

E D U C A T I O N A L  
S E R V I C E S

VAX/VMS  
Training

VAX/VMS  
Device Driver  
Optional  
Driver Routines

digital



# OPTIONAL DRIVER ROUTINES

Prepared by Educational Services  
of  
Digital Equipment Corporation

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## INTRODUCTION

The routines listed below need not be present in a driver. Their presence is determined by the physical characteristics of the device (when certain device registers need to be initialized). These routines ease the coding of other routines (making the UCB for a single-unit controller the owner UCB in the IDB, thereby eliminating the need for REQCHAN and RELCHAN macros), or supply information (producing error log reports about the device). These routines include:

- Timeout Routine
- Cancel I/O Routine
- Controller Initialization Routine
- Unit Initialization Routine
- Register Dump Routine (General Error Logging)

## OBJECTIVES

Upon completion of this module, you will be able to:

1. Write the following driver routines:
  - timeout
  - cancel I/O
  - unit initialization
  - controller initialization
  - register dump
2. Incorporate error logging capabilities in a driver.
3. Interpret the error reports generated by ANALYZE/ERROR\_LOG which relate to your driver.

## OPTIONAL DRIVER ROUTINES

### RESOURCES

1. Guide to Writing a Device Driver for VAX/VMS
2. VAX/VMS Guide to System Management and Daily Operations

### LEARNING ACTIVITIES

1. Study drivers which have unit initialization routines, controller initialization routines, cancel I/O routines, and register dump routines (i.e., those that perform error-logging).
2. Create an error log report.

## OPTIONAL DRIVER ROUTINES

### TOPICS

- Timeout routine
- Powerfail recovery routine
- Cancel I/O routine
- Controller initialization routine
- Unit initialization routine
- Error logging



## OPTIONAL DRIVER ROUTINES

### TIMEOUT ROUTINE

The driver timeout routine is invoked:

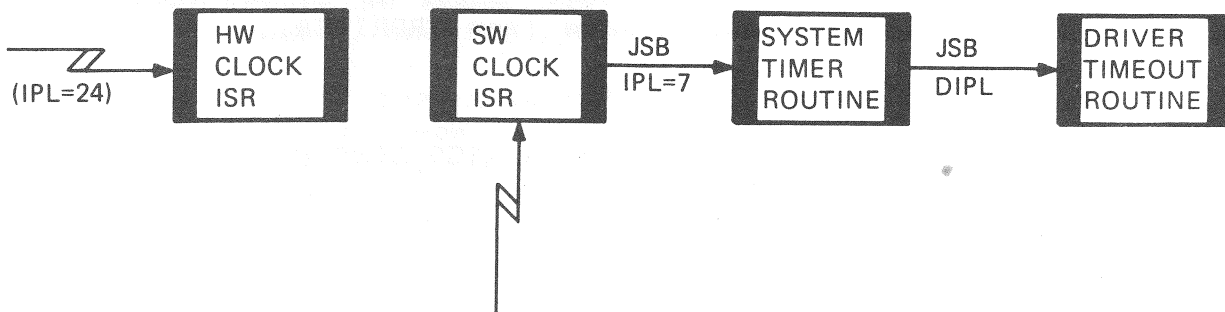
- by the system timer routine, running at IPL = 8 (was invoked at IPL = 7).
- when the timeout interval, specified in a WFIKPCB or WFIRLCH macro, expires.
- after a powerfail

The system timer routine runs once every second. It scans all UCBs that have timeouts enabled (UCB\$V\_TIM), to see if a timeout should occur, and updates all due time fields for UCBs expecting a timeout. Before calling the driver timer routine, the system timer routine:

- clears bits UCB\$V\_INT and UCB\$V\_TIM in UCB\$W\_STS to disable interrupts or another timeout.
- sets the timeout bit UCB\$V\_TIMEOUT in UCB\$W\_STS.
- sets IPL to device IPL.
- restores the saved fork process context.
- calls the timeout routine (via JSB).

The driver timeout routine normally does one of the following:

- retries the request (a fixed number of times).
- aborts the I/O request.
- sends a message to an operator, and waits.



