ø	EM Err	Logic
Ø	Ø	Ø	B	Ø	HC Err	Logic
Ø	Ø	Ø	B	Ø	HD Err	Logic
Ø	Ø	Ø	B	Ø	HT Err	Logic
Ø	Ø	Ø	B	B	KC Err	Keyboard and Logic
Ø	Ø	Ø	B	B	KD Err	Keyboard and Logic
Ø	Ø	Ø	B	B	KT Err	Keyboard and Logic
Ø	Ø	B	Ø	Ø	None	Logic
Ø	Ø	B	Ø	B	KB Err	Keyboard and Logic
Ø	Ø	B	B	Ø	IC Err	Logic
Ø	Ø	B	B	Ø	ID Err	Logic
Ø	Ø	B	B	Ø	IT Err	Logic
Ø	Ø	B	B	B	KC Err	Keyboard and Logic
Ø	Ø	B	B	B	KD Err	Keyboard and Logic
Ø	Ø	B	B	B	KT Err	Keyboard and Logic
Ø	B	Ø	Ø	Ø	None	Logic
Ø	B	Ø	Ø	B	KB Err	Keyboard and Logic
Ø	B	Ø	B	Ø	IC Err	Logic
Ø	B	Ø	B	Ø	ID Err	Logic
Ø	B	Ø	B	Ø	IT Err	Logic
Ø	B	Ø	B	B	KC Err	Keyboard and Logic
Ø	B	Ø	B	B	KD Err	Keyboard and Logic
Ø	B	Ø	B	B	KT Err	Keyboard and Logic
Ø	B	B	Ø	Ø	None	Logic
Ø	B	B	Ø	B	KB Err	Keyboard and Logic
Ø	B	B	B	Ø	IC Err	Logic
Ø	B	B	B	Ø	ID Err	Logic
Ø	B	B	B	Ø	IT Err	Logic
Ø	B	B	B	B	KC Err	Keyboard and Logic
Ø	B	B	B	B	KD Err	Keyboard and Logic
Ø	B	B	B	B	KT Err	Keyboard and Logic

Ø = Indicator off

B = Indicator blinking



Table 6-6 VK100 Troubleshooting

Type of Problem	Symptom	Check	Corrective Action
Power	No indicators, no video on monitor, no SET-UP key response, no fan	Line fuse	Replace if open.
		Power cord	Reconnect at both ends.
			Replace power cord if open.
		Power supply connections J2 and J3	Reconnect power supply.
			Replace power supply.
	No indicators, no video on monitor, no SET-UP key response. Fan is on.	Check power supply voltages: +12, +5, -12, (Fig. 6-1)	If voltages are wrong replace power supply. If voltages are ok:
			Replace keyboard.
			Replace logic board.
	No indicators, no SET-UP key response. Fan is on and video present on monitor.		Replace keyboard. Replace logic module.
	No fan, SET-UP key responds, Indicators are on and video is present on monitor.	Fan is obstructed.	Clear obstruction.
		Fan cable.	Replace power supply.
	Error code displayed in indicator (self-test error).		See Tables 6-4 and 6-5.

Table 6-6 VK100 Troubleshooting (Cont)

Type of Problem	Symptom	Check	Corrective Action
Video with a color monitor.	No cursor displayed.	HP, HM, or VM SET-UP features are set wrong.	Change SET-UP feature settings.
		Monitor brightness	Increase monitor brightness.
		Monitor power on	Turn monitor power on.
		Have customer check monitor fuse.	Have customer replace monitor fuse.
		Run color bar and screen alignment self-tests.	Replace logic board. Replace video cable.
	Wrong color displayed.	Have customer swap monitor with another monitor.	If problem is solved the monitor is bad. Monitor repair is the customer's responsibility.
		Check video connections.	Reconnect video cable. Replace video cable.
			Have customer adjust monitor.
	Incorrect data displayed or sync is lost.		Replace video cable.
			Replace logic module.

Table 6-6 VK100 Troubleshooting (Cont)

Type of Problem	Symptom	Check	Corrective Action
		Monitor is bad.	Monitor repair is the customer's responsibility.
	No color is displayed. The monitor display is always white.		Replace logic module.
Video with black and white (monochrome) monitor.	No cursor displayed.	HP, HM or VM SET-UP features are set wrong.	Change SET-UP feature settings.
		Monitor brightness.	Increase monitor brightness.
		Monitor power on.	Turn monitor power on.
		Have customer check monitor fuse.	Have customer replace monitor fuse.
		Run color bar and screen alignment self-test.	Replace video cable. Replace logic module.
		Have customer swap monitor with another.	If problem is solved, the monitor is bad.  Monitor repair is the customer's responsibility.
			Replace video cable.  Replace logic module.
	Incorrect data is displayed or sync is lost.		

Table 6-6 VK100 Troubleshooting (Cont)

Type of Problem	Symptom	Check	Corrective Action
		Monitor is bad.	Monitor repair is the customer's responsibility.
Hardcopy	No hardcopy output (1 or more terminals)	Make sure all VK100 and LA34VA terminals are turned on.	
		Make sure correct I/O cables are used and connected.	
		Perform the hardcopy self-test on all VK100 terminals in the string.	Replace logic module on failing unit. Replace hardcopy cable.
	Wrong data is printed.	Perform the LA34VA self-test.	The problem is in the LA34VA.
		Check the SET-UP parameters at VK100 and LA34VA terminals.	Change the SET-UP parameters.
		Perform the hardcopy self-test.	Replace logic module.  The problem is in the LA34VA.

Table 6-6 VK100 Troubleshooting (Cont)

Type of Problem	Symptom	Check	Corrective Action
Communication	VK100 does not communicate with the host system.	Check the SET-UP parameter settings in the terminal and make sure that they agree with the host system.	Change the SET-UP parameters.
		Perform the external communications self-tests.	Replace logic module.
			Replace communications cable.
			The problem is in either the modem (if one is used) or the system.

Table 6-7 On-Site Recommended Spares

Qty	Description	Part Number
1	Logic module	54-14230-00
1	Power supply assembly	70-17387-00
1	Keyboard assembly	70-17397-FS
1	Y type cable	17-00197-00
1	Video cable, coaxial	17-00223-00
1	Loopback connector (EIA)	12-15336-00
1	Loopback connector (20 mA)	70-15503-00
1	Power cord (115 V)	17-00083-09
1	Power cord (230 V)	17-00083-10
1	Power cable (dc)	70-17389-00
10	Plunger, 5/16 dia.	90-09964-00
10	Grommet, snap-in, 5/16 dia.	90-09966-01
4	Screw, sems, slotted head, 4-40 X 3/8	90-09702-00
1	Fuse, 2 A, 250 V box of 5	90-07215-00
4	Screw, sems, slotted head, 10-32 X 3/8	90-06444-00
1	Keycap removal tool	74-16355