TK-9091

Figure 9-1 Timer and Timeout Sequence

## OPTIONAL DRIVER ROUTINES

A timeout routine may perform some of the following:

- Modifies device status register(s) (e.g., clears error bits).
- Sets IPL to fork level with SETIPL UCB\$B\_FIPL(R5), not using IOFORK. A synchronization problem could arise if IOFORK is used, since the fork dispatcher, at fork IPL, when returning control would try to return control to the timer routine (at IPL = 8). IPL cannot be lowered in this fashion. By setting IPL to fork level (with SETIPL) the fork dispatcher is never invoked, since it is invoked only by IOFORK.
- Returns system resources (e.g., data path, mapping registers).
- Checks for the cancel bit (UCB\$V\_CANCEL in UCB\$W\_STS). If set,
  - places SSS\_ABORT or SSS\_CANCEL in R0.
  - writes other status information in R0 and R1.
  - invokes REQCOM.
- Checks the powerfail bit (UCB\$V\_POWER in UCB\$W\_STS). If set, attempts powerfail recovery, if possible (discussed later).
- Logs a device timeout error by calling ERL\$DEVICTMO (error logging is discussed in another module).
- Updates a retry counter (stored in the UCB). If threshold is exhausted, proceeds as for cancel, otherwise, clears UCB\$V\_TIMEOUT in UCB\$W\_STS, and retries the operation.
- Sends a message to an operator and retries the operation (perhaps sending the message after a fixed number of timeouts). To send a message (see CRDRIVER):
  - save R3 and R4 on stack.
  - load a message code such as MSG\$\_DEVOFFLIN into R4.
  - load the address of the operator's mailbox into R3 (e.g., SYS\$GL\_OPRMBX).
  - send the message using JSB G^EXE\$SENDEVMSG
  - restore R3 and R4 from stack.

## OPTIONAL DRIVER ROUTINES

### POWERFAIL RECOVERY

After a powerfailure, routine EXE\$RESTART in module POWERFAIL of the executive performs the following:

- raises IPL to 31.
- sets bit UCB\$V\_POWER in UCB\$W\_STS in all UCBs.
- calls all controller initialization routines.
- calls all unit initialization routines.
- for each UCB with either UCB\$V\_INT or UCB\$V\_TIM set (in UCB\$W\_STS):
  - clears UCB\$V\_INT
  - sets UCB\$V\_TIM
  - clears UCB\$L\_DUETIM

In effect, the unit will timeout, and the driver timeout routine is entered.

When a powerfailure is detected by the timeout routine, the routine can either abort the operation (if no recovery is possible), or retry the entire operation (if that is possible for the particular function code for the device). When retrying the operation, all counters, flags, and relevant fields in the UCB should be restored to their original state (possibly by recopying them from the IRP). Also, the address of the IRP may have been destroyed, so as a precaution, the driver should restore the IRP address

```
MOVL UCB$L_IRP(R5), R3
```

If a powerfailure is detected before the WFIKPCH macro is issued, but after a DSBINT macro, then an ENBINT macro should be issued to remove the saved IPL from the stack. Device registers should be reloaded, and the I/O operation retried.

In any case, the driver is responsible for clearing the UCB\$V\_POWER bit in UCB\$W\_STS. Sometimes, drivers clear this bit when starting an I/O operation, in case a powerfail occurred while the device was inactive (yet the powerfail bit was still set).

## OPTIONAL DRIVER ROUTINES

### CANCEL I/O ROUTINE

The address of the cancel I/O routine is placed in the DDT. The cancel I/O routine is called whenever

- a channel to the device is deassigned.
- the device is deallocated.
- a \$CANCEL system service is issued.  
(forced by VMS on image exit and process deletion)

When called, the cancel I/O routine may expect

- to be at fork IPL
- R2 = negated value of channel index number
- R3 = IRP address
- R4 = PCB address for process issuing \$CANCEL
- R5 = UCB address
- R8 = Reason for call (i.e., CAN\$C\_CANCEL, CAN\$C\_DASSGN;  
see \$CANDEF)

Before being called, all IRPs queued to the UCB from the specific process and with the specified channel number are removed from the queue, and have SSS\_CANCEL placed into IRP\$LMEDIA before they are placed on the I/O postprocessing queue. Therefore, the cancel I/O routine need only concern itself with the current I/O request.

Normally, DMA devices do not have a cancel I/O entry point since I/O operations cannot be stopped once a transfer has started.

Frequently, cancel I/O routines simply contain a

```
JMP G^IOC$CANCELIO
```

which verifies that

- the unit is busy.
- the current IRP is for the process requesting \$CANCEL.
- the current IRP is for the channel over which the \$CANCEL was issued.

If the above conditions are met, IOC\$CANCELIO sets the UCB\$V\_CANCEL bit in UCB\$W\_STS. The timeout and/or start I/O routines should check for this bit being set, and terminate the I/O operation after putting appropriate status information into R0 and R1.

## OPTIONAL DRIVER ROUTINES

Another common use of the cancel I/O routine is to restore the UCB fields to their original states when a user is done with the device (resetting flags, counters, etc.), turning the unit on/off-line, clearing error bits, etc. To tell when a user is deassigning/deallocating the device, test for the reference count (going to 0 for nonshareable devices, or decreasing by 1 for shareable devices). For example:

```
TSTW   UCB$W_REFC(R5)           ; nonshareable device
BEQL   GOING_AWAY                ; being deassigned/
                                   ; deallocated
```

Note that R4 does not contain the CSR address, and if your cancel routine will request some device activity (and call on WFIKPCH), you will need to save and restore the PCB address passed in R4 (probably in an extension to the UCB).

## CONTROLLER INITIALIZATION ROUTINE

The Controller Initialization Routine is invoked

- at IPL\$\_POWER (31).
- when unit CONNECTed or driver RELOADed (SYSGEN).
- after powerfailure.
- R4 = CSR address.
- R5 = IDB address.
- R6 = DDB address.
- R8 = CRB address.

The processing involved is device-dependent, but may include:

- initializing fields in CRB or IDB (e.g., VEC addresses in CRB that are more than 256 bytes away from start of CRB, and therefore cannot be initialized by DPT\_STORE macro).
- initialize owner field (IDB\$L\_OWNER) of the IDB so REQCHAN and RELCHAN macros are not necessary (for single-unit controllers).

## OPTIONAL DRIVER ROUTINES

- permanently allocating resources such as data paths or mapping registers (e.g., setting bit VEC\$V\_PATHLOCK in CRB\$L\_INTD + VEC\$B\_DATAPATH to permanently allocate a data path, after calling REQ DPR, or VEC\$V\_MAPLOCK in CRB\$L\_INTD + VEC\$W\_MAPREG to permanently allocate a mapping register, after calling REQ MPR). Be careful to check for powerfailure first, so resources are not doubly allocated (UCB\$V\_POWER in UCB\$W\_STS).

### UNIT INITIALIZATION ROUTINE

The Unit Initialization Routine is invoked

- at IPL\$ POWER (31).
- when unit is CONNECTed (SYSGEN).
- after powerfailure.
- R3 = CSR address (primary).
- R4 = CSR address (secondary, differs for MASSBUS devices only, when it contains the MBA CSR address).
- R5 = UCB address.

The processing involved is also device-dependent. The same things can be done in the unit initialization routines as in the controller initialization routines. Usually, the unit initialization routine sets bits in the UCB and the owner field of the IDB, while the controller initialization routines initialize fields in the CRB and IDB. Among the operations not listed in the controller initialization section are:

- clear error bits in device register(s).
- setting device on-line (UCB\$V\_ONLINE in UCB\$W\_STS).

## OPTIONAL DRIVER ROUTINES

To perform unit initialization, and to initialize fields used in the start I/O routine, a MASSBUS driver must locate the device registers for the unit. For a single-device MASSBUS controller, the following steps are taken:

- Extract the unit number from UCB\$W\_UNIT and store it in UCB\$B\_SLAVE. For example:

```
MOVZWL UCB$W_UNIT(R5), R3      ; get drive unit number
MOVB R3, UCB$B_SLAVE(R5)      ; set slave unit number
```

- Multiply the slave number by 32 to derive the longword offset to the device registers for the driver (store the result in UCB\$B\_SLAVE+1). For example:

```
MULL #107/4, R3
MOVB R3, UCB$B_SLAVE+1(R5)
```

- Assuming that the offset to the device registers is in R3, and R4 contains the MBA CSR, the driver can load the address of the device registers into a general register as follows:

```
MOVAL MBA$L_ERB(R4)[R3],R3
```

(MBA\$L\_ERB is a fixed offset to the start of the external registers.) The configuration register is the first register in the space reserved for MBA registers.

For a multidevice MASSBUS controller, the driver uses R3, R4, and R5 (passed by the driver loading procedure) to locate the device registers:

- Computes the MBA unit number of the controller by using R3 to determine the number of bytes from the start of MBA address space to the device registers, and dividing the result by 128. The result is stored in UCB\$B\_SLAVE.