Table 6-8 DIGITAL Servicenter Recommended Spares

Qty	Description	Part Number
1	Logic module	54-14230-00
1	Power supply assembly	70-17387-00
1	Power supply module (PCB only)	12-16987-00
1	Power cable (dc)	70-17389-00
1	Receptacle assembly (ac)	70-17411-00
1	Power cord (115 V)	17-00083-09
1	Power cord (230 V)	17-00083-10
1	Power switch, 2-pole, 16 A	12-17051-00
1	Fan assembly	12-16488-00
1	Fuseholder	12-16931-00
1	Keyboard assembly	70-17397-FS
1	Keyboard distribution cable	70-17390-00
10	Indicator, ANCD @ 10 mA	11-10864-00
10	Keyboard plunger	12-11862-00
10	Keyboard spring	12-11863-00
20	Keyboard contact, quadfurcated	12-11865-00
20	Keyboard contact	12-11866-00
1	Switch, array cap. solid adapter	12-14332-00
1	Fuse, reg. blow, 2 A 250 V (box of 5)	90-07215-00
2	Screw, Sems, slotted head, 10-32 X 3/8	90-06444-00
10	Support, C Bd. standoffs	90-09313-00
10	Screw, Sems, slotted head, 4-40 X 3/8	90-06444-00
10	Plunger, 5/16 dia.	90-09964-00
10	Grommet, snap-in, 5/16 dia.	90-09966-01
10	Screw, captive, hex slotted	12-16682-00
10	Bumper, round	90-09538-00
10	Bumper, square	90-09624-00
10	Fastener, pinch-on	90-09601-00
10	Screw, hex head, slotted, 6-32 X 5/16	90-09967-00
2	Case, bottom	70-17394-00
2	Case, top	70-17395-00
1	Y type cable	17-00197-00
1	Video cable, coax	17-00223-00
1	Loopback connector (EIA)	12-15336-00
1	Loopback connector (20 mA)	70-15503-00
2	Foam insert, top	99-06742-00
2	Foam insert, bottom	99-06742-01
2	Carton, die-cut	99-06793-00
2	Polybag	99-05128-17
2	Tape	99-06486-00

## 6.6 ADJUSTMENTS

The VK100 is not adjustable. All power supply and video outputs are constant. The appropriate module must be replaced if an output is low or not present.

The video monitor is adjustable. The monitor is provided by the customer and is the responsibility of the customer. Adjustments to the monitor must be made by the customer or a service technician who has been qualified by the monitor manufacturer. DIGITAL does not supply any monitor for use with the VK100 terminal.

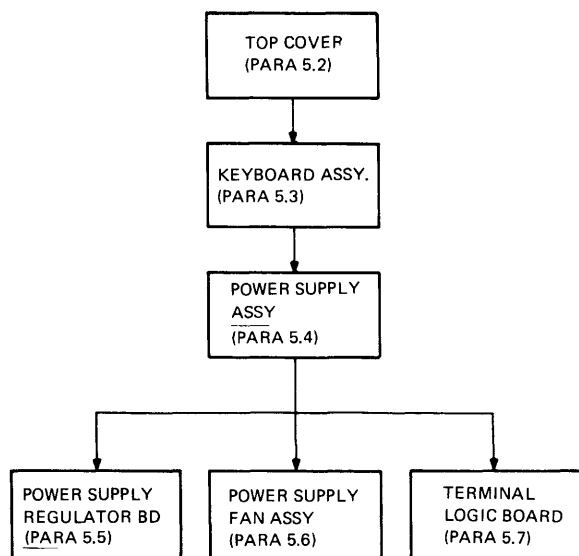
The best way to determine if the monitor requires adjustment is to swap the suspected bad monitor with one that is working correctly. If the problem disappears the monitor is bad. If the problem remains the VK100 terminal contains a problem. Use the procedures in Chapters 2 and 3 to test the terminal and locate the problem.

## 6.7 REMOVAL AND REPLACEMENT

To remove or replace a subassembly, the only tools necessary are:

Common blade screwdriver or  
1/4 inch nutdriver

Figure 6-2 lists all removal procedures in this chapter and the sequence in which they are performed. As an example, Figure 6-2 shows that to remove the terminal logic board the top cover, keyboard assembly, and power supply assembly removal procedures must be performed first.



MA-6709

Figure 6-2 Module Removal Sequence

### 6.7.1 Top Cover Removal

To remove the top cover perform the following steps.

1. Remove power from the terminal by disconnecting the ac plug.
2. Turn the terminal over so that the bottom of the terminal is accessible.
3. Loosen the four (4) captive screws at the corners of the terminal (Figure 6-3). The screws may be loosened with either a nutdriver or a blade-type screwdriver.
4. Grasp the top and bottom halves of the terminal and turn the terminal over so that the keyboard is face up.
5. Grasp the top cover by its sides and lift the cover up and off the terminal.
6. Install the top cover by performing steps 1 through 5 in reverse.

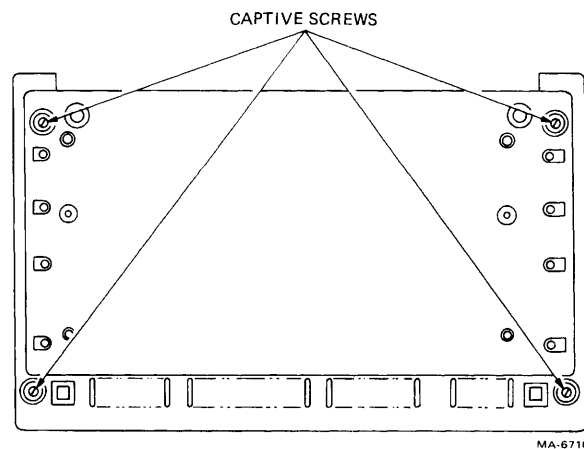


Figure 6-3 VK100 Terminal (Bottom View)



### 6.7.2 Keyboard Assembly Removal

To remove the keyboard assembly perform the following steps.

1. Remove the terminal top cover (Paragraph 6.7.1).
2. Release the four (4) pop fasteners securing the keyboard assembly to the terminal (Figure 6-4). To release the pop fasteners pull up on the plungers.
3. Gently remove the keyboard assembly from the terminal and place it in front of the terminal.
4. Disconnect the keyboard ribbon cable from the logic board.

#### CAUTION

Do not disconnect the keyboard ribbon cable from the keyboard. Any attempts to do so will damage the connector and force replacement of the entire keyboard assembly.

5. Remove the keyboard assembly.
6. Install the keyboard assembly by performing steps 1 through 5 in reverse.

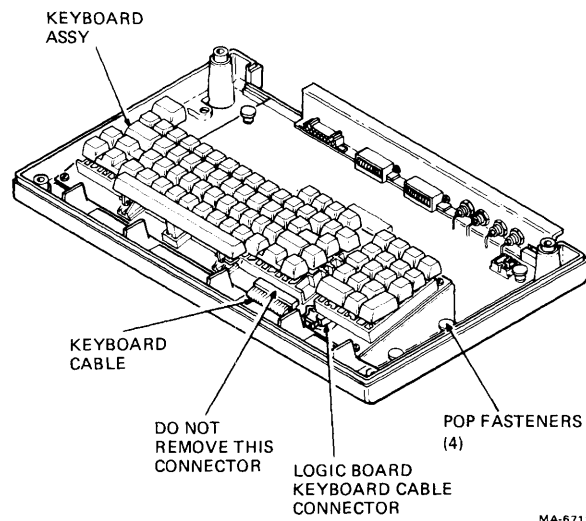


Figure 6-4 Keyboard Assembly Removal

### 6.7.3 Power Supply Assembly Removal

To remove the power supply assembly perform the following steps.

1. Remove the terminal top cover (Paragraph 6.7.1).
2. Remove the keyboard assembly (Paragraph 6.7.2).
3. From the rear of the terminal, remove the grounding screw securing the connector bracket to the power supply chassis (Figure 6-5). The screw may be removed with either a nutdriver or a blade-type screwdriver.
4. Release the four (4) pop fasteners securing the power supply assembly to the terminal (Figure 6-6). To release the pop fasteners pull up on the plungers.