For example:

```
SUBL3 R4,R3,R2                ; calculate offset to
                               ; drive control register
MOVAB -MBA$L_ERB(R2),R2       ; subtract out external
                               ; register base
DIVW3 #107,R2,UCB$B_SLAVE(R5) ; set adapter driver
                               ; number
```

## OPTIONAL DRIVER ROUTINES

- Stores the drive offset constant in UCB\$B\_SLAVE+1 (equals slave value multiplied by 32). For example:  

```
MULB3 #1@7/4,UCB$B_SLAVE (R5), UCB$B_SLAVE+1 (R5)
```
- Performs any initialization functions required.

## DRIVER ERROR LOGGING

- Is an optional driver feature.
- Is a cooperative effort between a driver, system subroutines, an error formatting process (ERRFMT), and a report generation program invoked with ANALYZE/ERROR\_LOG.
- Provides a mechanism whereby device errors and device timeouts can be recorded, and later analyzed.

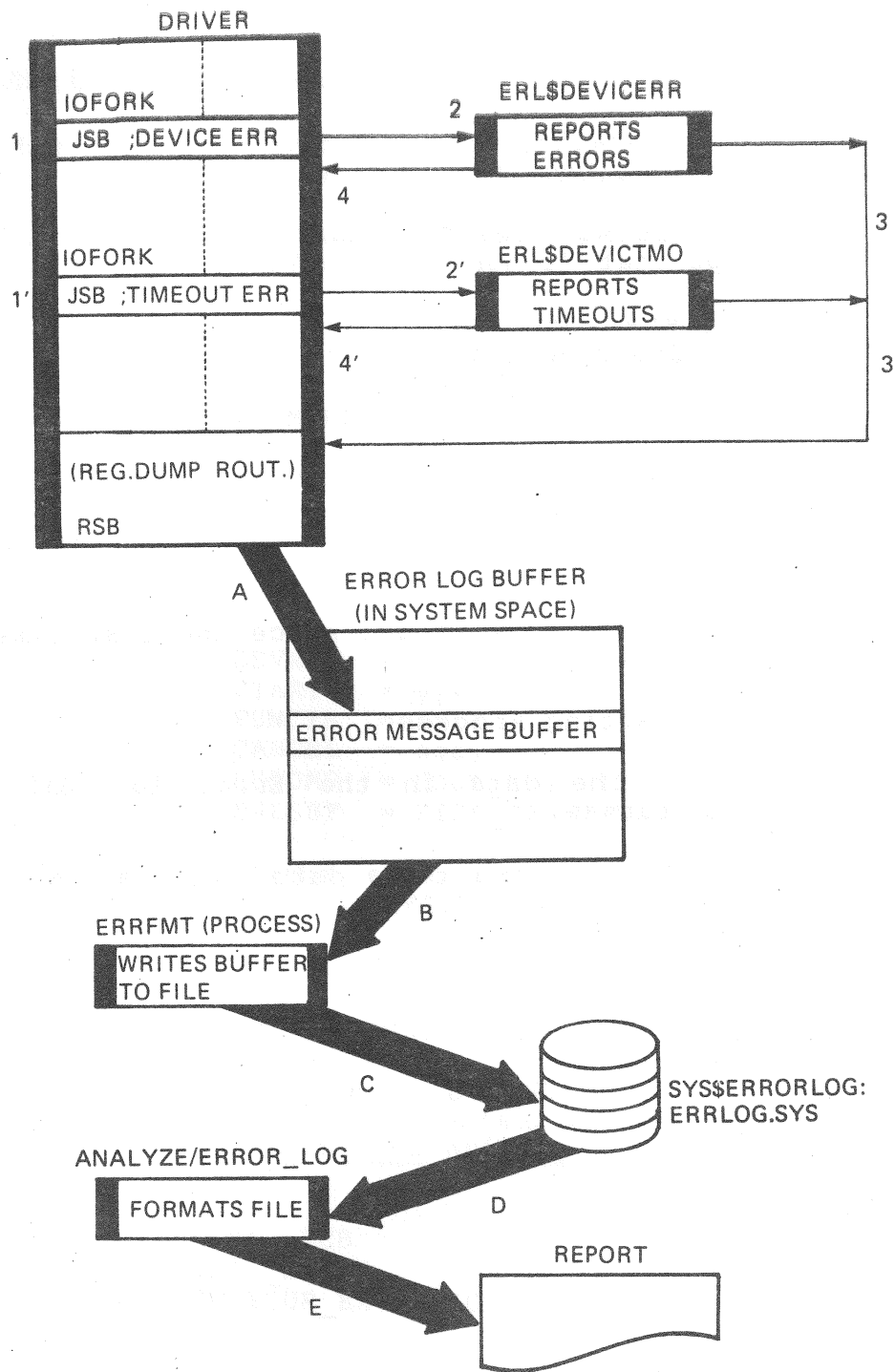
## Error Logging Components

Figure 9-2 summarizes the flow of data and control among the major components involved in error logging. The following notes are keyed to the figure.