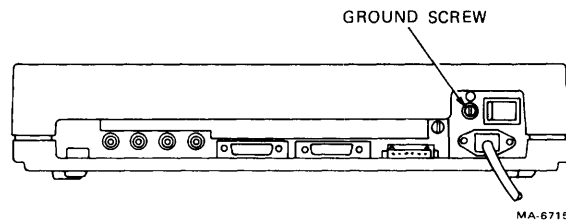


Figure 6-5 VK100 Terminal (Rear View)

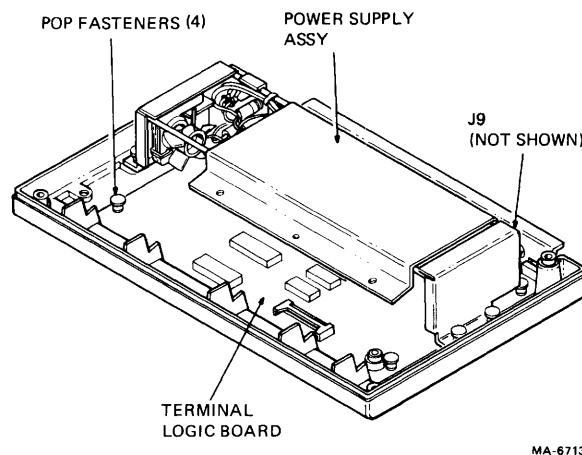


Figure 6-6 Power Supply Assembly Removal

5. Gently remove the power supply assembly from the terminal and place it next to the rear edge of the terminal.
6. Disconnect the 6-wire power output cable from J9 on the terminal logic board.
7. Remove the power supply assembly.

NOTE

P14 connects to J14 for 115 V operation,  
or P14 connects to J13 for 230 V  
operation.

8. Install the power supply assembly by performing steps 1 through 6 in reverse.

#### 6.7.4 Power Supply Regulator Board Removal

To remove the power supply regulator perform the following steps.

1. Remove the terminal top cover (Paragraph 6.7.1).
2. Remove the keyboard assembly (Paragraph 6.7.2).
3. Remove the power supply assembly (Paragraph 6.7.3).
4. Disconnect the 3-wire connector from J11 on the regulator board.
5. Disconnect the 6-wire connector from J14 (115 V) or J13 (230 V) on the regulator board.
6. Remove the power output cable from J10 on the regulator board.
7. Remove the four (4) screws securing the regulator board to the power supply chassis. Remove the regulator board. The screws may be removed with either a nutdriver or a blade-type screwdriver.
8. Install the power supply assembly by performing steps 1 through 6 in reverse.

#### 6.7.5 Power Supply Fan Assembly Removal

To remove the power supply assembly perform the following steps.

1. Remove the terminal top cover (Paragraph 6.7.1).
2. Remove the keyboard assembly (Paragraph 6.7.2).
3. Remove the power supply assembly (Paragraph 6.7.3).
4. Disconnect the 6-wire connector from J14 (115 V) or J13 (230 V) on the power supply regulator board.
5. Remove the two (2) screws securing the fan assembly to the power supply chassis (Figure 6-7). The screws may be removed with either a nutdriver or a blade-type screwdriver.
6. Install the power supply assembly by performing steps 1 through 4 in reverse.

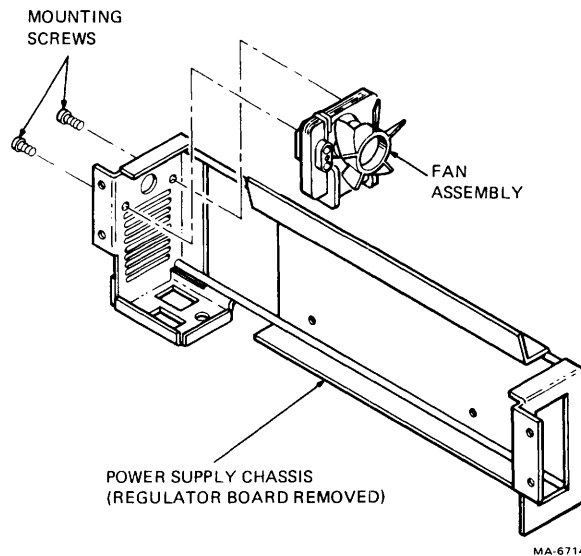


Figure 6-7 Power Supply Fan Assembly Removal

#### 6.7.6 Terminal Logic Board Removal

Perform the following steps to remove the terminal logic board.

1. Remove the terminal top cover (Paragraph 6.7.1).
2. Remove the keyboard assembly (Paragraph 6.7.2).
3. Remove the power supply assembly (Paragraph 6.7.3).
4. Release the four (4) pop fasteners securing the logic board to the bottom cover (Figure 6-8). To release the pop fasteners pull up on the plungers.
5. Remove the terminal logic board.
6. Install the terminal logic board by performing steps 1 through 5 in reverse.
7. Be sure to set the default SET-UP switches to the customer settings.

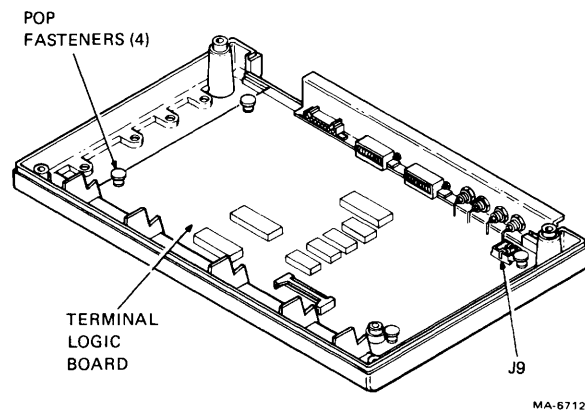


Figure 6-8 Terminal Logic Board Removal

APPENDIX A  
VK100 TERMINAL SPECIFICATIONS

**VK100 TERMINAL SPECIFICATIONS**

**Dimensions**

Height	9.88 cm (3.89 in)
Width	49.30 cm (19.40 in)
Depth	31.10 cm (12.25 in)

**Weight**

Shipping weight	5.7 kg (12.5 lbs)
-----------------	-------------------

**Environment**

Operating

Temperature	10` to 40` C (50` to 104` F)
Relative humidity	10% to 90%
Max wet bulb	28` (82` F)
Min dew point	2` C (36` F)
Altitude	2.4 km (8,000 ft)

Nonoperating

Temperature	-40` to 66` C (-40` to 151` F)
Relative humidity	5% to 95%
Altitude	9.1 km (30,000 ft)

**Power**

Line voltage	90--128 V RMS single phase, 2 wire with ground wire 180--256 V RMS single phase, 2 wire with ground wire (internally selectable)
--------------	--

Line frequency	46 Hz to 61 Hz
----------------	----------------

Current	1.3 Arms max at 115 Vrms 0.7 Arms max at 230 V
---------	---

## Power

Input power	120 VA apparent, 60 W max
Current limiting	2 A/250 V normal blow fuse
Power cord	2.0 m (6.5 ft), 3 prong

## Product Safety

UL: Listing per UL 478  
CSA: certification per CSA  
C22.2. No. 154  
IEC 435 and VDE 0804  
compliance

## Program Memory

13K bytes available to the user  
and down-line loadable:  
7.8K for BASIC programs  
2+K for ReGIS macrographs and  
keypad key definitions  
three soft character sets each  
95 X 10 X 8 bytes

## Display Outputs

### Text mode

24 lines X 84 characters max  
or 24 lines X 42 double-width  
characters

### Character

8 X 10 dot matrix with  
descenders

### Character set

95-character displayable ASCII  
subset (upper and lowercase,  
numeric and punctuation)

### Text cursor type

Blinking block character; can be  
disabled in SET-UP

## Graphics mode

768 pixels horizontal  
240 pixels vertical

### Graphic cursor type

Diamond shape with cross hair in  
the center; can be disabled in  
SET-UP

### Locator cursor type

Large cross hair

Graphic pattern memories	<p>Permanent UK/US ASCII character set: 128 characters, 8 X 10 dot matrix</p> <p>Three user programmable and down-line loadable soft alphabet character sets: 95 characters each, 8 X 10 dot matrix</p>
Visual attributes	<p>Four bits per segment of 12 horizontal pixels</p> <p>Eight levels of grey for black and white monitors</p> <p>Eight colors for color monitor: black, blue, red, magenta, green, cyan, yellow, and white</p> <p>Blink</p>
Video outputs	<p>Output to drive one black and white (composite video) and one color (RGB) monitor (with composite green video) simultaneously</p> <p>Adjustable horizontal and vertical margins to accommodate monitor overscan</p> <p>Adjustable horizontal centering</p> <p>50/60 Hz refresh, noninterlaced or interlaced</p>
Keyboard	
General	83-key unit
Key layout	65-key arrangement and sculpturing similar to standard typewriter keyboard, with an 18-key auxiliary keypad
Auxiliary keyboard	18-key numeric pad with period, comma, minus, ENTER, and four function keys
Visual indicators	Seven indicators: five indicators dedicated to ON-LINE, LOCAL, NO SCROLL, BASIC and HARD COPY; two indicators user-programmable



## Keyboard

### Audible signals

Keyclock: sound simulates typewriter  
Bell: sounds upon receipt of BEL code, or sounds nine characters from right margin (keyboard selectable)

## Communication

### Type

EIA RS-232-C/CCITT V 24 or 20 mA passive current loop (keyboard selectable)

### Speeds

Full-duplex: 110 (two stop bits), 300, 600, 1,200, 2,400, 4,800, 9,600 and 19,200 baud; transmit and receive speeds are independent of each other

### Code

ASCII

### Character format

Asynchronous serial

### Character size

Eight bits including parity bit

### Parity

Even, odd, or none (keyboard selectable)

### Synchronization

Keyboard selectable via automatic generation of XON/XOFF control codes

### Modes

Normal line, single character, local echo (keyboard selectable)

## Hardcopy Interface

Drive an LA34VA graphics printer with daisy-chaining capability

Auto hardcopy

## APPENDIX B CALCULATIONS

### CALCULATION #1

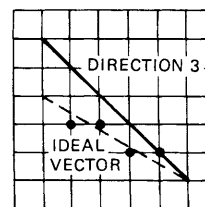
Error Register = 2  
 DVM Register = 374 (1's complement of 3)  
 Carry In = 1  
 Error Register = 377<sub>8</sub>  
                     No Carry   Decrement  
 Strobe                              Major and Minor Axis

Error Register = 377<sub>8</sub>  
 DU Register = 005<sub>8</sub>  
 Error Register = 004<sub>8</sub>  
                     Carry  
 Strobe

Direction -- Decrement X and Y  
 Do a Pixel Write  
 Decrement Down Counter  
     5 - 1 = 4  
 Downcounter = 4

### RULES AND DRAW VECTOR

1. Do not write in direction if  
    2 from an odd line or  
    6 from an even line.
2. Do not write if the direction is  
    5 or 7, the scan line is even  
    (Y0) and the last direction was 6.
3. Do not write if the direction is  
    1 or 3, the scan line is odd and  
    the last direction was 2.



MA 9756

## CALCULATION #2

Error Register =  $004_8$

DVM Register =  $374_8$

Carry In =  $1_8$

Error Register =  $001_8$

Carry

Decrement  
Major Axis

Strobe → Set Carry<sub>FF</sub>

Error Register =  $001_8$

DU Register =  $005_8$

$006_8$

Error Register =  $001_8$

(No Error CLK)

Strobe

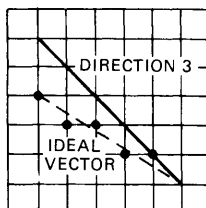
Direction -- Decrement X

Do a Pixel Write

Decrement Down Counter

$$4 - 1 = 3$$

**DRAW VECTOR**



MA 9757

### CALCULATION #3

Error Register = 1

DVM Register = 374

Carry In = 1

Error Register = 376

Strobe                      No Carry    Decrement  
   Major and Minor Axis

Error Register = 376

DU Register = 005

Error Register = 003

                                    Carry

Strobe

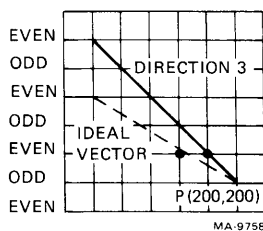
Direction -- Decrement X and Y.

Do a Pixel Write

Decrement Down Counter

$$3 - 1 = 2$$

### DRAW VECTOR



#### CALCULATION #4

Error Register = 003

DVM Register = 374

Carry In = 1

Error Register = 000

Carry      Decrement  
Major Axis

Strobe

Error Register = 000

DU Register = 005  
005

Error Register = 000

Strobe

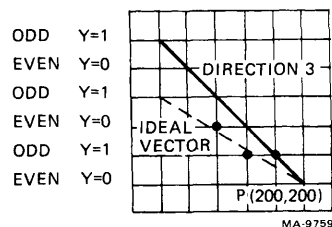
Direction -- Decrement X

Do a Pixel Write

Decrement Down Counter

2 - 1 = 1

#### DRAW VECTOR



#### CALCULATION #5

Error Register = 000

DVM Register = 374

Carry In = 001

Error Register = 375

Strobe                      No Carry    Decrement  
   Major and Minor Axis

Error Register = 375

DU Register = 005

Error Register = 002

                                    Carry

Strobe

Direction -- Decrement X and Y

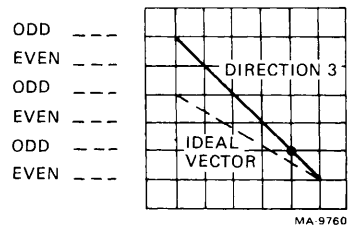
Do a Pixel Write

Decrement Down Counter

1 - 1 = 0

DRAW VECTOR

VECTOR COMPLETE



# ILLUSTRATED PARTS BREAKDOWN

# VK100 GIGI TERMINAL

## HOW TO USE THE IPB

### GENERAL

This IPB is compiled following the organization and nomenclature of the engineering drawing structure.

### MAJOR ASSEMBLY LOCATOR

The Major Assembly Locator (first illustration) is an index that provides a description and a figure reference for all illustrations used in this manual.

### INDENTED PARTS LIST

This manual identifies each assembly being broken down (figure reference callout), and all parts of that assembly. Further breakdown of an assembly is shown by an asterisk (\*) preceding the item callouts in the Description Column. The number of asterisks preceding an item is used to denote the subordination of that item with respect to the Major Assembly. A single asterisk preceding an item description indicates that the item is part of the major assembly being illustrated. Items that are subordinate to single asterisks items, are denoted by two asterisks (\*\*) and immediately follow the related single asterisk item. Additional asterisks are used, as required, to denote further subordination. This system of part identification, provides a means for the user to identify the next higher assembly item and make alternate selections for parts when the required replacement part or assembly is not immediately available.

### COLUMN CALLOUT DESCRIPTION

**Figure & Item** — Indicates the figure number and item number of each part.

**Description** — Lists the name of the part and pertinent specifications (when required). Asterisks preceding the description denote the subordination of the part to the next higher assembly.