### Device Error:

1. Driver detects a device error and calls system routine ERL\$DEVICERR.
2. ERL\$DEVICERR
  - logs device error.
  - allocates error message buffer space for error log buffer.
  - fills in pertinent information (device class and type, etc.).
  - calls driver register dump routine.
3. Driver Register Dump Routine
  - dumps device register contents in allocated error message buffer.
  - returns to ERL\$DEVICERR.
4. ERL\$DEVICERR returns control to driver.

# OPTIONAL DRIVER ROUTINES



MKV84-1882

Figure 9-2 Control and Data Flow of Driver Error Logging

## OPTIONAL DRIVER ROUTINES

### Timeout Error:

- 1' Driver detects a device timeout error and calls a system routine ERL\$DEVICTMO.
  - 2',3',4' ERL\$DEVICTMO does the same thing as ERL\$DEVICERR except that it marks the error as a timeout error.
- A. Driver Register Dump routine dumps device register contents in Error Message Buffer.
  - B. The Error Formatting Process ERRFMT is awakened:
    - if Error Log Buffer is full, or
    - if ten messages have been written into the Error Log Buffer, or
    - if 30 seconds have elapsed since the last time ERRFMT was awakened.
  - C. The Error Formatting Process
    - transforms the data in the Error Log Buffer into standard format.
    - writes the formatted data on a disk file SYS\$ERRORLOG: ERRLOG.SYS.
  - D,E. The User
    - renames ERRLOG.SYS to ERRLOG.OLD.
    - use ANALYZE/ERROR\_LOG command to generate a report from ERRLOG.OLD

## OPTIONAL DRIVER ROUTINES

### Necessary Steps for Error Logging

1. Include the \$EMBDEF macro to define EMB symbols for your driver (not in template driver).
2. In the driver prologue table, set the DEV\$V\_ELG bit in the UCB\$L\_DEVCHAR field:

```
DPT_STORE    INIT
DPT_STORE    UCB, UCB$L_DEVCHAR, L, <-
              DEV$M_AVL!-           ; device available
              DEV$M_ELG>           ; enable error log.
DPT_STORE    REINIT
DPT_STORE    END
```

3. In the driver dispatch table, specify a register dump routine and an error log buffer size:

```
DDTAB -
DEVNAM = xxx, -
START  = yyy, -
FUNCTB = zzz, -
CANCEL = aaa, -
REGDMP = YOUR_REGISTER_DUMP_ROUTINE_ADDR,-
ERLGBF = SIZE_OF_ERROR_LOG_BUFFER
```

The size of the error log buffer is computed in the following way:

```
SIZE_OF_ERROR_LOG_BUFFER = 4 (for register count) +
                          4 * (number of registers
                              saved) + EMB$L_DV_REGSAV (for
                              system overhead)
```

4. Include the error log extension to the UCB (see Appendix A of the Guide to Writing a Device Driver for VAX/VMS Manual):

```
$DEFINI UCB
.=UCB$L_DPC+4           ; include error log ext.
$DEF  UCB$W_YOUR_EXTENSIONS .BLKW 1
      .                 ; to hold register dump
      .                 ; data
      .
$DEF  UCB$K_MY_UCBLEN    ; length of extended UCB
$DEFEND UCB
```

[In the driver prologue table, specify  
UCBSIZE = <UCB\$K\_MY\_UCBLEN>]

## OPTIONAL DRIVER ROUTINES

In your driver, place driver register contents, or what is written to driver registers, in the extensions reserved for each register (before an I/O operation is initiated, or after the I/O operation completes).

5. Within your driver, code JSB calls to system routines for reporting device errors or device timeouts. These routines should be called at fork IPL.

JSB G^ERL\$DEVICERR ; for device errors

or JSB G^ERL\$DEVICTMO ; for device timeouts

6. Write a register dump routine which writes the number of device registers to be dumped, and their current contents, into the error buffer. This routine is called by ERL\$DEVICERR or ERL\$DEVICTMO.

When called, the routine may assume that:

R0 = address of buffer into which device registers are dumped.

R4 = address of the controller status register (CSR), assuming that the driver used the WFIKPCB macro to wait for an interrupt or timeout.