**DEC Part No.** — Lists the DEC part ordering number. A blank in this column indicates a DEC part number was not assigned at the time of publication.

**ECO Cut-In** — The notation at the top of this column indicates the ECO level of the system (option), at which the IPB was initially prepared. Subsequent ECO level designations, that modify existing parts or add new parts to the device, are inserted in the ECO Cut-In column next to the part that is added or modified. A bracket ([]) preceding the item description is used to indicate the parts affected by ECO's.

**Vendor Code/Part No.** — Indicates vendor parts that are not stocked by DEC. Refer to the Field Service Spares Catalog (vendor part number to DEC part number) for the vendor code cross-reference.

**Used On Code** — Letters in this column correspond to the variation codes assigned in Figure 1. Parts with an Alpha notation(s) are used only in those option variations. A blank indicates that the part is used on all option variations.

**Ref Fig No.** — A cross reference between illustrations. For each Major Assembly, the number in this column denotes the figure of the next higher assembly. For all subassemblies, the number in this column denotes the figure showing additional detailed breakdown.

### SYMBOL USAGE

**Hardware Designators** — Alpha designators for screws (S), washers (W), nuts (N), and retaining rings (R) are inserted after the item number callouts on the illustration when stacked item numbers are used.

**Attaching Hardware** — The @ symbol is inserted before any part that is used as attaching hardware. Attaching hardware is denoted as those parts that are not an integral part of the referenced assembly.

**(NFR) Not Field Repairable** — The (NFR) symbol is inserted after any assembly that is not to be field dismantled.

**Other Symbols** — Any other symbols that are required for kits, accessories, etc., will be explained and appear as part of the item description.

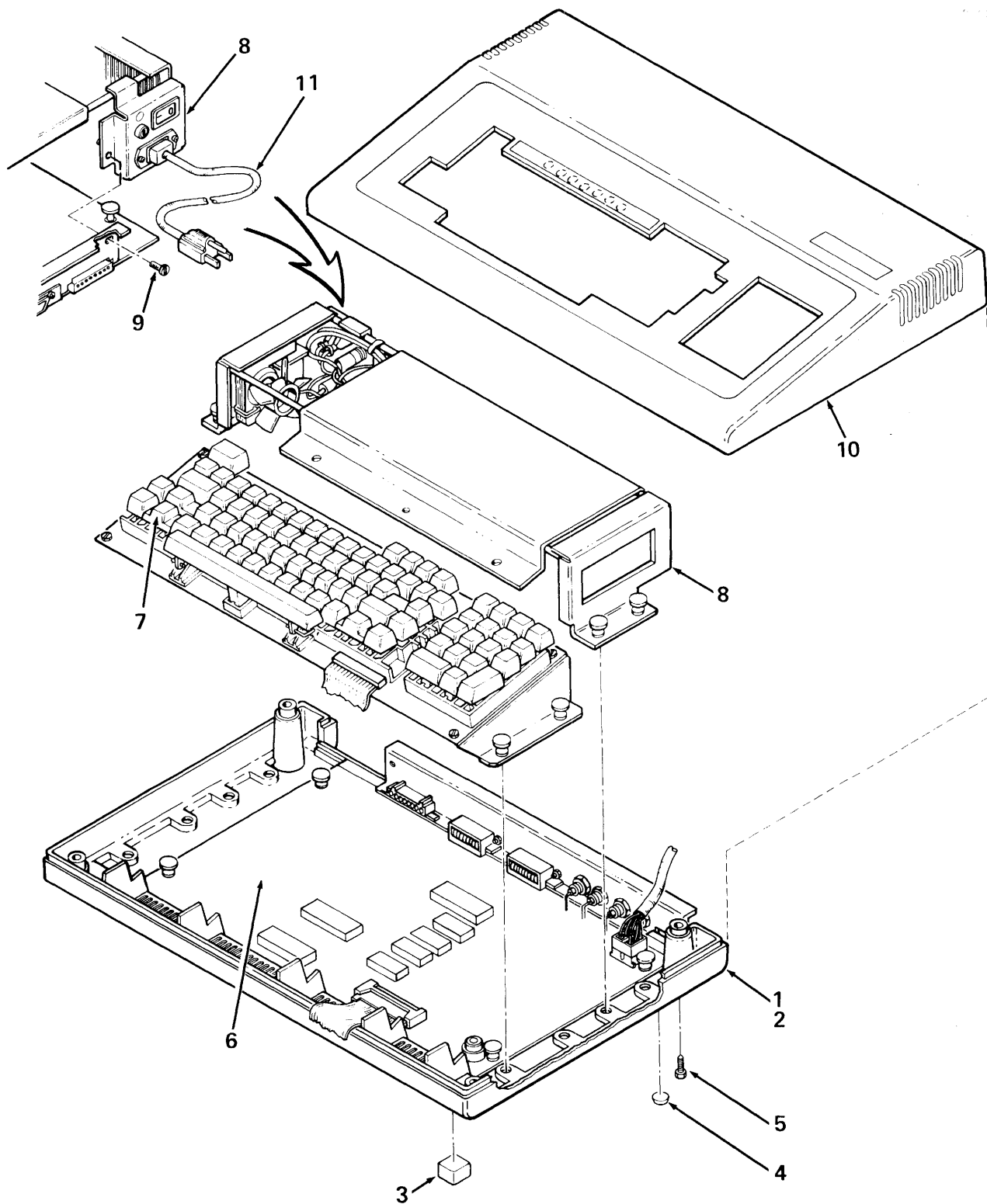
REVISION HISTORY				OTHER IPB MANUALS REQUIRED TO SUPPORT THIS OPTION. . . . .
PRINTING	ECO LEVEL	DATE	PAGES AFFECTED	
1st Printing	VK100 00000-00000 70-17387 00000-00000 70-17397 00000-00000 70-17484 00000-00000 54-14228 00000-00000 70-17388 00000-00000 70-17389 00000-00000 70-17411 00000-00000	9-29-81	N/A	N/A

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None of the descriptions contained in this manual imply the granting of any license whatsoever to make, use or sell equipment constructed in accordance therewith.