R5 = address of the device's UCB. (Store the registers to be dumped in user-defined extensions to the UCB.)

The routine should save and restore R3-R11 if it requires their use.

The routine begins by writing the number of device registers to be dumped into the buffer (as a longword value).

Then all the device registers are placed into the buffer (each one as a longword value).

The register dump routine exits with an RSB to return control to ERL\$DEVICERR or ERL\$DEVICTMO.

Example 9-1 is a register dump routine that saves four register values. The register values were placed into fields in the UCB before calling ERL\$DEVICERR or ERL\$DEVICTMO. (Note that the fields are user-defined extensions to the UCB.) The symbol PT\_NUM\_REGS has been equated to 4 earlier in the driver.

## OPTIONAL DRIVER ROUTINES

```

11620           .SBTTL  PT_REG_DUMP, Device register dump routine
11640
11650      ;++
11660      ; PT_REG_DUMP, Dumps the contents of device registers to a buffer
11670      ;
11680      ; Functional description:
11690      ;
11700      ;     Writes the number of device registers, and their current
11710      ;     contents into a diagnostic or error buffer. Reader and
11720      ;     punch both have two registers (a status register, and a
11730      ;     data register).
11740      ;
11750      ; Inputs:
11760      ;
11770      ;     R0      - address of the output buffer
11780      ;     R4      - address of the CSR (controller status register)
11790      ;     R5      - address of the UCB (unit control block)
11800      ;
11810      ; Outputs:
11820      ;
11830      ;     The routine must preserve all registers except R1-R3.
11840      ;
11850      ;     The output buffer contains the current contents of the device
11860      ;     registers. R0 contains the address of the next empty longword in
11870      ;     the output buffer.
11880      ;
11890      ;--
11900
11910      PT_REG_DUMP:
11920          MOVZBL  #PT_NUM_REGS,(R0)+      ; Dump device registers
11930          MOVZWL  UCB#W_PT_PPS(R5),(R0)+  ; STORE DEVICE REGISTER COUNT
11940          MOVZBL  UCB#B_PT_PPB(R5),(R0)+  ; STORE PUNCH STATUS REGISTER
11943          MOVZWL  UCB#W_PT_PRS(R5),(R0)+  ; STORE PUNCH DATA REGISTER
11946          MOVZBL  UCB#B_PT_PRB(R5),(R0)+ ; STORE READER STATUS REGISTER
11950          RSB                                ; STORE READER DATA REGISTER
          RSB                                ; Return

```

### Example 9-1 Register Dump Routine

## OPTIONAL DRIVER ROUTINES

### Notes on Error Logging

- Enabling/disabling error logging may be implemented by a driver. Usually, an `IO$SETCHAR` function is provided which sets/clears the `DEV$V_ELG` bit in `UCB$L_DEVCHAR` field.
- Error logging may be enabled on a per `$QIO` basis. This is typically performed:
  - at the beginning of the start I/O routine. Move the function code specified by the user (`IRP$W_FUNC`) into `UCB$W_FUNC` (part of the UCB error log extension)
  - if the user has issued a `$QIO` function with the function modifier `IO$M_INHERLOG`, error logging is inhibited for that `$QIO`.
- When the driver calls the system routines `ERL$DEVICERR` or `ERL$DEVICTMO`, an error logging buffer is allocated, and its address is stored in `UCB$L_EMB`.
- Device class and device type (`UCB$B_DEVCLASS` and `UCB$B_DEVTYPE`) are written into the error logging buffer by the system routines.
- The bit `UCB$V_ERLOGIP` (in `UCB$W_STS`) is set by the system routines to indicate error logging is in progress. The bit is cleared by `IOC$REQCOM` after storing the device status, error count, and I/O status block in the error logging buffer.

### Obtaining Error Reports

The following steps may be taken to obtain an error report. For full details, see the VAX/VMS System Management and Operations Guide.

1. Set the default to `SYS$ERRORLOG`
2. Rename `ERRLOG.SYS` to `ERRLOG.OLD`.
3. Use `ANALYZE/ERROR_LOG` to generate a report.

## OPTIONAL DRIVER ROUTINES

The following commands were used to obtain the SYE report in Example 9-2.

```
___ INPUT FILE?           file spec for ERRLOG.OLD
___ OUTPUT FILE?         any file spec (later PRINTed)
___ OPTIONS?            S      (standard)
___ DEVICE NAME?       UNKNOWN [all UNKNOWN device entries]
___ AFTER DATE?       ___ <CR> [first entry]
___ BEFORE DATE?      ___ <CR> [last entry]
```

The driver had an error log routine that dumped two registers. The error log routines were called with the first register to be dumped containing 200 (hex), and the second register containing 20 (hex). Three errors were logged.