VK100-01

Figure 1. VK100 GIGI Terminal



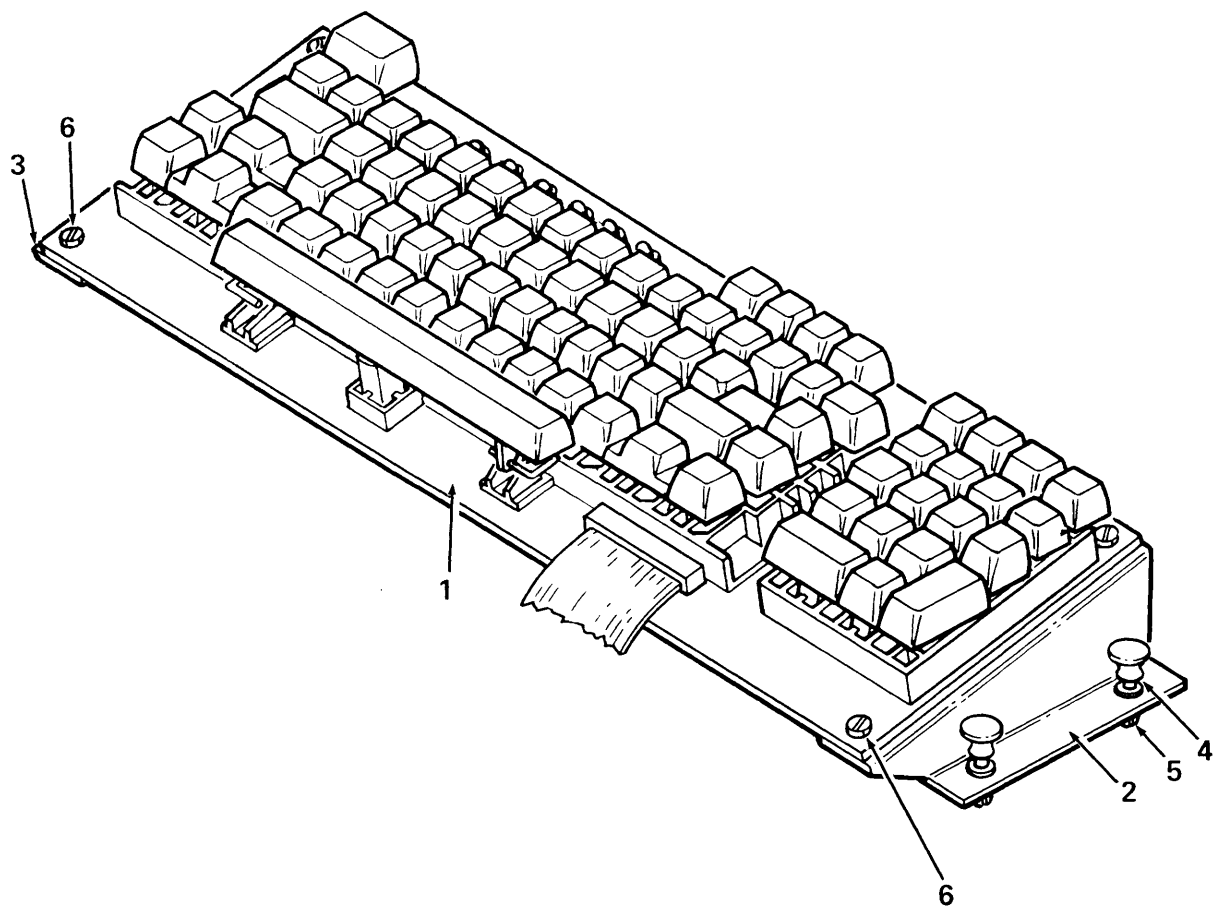
FIG. & ITEM NO.	DESCRIPTION	DEC PART NO.	ECO CUT-IN VK100 00000	USED ON CODE	REF FIG NO.
1—	VK100 GIGI TERMINAL Code A — Used on Model VK100-AA 115V Code B — Used on Model VK100-AB 230V	VK100-AA VK100-AB		A B	
1	*KEYBOARD BASE ASSEMBLY	70-17394-00			
2	**Enclosure, Bottom Keyboard	74-23626-00			
3	**Bumper, Square (Adhesive Backed)	90-09624-00			
4	**Bumper, Self Stick	90-09538-00			
5	**Screw, Slotted Hex Hd No. 6-32 x 3/4	12-16682-00			
6	*VK100 Logic Board	54-14230-00			
7	*KEYBOARD/KEYCAP ASSEMBLY	70-17397-00			3
8	*POWER SUPPLY ASSEMBLY 115V	70-17387-00		A	2
	*POWER SUPPLY ASSEMBLY 230V	70-17387-01		B	2
9	*Screw, Slotted Hex Hd No. 6-32 x 5/16	90-09967-00			
10	*Keyboard Top Assembly	70-17409-00			
11	*Power Cord 115V	17-00083-09		A	
	*Power Cord 230V	17-00083-10		B	
	Labels (Not Shown)				
	*Label, "Electrical Data" Rear Panel	36-17318-00			
	*Label, "Electrical Data"	36-13209-00			
	*Label, "FCC Class A Processor"	36-17880-02		A	



*Figure 2. Power Supply Assembly*

FIG. & ITEM NO.	DESCRIPTION	DEC PART NO.	ECO CUT-IN 70-17387 00000	USED ON CODE	REF FIG NO.
2-	POWER SUPPLY ASSEMBLY 115V	70-17387-00		A	1
	POWER SUPPLY ASSEMBLY 230V	70-17387-01		B	1
1	*Power Supply Chassis Assembly	70-17483-00			
2	*Power Supply, Switching	12-16987-00			
3	*Fan Assembly 115/230V 50-60 HZ	12-16488-01			
4	*Screw, Slotted Hex Hd No. 10-32 x 3/8	90-06444-00			
5	*Fuseholder, (F1) 12A 250V	12-16391-00			
6	*Tubing, Shrink	91-07685-00			
7	*Fuse, 2A 250V	90-07215-00			
8	*A.C. RECEPTACLE ASSEMBLY	70-17411-00			8
9	*Screw, Slotted Pan Hd No. 4-40 x 3/8	90-09702-00			
10	*Switch Rocker (2 Position)	12-17051-00			
11	*A.C. WIRING HARNESS ASSEMBLY	70-17388-00			6
12	*Screw, Slotted Hex Hd No. 6-32 x 5/16	90-09967-00			
13	*Plunger	90-09964-00			
14	*Grommet, Snap-In	90-09966-01			
15	*Cable Tie (Bundle)	90-07031-00			
16	*Nut, Kep No. 10-32	90-06565-01			
17	*D.C. POWER CABLE ASSEMBLY	70-17389-0J			7
	Decals/Labels (Not Shown)				
	*Label, "Danger Stored High Voltage"	36-16930-00			
	*Label, "2 A 250V"	36-17165-00			
	*Label, "Power Supply"	90-09255-00			
	*Decal, "Ground"	36-12680-00			

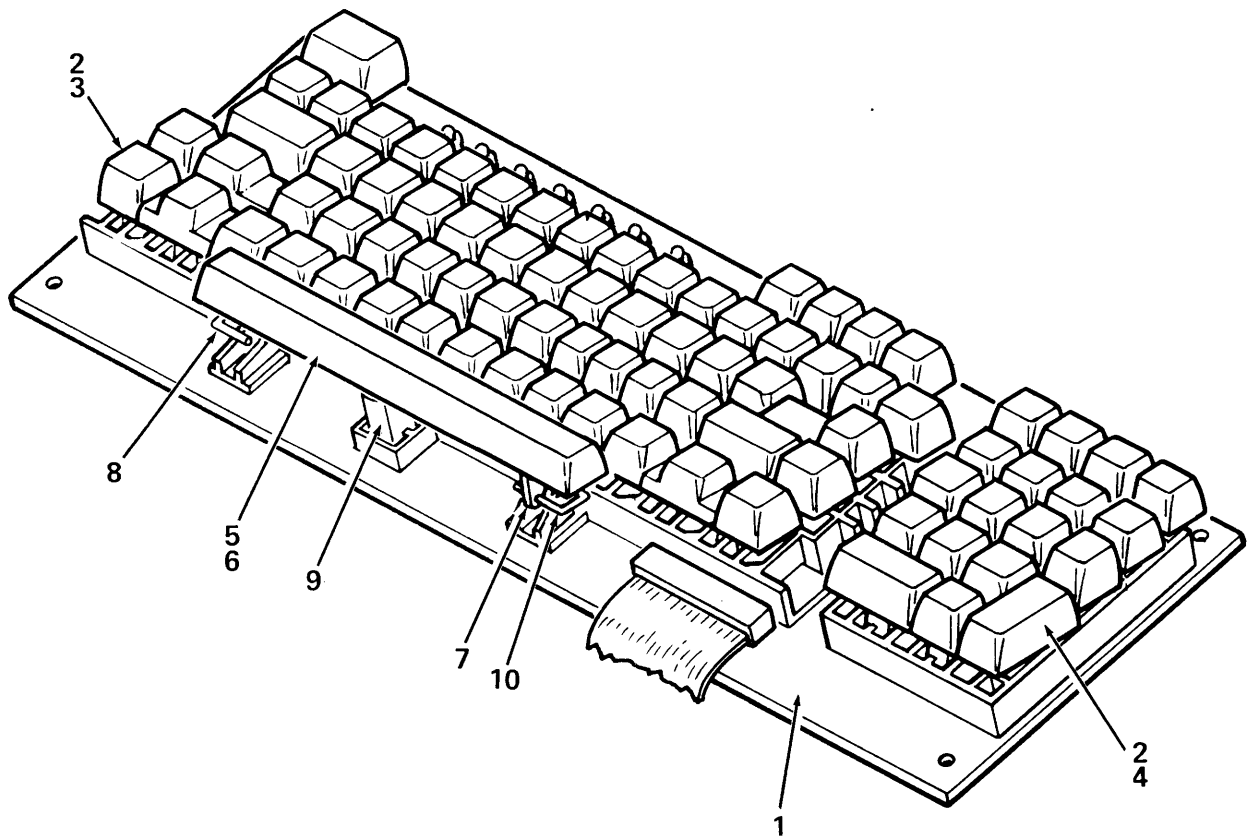
FIG. & ITEM NO.	DESCRIPTION	DEC PART NO.	ECO CUT-IN 70-17397 00000	USED ON CODE	REF FIG NO.
3—	KEYBOARD/KEYCAP ASSEMBLY	70-17397-00			1
1	*VK100 KEYBOARD/KEYCAP ASSEMBLY	70-17484-00			4
2	*Bracket, Key Array Support (R.H.)	74-23702-00			
3	*Bracket, Key Array Support (L.H.)	74-23702-01			
4	*Plunger	90-09964-00			
5	*Grommet, Snap-In	90-09966-01			
6	*Screw, Slotted Hex Hd No. 6-32 x 5/16	90-09967-00			



VK100-03

Figure 3. Keyboard/Keycap Assembly

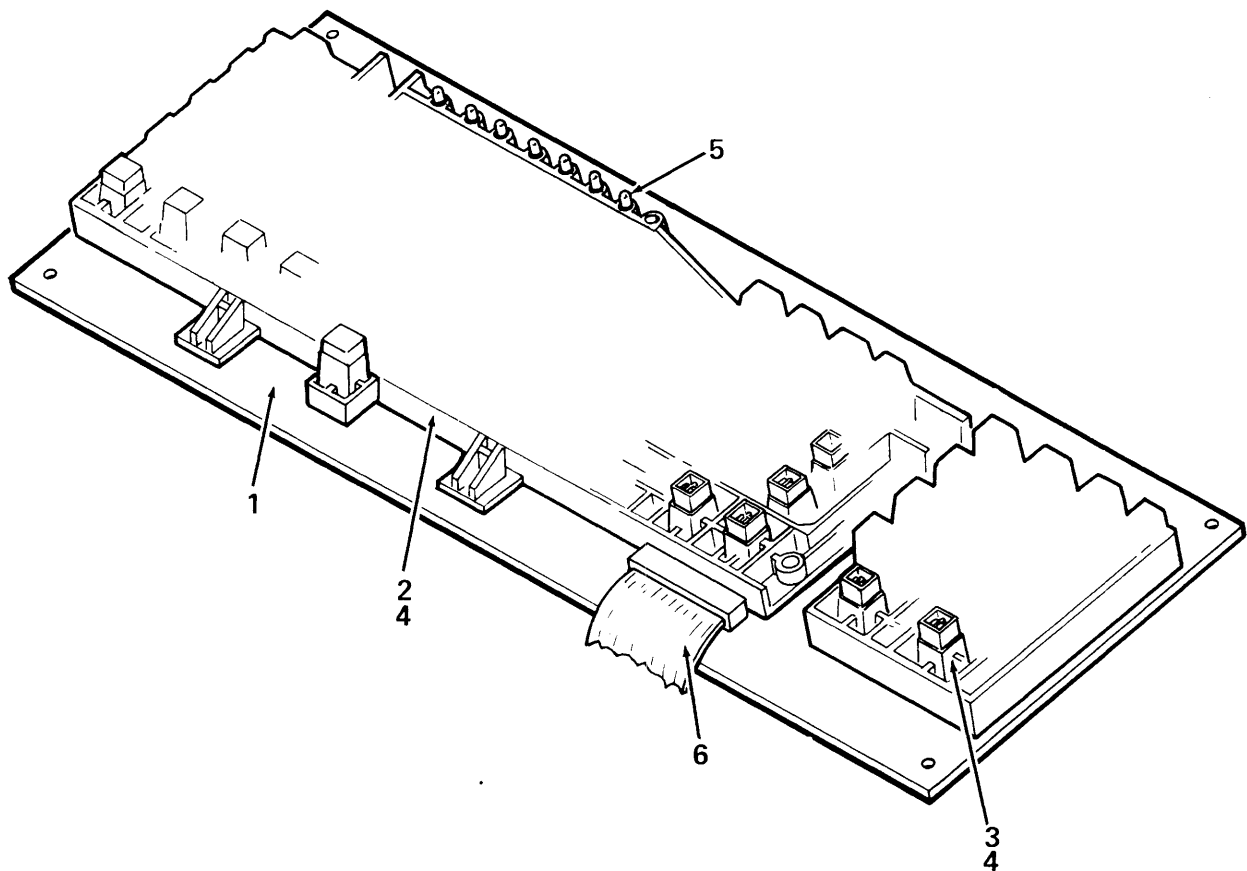
FIG. & ITEM NO.	DESCRIPTION	DEC PART NO.	ECO CUT-IN 70-17484 00000	USED ON CODE	REF FIG NO.
4—	VK100 KEYBOARD/KEYCAP ASSEMBLY	70-17484-00			3
1	*VK100 KEYBOARD MODULE ASSEMBLY	54-14228-00			5
2	*Adapter, Keycap	12-14332-00			
3	*Keycap Set (Basic Set)	12-14333-72			
4	*Keycap Set (Basic Numeric Pad)	12-14333-LA			
5	*SPACE BAR ASSEMBLY	70-15050-00			
6	**Bar, Space	12-11857-02			
7	**Bracket, Space Bar	74-24159-00			
8	**Bar, Equalizer	12-11858-00			
9	**Switch, Keyboard Cap Tilted	12-11860-00			
10	*Clip, Space Bar Equalizer	74-24160-00			