The following notes are keyed to Example 9-2:

1. If ERL\$DEVICTMO is called, the entry is identified as a device timeout, rather than a device error. Otherwise, the entry contains the same information.
2. Fields of interest in the IRP and UCB (at the time the error logging routines are called) are displayed.
3. Note that 21 (hex) corresponds to the IO\$\_READLBLK function code.
4. The device name is always stored in a 16-byte field.
5. These are the registers dumped by the driver routine. First is the count (2), followed by the first register, then the second register.

OPTIONAL DRIVER ROUTINES

V A X / V M S

SYSTEM ERROR REPORT

COMPILED 26-JUN-1980 14:23  
PAGE 1.

\*\*\*\*\* ENTRY  
UNKNOWN DEVICE TYPE, DEVICE ERROR  
ERROR SEQUENCE 1738.

2. \*\*\*\*\*  
LOGGED 19-JUN-1980 14:34:32.08  
SYSTEM ID REGISTER 118700D

ERROR LOG RECORD

ERF\$L\_SID 0118700D

ERL\$W\_ENTRY 0001

EXE\$GQ\_SYSTIME AE87C100  
00885138

ERL\$GL\_SEQUENCE 06CA

UCB\$B\_ERTCNT 00

UCB\$B\_ERTMAX 00

IRP\$Q\_IOSB 0000008C  
00000000

UCB\$W\_STS 0110

UCB\$B\_DEVCLASS 64

UCB\$B\_DEVTYPE 64

IRP\$L\_PID 0024000D

IRP\$W\_BOFF 0030

IRP\$W\_BCNT 0024

UCB\$L\_MEDIA 00000000

UCB\$W\_UNIT 0000

UCB\$W\_ERRCNT 0001

UCB\$L\_OPCNT 00000000

UCB\$L\_DWNUIC 00000000

UCB\$L\_DEVCHAR 04440001

UCB\$B\_SLAVE 00

IRP\$W\_FUNC 0021

DDB\$T\_NAME 41435003  
00000000  
00000000  
00000000

LONGWORD 1. 00000002

LONGWORD 2. 00000200

SYSTEM ID REGISTER

ERROR ENTRY TYPE

64 BIT TIME WHEN ERROR LOGGED

UNIQUE ERROR SEQUENCE = 1738.

REMAINING RETRIES = 0.

MAXIMUM RETRIES = 0.

FINAL IOSB

FINAL DEVICE STATUS

DEVICE CLASS = 100.

DEVICE TYPE = 100.

REQUESTING PROCESS ID

TRANSFER BYTE OFFSET = 48.

TRANSFER BYTE COUNT = 36.

DEVICE DEPENDANT PHYSICAL ADDRESS

PHYSICAL UNIT NUMBER = 0.

UNIT ERROR COUNT = 1.

UNIT OPERATION COUNT = 0.

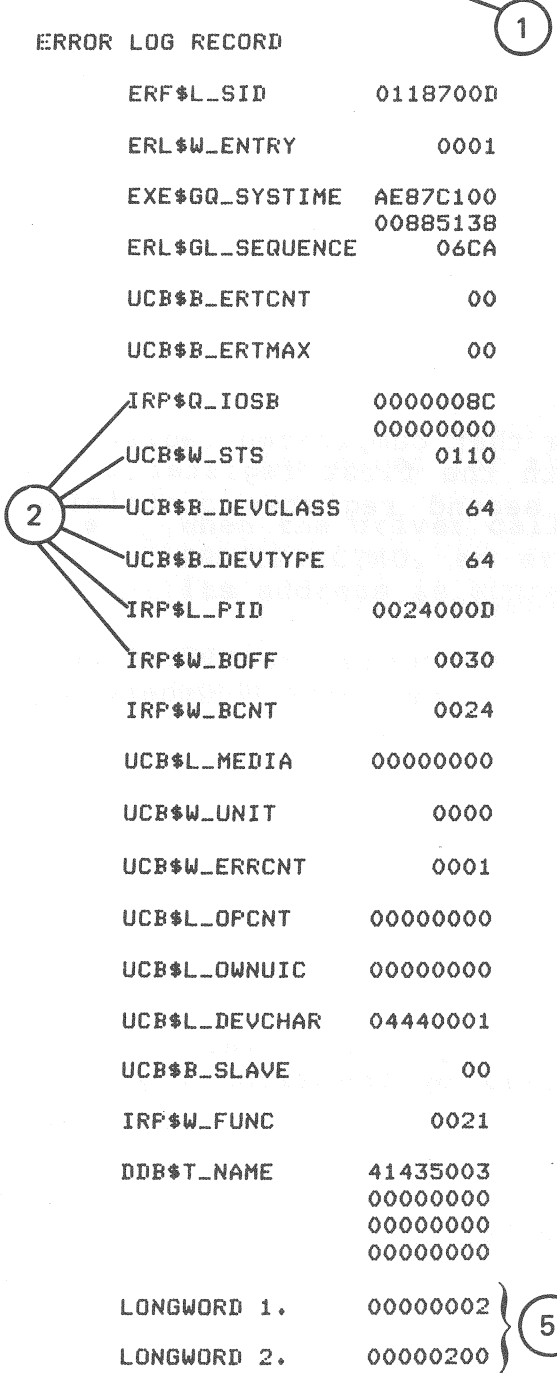
VOLUME OWNER UIC = [000,000]

DEVICE CHARACTERISTICS

DEVICE SLAVE CONTROLLER = 0.

QIO FUNCTION CODE

/.PCA...../



*Device registers*

Example 9-2 Sample SYE Error Report

OPTIONAL DRIVER ROUTINES

V A X / V M S

SYSTEM ERROR REPORT

COMPILED 26-JUN-1980 14:25

PAGE 2.

LONGWORD 3. 00000020 }

5

\*\*\*\*\* ENTRY  
UNKNOWN DEVICE TYPE, DEVICE ERROR  
ERROR SEQUENCE 1739.

3. \*\*\*\*\*  
LOGGED 19-JUN-1980 14:34:38.71  
SYSTEM ID REGISTER 118700D

ERROR LOG RECORD

ERF\$L\_SID 0118700D  
ERL\$W\_ENTRY 0001  
EXE\$GQ\_SYSTIME B27B6960  
00885138  
ERL\$GL\_SEQUENCE 06CB  
UCB\$B\_ERTCNT 00  
UCB\$B\_ERTMAX 00  
IRP\$Q\_IOSB 0000008C  
00000000  
UCB\$W\_STS 0110  
UCB\$B\_DEVCLASS 64  
UCB\$B\_DEVTYPE 64  
IRP\$L\_PID 0024000D  
IRP\$W\_BOFF 0030  
IRP\$W\_BCNT 0024  
UCB\$L\_MEDIA 00000000  
UCB\$W\_UNIT 0000  
UCB\$W\_ERRCNT 0002  
UCB\$L\_OPCNT 00000001  
UCB\$L\_OWNUIC 00000000  
UCB\$L\_DEVCHAR 04440001  
UCB\$B\_SLAVE 00  
IRP\$W\_FUNC 0021  
DDB\$T\_NAME 41435003  
00000000  
00000000  
00000000  
LONGWORD 1. 00000002

SYSTEM ID REGISTER

ERROR ENTRY TYPE

64 BIT TIME WHEN ERROR LOGGED

UNIQUE ERROR SEQUENCE = 1739.

REMAINING RETRIES = 0.

MAXIMUM RETRIES = 0.

FINAL IOSB

FINAL DEVICE STATUS

DEVICE CLASS = 100.

DEVICE TYPE = 100.

REQUESTING PROCESS ID

TRANSFER BYTE OFFSET = 48.

TRANSFER BYTE COUNT = 36.

DEVICE DEPENDANT PHYSICAL ADDRESS

PHYSICAL UNIT NUMBER = 0.

UNIT ERROR COUNT = 2.

UNIT OPERATION COUNT = 1.

VOLUME OWNER UIC = [000,000]

DEVICE CHARACTERISTICS

DEVICE SLAVE CONTROLLER = 0.

QIO FUNCTION CODE

/.PCA...../

Example 9-2 Sample SYE Error Report (Cont)





THE UNIVERSITY OF CHICAGO  
DIVISION OF THE PHYSICAL SCIENCES  
DEPARTMENT OF CHEMISTRY  
5708 SOUTH CAMPUS DRIVE  
CHICAGO, ILLINOIS 60637  
TEL: 773-936-3700  
FAX: 773-936-3701  
WWW: WWW.CHEM.UCHICAGO.EDU

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CHICAGO, ILLINOIS 60637





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