VK100-04

Figure 4. VK100 Keyboard/Keycap Assembly

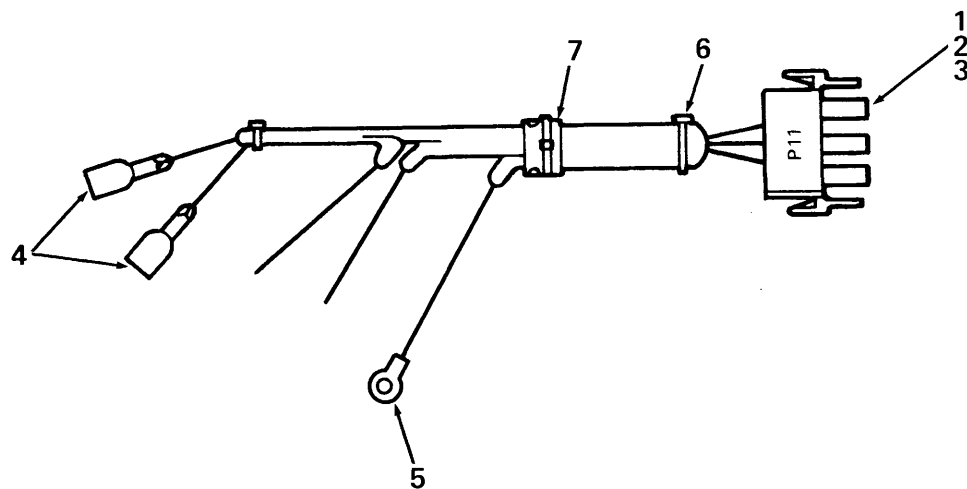
FIG. & ITEM NO.	DESCRIPTION	DEC PART NO.	ECO CUT-IN 54-14228 00000	USED ON CODE	REF FIG NO.
5—	VK100 KEYBOARD MODULE ASSEMBLY	54-14228-00			4
1	*Board, Etch (Rev. C)	50-14227-00			
2	*Keyboard Array Assembly	70-13910-00			
3	*18 Key Numeric Pad Assembly	70-14561-00			
4	*Screw, Phl Pan Hd No. 4-24 x 3/8	90-10033-00			
5	*LED 2MCD 10MA	11-10864-00			
6	*Keyboard Distribution Cable Assembly	70-17390-0J			



VK100-05

Figure 5. VK100 Keyboard Module Assembly

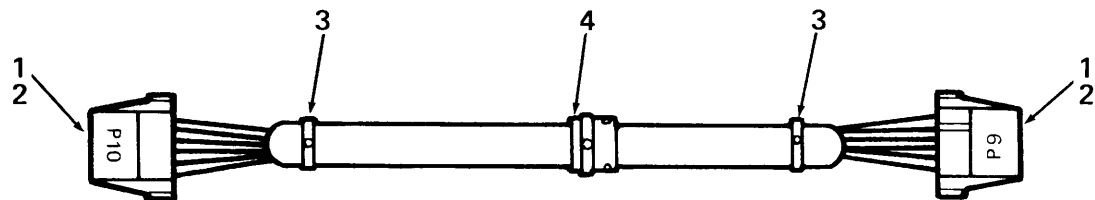
FIG. & ITEM NO.	DESCRIPTION	DEC PART NO. <sup>A</sup>	ECO CUT-IN 70-17388 00000	USED ON CODE	REF FIG NO.
6—	A.C. WIRING HARNESS ASSEMBLY	70-17388-00			2
1	*Connector (P11), Universal (Socket Housing) 3-Pin Mate-N-Lok	12-12167-00			
2	*Terminal (P11), Universal Socket Contact	12-12169-01			
3	*Terminal (P11), Universal Ground Socket Contact	12-17519-00			
4	*Terminal, Quick Connect	12-17000-00			
5	*Terminal, Ring	90-07930-00			
6	*Cable Tie (Bundle)	90-07031-00			
7	*Label, "Cable Identification"	90-09532-00			
	*Wire, Strand, 18 AWG (Brown)	91-07786-11			
	*Wire, Strand, 18 AWG (Blue)	91-07786-66			
	*Wire, Strand, 18 AWG (Green/Yellow)	91-07410-54			



VK100-06

Figure 6. A.C. Wiring Harness Assembly

FIG. & ITEM NO.	DESCRIPTION	DEC PART NO. <sup>A</sup>	ECO CUT-IN 70-17389 00000	USED ON CODE	REF FIG NO.
7-	D.C. POWER CABLE ASSEMBLY	70-17389-00			2
1	*Connector (P9, P10), Socket Housing 6 Pin Mate-N-Lok	12-10821-06			
2	*Terminal (P9, P10), Socket Contact	12-09379-00			
3	*Cable Tie (Bundle)	90-07031-00			
4	*Label, "Cable Identification"	90-09532-00			
	*Wire, Strand, 18 AWG (Red)	91-07786-22			
	*Wire, Strand, 18 AWG (Orange)	91-07786-33			
	*Wire, Strand, 18 AWG (Blue)	91-07786-66			
	*Wire, Strand, 18 AWG (Black)	91-07786-00			

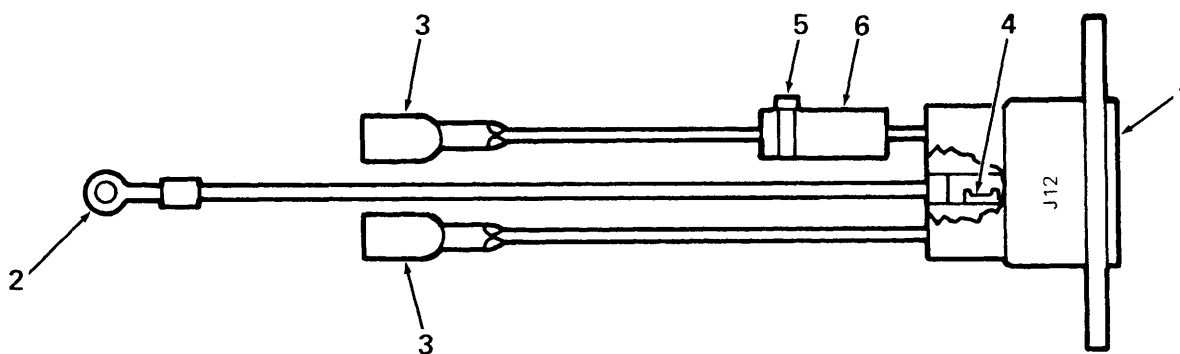


VK100-07

Figure 7. D.C. Power Cable Assembly



FIG. & ITEM NO.	DESCRIPTION	DEC PART NO. <sup>A</sup>	ECO CUT-IN 70-17411 00000	USED ON CODE	REF FIG NO.
8—	A.C. RECEPTACLE ASSEMBLY	70-17411-00			2
1	*Connector (J12), 3 Pin Power Plug	12-17046-00			
2	*Terminal, Ring	90-07930-00			
3	*Terminal, Quick Connect	12-17000-00			
4	*Terminal, Spade	12-17045-00			
5	*Cable Tie (Bundle)	90-07031-00			
6	*Label, "Cable Identification"	90-09532-00			
	*Wire, Strand 18 AWG (Green/Yellow)	91-07410-54			
	*Wire, Strand 18 AWG (Blue)	91-07786-66			
	*Wire, Strand 18 AWG (Brown)	91-07786-11			
					DEC



VK100-08

Figure 8. A.C. Receptacle Assembly

## ILLUSTRATED PARTS BREAKDOWN COMMENT SHEET

Any and all comments and suggestions for correcting errors and/or additional information to improve this manual will be reviewed and researched for possible use when this manual is revised and/or reprinted. Enter your comments and suggestions in the form provided below and return to Technical Documentation.

MODEL VK100 GIGI TERMINAL

PUBLICATION NO. EK-VK100-IP-001

FIGURE NO. \_\_\_\_\_ ITEM NO. \_\_\_\_\_

CHANGE FROM \_\_\_\_\_

CHANGE TO \_\_\_\_\_

FIGURE NO. \_\_\_\_\_ ITEM NO. \_\_\_\_\_

CHANGE FROM \_\_\_\_\_

CHANGE TO \_\_\_\_\_

FIGURE NO. \_\_\_\_\_ ITEM NO. \_\_\_\_\_

CHANGE FROM \_\_\_\_\_

CHANGE TO \_\_\_\_\_

FIGURE NO. \_\_\_\_\_ ITEM NO. \_\_\_\_\_

CHANGE FROM \_\_\_\_\_

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CHANGE FROM \_\_\_\_\_

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FIGURE NO. \_\_\_\_\_ ITEM NO. \_\_\_\_\_

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